



Sign Language Detection

using LSTM model

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CSSE-03

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OBJECTIVE

To create a sign language detection system using Keras' Long Short Term Memory model and Dense model. It's objective would be identifying words through actions in real time on any simplified system.

INTRODUCTION

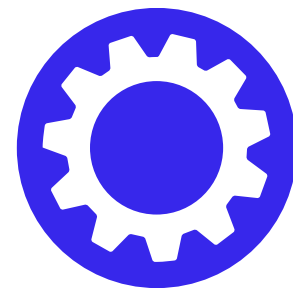
1. What does sign language represent and why is it important?
2. What purpose does the sign language detection system serve?
3. How does it work?



The community of the deaf and dumb uses gestures to communicate in sign language. This group relied on sign language for communication when it was hard to transmit audio or when typing and writing were challenging but there was still the potential of vision.

Sign language has three components

- a. Fingerspelling : used to spell words letter by letter
- b. Word level sign vocabulary : used for majority of communication
- c. Non-manual features : facial expression and tongue, mouth and body position



Any movement of a bodily part, such as the hand or face, is a type of gesture. Here, we are utilizing sequence processing and deep learning for gesture identification. Gesture recognition makes it possible for computers to comprehend human behavior and serves as a translator between computers and people. This could make it possible for people to communicate organically with computers without coming into contact with any mechanical parts physically.



Image feed from the camera

Image resize

Normalization

Data store of RGB image

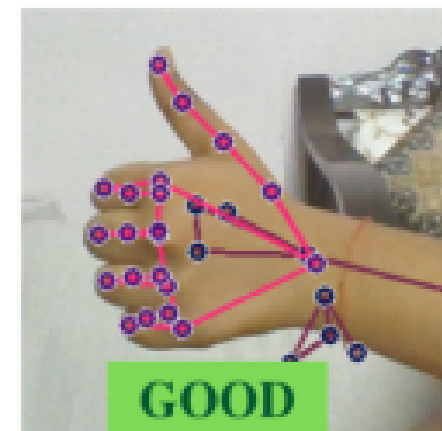
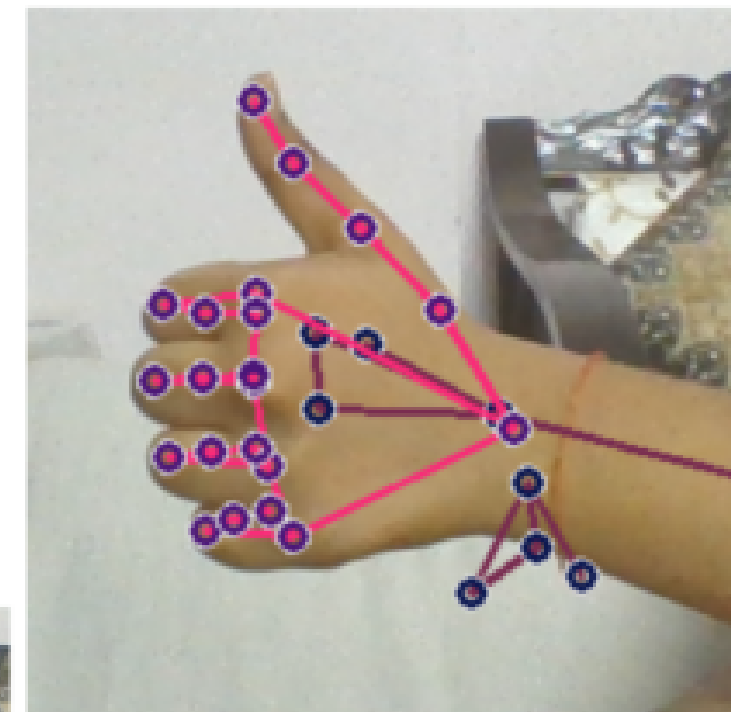
Partition training and testing data

Fine tune the architecture and weights for the model

Trainign LSTM and Dense based predictor

Check if the results match the desired accuracy

Real time testing using LSTM and Dense model under tensorflow and keras



Output

NEW MODULES UTILIZED

01

Tensorflow

- Python library for quick numerical computation.
- Can work with huge data set with unique properties.

