```
/* USER CODE BEGIN Header */
2
     *********************
3
             : main.c
: Main program body
     * @file
4
     * @brief
5
     **********************
6
7
     * @attention
9
     * Copyright (c) 2023 STMicroelectronics.
    * All rights reserved.
10
11
12
    * This software is licensed under terms that can be found in the LICENSE file
13
     * in the root directory of this software component.
     * If no LICENSE file comes with this software, it is provided AS-IS.
14
15
     ******************
16
17
   /* USER CODE END Header */
18
   /* Includes -----*/
19
20
   #include "main.h"
   #include "fatfs.h"
21
22
   /* Private includes -----*/
23
   /* USER CODE BEGIN Includes */
24
25
   #include "fram func.h"
26
   #include "sd card func.h"
27
28
   /* USER CODE END Includes */
29
   /* Private typedef -----*/
30
   /* USER CODE BEGIN PTD */
31
32
33
   /* USER CODE END PTD */
34
   /* Private define -----*/
35
   /* USER CODE BEGIN PD */
36
37
   //#define MEMORY SIZE 524288
38
   /* USER CODE END PD */
39
   /* Private macro -----*/
40
41
   /* USER CODE BEGIN PM */
42
43
   /* USER CODE END PM */
44
   /* Private variables -----*/
45
46
   DAC HandleTypeDef hdac1;
47
48
   I2C HandleTypeDef hi2c1;
49
   I2C HandleTypeDef hi2c2;
50
51
   SD HandleTypeDef hsd1;
52
53
   SPI HandleTypeDef hspil;
54
   SPI HandleTypeDef hspi2;
55
   DMA HandleTypeDef hdma spi1 rx;
   DMA HandleTypeDef hdma spi1 tx;
56
57
58
   TIM HandleTypeDef htim16;
59
60
   UART HandleTypeDef huart1;
61
62
   HCD HandleTypeDef hhcd USB OTG FS;
63
64
   /* USER CODE BEGIN PV */
65
   /* USER CODE END PV */
66
67
   /* Private function prototypes -----*/
68
69
   void SystemClock_Config(void);
70
   static void MX_GPIO_Init(void);
   static void MX_DAC1_Init(void);
   static void MX_SDMMC1_SD_Init(void);
   static void MX_SPI1_Init(void);
```

```
static void MX USART1 UART Init (void);
 74
 75
     static void MX I2C1 Init(void);
 76
     static void MX I2C2 Init(void);
 77
     static void MX SPI2 Init(void);
 78
     static void MX DMA Init(void);
     static void MX_USB_OTG FS HCD Init(void);
 79
 80
     static void MX TIM16 Init (void);
 81
     /* USER CODE BEGIN PFP */
 82
 83
     /* USER CODE END PFP */
 84
     /* Private user code -----*/
 85
 86
     /* USER CODE BEGIN 0 */
 87
     const uint32 t TAB SIZE = (MEMORY SIZE/16);
 88
     enum color Led LED STATE = OFF;
 89
     bool reset = true;
 90
     bool start = true;
 91
     bool acqu = true;
 92
     /* USER CODE END 0 */
 93
 94
 95
       * @brief The application entry point.
 96
       * @retval int
       * /
 97
 98
     int main(void)
 99
       /* USER CODE BEGIN 1 */
100
101
         //FRESULT res; /* FatFs function common result code */
102
         TCHAR* fileName0 ;
103
         TCHAR* fileName1 ;
104
         TCHAR* fileName2 ;
105
         TCHAR* fileName3;
         TCHAR* file Init = "INIT.txt";
106
         uint8_t TX_Data ADC[2];
107
108
         uint8 t TX FRAM TEST R[10] ;
109
         uint16_t DATA_SD;
110
         uint16_t DATA_ind [TAB_SIZE/2];
111
         uint8 t pretrigValue = 100;
112
113
         //uint8 t RX DATA [524288]; -> TOO BIG
114
115
116
       /* USER CODE END 1 */
117
        /* MCU Configuration-----*/
118
119
120
        /* Reset of all peripherals, Initializes the Flash interface and the Systick. */
121
       HAL Init();
122
123
       /* USER CODE BEGIN Init */
124
125
       /* USER CODE END Init */
126
127
       /* Configure the system clock */
128
       SystemClock_Config();
129
130
       /* USER CODE BEGIN SysInit */
131
132
       /* USER CODE END SysInit */
133
134
       /* Initialize all configured peripherals */
135
       MX GPIO Init();
136
       MX DAC1 Init();
137
       MX SDMMC1 SD Init();
138
       MX_SPI1_Init();
       MX_USART1_UART_Init();
139
140
       MX_I2C1_Init();
141
       MX_I2C2_Init();
142
       MX_SPI2_Init();
143
       MX_DMA_Init();
144
       MX_USB_OTG_FS_HCD_Init();
145
       MX_FATFS_Init();
146
       MX_TIM16_Init();
```

```
/* USER CODE BEGIN 2 */
147
148
149
       /* USER CODE END 2 */
150
       /* Infinite loop */
151
152
       /* USER CODE BEGIN WHILE */
153
       uint8_t start_Add[4] ;
154
        uint3\overline{2} t start Add tot = 0;
        uint32_t Add_= 0;
uint8_t TX_32 = 0;
155
156
157
        uint16_t boucle = 0;
        uint8_t wtext_0 [100];
uint8_t wtext_1 [100];
uint8_t wtext_2 [100];
uint8_t wtext_3 [100];
159
160
161
        uint8 t* receive;
162
        uint8 t chann;
163
        double* dataInit_;
164
165
        double triggDacValue;
        PIN reset();
166
167
        //FRAM device(hspi1);
168
       while (1)
169
170
         acqu = true;
171
         TX 32 = 0;
172
         start = true;
173
         HAL SuspendTick();
         WFI();
174
175
         //-----RESET
176
         FPGA-----
177
         HAL GPIO WritePin (FPGA RESET GPIO Port, FPGA RESET Pin, GPIO PIN RESET);
