

# Im2mesh Function List and Parameters

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## Functions

Functions are sorted according to the workflow of Im2mesh package.

### im2mesh

Generate triangular mesh based on grayscale segmented image using MESH2D mesh generator (Darren Engwirda)

```
[ vert, tria, tnum ] = im2mesh( im );    % this use default opt setting  
[ vert, tria, tnum ] = im2mesh( im, opt );
```

### im2meshBuiltIn

Generate triangular mesh based on grayscale segmented image using matlab built-in function generateMesh

```
[ vert, tria, tnum ] = im2meshBuiltIn( im );    % this use default setting  
[ vert, tria, tnum ] = im2meshBuiltIn( im, opt );
```

### plotMeshes

Plot meshes

```
plotMeshes( vert, tria, tnum );
```

### tricast

Evaluate mesh quality

```
tricast(vert, tria, tnum);
```

### im2Bounds

Extract exact polygonal boundaries from grayscale segmented image using getExactBounds.m

```
bounds = im2Bounds( im );
```

### getExactBounds

Get the exact boundaries (polygonal) of binary image

```
Bs = getExactBounds( bw );
```

### **totalNumVertex**

Calculate the total number of vertices in all polygonal boundaries

```
num_vert = totalNumVertex( bounds );
```

### **getCtrlPnts**

Get control points in polygon boundaries

```
new_bounds = getCtrlPnts( bounds, tf_avoid_sharp_corner, size_im );
```

### **plotBounds**

Plot polygon boundaries

```
plotBounds( bounds );  
plotBounds( bounds, true );      % show starting and control points
```

### **totalNumCtrlPnt**

Calculate the total number of control points in all polygonal boundaries. Each polygon has at least one ccontrol point (i.e., the starting vertex).

```
num_ctrlp = totalNumCtrlPnt( bounds );
```

### **smoothBounds**

Smooth polygon boundaries using 2d Taubin Smoothing (taubinSmooth.m)

```
new_bounds = smoothBounds( bounds, lambda, mu, iters, ...  
                           threshold_num_turning, threshold_num_vert );
```

### **smoothBoundsCCMA**

Smooth polygon boundaries using CCMA smoothing algorithm (CCMA.m)

CCMA stand for curvature corrected moving average (<https://github.com/UniBwTAS/ccma>).

```
new_bounds = smoothBoundsCCMA( bounds, w_ma, w_cc, ...  
                              threshold_num_turning, threshold_num_vert );
```

### **simplifyBounds**

Simplify polygon boundaries using Douglas–Peucker algorithm (dpsimplify.m)

```
new_bounds = simplifyBounds( bounds, tolerance, threshold_num_vert )
```

### **delZeroAreaPoly**

Delete polygon with zero area

```
bounds = delZeroAreaPoly( bounds );
```

### **getPolyNodeEdge**

Get nodes and edges of polygonal boundary

```
[ poly_node, poly_edge ] = getPolyNodeEdge( bounds );
```

### **regroup**

Organize cell array poly\_node, poly\_edge into array nodeU, edgeU & cell array part for MESH2D

```
[ nodeU, edgeU, part ] = regroup( poly_node, poly_edge );
```

### **poly2mesh**

Generate meshes of parts defined by polygons using MESH2D mesh generator (Darren Engwirda)

```
[vert,tria,tnum] = poly2mesh( poly_node, poly_edge, hmax, mesh_kind, grad_limit );
```

### **bound2polyshape**

Convert polygonal boundaries to a cell array of polyshape object

```
p = bound2polyshape( bounds );
```

### **poly2meshBuiltIn**

generate meshes of parts defined by polygons using matlab built-in function generateMesh.

```
[ vert, tria, tnum ] = im2meshBuiltIn( im, opt );
```

### **getNodeEle**

Get node coordinates and elements from mesh

```
[ nodecoor_list, nodecoor_cell, ele_cell ] = getNodeEle( vert, tria, tnum, ele_order );
```

### **getInterf**

Find nodes at the interface between different phases.

```
interfnod_cell = getInterf( nodecoor_cell );
```

### **getBCNode**

Find nodes at the boundary.

```
[ xmin_node_cell, xmax_node_cell, ...  
  ymin_node_cell, ymax_node_cell ] = getBCNode( nodecoor_cell );
```

### **printInp\_multiPart**

Print the nodes and elements into Inp file 'test\_multi\_parts.inp', test in software Abaqus. Each phase corresponds to one part in Abaqus.

```
printInp_multiPart( nodecoor_cell, ele_cell, ele_type, precision_nodecoor );
```

### **printInp\_multiSect**

Print the nodes and elements into Inp file 'test\_multi\_sections.inp', test in software Abaqus. One part with multiple sections. Each phase corresponds to one section in Abaqus.

```
printInp_multiSect( nodecoor_list, ele_cell, ele_type, precision_nodecoor );
```

### **printBdf**

Print the nodes and elements into Inp file 'test.bdf'

```
printBdf( nodecoor_list, ele_cell, precision_nodecoor );
```

