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# Lab 2: Exercises 1-6

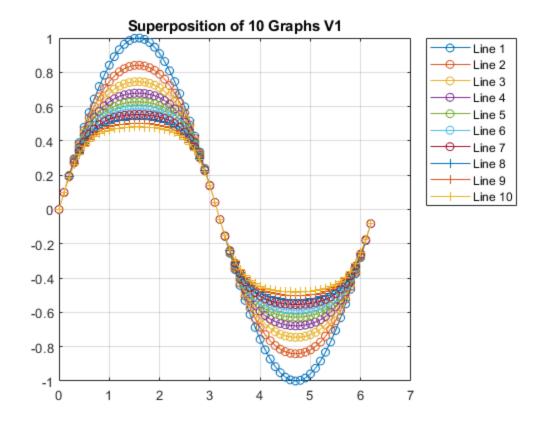
by: Michelle Pichardo Munoz

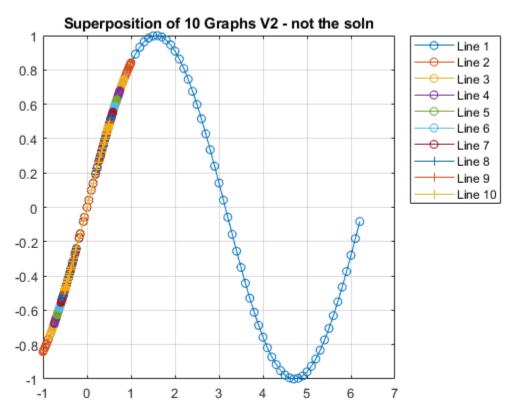
```
% Best Practices -- I'll add it to every Excersise for clean up
close all; % closes all open windows
clear all; % deletes the workspace
```

```
% Using a for-loop, calculate the summation of all the integers from 1-10
% i.e.: 1+2+3+4+5+6+7+8+9+10 = 55
% Best Practices
close all; % closes all open windows
clear all; % deletes the workspace
% create a variable to store the result : set it to zero
sum = 0;
% for loop
% where i [starts at 1, steps by 1, ends at 10]
    i = [1,2,3,4,5,6,7,8,9,10]
for i = 1:1:10
    % take our variable and add it by each i in the set
    sum = i + sum;
    disp(i) % uncomment to check CTL+SHIFT+R
end
% Display the final value of our variable
disp (sum)
    55
```

```
% Best Practices
close all; % closes all open windows
clear all; % deletes the workspace
% Create a vector x = 0:0.1:2*pi
x = 0:0.1:2*pi;
                                 % Domain of our functions
% Using a for-loop, generate 10 different plots on the same figure
% where the curves are y1 = \sin(x), y2 = \sin(y1), y3 = \sin(y2) ...
% Define the data matrix
% matrix of row vecotors
data matrix = [x ; sin(x)];
% Define the end condition
% since we already have the first graph data filed we need 9 more
N = 9;
% Fill the matrix using a for-loop
for i = 1:1:N
    % Create the matrix holding all our data by incrimenting
    % through the rows
    data_matrix(i+2,:) = sin(data_matrix(i+1,:));
end
% Graph of all fuctions on the x-domain -----
% Define the figure
fig = figure();
% Define the axes
ax = axes(fiq);
% Difine markers
ax.LineStyleOrder = {'-o','-+','-*','-x','-s','-d','-v','->','-h','-^'};
% hold on: retain the current axes and properties
hold on
% add a box about the figure
box on
% add a grid for fun
grid on
% Start for-loop to plot we want 10, so N+1 = 9+1 =10
for i = 1:1:N+1
    %Plot the data by also incrimenting through the rows
   plot(data_matrix(1,:),data_matrix(i+1,:), ...
        'DisplayName', ['Line ', num2str(i)])
% add a legend outside of the main graph to reduce clutter
legend('Location','bestoutside')
% add a title
```

```
title('Superposition of 10 Graphs V1')
% hold off: reset any following plot to default properties
hold off
% I still think the wording of the problem needs to be adjusted:-----
% This is the graph such that I plot:
% x vs y1, y1 vs y2, and so on
% Define the figure
fig = figure();
% Define the axes
ax = axes(fiq);
% Difine markers
ax.LineStyleOrder = {'-o','-+','-*','-x','-s','-d','-v','->','-h','-^'};
% hold on: retain the current axes and properties
hold on
% add a box about the figure
box on
% add a grid for fun
grid on
% Start for-loop to plot we want 10, so N+1 = 9+1 =10
for i = 1:1:N+1
    %Plot the data by also incrimenting through the rows
    plot(data_matrix(i,:),data_matrix(i+1,:), ...