178
         HAL Delay (100);
         HAL GPIO WritePin(FPGA RESET GPIO Port, FPGA RESET Pin, GPIO PIN SET);
179
         //------RESET
180
181
         PIN reset();
182
         //----INIT-----INIT-----
183
         //----init file sd ------
184
         sprintf((char*)wtext 0, "FRAM0 %d.bin",boucle);
185
         fileName0 = (TCHAR*) wtext 0;
         SD_create_file(SDFile, fileName0);
186
187
         sprintf((char*)wtext_1, "FRAM1_%d.bin",boucle);
188
         fileName1 = (TCHAR*) wtext 1;
189
         SD create file(SDFile, fileName1);
         sprintf((char*)wtext 2, "FRAM2 %d.bin",boucle);
190
         fileName2 = (TCHAR*)wtext 2;
191
192
         SD create file(SDFile, fileName2);
         sprintf((char*)wtext 3, "FRAM3 %d.bin",boucle);
193
194
         fileName3 = (TCHAR*)wtext 3;
195
         SD create file(SDFile, fileName3);
196
         //----init
197
         value-----
198
         dataInit = initValue(SDFile, file Init);
199
200
         chann = (uint8 t)dataInit [0];
201
         if(chann >4){
202
            chann = 0;
203
204
         triggDacValue = dataInit [1]*(0.02)+1;
205
         if(triggDacValue <1 || triggDacValue>3.3){
206
            triggDacValue = 1;
207
208
         pretrigValue = (uint8 t)dataInit [2];
209
         if(pretrigValue >100){
210
            pretrigValue = 100;
211
212
         CONTROL-----
         if(LED STATE != RED) {
213
```

```
214
           LED on (BLUE);
215
        }
216
        else{
217
            while(1){
218
               //reset the systeme
219
            }
220
        }
221
222
        //-----init trigg dc value-----
        uint32 t triggDac = (uint32 t)((triggDacValue/VREF VOLTAGE)*DAC MAX VALUE);
223
        HAL_DAC_SetValue(&hdac1, DAC1_CHANNEL_2, DAC_ALIGN_12B_R, triggDac);
224
225
        HAL_DAC_Start(&hdac1, DAC1_CHANNEL_2);
        HAL DAC SetValue(&hdac1, DAC1 CHANNEL 1, DAC ALIGN 12B R, triggDac);
226
        HAL DAC Start (&hdac1, DAC1 CHANNEL 1);
227
228
        //----init pretrigg value-----
229
230
        HAL SPI Transmit (&hspi1, (uint8 t*) &pretrigValue, 1, 100);
231
        HAL GPIO WritePin (FPGA PRETRIG GPIO Port, FPGA PRETRIG Pin, GPIO PIN SET);
232
        HAL SPI Transmit (&hspil, (uint8 t*)&pretrigValue,1, 100);
233
        HAL GPIO WritePin (FPGA PRETRIG GPIO Port, FPGA PRETRIG Pin, GPIO PIN RESET);
234
235
        //-----init trigg channel ------
236
        setTriggChannel(chann);
        //----RESET FRAM
237
        REG-----
        FRAM_reset reg(hspi1);
238
        //-----WRITE FRAM
239
        REG-----
        FRAM_write reg(hspi1);
240
        //-----ADC WRITE
241
        REG-----
        TX Data ADC[0] = 0xA2;
242
        TX Data ADC[1] = 0x80;
243
        HAL GPIO WritePin (SELECTOR M1 GPIO Port, SELECTOR M1 Pin, GPIO PIN SET);
244
        HAL SPI Transmit(&hspi1, (uint8 t*)TX Data ADC,2, 100);
2.45
        HAL GPIO WritePin (SELECTOR M1 GPIO Port, SELECTOR M1 Pin, GPIO PIN RESET);
246
247
        HAL Delay(100);
248
249
        //-----WRITE
        FRAM-----
250
        PIN reset();
251
        TX FRAM TEST R[0] = 2;
252
        for(int i =1; i<5;i++){</pre>
253
          TX FRAM TEST R[i] = 0;
254
255
        TX FRAM TEST R[3] = 0;
        TX_FRAM_TEST_R[4] = 0;
TX_FRAM_TEST_R[5] = 56;
256
257
258
259
        HAL GPIO WritePin (SELECTOR M3 GPIO Port, SELECTOR M3 Pin, GPIO PIN SET);
        HAL SPI Transmit (&hspi1, (uint8 t*) TX FRAM TEST R,6, 100);
260
261
        HAL Delay(100);
262
        //-----ADC TO
263
        FRAM-----
        HAL GPIO WritePin(SELECTOR M1 GPIO Port, SELECTOR M1 Pin, GPIO PIN SET);
264
        //----SLEEP
265
        MODE-----
266
        //HAL PWR EnterSLEEPMode(PWR LOWPOWERREGULATOR ON, PWR SLEEPENTRY WFI);
267
        while(acqu){
268
            HAL SuspendTick();
            ___WFI();
269
270
        }
271
        //HAL PWR ENTER
272
        PIN reset();
273
        while(TX 32 <16) {</pre>
274
             if(TX 32 == 0){
275
                 PIN reset();
276
                 HAL_GPIO_WritePin(SELECTOR_M0_GPIO_Port, SELECTOR_M0_Pin, GPIO_PIN_SET);
                 HAL GPIO WritePin (SELECTOR M1 GPIO Port, SELECTOR M1 Pin, GPIO PIN SET); HAL GPIO WritePin (SELECTOR M3 GPIO Port, SELECTOR M3 Pin, GPIO PIN SET);
277
278
                 HAL_SPI_Receive(&hspi1, (uint8_t*)start_Add,4, 100);
279
280
                 HAL Delay(100);
```

```
start Add tot = (((uint32 t)start Add[0]) << 24) + (((uint32 t)start Add[1)) << 24) 
281
                                    ]) << 16)</pre>
282
                                                                                  +(((uint32 t)start Add[2])<<8)+((uint32 t)
                                                                                   start Add[3]);
283
                                    PIN reset();
284
                                    start Add tot = start Add tot>>12;