02

OpenCV

- Can speed up the incorporation of A.I. into products.
- Written up in basic language C, so can be tweaked to personlize wish.

03

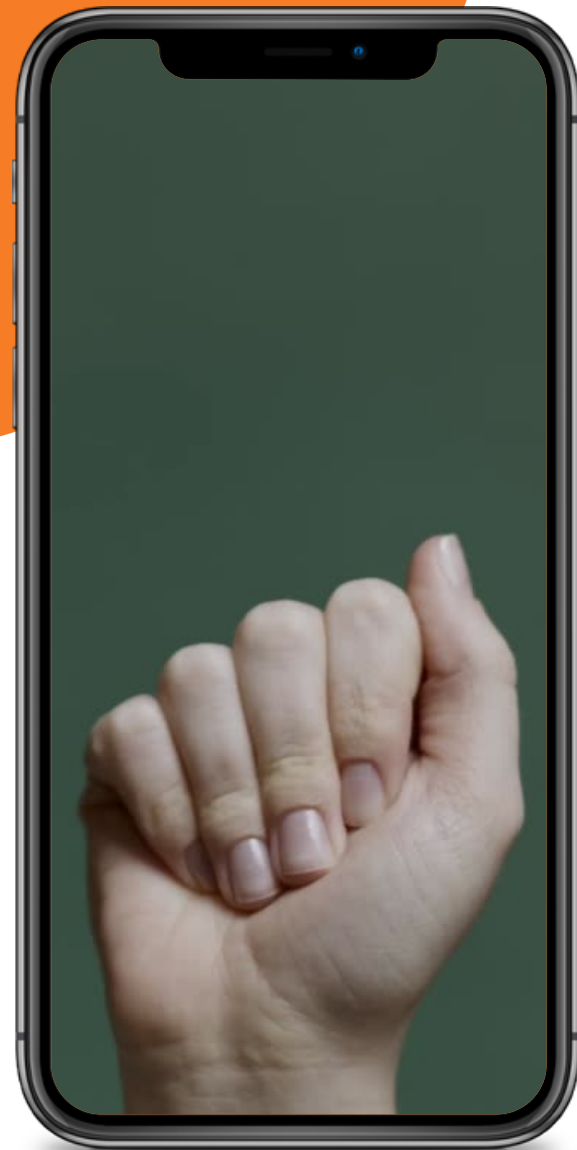
MediaPipe

- Quick prototyping for perception.
- For live and streaming videos it provides adaptable machine learning solutions.

