# Système d'illumination de trottoir nocturne pour piétons

\* ELG 4539: Électronique III

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Abstract—Nous avons construits un dispositif capable de différencier les entités sur le trottoir basé sur des capteurs de mouvement infra-rouge et des capteurs de poids, tous reliés à un microcontrôleur Arduino, qui effectuera un CAN sur les signaux analogiques et un Raspberry pi 4 qui effectue une prise de décision basée sur le flux de données reçues.

Index Terms—Raspberry Pi, Arduino, Capteur de Poids, Capteur Infrarouge, Django

#### I. INTRODUCTION

Le gouvernement du Québec définit la pollution lumineuse comme toute lumière projetée vers le ciel qui obstrue l'observation des étoiles [1]. Cet effet est dû à la projection et la réflexion de la lumière vers le ciel ainsi qu'une surabondance de lumière. Ce phénomène représente un manque d'efficacité dans le déploiement de la lumière. D'un point de vue environnementaliste, c'est aussi un gaspillage d'énergie puisque l'énergie lumineuse qui s'échappe vers le ciel ne contribue pas à la tâche voulue d'un lampadaire, qui est par exemple d'illuminer une rue ou un trottoir.

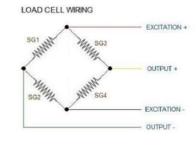
Les capteurs infrarouges pyroélectriques (PIR) comptent parmi la classe de capteurs détecteurs thermiques [2]. Ces capteurs mesurent la radiation incidente grâce au changement de leur température. Lorsqu'on présente au détecteur un certain matériel absorbant, on peut le configurer pour répondre à une certaine plage de fréquences. Les PIR ont été conçus principalement pour la détection des corps humains, ce qui veut dire que les longueurs d'onde désirées sont de huit à douze micromètres.

## II. CONCEPTION

# A. Conception Matérielle

Pour le hardware du projet, nous avons décidé de sélectionner deux types de capteurs : le HX711 et le SR-501. Le capteur de tension HX711 est composé d'un Wheatstone bridge, ce circuit utilise 4 résistances arrangées comme dans la figure ci-dessous. Le voltage de sortie mesurée varie selon

la tension mécanique appliquée sur le membre du capteur. Il suffit par la suite qu'à calibrer ce voltage de sortie à l'aide un poids ou une force connue. Le capteur a une limite de poids de 20 kilogrammes, mais dans le cas des simulations pour ce projet, ce n'est pas un problème.



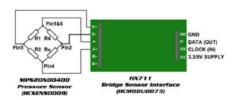


Fig. 1. Capteur de Poids HX711. [3]

Quant au capteurs SR-501, ils fonctionnent en détectant la radiation infra-rouge et en donnant une valeur de sorite binaire, soit 0 ou 1, dépendamment du rapport entre la radiation détectée et un certain seuil. Ces capteurs ont une limitation sur leur temps d'activation. Lorsque la sortie d'un capteur passe de 1 à 0, elle sera prise en mode LOW pour 2 secondes. Cela veut dire que la sortie du capteur sera fixe à 0 pour deux secondes peu importe la radiation mesurée. Ceci prouve être une contrainte pour la conception des cas de test.

Dans notre cas, nous avons 5 capteurs infrarouges et un capteur de poids. Le schéma ci-dessous représente le raccordement des capteurs infrarouges à un Arduino. Le logiciel utiliser

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pour ce schéma ne comprenait pas le capteur HX711 dans sa base de données et l'Arduino Nano non plus. Le HX711 as 4 pins, comme vu dans la figure plus haute, où une pin est pour l'alimentation 5 volts, une autre pour la terre, une troisième pour la pin d'entré digitale du Arduino et la dernière pour l'horloge. [4]

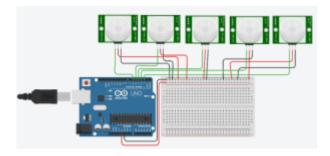


Fig. 2. Intégration de capteurs IR Hc-Sr501. [5]

#### B. Conception Logicielle

#### III. MISE EN OEUVRE

Before you begin to format your paper, first write and save the content as a separate text file. Complete all content and organizational editing before formatting. Please note sections III-A–III-E below for more information on proofreading, spelling and grammar.

Keep your text and graphic files separate until after the text has been formatted and styled. Do not number text heads—LATEX will do that for you.

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## B. Units

- Use either SI (MKS) or CGS as primary units. (SI units are encouraged.) English units may be used as secondary units (in parentheses). An exception would be the use of English units as identifiers in trade, such as "3.5-inch disk drive".
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$$a + b = \gamma \tag{1}$$

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Please use "soft" (e.g., \eqref{Eq}) cross references instead of "hard" references (e.g., (1)). That will make it possible to combine sections, add equations, or change the order of figures or citations without having to go through the file line by line.

Please don't use the {eqnarray} equation environment. Use {align} or {IEEEeqnarray} instead. The {eqnarray} environment leaves unsightly spaces around relation symbols.

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- The word "data" is plural, not singular.
- The subscript for the permeability of vacuum  $\mu_0$ , and other common scientific constants, is zero with subscript formatting, not a lowercase letter "o".
- In American English, commas, semicolons, periods, question and exclamation marks are located within quotation marks only when a complete thought or name is cited, such as a title or full quotation. When quotation marks

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  word alternatively is preferred to the word "alternately"
  (unless you really mean something that alternates).
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- In your paper title, if the words "that uses" can accurately replace the word "using", capitalize the "u"; if not, keep using lower-cased.
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- The abbreviation "i.e." means "that is", and the abbreviation "e.g." means "for example".

An excellent style manual for science writers is [7].

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a) Positioning Figures and Tables: Place figures and tables at the top and bottom of columns. Avoid placing them in the middle of columns. Large figures and tables may span across both columns. Figure captions should be below the figures; table heads should appear above the tables. Insert figures and tables after they are cited in the text. Use the abbreviation "Fig. 3", even at the beginning of a sentence.

TABLE I TABLE TYPE STYLES

Table	Table Column Head		
Head	Table column subhead	Subhead	Subhead
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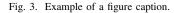


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## IV. DISCUSSION

#### V. CONCLUSION

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#### REFERENCES

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