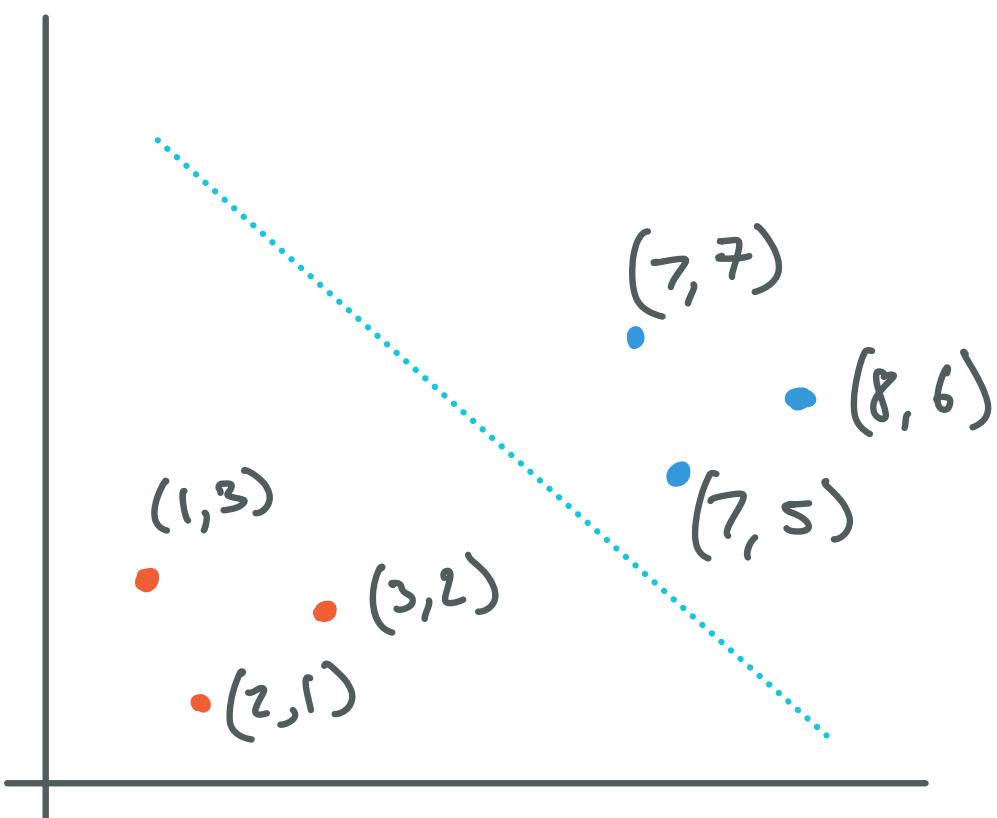


## Linearly Separable data



"randomly" initialized weight matrix

working in 2D so weight matrix  
(really vector) has size  $n+1$  w/  
 $n = \text{dimension}$

$$\omega = (0.5, 0.5, 0.5)$$

“randomly &  
initialized  
to 0.5”

we also have a data matrix  
(this time an actual matrix)

that holds each data point as a row. we construct it as such

$$D = \begin{pmatrix} 1, x_1, y_1, \bullet \\ \vdots \\ 1, x_n, y_n, \bullet \end{pmatrix}$$

So, b/c we are working in 2D space, each row is four elements long. The first element of each row is always 1. This is b/c, what we are ultimately constructing is a  $y = mx + b$  relation that splits the data. Therefore, in order for the  $b$  value to be non-zero, the first element of each row must be 1. This will become more obvious when we do the actual lin-alg. then, the next two values are the  $x$  &  $y$  position, & the final element of each row is the data type,

(as the perceptron is ultimately a classification algorithm). In this case, our data types are blue & orange. We will call blue 1 & orange 0, so our real data matrix for this example becomes

$$D = \begin{pmatrix} 1 & 1 & 3 & 0 \\ 1 & 7 & 7 & 1 \\ 1 & 8 & 6 & 1 \\ 1 & 7 & 5 & 1 \\ 1 & 3 & 2 & 0 \\ 1 & 2 & 1 & 0 \end{pmatrix}$$

We can therefore see that

$$D \in \mathbb{R}^{m \times n} \text{ s.t. } m = \text{Spatial dimension} + 2$$

$\&$

$$n = \# \text{ of data points}$$

Now we 'train' the weight matrix. We take the dot product of the weight vector w/ the first row (s only first three entries) of the data matrix

$$\text{So } \text{output} = \begin{pmatrix} 0.5 \\ 0.5 \\ 0.5 \end{pmatrix} (1 \ 1 \ 3)$$