04

Keras

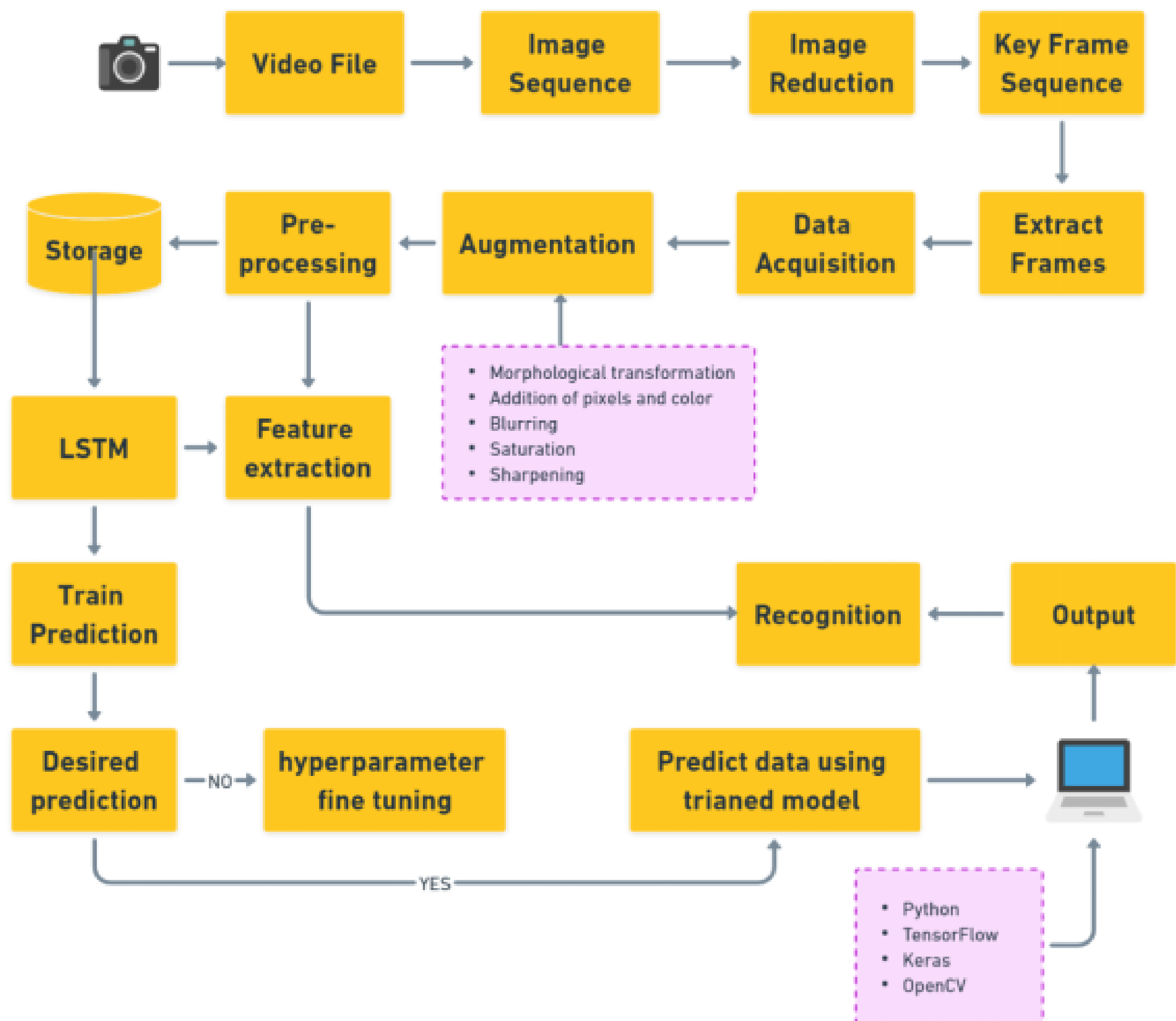
- Implementation of neural network is simple
- Multiple backend NN computation is supported.



MOTIVATION BEHIND IT

Human computer interaction has several potential uses for sign language and hand gestures, which are effective forms of human communication. When compared to conventional devices, vision-based hand gesture recognition techniques have many demonstrated advantages. Nevertheless, sign language gesture recognition is a challenging problem, and the current work only makes a small contribution to getting the outcomes required. This project introduced a vision-based system capable of deciphering discrete hand gestures and assisting with action-based communication. In order to forecast the activity and even indicate the likelihood, this study relied on LSTM and Dense models.