        'DisplayName', ['Line ', num2str(i)])
end
% add a legend outside of the main graph to reduce clutter
legend('Location','bestoutside')
% add a title
title('Superposition of 10 Graphs V2 - not the soln')
% hold off: reset any following plot to default properties
hold off
```





# **Accident**

```
made a loop for several subplots
    I didn't want to delete it (saved for later)
data_matrix = [x ; sin(x)];
N = 10
for i = 1:1:N
    data_matrix(i+2,:) = sin(data_matrix(i+1,:));
    subplot(N,1,i);
    plot(data_matrix(i,:),data_matrix(i+1,:));
    title(sprintf('Graph of Plot %s', i));
end
```

### **Exercise 3**

```
% Using an if/else statement
   display one of three different messages depending on the value of the
   variable grade.
  If a grade is: >= 0.9 display "You aced the course."
% If a grade is: 0.8>= grade <= 0.9 display "You almost aced the course."
% If a grade is: <= 0.8 display "You didn't ace the course... nice try."
% Best Practices
close all; % closes all open windows
clear all; % deletes the workspace
grade = 1;
if grade >= 0.9
    fprintf('You aced the course.\n')
elseif grade > 0.8 && grade < 0.9
    fprintf('You almost aced the course.\n')
elseif grade <= 0.8
    fprintf("You didn't ace the course... nice try.\n")
end
You aced the course.
```

```
% Useing a while-loop
%    divide 1_000 by 2 until the result is less than 1
%    Count and display on the workspace the total number of iterations
% Best Practices
close all; % closes all open windows
clear all; % deletes the workspace
% Declare our given value
N = 1000;
```

```
% Program:
% For any number between [-1,1] calculate and displays
   the arccosine and arcsine of the number in both deg & radians
  Output range: [0,180]deg , [0,pi]rad
% e.g.:
        given 0, arccosine is either 90deg or pi/2 rad
        and 270deg and 3pi/2 rad
% Best Practices
close all; % closes all open windows
clear all; % deletes the workspace
% define the number to examine
number angle = 1;
% create if statement with conditionals
      bounds: [-1,1]
if number angle >= -1 && number angle <= 1</pre>
    % Store the rad and degree values of the provided number
   x_rad = acos(number_angle);
   y_rad = asin(number_angle);
   x_{deg} = rad2deg(x_{rad});
   y deg = rad2deg(y rad);
    % set of print statements returning the rad and deg
    fprintf("Arc-Values of given numeber: %.2f\n", number_angle)
    fprintf("Arcos(%.2f) = %.2f deg, Arcsin(%f) = %.2f deg\n", ...
        number_angle, x_deg, number_angle, y_deg)
    fprintf("Arcos(%.2f) = %.2f rad, Arcsin(%f) = %.2f rad n", ...