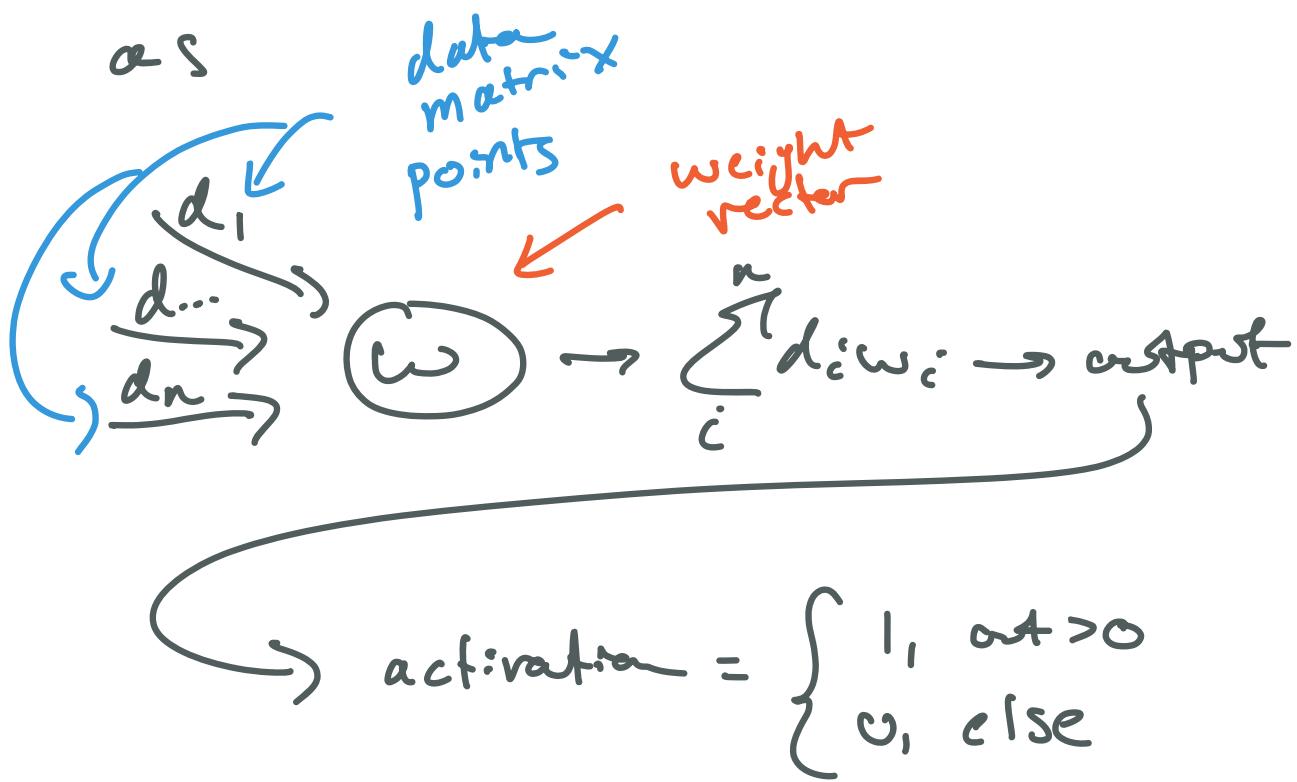
$$\Rightarrow \text{output} = 2.5$$

We then run this output through a simple activation function which for this model we define as

$$f(x) = \begin{cases} 1, \text{out} > 0 \\ 0 \text{ else} \end{cases}$$

OR you can think of it

as



Then, we take this final value (0 or 1) & compare it to what that row in the data matrix actually corresponded to. Remember, we only used the first 3 elements of each data matrix row, as the last value is what we test on. Also recall we defined orange = 0 & blue = 1 ... So...

We take the dot product of the weight vector  $w$  the  $i^{\text{th}}$  row (again, only first 3 elements) of the data matrix  $X$  to test if we get the correct output.

- If we do, we do not change the weight vector.
- If we don't (prediction  $\neq$  actual value), we update each element of the weight matrix according to

$$w_j = \eta \cdot \text{error} \cdot d_{ij}$$

where

$w_j$  =  $j^{\text{th}}$  element of the weight matrix

$\eta$  = learning rate (hyperparameter)

error = actual - pred.z.fcn  
(so either 1 or -1 or 0)

$d_{ij}$  =  $j^{\text{th}}$  element of  $i^{\text{th}}$  row of  
the data matrix.