                                    //start Add tot = 0;
285
                                   HAL TIM Base Start IT(&htim16);
286
287
                           //----READ FRAM
288
289
                           for (uint32 t i = 0; i<(TAB SIZE/2) ; i++) {</pre>
                                    Add_ = i*2+TAB_SIZE*TX_32+(MEMORY_SIZE);
290
291
                                    if(Add_> MEMORY_SIZE){
                                           Add = Add - MEMORY_SIZE;
292
293
                                    }
294
                                   //receive = FRAM read(FRAM 0,i*2+TAB SIZE*TX 32, hspi1, 2);
295
                                  receive = FRAM read(FRAM 0, Add , hspi1, 2);
296
                                  DATA SD = (((uint16 t) receive [0]) << 8) + (uint16 t) (receive [1]);
                                  // DATA_SD = (((uint16_t)RX_FAST[i*2]) << 8) + (uint16_t)(RX_FAST[i*2+1]);
297
298
                                   DATA ind[i] = DATA SD;
299
300
                            SD write data(SDFile, fileName0, DATA ind);
                             //-----READ FRAM
301
                            for (uint32 t i = 0; i<(TAB SIZE/2); i++) {
302
                                    Add = i*2+TAB SIZE*TX 32+(MEMORY SIZE);
303
                                    if(Add > MEMORY SIZE){
304
305
                                           Add_ = Add_ - MEMORY_SIZE;
306
307
                                    receive = FRAM read (FRAM 1, Add , hspi1, 2);
308
                                    DATA SD = (((uint16 t)receive[0])<<8)+(uint16 t)(receive[1]);
309
                                    //DATA SD = (short) DATA SD;
                                   DATA ind[i] = DATA SD;
310
311
                            SD_write_data(SDFile, fileName1, DATA_ind);
312
                             //-----READ FRAM
313
314
                            for(uint32_t i = 0; i<TAB_SIZE/2 ; i++) {</pre>
315
                                    Add_ = i*2+TAB_SIZE*TX_32+(MEMORY_SIZE-start_Add_tot);
316
                                    if(Add_> MEMORY_SIZE){
317
                                          Add_ = Add_ - MEMORY_SIZE;
318
319
                                    receive = FRAM_read(FRAM_2,Add_, hspi1, 2);
320
                                    DATA SD = (((uint16 t)receive[0]) << 8) + (uint16 t)(receive[1]);
321
                                    //DATA SD = (short)DATA SD;
                                    DATA ind[i] = DATA SD;
322
323
324
                            SD write data(SDFile, fileName2, DATA ind);
                            //-----READ FRAM
325
326
                            for(uint32 t i = 0; i<TAB SIZE/2 ; i++){</pre>
                                   Add = i*2+TAB SIZE*TX 32+(MEMORY_SIZE-start_Add_tot);
327
328
                                    if (Add_> MEMORY_SIZE) {
329
                                          Add_ = Add_ - MEMORY_SIZE;
330
331
                                   receive = FRAM read(FRAM 3,Add , hspi1, 2);
332
                                    DATA SD = (((uint16 t)receive[0])<<8)+(uint16 t)(receive[1]);
333
                                    //DATA SD = (short) DATA SD;
334
                                    DATA ind[i] = DATA SD;
335
                            }
336
                            SD write data(SDFile, fileName3, DATA ind);
337
338
                             //receive = FRAM read(FRAM 3, TX 32, hspi1, 2);
                             //DATA\_SD = (((uint16_t)receive[0]) << 8) + (uint16_t)(receive[1]);
339
                             //DATA\_SD = (short)DATA\_SD;
340
341
                             //SD write data(SDFile, fileName3, DATA SD);
342
343
                     if(TX 32==16){
344
                            HAL_TIM_Base_Stop(&htim16);
345
                            if(LED STATE != RED) {
346
                                   LED off();
347
                                   LED_on(GREEN); //6
```

```
348
349
                else{
350
                    LED off();
351
                    LED on (RED);
352
                }
353
            }
354
            boucle++;
355
          /* USER CODE END WHILE */
356
          /* USER CODE BEGIN 3 */
357
358
        1
359
        /* USER CODE END 3 */
360
      }
361
362
363
        * @brief System Clock Configuration
364
        * @retval None
        * /
365
366
      void SystemClock Config(void)
367
368
        RCC OscInitTypeDef RCC OscInitStruct = {0};
369
        RCC ClkInitTypeDef RCC ClkInitStruct = {0};
370
371
        /** Configure the main internal regulator output voltage
372
373
        if (HAL PWREx ControlVoltageScaling(PWR REGULATOR VOLTAGE SCALE1) != HAL OK)
374
        {
375
          Error Handler();
376
        }
377
378
        /** Initializes the RCC Oscillators according to the specified parameters
379
        * in the RCC OscInitTypeDef structure.
