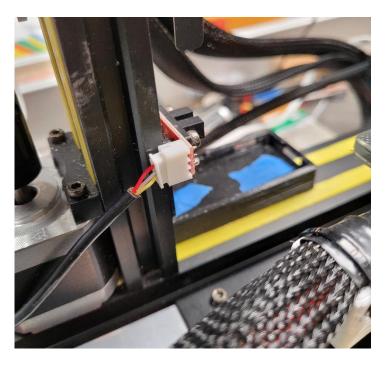


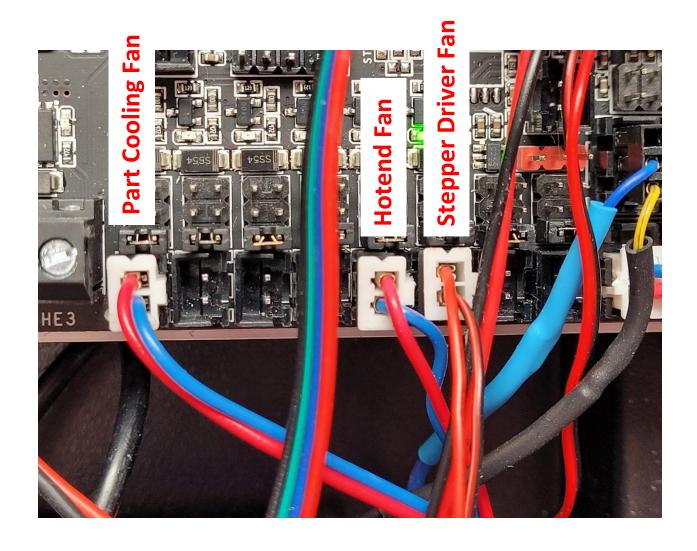
Note that all DIAG jumpers are removed since hardware endstops are used. Note that I had to change the pin order on at least one of the Z stops. The sensor ends of the cables are shown on the next page.

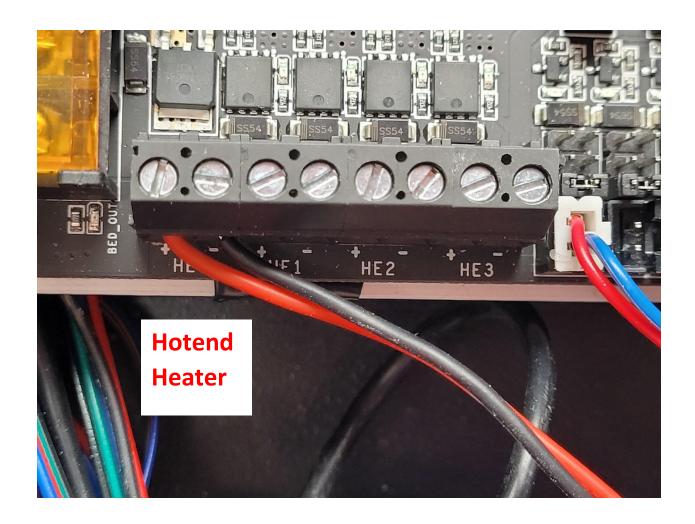


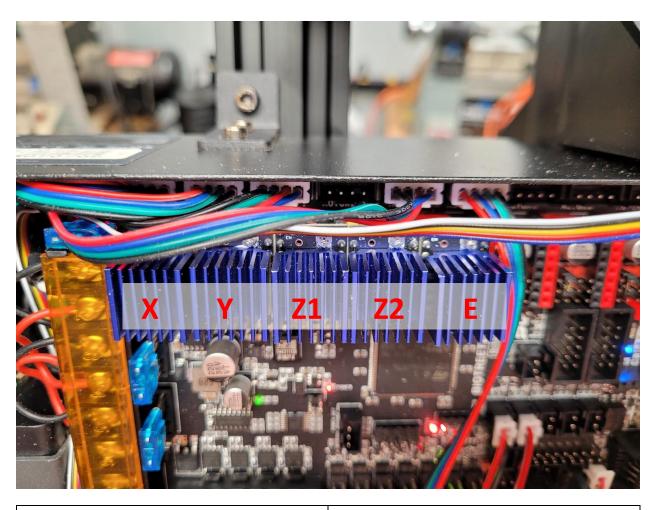
Z1 End Stop (Display/Extruder Side)