BLOCK DIAGRAM



```

44 cv2.
45
46 # NEW Ex
47 keypoint
48 npy_path
49 np.save(
50
51 # Break
52 if cv2.w
53     brea
54
55 cap.release()
56 cv2.destroyAllWindows()
    
```

```

In [158]: 1 cap.release()
          2 cv2.destroyAllWindows()
    
```

6. Preprocess Data

```

In [6]: 1 from sklearn.model_selec
        2 from tensorflow.keras.ut
    
```

```

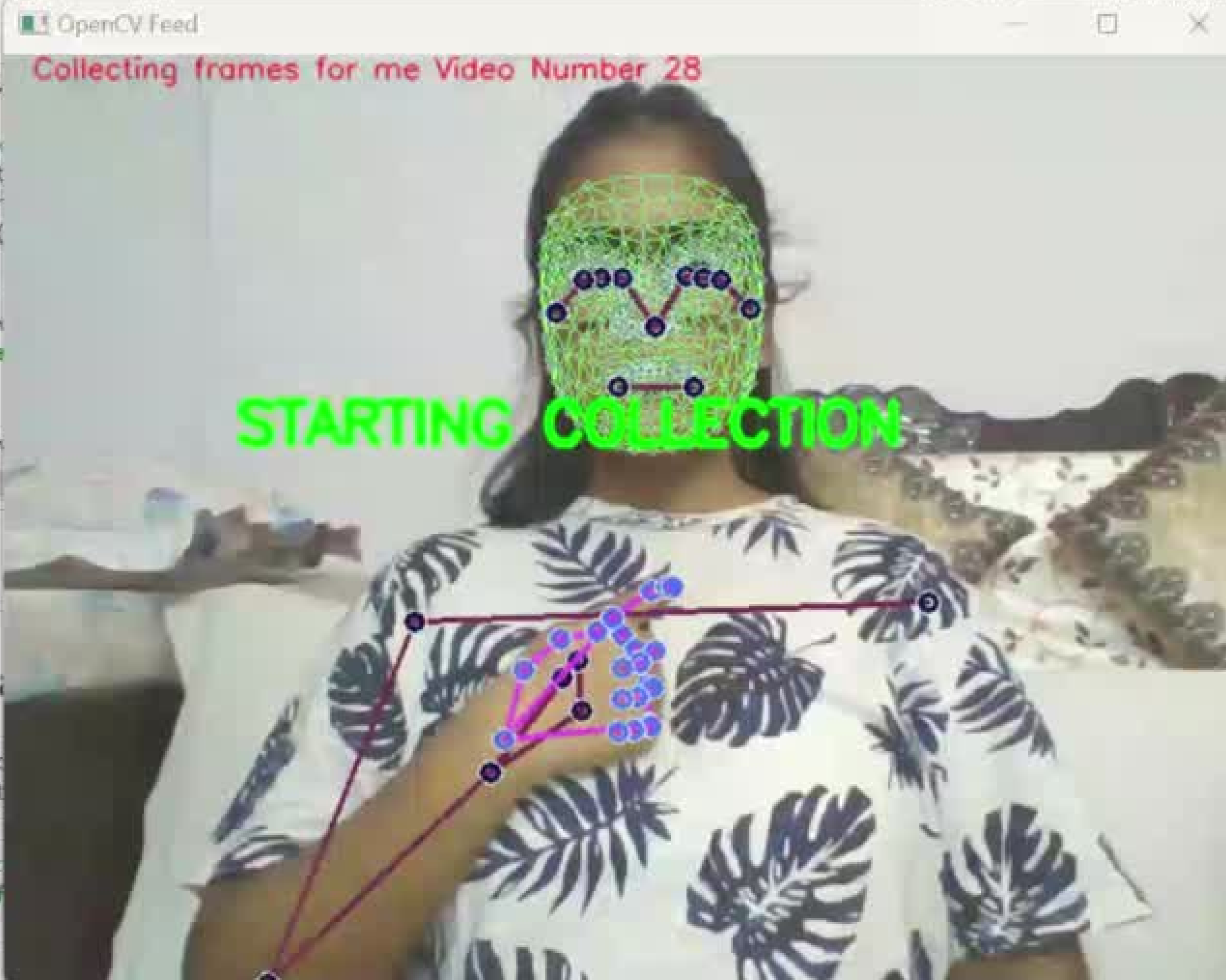
In [10]: 1 # label dic to label eac
         2 label_map = {label:num f
    
```

```

In [163]: 1 label_map
    
```

```

Out[163]: {'hello': 0, 'thanks': 1, 'iloveyou': 2}
    
```