380
        RCC_OscInitStruct.OscillatorType = RCC_OSCILLATORTYPE HSI48|RCC OSCILLATORTYPE MSI;
381
382
        RCC OscInitStruct.HSI48State = RCC HSI48 ON;
383
        RCC OscInitStruct.MSIState = RCC MSI ON;
384
        RCC OscInitStruct.MSICalibrationValue = 0;
385
        RCC OscInitStruct.MSIClockRange = RCC MSIRANGE 6;
386
        RCC_OscInitStruct.PLL.PLLState = RCC_PLL_ON;
387
        RCC_OscInitStruct.PLL.PLLSource = RCC_PLLSOURCE MSI;
        RCC_OscInitStruct.PLL.PLLM = 1;
388
        RCC_OscInitStruct.PLL.PLLN = 32;
389
390
        RCC_OscInitStruct.PLL.PLLP = RCC_PLLP_DIV2;
391
        RCC_OscInitStruct.PLL.PLLQ = RCC_PLLQ_DIV2;
392
            OscInitStruct.PLL.PLLR = RCC
                                          PLLR DIV2;
393
        if (HAL RCC OscConfig(&RCC OscInitStruct) != HAL OK)
394
395
          Error Handler();
396
397
398
        /** Initializes the CPU, AHB and APB buses clocks
399
        RCC_ClkInitStruct.ClockType = RCC CLOCKTYPE HCLK|RCC CLOCKTYPE SYSCLK
400
401
                                     |RCC CLOCKTYPE PCLK1|RCC CLOCKTYPE PCLK2;
402
        RCC ClkInitStruct.SYSCLKSource = RCC SYSCLKSOURCE PLLCLK;
403
        RCC ClkInitStruct.AHBCLKDivider = RCC SYSCLK DIV1;
        RCC ClkInitStruct.APB1CLKDivider = RCC HCLK DIV1;
404
405
        RCC ClkInitStruct.APB2CLKDivider = RCC HCLK DIV1;
406
407
        if (HAL RCC ClockConfig(&RCC ClkInitStruct, FLASH LATENCY 3) != HAL OK)
408
409
          Error Handler();
410
        }
411
      }
412
413
        * @brief DAC1 Initialization Function
414
415
        * @param None
416
        * @retval None
417
418
      static void MX DAC1 Init(void)
419
      {
420
```

```
421
        /* USER CODE BEGIN DAC1 Init 0 */
422
423
        /* USER CODE END DAC1 Init 0 */
424
425
        DAC ChannelConfTypeDef sConfig = {0};
426
427
        /* USER CODE BEGIN DAC1 Init 1 */
428
429
        /* USER CODE END DAC1 Init 1 */
430
431
        /** DAC Initialization
        */
432
433
        hdac1.Instance = DAC1;
434
        if (HAL_DAC_Init(&hdac1) != HAL_OK)
435
436
          Error Handler();
437
438
        /** DAC channel OUT1 config
439
        * /
440
441
        sConfig.DAC SampleAndHold = DAC SAMPLEANDHOLD DISABLE;
        sConfig.DAC Trigger = DAC TRIGGER NONE;
442
        sConfig.DAC_OutputBuffer = DAC_OUTPUTBUFFER_ENABLE;
443
        sConfig.DAC ConnectOnChipPeripheral = DAC_CHIPCONNECT_DISABLE;
444
        sConfig.DAC UserTrimming = DAC TRIMMING FACTORY;
445
446
        if (HAL DAC ConfigChannel (&hdac1, &sConfig, DAC CHANNEL 1) != HAL OK)
447
448
          Error Handler();
449
        }
450
451
        /** DAC channel OUT2 config
452
453
        if (HAL DAC ConfigChannel(&hdac1, &sConfig, DAC CHANNEL 2) != HAL OK)
454
455
          Error Handler();
456
457
        /* USER CODE BEGIN DAC1 Init 2 */
458
459
        /* USER CODE END DAC1 Init 2 */
460
461
      }
462
463
      /**
464
        * @brief I2C1 Initialization Function
465
        * @param None
466
        * @retval None
467
      static void MX I2C1 Init(void)
468
469
470
471
        /* USER CODE BEGIN I2C1 Init 0 */
472
473
        /* USER CODE END I2C1 Init 0 */
474
475
        /* USER CODE BEGIN I2C1_Init 1 */
476
477
        /* USER CODE END I2C1 Init 1 */
478
        hi2c1.Instance = I2C1;
479
        hi2c1.Init.Timing = 0x10707DBC;
480
        hi2c1.Init.OwnAddress1 = 0;
481
        hi2c1.Init.AddressingMode = I2C ADDRESSINGMODE 7BIT;
482
        hi2c1.Init.DualAddressMode = I2C DUALADDRESS DISABLE;
483
        hi2c1.Init.OwnAddress2 = 0;
484
        hi2c1.Init.OwnAddress2Masks = I2C OA2 NOMASK;
485
        hi2c1.Init.GeneralCallMode = I2C GENERALCALL DISABLE;
486
        hi2c1.Init.NoStretchMode = I2C NOSTRETCH DISABLE;
487
        if (HAL I2C Init(&hi2c1) != HAL OK)
488