Z2 End Stop





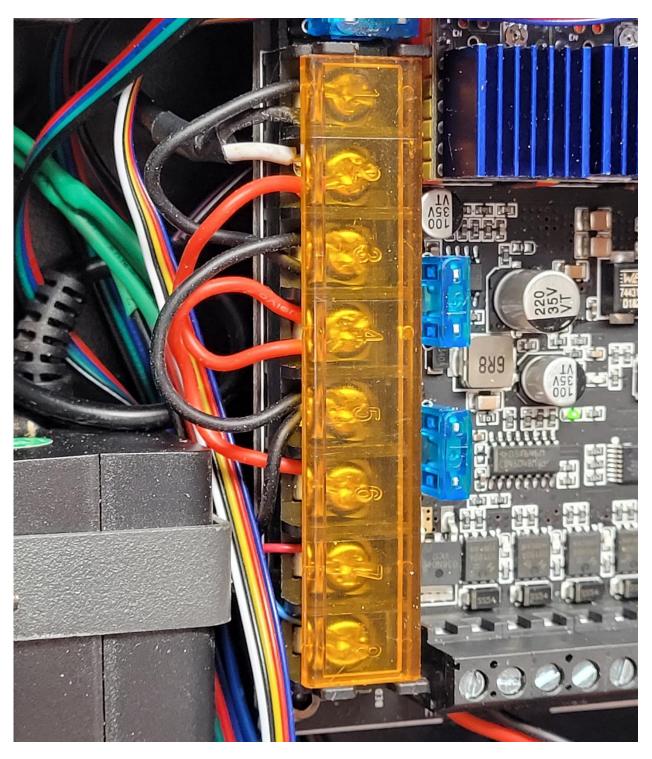


MOTOR0	X
MOTOR1	Υ
MOTOR2_1	Z 1
MOTOR2_2	NOT USED
MOTOR3	Z 2
MOTOR4	E

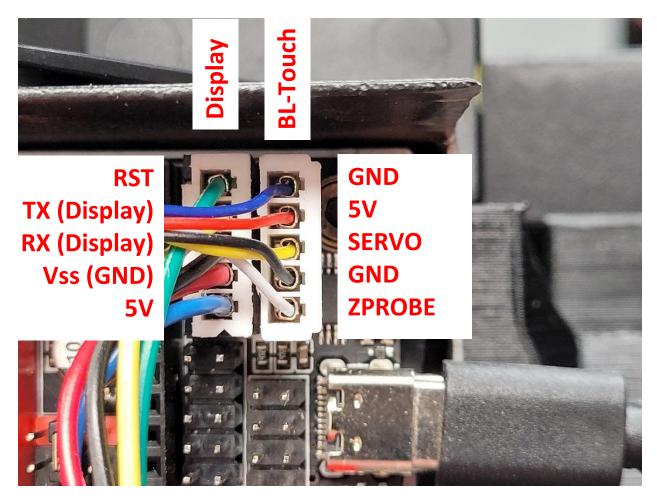
The motor wire colors for my stepper motors likely don't match stock as I used replacement cables that were longer and swapped pins to get rotation correct.



All stepper drivers (TMC2209) had the jumper shown installed to use the drivers in UART mode.



I ran all power input to the board from the small power supply and added jumper wires between the input terminals. I wired the MOSFET control wires into the Bed Out. I also ran a common neutral between the large and small power supplies.



I had to change the pin order on both my display cable and BL-Touch cable. Note that for the stock display, RX on the display connects to TX on the Octopus and TX on the display connects to RX on the Octopus. For the BTT TFT35 E3 V3.0, I did not have to swap RX and TX. For some BL-Touch/CR-Touch models, the cable supplied has the probe end wired in reverse order. The probe end of my cable is shown on the next page. If wires are in the wrong order, probability of damaging the probe or board is high.