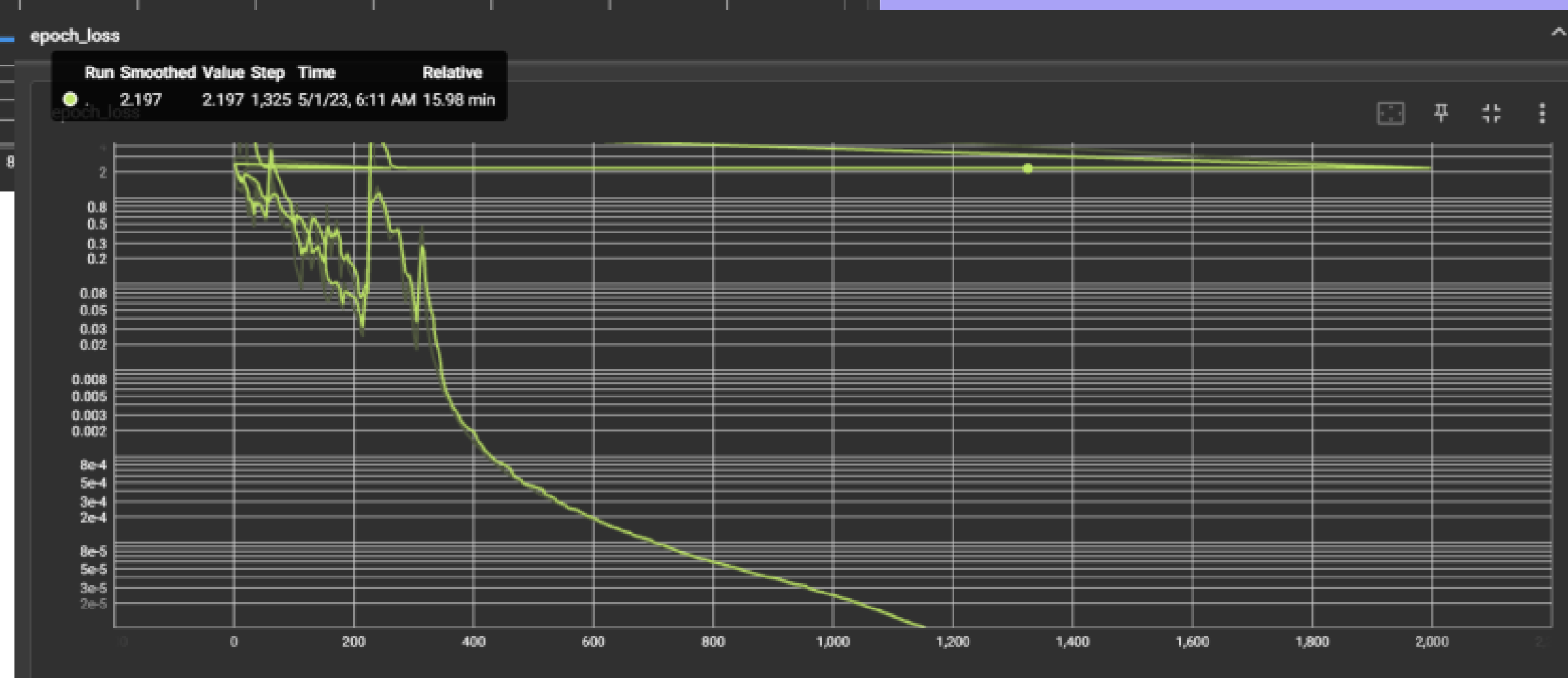
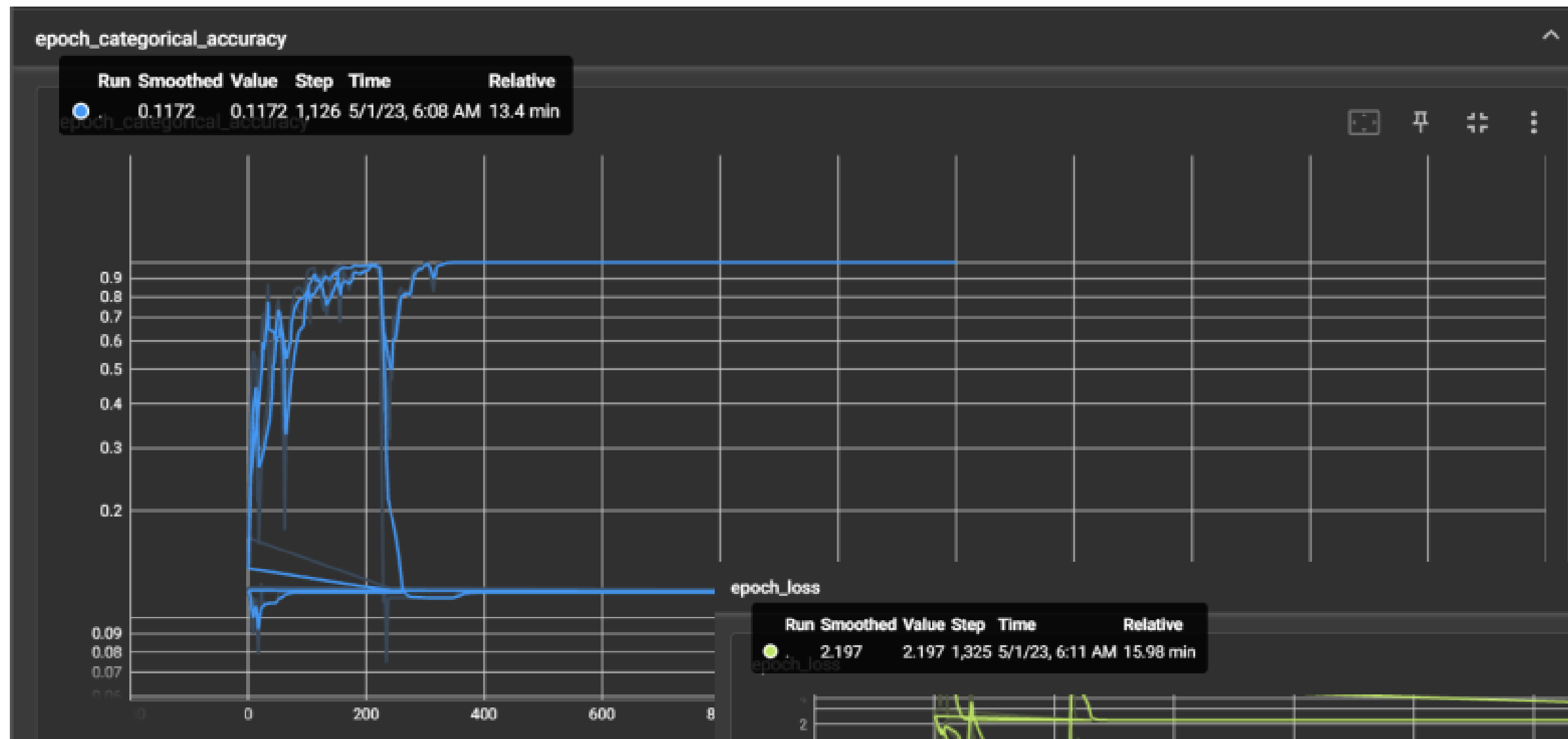
```
Epoch 1737/2000
4/4 [-----] - 0s 101ms/step - loss: 3.7645e-07 - categorical_accuracy: 1.0000
Epoch 1738/2000
4/4 [-----] - 0s 100ms/step - loss: 3.7645e-07 - categorical_accuracy: 1.0000
Epoch 1739/2000

4/4 [-----] - 0s 101ms/step - loss: 3.7645e-07 - categorical_accuracy: 1.0000
Epoch 1740/2000
4/4 [-----] - 0s 109ms/step - loss: 3.7018e-07 - categorical_accuracy: 1.0000
Epoch 1741/2000
4/4 [-----] - 0s 108ms/step - loss: 3.7018e-07 - categorical_accuracy: 1.0000