489
          Error_Handler();
490
        }
491
492
        /** Configure Analogue filter
493
```

```
494
        if (HAL I2CEx ConfigAnalogFilter(&hi2c1, I2C ANALOGFILTER ENABLE) != HAL OK)
495
496
          Error Handler();
497
        }
498
499
        /** Configure Digital filter
500
        * /
501
        if (HAL I2CEx ConfigDigitalFilter(&hi2c1, 0) != HAL OK)
502
        {
503
          Error Handler();
504
        }
505
        /* USER CODE BEGIN I2C1 Init 2 */
506
507
        /* USER CODE END I2C1 Init 2 */
508
509
      }
510
511
512
        * @brief I2C2 Initialization Function
513
        * @param None
514
        * @retval None
        * /
515
516
      static void MX I2C2 Init(void)
517
      {
518
519
       /* USER CODE BEGIN I2C2 Init 0 */
520
521
        /* USER CODE END I2C2 Init 0 */
522
523
        /* USER CODE BEGIN I2C2 Init 1 */
524
525
        /* USER CODE END I2C2_Init 1 */
526
       hi2c2.Instance = I2C2;
527
        hi2c2.Init.Timing = 0 \times 10707 DBC;
528
       hi2c2.Init.OwnAddress1 = 0;
529
       hi2c2.Init.AddressingMode = I2C ADDRESSINGMODE 7BIT;
        hi2c2.Init.DualAddressMode = I2C DUALADDRESS DISABLE;
530
5.31
        hi2c2.Init.OwnAddress2 = 0;
532
        hi2c2.Init.OwnAddress2Masks = I2C_OA2_NOMASK;
533
        hi2c2.Init.GeneralCallMode = I2C_GENERALCALL_DISABLE;
534
        hi2c2.Init.NoStretchMode = I2C NOSTRETCH DISABLE;
535
        if (HAL I2C Init(&hi2c2) != HAL OK)
536
537
          Error Handler();
538
        }
539
540
        /** Configure Analogue filter
541
542
        if (HAL I2CEx ConfigAnalogFilter(&hi2c2, I2C ANALOGFILTER ENABLE) != HAL OK)
543
544
          Error_Handler();
545
        }
546
547
        /** Configure Digital filter
548
        if (HAL I2CEx ConfigDigitalFilter(&hi2c2, 0) != HAL OK)
549
550
551
          Error_Handler();
552
        }
553
        /* USER CODE BEGIN I2C2 Init 2 */
554
555
        /* USER CODE END I2C2_Init 2 */
556
557
      }
558
559
560
        * @brief SDMMC1 Initialization Function
561
        * @param None
562
        * @retval None
563
564
      static void MX SDMMC1 SD Init(void)
565
      {
566
```

```
567
        /* USER CODE BEGIN SDMMC1 Init 0 */
568
569
        /* USER CODE END SDMMC1 Init 0 */
570
571
        /* USER CODE BEGIN SDMMC1 Init 1 */
572
573
        /* USER CODE END SDMMC1_Init 1 */
574
        hsd1.Instance = SDMMC1;
575
        hsd1.Init.ClockEdge = SDMMC CLOCK EDGE RISING;
576
        hsd1.Init.ClockBypass = SDMMC CLOCK BYPASS DISABLE;
577
        hsd1.Init.ClockPowerSave = SDMMC CLOCK POWER SAVE DISABLE;
578
        hsd1.Init.BusWide = SDMMC BUS WIDE 1B;
579
        hsd1.Init.HardwareFlowControl = SDMMC HARDWARE FLOW CONTROL DISABLE;
580
        hsd1.Init.ClockDiv = 4;
581
        /* USER CODE BEGIN SDMMC1 Init 2 */
582
583
        /* USER CODE END SDMMC1 Init 2 */
584
585
586
587
588
        * @brief SPI1 Initialization Function
589
        * @param None
590
        * @retval None
        * /
591
592
      static void MX SPI1 Init(void)
593
594
595
        /* USER CODE BEGIN SPI1 Init 0 */
596
597
        /* USER CODE END SPI1 Init 0 */
598
599
        /* USER CODE BEGIN SPI1 Init 1 */
600
        /* USER CODE END SPI1 Init 1 */
601
602
        /* SPI1 parameter configuration*/
603
        hspil.Instance = SPI1;
604
        hspil.Init.Mode = SPI MODE MASTER;
605
        hspi1.Init.Direction = SPI_DIRECTION_2LINES;
606
        hspi1.Init.DataSize = SPI_DATASIZE_8BIT;
607
        hspi1.Init.CLKPolarity = SPI POLARITY HIGH;
608
        hspi1.Init.CLKPhase = SPI PHASE 2EDGE;
        hspil.Init.NSS = SPI_NSS_SOFT;
609
610
        hspil.Init.BaudRatePrescaler = SPI BAUDRATEPRESCALER 8;
611
        hspil.Init.FirstBit = SPI FIRSTBIT MSB;
612
        hspil.Init.TIMode = SPI TIMODE DISABLE;
