

Jump Conditions

Let (n_1, n_2) be the normal to the interface in the physical space.

Kinematic \Rightarrow

$$n_1 \bar{V}_{1E} + n_2 \bar{V}_{2E} = n_1 V_{1I} + n_2 V_{2I}$$

Dynamics \Rightarrow

$$\text{Solid traction} = \underline{\underline{\bar{t}}} = \beta \underline{\underline{n}} \cdot \underline{\underline{P}}$$

$$\underline{\underline{\bar{t}}} = \underline{\underline{\beta \cdot \underline{\underline{P}}}}$$

$$\bar{t}_1 = \beta \frac{r_x P_{11} + r_y P_{21}}{(r_x^2 + r_y^2)^{1/2}}$$

Case 2

$$= \frac{\beta}{(\quad)^{1/2}} \tilde{P}_{11}$$

$$\bar{t}_2 = \frac{\beta}{(\quad)^{1/2}} \tilde{P}_{12}$$

or

$$\bar{t}_1 = - \frac{p}{c^{1/2}} \bar{P}_{11} \quad \text{case 1}$$

$$\bar{t}_2 = - \frac{p}{c^{1/2}} \bar{P}_{12}$$

gas fluid traction

$$\underline{t} = - \underline{n} p \quad (\text{outward normal for fluid})$$

So,

$$-p = n_1 \bar{t}_1 + n_2 \bar{t}_2$$

$$0 = n_2 \bar{t}_1 - n_1 \bar{t}_2$$

Case 1

$$n_1 (\bar{v}_1 - \xi_p z_{1p} - \xi_s z_{1s}) + n_2 (\bar{v}_2 - \xi_p z_{2p} - \xi_s z_{2s}) \\ = n_1 (v_1 + n_1 \xi) + n_2 (v_2 + n_2 \xi)$$

$$n_1 (\bar{v}_1 - v_1) + n_2 (\bar{v}_2 - v_2)$$

(1) \Rightarrow

$$= \xi + (n_1 z_{1p} + n_2 z_{2p}) \xi_p + (n_1 z_{1s} + n_2 z_{2s}) \xi_s$$

$$-p_s = \frac{-\beta}{(c_x^2 + c_y^2) v_m} \left[n_1 (\tilde{P}_{11} + p_0 c_p z_{1p} \xi_p + p_0 c_s z_{1s} \xi_s) \right. \\ \left. + n_2 (\tilde{P}_{12} + p_0 c_p z_{2p} \xi_p + p_0 c_s z_{2s} \xi_s) \right] \\ = -(p - p a \xi)$$

$$-\frac{\beta}{(\quad) v_m} (n_1 \tilde{P}_{11} + n_2 \tilde{P}_{12}) + p = p a \xi$$

(2) \Rightarrow

$$+\frac{\beta}{(\quad) v_m} \left[p_0 c_p (n_1 z_{1p} + n_2 z_{2p}) \xi_p \right. \\ \left. + p_0 c_s (n_1 z_{1s} + n_2 z_{2s}) \xi_s \right]$$

$$0 = \frac{-\beta}{(r_x^2 + r_y^2)^{3/2}} \left[n_2 \left(\tilde{P}_{11} + \rho_0 c_p z_{1p} \xi_p + \rho_0 c_s z_{1s} \xi_s \right) - n_1 \left(\tilde{P}_{12} + \rho_0 c_p z_{2p} \xi_p + \rho_0 c_s z_{2s} \xi_s \right) \right]$$

$$-n_2 \tilde{P}_{11} + n_1 \tilde{P}_{12} = \rho_0 c_p (n_2 z_{1p} - n_1 z_{2p}) \xi_p$$

(3) \Rightarrow

$$+ \rho_0 c_s (n_2 z_{1s} - n_1 z_{2s}) \xi_s$$

Matrix form

$$\begin{bmatrix} 1 & z_{np} & z_{ns} \\ \rho_0 c_p & \rho_0 c_p z_{np} & \rho_0 c_s z_{ns} \\ 0 & \rho_0 c_p z_{tp} & \rho_0 c_s z_{ts} \end{bmatrix} \begin{bmatrix} \xi \\ \xi_p \\ \xi_s \end{bmatrix} = \begin{bmatrix} \Delta V \\ \Delta P \\ 0 \end{bmatrix}$$

Maple gives

$$\xi = \frac{\alpha \omega_p \omega_s (z_{pn} z_{st} - z_{sn} z_{pt}) \Delta V}{\alpha \omega_p \omega_s () - \omega \omega_s z_{pn} z_{st} + \omega \omega_p z_{sn} z_{pt} + \frac{(z_{sn} z_{pt} \omega_p - z_{pn} z_{st} \omega_s) \Delta P}{\text{same denom.}}}$$

where

$$\omega = \rho a, \quad \omega_p = \rho_0 c_p, \quad \omega_s = \rho_0 c_s$$

$$\alpha = \frac{\beta}{()^{1/2}}$$

$$z_{pn} = n_1 z_{1p} + n_2 z_{2p}$$

$$z_{pt} = n_2 z_{1p} - n_1 z_{2p}$$

~~etc.~~ $\Delta V = n_1 (\bar{v}_1 - v_1) + n_2 (\bar{v}_2 - v_2)$

$$\Delta p = -\alpha (n_1 \tilde{P}_{11} + n_2 \tilde{P}_{12}) + p.$$

Case 2.

$$n_1 (\bar{v}_1 + \xi_p z_{1p} + \xi_s z_{1s}) + n_2 (\bar{v}_2 + \xi_p z_{2p} + \xi_s z_{2s})$$

= same

$$n_1 (\bar{v}_1 - v_1) + n_2 (\bar{v}_2 - v_2)$$

$$(1) \Rightarrow = \xi - (n_1 z_{1p} + n_2 z_{2p}) \xi_p - (n_1 z_{1s} + n_2 z_{2s}) \xi_s$$

$$-p_I = \frac{\beta}{(\)^{1/2}} [\text{same}] = -(p - p_a \xi)$$

$$\frac{\beta}{(\)^{1/2}} (n_1 \tilde{P}_{11} + n_2 \tilde{P}_{12}) + p = p_a \xi$$

$$(2) \Rightarrow - \frac{\beta}{(\)^{1/2}} [\text{same}]$$

$$(3) \Rightarrow \text{same.}$$