Epoch 1742/2000
4/4 [-----] - 0s 97ms/step - loss: 3.6808e-07 - categorical_accuracy: 1.0000
Epoch 1743/2000
4/4 [-----] - 0s 106ms/step - loss: 3.6599e-07 - categorical_accuracy: 1.0000
Epoch 1744/2000
4/4 [-----] - 0s 100ms/step - loss: 3.6181e-07 - categorical_accuracy: 1.0000
Epoch 1745/2000
4/4 [-----] - 0s 100ms/step - loss: 3.6286e-07 - categorical_accuracy: 1.0000
Epoch 1746/2000
4/4 [-----] - 0s 100ms/step - loss: 3.5972e-07 - categorical_accuracy: 1.0000
Epoch 1747/2000
4/4 [-----] - 0s 97ms/step - loss: 3.5763e-07 - categorical_accuracy: 1.0000
Epoch 1748/2000
4/4 [-----] - 0s 105ms/step - loss: 3.5658e-07 - categorical_accuracy: 1.0000
Epoch 1749/2000
4/4 [-----] - 0s 98ms/step - loss: 3.5763e-07 - categorical_accuracy: 1.0000
Epoch 1750/2000
4/4 [-----] - 0s 102ms/step - loss: 3.5658e-07 - categorical_accuracy: 1.0000
Epoch 1751/2000
4/4 [-----] - 0s 103ms/step - loss: 3.5554e-07 - categorical_accuracy: 1.0000
Epoch 1752/2000
4/4 [-----] - 0s 104ms/step - loss: 3.4612e-07 - categorical_accuracy: 1.0000
Epoch 1753/2000
3/4 [----->.....] - ETA: 0s - loss: 3.1913e-07 - categorical_accuracy: 1.0000
```