613
        hspi1.Init.CRCCalculation = SPI CRCCALCULATION DISABLE;
        hspil.Init.CRCPolynomial = 7;
614
        hspi1.Init.CRCLength = SPI CRC LENGTH DATASIZE;
615
616
        hspi1.Init.NSSPMode = SPI_NSS_PULSE_DISABLE;
617
        if (HAL_SPI_Init(&hspi1) != HAL_OK)
618
619
          Error Handler();
620
621
        /* USER CODE BEGIN SPI1 Init 2 */
622
623
        /* USER CODE END SPI1 Init 2 */
624
625
      }
626
627
      /**
628
        * @brief SPI2 Initialization Function
629
        * @param None
630
        * @retval None
        */
631
632
      static void MX_SPI2_Init(void)
633
634
635
        /* USER CODE BEGIN SPI2 Init 0 */
636
637
        /* USER CODE END SPI2 Init 0 */
638
639
        /* USER CODE BEGIN SPI2 Init 1 */
```

```
640
641
        /* USER CODE END SPI2 Init 1 */
642
        /* SPI2 parameter configuration*/
643
        hspi2.Instance = SPI2;
644
        hspi2.Init.Mode = SPI MODE MASTER;
645
        hspi2.Init.Direction = SPI DIRECTION 1LINE;
646
        hspi2.Init.DataSize = SPI DATASIZE 4BIT;
647
        hspi2.Init.CLKPolarity = SPI POLARITY LOW;
648
        hspi2.Init.CLKPhase = SPI PHASE 1EDGE;
        hspi2.Init.NSS = SPI NSS SOFT;
649
650
        hspi2.Init.BaudRatePrescaler = SPI BAUDRATEPRESCALER 2;
651
        hspi2.Init.FirstBit = SPI FIRSTBIT MSB;
652
        hspi2.Init.TIMode = SPI TIMODE DISABLE;
653
        hspi2.Init.CRCCalculation = SPI CRCCALCULATION DISABLE;
654
        hspi2.Init.CRCPolynomial = 7;
        hspi2.Init.CRCLength = SPI CRC LENGTH DATASIZE;
655
656
        hspi2.Init.NSSPMode = SPI NSS PULSE ENABLE;
657
        if (HAL SPI Init(&hspi2) != HAL OK)
658
659
          Error Handler();
660
661
        /* USER CODE BEGIN SPI2 Init 2 */
662
663
        /* USER CODE END SPI2 Init 2 */
664
665
      }
666
667
668
        * @brief TIM16 Initialization Function
669
        * @param None
670
        * @retval None
        */
671
672
      static void MX TIM16 Init(void)
673
674
675
        /* USER CODE BEGIN TIM16 Init 0 */
676
        /* USER CODE END TIM16 Init 0 */
677
678
679
        /* USER CODE BEGIN TIM16 Init 1 */
680
681
        /* USER CODE END TIM16 Init 1 */
682
        htim16.Instance = TIM16;
683
        htim16.Init.Prescaler = 6400-1;
684
        htim16.Init.CounterMode = TIM COUNTERMODE UP;
685
        htim16.Init.Period = 1000;
686
        htim16.Init.ClockDivision = TIM CLOCKDIVISION DIV1;
687
        htim16.Init.RepetitionCounter = 0;
        htim16.Init.AutoReloadPreload = TIM AUTORELOAD PRELOAD DISABLE;
688
689
        if (HAL_TIM_Base_Init(&htim16) != HAL_OK)
690
691
          Error Handler();
692
693
        /* USER CODE BEGIN TIM16 Init 2 */
694
695
        /* USER CODE END TIM16 Init 2 */
696
697
      }
698
699
700
        * @brief USART1 Initialization Function
701
        * @param None
702
        * @retval None
703
704
      static void MX_USART1_UART_Init(void)
705
706
707
        /* USER CODE BEGIN USART1 Init 0 */
708
709
        /* USER CODE END USART1 Init 0 */
710
711
        /* USER CODE BEGIN USART1 Init 1 */
712
```

```
/* USER CODE END USART1 Init 1 */
713
714
        huart1.Instance = USART1;
715
        huart1.Init.BaudRate = 115200;
716
        huart1.Init.WordLength = UART_WORDLENGTH 8B;
717
        huart1.Init.StopBits = UART STOPBITS 1;
        huart1.Init.Parity = UART PARITY NONE;
718
719
        huart1.Init.Mode = UART MODE TX RX;
720
        huart1.Init.HwFlowCtl = UART HWCONTROL NONE;
721
        huart1.Init.OverSampling = UART OVERSAMPLING 16;
722
        huart1.Init.OneBitSampling = UART_ONE_BIT_SAMPLE_DISABLE;
723
        huart1.AdvancedInit.AdvFeatureInit = UART ADVFEATURE NO INIT;
724
        if (HAL UART Init(&huart1) != HAL OK)
725
726
          Error Handler();
727
728
        /* USER CODE BEGIN USART1 Init 2 */