### **printTria**

Print nodes and elements into file 'test.node' & 'test.ele'. Only support triangular element with 3 nodes. Precision is number of digits behind decimal point, for node coordinates

```
printTria( vert, tria, tnum, precision_nodecoor );
```

### **getPixelPercent**

Calculate the area percentage of each grayscale in image

```
percent_pixel = getPixelPercent( im );
```

### getPolyShapePercent

Calculate the area percentage of each phase in polygonal boundaries

```
percent_polyarea = getPolyShapePercent( bounds );
```

## Parameters

### Parameters and their default values of function im2mesh

```
opt.tf_avoid_sharp_corner = false;  
opt.lambda = 0.7;  
opt.mu = -0.4;  
opt.iters = 10;  
opt.threshold_num_turning = 10;  
opt.threshold_num_vert_Smo = 10;  
opt.tolerance = 0.3;  
opt.threshold_num_vert_Sim = 10;  
opt.grad_limit = 0.25;  
opt.hmax = 500;  
opt.mesh_kind = 'del aunay';  
opt.select_phase = [];
```

### Parameters and their default values of function im2meshBuiltIn

```
opt.tf_avoid_sharp_corner = false;  
opt.lambda = 0.7;  
opt.mu = -0.4;  
opt.iters = 10;  
opt.threshold_num_turning = 10;  
opt.threshold_num_vert_Smo = 10;  
opt.tolerance = 0.3;  
opt.threshold_num_vert_Sim = 10;  
opt.hgrad = 1.25;  
opt.hmax = 500;  
opt.hmin = 1;
```

### tf\_avoid\_sharp\_corner

Type: boolean.

For getCtrlPnts.

Meaning: Whether to avoid sharp corner when simplifying polygon. If true, two extra control points will be added around one original control point to avoid sharp corner when simplifying polygon.

### **lambda**

Type: Float. Range:  $0 < \text{Lambda} < 1$ .

For smoothBounds.

Meaning: How far each node is moved toward the average position of its neighbours during every second iteration.

### **mu**

Type: Float. Range:  $-1 < \text{Mu} < 0$ .

For smoothBounds.

Meaning: How far each node is moved opposite the direction of the average position of its neighbours during every second iteration.

### **iters**

Type: Integer. Range:  $\geq 0$ .

For smoothBounds.

Meaning: Number of iterations in Taubin smoothing. If you don't need polyline smoothing, set Iterations to 0.

### **threshold\_num\_turning**

Type: Integer. Range:  $\geq 0$ .

For smoothBounds.

Meaning: Threshold value for the number of turning points in a polyline. Only those polylines with number of turning points greater than this threshold will be smoothed.

### **threshold\_num\_vert\_Smo**

Type: Integer. Range:  $\geq 0$ .

For smoothBounds.

Meaning: Threshold value for the number of vertices in a polyline. Only those polylines with number of vertices greater than this threshold will be smoothed.

**tolerance**

Type: Float. Range:  $\geq 0$ .

For simplifyBounds.

Meaning: The maximum allowable deviation of a vertex from the simplified curve. It's for Douglas-Peucker algorithm. If you don't need to simplify polylines, set tolerance to 0.

**threshold\_num\_vert\_Sim**

Type: Integer. Range:  $\geq 0$ .

For simplifyBounds.

Meaning: Threshold value for the number of vertices in a polyline. Only those polylines with number of vertices greater than this threshold will be simplified.

**grad\_limit**

Type: Float. Range:  $> 0$ . Typical value: 0.2 - 0.5.

For poly2mesh & MESH2D.

Meaning: Gradient-limit, a limit on the gradient of mesh-size function.

**hmax**

Type: Float. Range:  $> 0$ .

For poly2mesh & MESH2D.

Meaning: Maximum mesh edge lengths. This is an approximate upper bound on the mesh edge lengths.

**mesh\_kind**

Value: 'delaunay' or 'delfront'

For poly2mesh & MESH2D.

Meaning: Meshing algorithm used to create mesh-size functions based on an estimate of the "local-feature-size" associated with a polygonal domain. 'delaunay' means Delaunay-refinement. 'delfront' means Frontal-Delaunay.

**select\_phase**

Type: vector

Meaning: Select certain phases in image for meshing. If 'select\_phase' is [], all the phases will be chosen.



'select\_phase' is an index vector for sorted grayscales (ascending order) in an image. For example, an image with grayscales of 40, 90, 200, 240, 255. If u're interested in 40, 200, and 240, then set 'select\_phase' as [1 3 4]. Those phases corresponding to grayscales of 40, 200, and 240 will be chosen to perform meshing.

### **hgrad**

Type: Float. Range:  $1 \leq \text{Mesh Growth Rate} \leq 2$ . Typical value: 1.2 - 1.5.

For poly2meshBuiltIn & generateMesh

Meaning: Mesh growth rate, the rate at which the mesh transitions between regions of different edge size.

### **hmin**

Type: Float. Range:  $\geq 0$ .

For poly2meshBuiltIn & generateMesh

Meaning: Min mesh edge length, an approximate lower bound on the mesh edge lengths.