In [83]: 1 model.summary()

Model: "sequential"

Layer (type)	Output Shape	Param #
lstm (LSTM)	(None, 30, 64)	442112
lstm_1 (LSTM)	(None, 30, 128)	98816

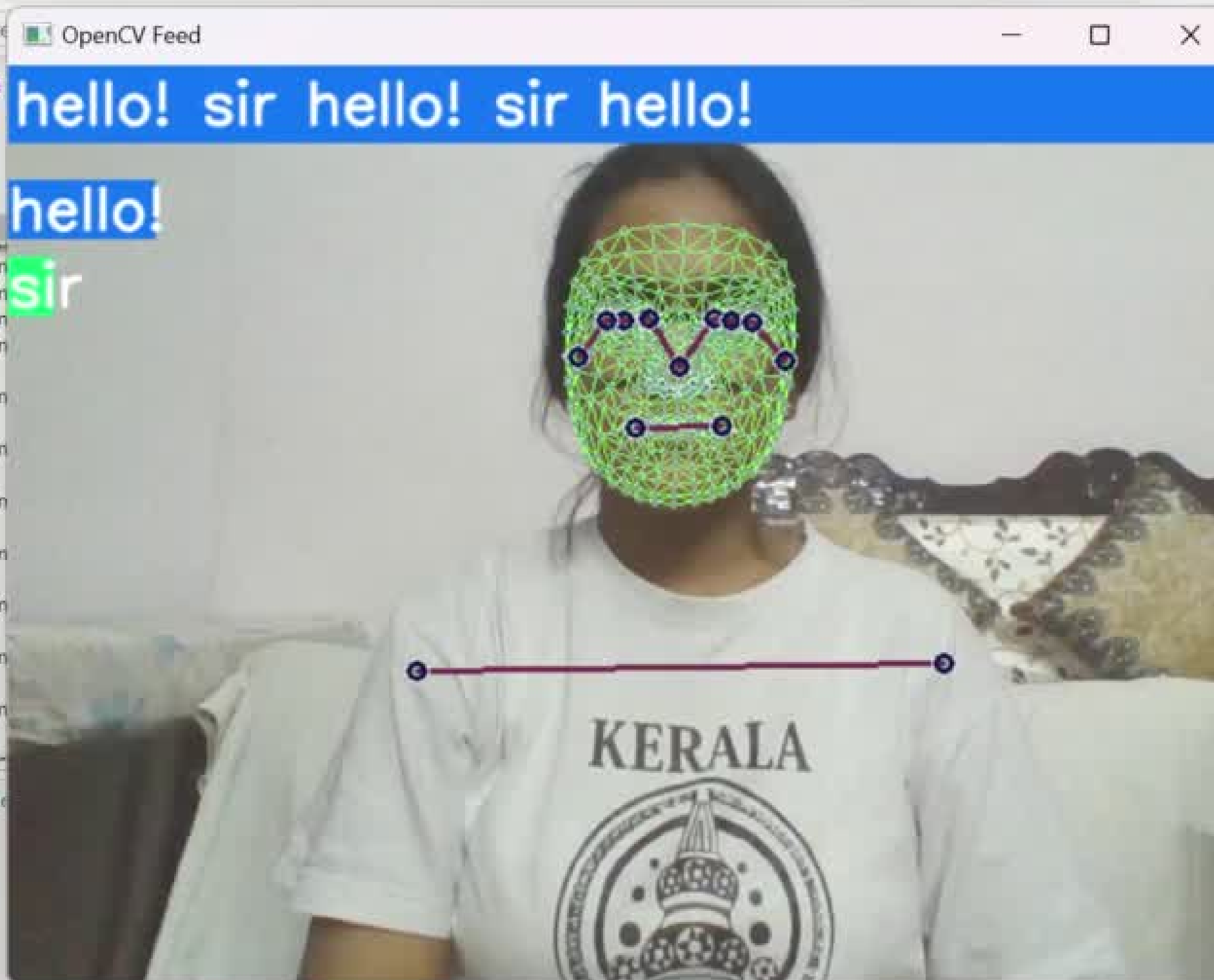


```
55 # Break gracefully
56 if cv2.waitKey(10) & 0xFF == ord('q'):
57     break
58 cap.release()
59 cv2.destroyAllWindows()
60
```

```
<class 'mediapipe.python.solution'
<class 'mediapipe.python.solution'
<class 'mediapipe.python.solution'
<class 'mediapipe.python.solution'
hello!
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<class 'mediapipe.python.solution'
hello!
```

In [125]:

```
1 ## 1. New detection variable
2 # sequence = []
3 # sentence = []
4 # predictions = []
5 # threshold = 0.8
6
7 # cap = cv2.VideoCapture(0)
8 ## Set mediapipe model
9 # with mp_holistic.Holistic(min_detection_confidence=0.5, min_tracking_confidence=0.5) as holistic:
10 #     while cap.isOpened():
```



hello!

sir

good morning

A photograph of a person's arm and shoulder. A red line connects two blue dots, representing a pose estimation model's output. The dots are located on the shoulder and elbow. The background is a plain, light-colored wall.



LINK TO THE PROJECT :

<https://github.com/Drishti228/Sign-Language-detection-using-LSTM>

LINK TO MY WEBSITE :

<https://drishti228.github.io/portfolio/>

THANK YOU