729
730
        /* USER CODE END USART1 Init 2 */
731
732
      }
733
734
735
        * @brief USB OTG FS Initialization Function
736
        * @param None
737
        * @retval None
738
739
      static void MX USB OTG FS HCD Init (void)
740
      {
741
742
        /* USER CODE BEGIN USB OTG FS Init 0 */
743
744
        /* USER CODE END USB OTG FS Init 0 */
745
746
        /* USER CODE BEGIN USB OTG FS Init 1 */
747
748
        /* USER CODE END USB_OTG_FS_Init 1 */
749
        hhcd_USB_OTG_FS.Instance = USB OTG FS;
750
        hhcd_USB_OTG_FS.Init.Host_channels = 12;
        hhcd_USB_OTG_FS.Init.speed = HCD_SPEED_FULL;
751
752
        hhcd_USB_OTG_FS.Init.dma_enable = DISABLE;
753
        hhcd_USB_OTG_FS.Init.phy_itface = HCD_PHY_EMBEDDED;
754
        hhcd_USB_OTG_FS.Init.Sof_enable = DISABLE;
755
        if (HAL_HCD_Init(&hhcd_USB_OTG_FS) != HAL_OK)
756
        {
757
          Error Handler();
758
759
        /* USER CODE BEGIN USB OTG FS Init 2 */
760
761
        /* USER CODE END USB OTG FS Init 2 */
762
763
      }
764
765
766
        * Enable DMA controller clock
767
768
      static void MX DMA Init(void)
769
770
771
        /* DMA controller clock enable */
        __HAL_RCC_DMA1_CLK ENABLE();
772
773
774
        /* DMA interrupt init */
775
        /* DMA1 Channel2 IRQn interrupt configuration */
776
        HAL NVIC SetPriority(DMA1 Channel2 IRQn, 0, 0);
777
        HAL NVIC EnableIRQ(DMA1 Channel2 IRQn);
778
        /* DMA1 Channel3 IRQn interrupt configuration */
779
        HAL NVIC SetPriority (DMA1 Channel3 IRQn, 0, 0);
780
        HAL NVIC EnableIRQ(DMA1_Channel3_IRQn);
781
782
      }
783
784
785
        * @brief GPIO Initialization Function
```

```
786
        * @param None
787
        * @retval None
788
789
      static void MX GPIO Init (void)
790
791
        GPIO InitTypeDef GPIO InitStruct = {0};
792
793
        /* GPIO Ports Clock Enable */
        __HAL_RCC_GPIOC_CLK_ENABLE();
794
795
          _HAL_RCC_GPIOH_CLK_ENABLE();
        __HAL_RCC_GPIOA_CLK_ENABLE();
796
797
          HAL RCC GPIOB CLK ENABLE();
          _HAL_RCC_GPIOD_CLK ENABLE();
798
799
800
        /*Configure GPIO pin Output Level */
        HAL GPIO WritePin (GPIOC, FPGA RESET Pin | FPGA PRETRIG Pin, GPIO PIN RESET);
801
802
803
        /*Configure GPIO pin Output Level */
        HAL GPIO WritePin(GPIOA, SELECTOR M0 Pin|SELECTOR M1 Pin|SELECTOR M2 Pin|
804
        SELECTOR M3 Pin, GPIO PIN RESET);
805
806
        /*Configure GPIO pin Output Level */
807
        HAL GPIO WritePin (GPIOB, UI LED G Pin | UI LED R Pin | UI LED B Pin | TRIG SRCO Pin
808
                                 |TRIG SRC1 Pin, GPIO PIN RESET);
809
810
        /*Configure GPIO pin : WAKE UP Pin */
811
        GPIO InitStruct.Pin = WAKE UP Pin;
812
        GPIO InitStruct.Mode = GPIO MODE IT RISING;
813
        GPIO InitStruct.Pull = GPIO PULLUP;
814
        HAL GPIO Init (WAKE UP GPIO Port, &GPIO InitStruct);
815
816
        /*Configure GPIO pins : FPGA RESET Pin FPGA PRETRIG Pin */
817
        GPIO InitStruct.Pin = FPGA RESET Pin|FPGA PRETRIG Pin;
818
        GPIO InitStruct.Mode = GPIO MODE OUTPUT PP;
819
        GPIO InitStruct.Pull = GPIO NOPULL;
820
        GPIO InitStruct.Speed = GPIO SPEED FREQ LOW;
821
        HAL GPIO Init(GPIOC, &GPIO InitStruct);
822
823
        /*Configure GPIO pins : SELECTOR MO Pin SELECTOR M1 Pin SELECTOR M2 Pin
        SELECTOR M3 Pin */
        GPIO InitStruct.Pin = SELECTOR MO Pin|SELECTOR M1 Pin|SELECTOR M2 Pin|
824
        SELECTOR M3 Pin;
825
        GPIO InitStruct.Mode = GPIO MODE OUTPUT PP;
        GPIO_InitStruct.Pull = GPIO_NOPULL;
826
827
        GPIO InitStruct.Speed = GPIO SPEED FREQ LOW;
828
        HAL GPIO Init (GPIOA, &GPIO InitStruct);
829
        /*Configure GPIO pins : UI LED G Pin UI LED R Pin UI LED B Pin TRIG SRCO Pin