## Calculating the weight matrix by hand

So now, let's calculate the  
weight matrix after 1  
epoch

→ 1 epoch means one pass  
through the entire data matrix.  
OR, taking the dot product of  
the weight vector w/ each

data matrix row exactly once.

initially sorted  
arbitrary

Recall

$$\vec{w} = \begin{pmatrix} 0.5 \\ 0.5 \\ 0.5 \end{pmatrix} \quad \text{and}$$

$$D = \begin{pmatrix} 1 & 1 & 3 & 0 \\ 1 & 7 & 7 & 1 \\ 1 & 8 & 6 & 1 \\ 1 & 7 & 5 & 1 \\ 1 & 3 & 2 & 0 \\ 1 & 2 & 1 & 0 \end{pmatrix}$$

So...

$$dp_1 = \begin{pmatrix} 0.5 \\ 0.5 \\ 0.5 \end{pmatrix} (1 \ 1 \ 3) = 2.5 > 0 \rightarrow dp_1 = 1$$

however, we see  $dP_1 \neq 1$ ,

so we update the weight vector

(for simplicity,  $\eta = \text{learning rate} = 1$ )

$$\text{error} = -1$$

$$\rightarrow \vec{w} = \begin{pmatrix} -0.5 \\ -0.5 \\ -1.5 \end{pmatrix}$$

$$dP_2 = \begin{pmatrix} -0.5 \\ -0.5 \\ -1.5 \end{pmatrix} (1 \neq 7) = -14.5 \neq 0 \rightarrow dP_2 = 0$$

which is false, so we update

$\vec{w}$  again

$$\text{error} = 1$$

$$\rightarrow \vec{w} = \begin{pmatrix} -0.5 \\ -3.5 \\ -10.5 \end{pmatrix}$$

$$dP_3 = \begin{pmatrix} -0.5 \\ -3.5 \\ -10.5 \end{pmatrix} (1 \neq 8 \neq 6) = -91.5 \neq 0$$

$\rightarrow dP_3 = 0$  again, false so we update

$$\text{error} = 1$$
$$\rightarrow \vec{\omega} = \begin{pmatrix} -0.5 \\ -28 \\ -63 \end{pmatrix}$$

$$dp_4 = \begin{pmatrix} -0.5 \\ -28 \\ -63 \end{pmatrix} (1 \neq 5) = \text{idk but def}$$

net > 0  $\rightarrow dp_4 = 0$  which is false so we update again!

$$\text{error} = 1$$

★ You can see here our weight values are quickly increasing. This is where the learning rate comes into play. If we chose a smaller learning rate, the weight values would be increasing much more slowly.

$\rightarrow$  Too high a learning rate, & you may overshoot the optimal weights. Too small a learning rate, & it'll take a while for the weights to

find the optimum (wastes compute)

So now

$$\vec{w} = \begin{pmatrix} -0.5 \\ -196 \\ -315 \end{pmatrix}$$

$$dp5 = \begin{pmatrix} -0.5 \\ -196 \\ -315 \end{pmatrix} (1 \ 3 \ 2) = -1218.5 \neq 0$$

$\rightarrow dp5 = 0$  wh, zh is TRUE so  
no update!

$$dp6 = \begin{pmatrix} -0.5 \\ -196 \\ -315 \end{pmatrix} (1 \ 2 \ 1) = -707.5 \neq 0$$

$\rightarrow dp6 = 0$  wh, zh is TRUE so  
no update.

→ Therefore, after one epoch  
(pass through the data matrix)  
our weight vector is

$$\vec{w} = \begin{pmatrix} -0.5 \\ -1.96 \\ -3.15 \end{pmatrix}$$

which is obviously not  
correct nor ideal, but that  
is why you have to choose  
an appropriate learning rate  
as well as do more than 1  
epoch

→ After a successful training  
run, you will have a weight  
vector in the form

$$\vec{w} = \begin{pmatrix} \alpha \\ \beta \\ \gamma \end{pmatrix}$$

From which you turn into  
a  $y = mx + b$  equation as  
 $\alpha$  is associated with  $b$ ,  $\beta$  with  
 $x$  &  $\gamma$  with  $y$

$$\Rightarrow \gamma y + \beta x + \alpha b = 0$$

$$\cancel{\phi} \Rightarrow y = -\left(\frac{\beta}{\gamma}x + \frac{\alpha}{\gamma}\right) \cancel{\phi}$$

→ And there is your decision  
boundary obtained from the  
weight vector that gets updated  
during training!!

→ It is easy to see how this  
can scale to n-dimensions &  
why we usually get computers to  
do this - the math is very tedious.

→ Unfortunately, however, the perceptron can only separate linearly separable data, which most real world data/functions/patterns are not !!

- ↳ To address this, we must add layers & non-linearities!
- ↳ Which we will get to next week!!