830
                                  TRIG SRC1 Pin */
831
        GPIO InitStruct.Pin = UI_LED_G_Pin|UI_LED_R_Pin|UI_LED_B_Pin|TRIG_SRCO_Pin
832
                                 |TRIG SRC1 Pin;
833
834
        GPIO InitStruct.Mode = GPIO MODE OUTPUT PP;
835
        GPIO InitStruct.Pull = GPIO NOPULL;
836
        GPIO_InitStruct.Speed = GPIO_SPEED_FREQ_LOW;
837
        HAL_GPIO_Init(GPIOB, &GPIO_InitStruct);
838
839
        /*Configure GPIO pin : FPGA DONE Pin */
840
        GPIO InitStruct.Pin = FPGA DONE Pin;
841
        GPIO InitStruct.Mode = GPIO MODE IT RISING FALLING;
842
        GPIO InitStruct.Pull = GPIO NOPULL;
843
        HAL GPIO Init (FPGA DONE GPIO Port, &GPIO InitStruct);
844
        /*Configure GPIO pin : SD_DETECT INT Pin */
845
846
        GPIO InitStruct.Pin = SD DETECT INT Pin;
847
        GPIO InitStruct.Mode = GPIO MODE INPUT;
848
        GPIO InitStruct.Pull = GPIO NOPULL;
849
        HAL GPIO Init (SD DETECT INT GPIO Port, &GPIO InitStruct);
850
851
        /*Configure GPIO pin : USB_VBUS_INT Pin */
852
        GPIO InitStruct.Pin = USB VBUS INT Pin;
        GPIO_InitStruct.Mode = GPIO MODE IT RISING;
853
        GPIO InitStruct.Pull = GPIO_NOPULL;
854
855
        HAL_GPIO_Init(USB_VBUS_INT_GPIO_Port, &GPIO_InitStruct);
```

```
856
857
        /*Configure GPIO pin : ARM BUTTON Pin */
858
        GPIO InitStruct.Pin = ARM BUTTON Pin;
859
        GPIO InitStruct.Mode = GPIO MODE IT FALLING;
860
        GPIO InitStruct.Pull = GPIO PULLUP;
861
        HAL GPIO Init (ARM BUTTON GPIO Port, &GPIO InitStruct);
862
863
        /* EXTI interrupt init*/
864
        HAL NVIC SetPriority (EXTI4 IRQn, 5, 0);
865
        HAL NVIC EnableIRQ(EXTI4 IRQn);
866
867
        HAL NVIC SetPriority (EXTI15 10 IRQn, 5, 0);
868
        HAL NVIC EnableIRQ (EXTI15 10 IRQn);
869
870
871
872
      /* USER CODE BEGIN 4 */
873
      #ifdef GNUC
        /* With GCC, small printf (option LD Linker->Libraries->Small printf
874
875
           set to 'Yes') calls __io_putchar() */
876
      int __io_putchar(int ch)
877
      #else
878
      int fputc(int ch, FILE *f)
879
      #endif /* GNUC */
880
881
        /* Place your implementation of fputc here */
882
        /* e.g. write a character to the UART3 and Loop until the end of transmission */
883
        HAL UART Transmit(&huart1, (uint8 t *)&ch, 1, HAL MAX DELAY);
884
        return ch;
885
886
      void HAL TIM PeriodElapsedCallback(TIM HandleTypeDef *htim) {
887
          if(htim== &htim16){
888
              HAL GPIO TogglePin (UI LED B GPIO Port, UI LED B Pin);
889
890
891
      /* USER CODE END 4 */
892
893
894
       * @brief This function is executed in case of error occurrence.
895
        * @retval None
896
897
      void Error Handler(void)
898
899
        /* USER CODE BEGIN Error Handler Debug */
        /* User can add his own implementation to report the HAL error return state */
900
901
          disable irq();
902
        while (1)
903
904
        }
        /* USER CODE END Error Handler Debug */
905
906
907
908
      #ifdef USE FULL ASSERT
909
910
        * @brief Reports the name of the source file and the source line number
911
                  where the assert param error has occurred.
912
        * @param file: pointer to the source file name
913
        * @param line: assert param error line source number
914
        * @retval None
915
916
      void assert failed(uint8 t *file, uint32 t line)
917
        /* USER CODE BEGIN 6 */
918
919
        /* User can add his own implementation to report the file name and line number,
920
           ex: printf("Wrong parameters value: file %s on line %d\r\n", file, line) */
        /* USER CODE END 6 */
921
922
      1
923
      #endif /* USE FULL ASSERT */
```

924