        number_angle, x_rad, number_angle, y_rad)
else
```

```
% Condition to tell the user they are out of bounds
fprintf('Out of Bounds, select a number between [-1,1]\n')
end

Arc-Values of given numeber: 1.00
Arcos(1.00) = 0.00 deg, Arcsin(1.000000) = 90.00 deg
Arcos(1.00) = 0.00 rad, Arcsin(1.000000) = 1.57 rad
```

```
% Given the dataset Lab2_Excercise6.mat
% - includes: x,y,z data of drone
% - We are only interested in certain instances where the drone flies
       close to the objective point (x: 0.0m, y:0.0 m, z:0.7m)
% Goal: filter the data & plot
\theta - plot when the drone is within +/- 0.2m on all axes
% (a) Filter the xdata to only keep w/in +/- 0.2m
       - plot the positions as well as the ref.line
% (b) Filter the ydata to only keep w/in +/- 0.2m
      - plot the positions as well as the ref.line
% (c) Filter the zdata to only keep w/in +/- 0.2m
       - plot the positions as well as the ref.line
% (d) Include legends, axes, and title for all 3 plots
% Best Practices
close all; % closes all open windows
clear all; % deletes the workspace
% Load in the variables from the .mat file
load Lab2_Exercise6.mat
% Set target parameters
xtarget = 0;
ytarget = 0;
ztarget = 0.7;
% Set the allowed error range
err = 0.2;
% Create a vector to store data
xnew = zeros(size(p_x(:,1)));
% Use a for-loop to select the desired points
i = [1:1:2775] i.e. p_x(:,1) 1st colum, entire row
for i = 1:length(p_x(:,1))
   % condition:
       if 0-002 \le \text{entry} \le 0+0.2 the code is:
   if p_x(i,1) >= xtarget - err && p_x(i,1) <= xtarget + err
       % if true then let that entry replace the same position
       % of the vector I called xnew
       xnew(i,1) = p_x(i,1);
```

```
else
       % if false then replace it with NaN (not a number)
       % this lets me graph it the vecotor
       xnew(i,1) = NaN;
   end
end
figure(1)
subplot(3,1,3) %-----
plot(xnew(:,1),'-o','DisplayName', 'Accepted x-Data')
ylabel('X meters')
xlabel('Incriments')
title('X Position')
legend('Location','bestoutside')
grid on
box on
subplot(3,1,2) %-----
plot(p_x(:,1),'DisplayName', 'Given x-Data')
ylabel('X meters')
xlabel('Incriments')
title('X Position')
legend('Location','bestoutside')
grid on
box on
subplot(3,1,1) %-----
plot(xtarget*ones(length(p_x),1), 'DisplayName','Target x-Location')
  Note: created a vector of length p x composed of 1's
2
          multipied it by the constant xtarget to get a vector
          of all xtarget (I could have used zeros function but meh)
ylabel('X meters')
xlabel('Incriments')
title('X Position')
legend('Location','bestoutside')
grid on
box on
hold off
% ----- 6 b -----
% Note: the process is the same, comments are omitted
ynew = zeros(size(p_y(:,1)));
for i = 1:length(p_x(:,1))
   if p_y(i,1) > ytarget - err && p_y(i,1) < ytarget + err
       ynew(i,1) = p_y(i,1);
   else
       ynew(i,1) = NaN;
   end
end
figure(2)
subplot(3,1,3) %-----
plot(ynew(:,1), '-o','DisplayName', 'Accepted y-Data')
ylabel('Y meters')
xlabel('Incriments')
```

```
title('Y Position')
legend('Location','bestoutside')
grid on
box on
subplot(3,1,2) %-----
plot(p_y(:,1),'DisplayName', 'Given y-Data')
ylabel('Y meters')
xlabel('Incriments')
title('Y Position')
legend('Location','bestoutside')
grid on
box on
subplot(3,1,1) %-----
plot(ytarget*ones(length(p_y),1), 'DisplayName','Target y-Location')
ylabel('Y meters')
xlabel('Incriments')
title('Y Position')
legend('Location','bestoutside')
grid on
box on
hold off
% ----- 6 c -----
% Note: the process is the same, comments are omitted
znew = zeros(size(p_z(:,1)));
for i = 1:length(p_z(:,1))
   if p_z(i,1) > ztarget - err && p_z(i,1) < ztarget + err
       znew(i,1) = p_z(i,1);
   else
      znew(i,1) = NaN;
   end
end
figure(3)
subplot(3,1,3) %-----
plot(znew(:,1),'-o', 'DisplayName', 'Accepted z-Data')
ylabel('Z meters')
xlabel('Incriments')
title('Z Position')
legend('Location','bestoutside')
grid on
box on
subplot(3,1,2) %-----
plot(p_y(:,1),'DisplayName', 'Given z-Data')
ylabel('Z meters')
xlabel('Incriments')
title('Z Position')
legend('Location','bestoutside')
grid on
box on
```

```
subplot(3,1,1) %-----
plot(ztarget*ones(length(p_z),1), 'DisplayName','Target z-Location')
ylabel('Z meters')
xlabel('Incriments')
title('Z Position')
legend('Location','bestoutside')
grid on
box on
hold off
% ----- 6 d -----
% I don't understand what this wants, and I won't assume 3D graphing
figure(4)
hold on
grid on
box on
plot(xnew(:,1),'-o','DisplayName', 'Accepted x-Data')
plot(ynew(:,1), '-o','DisplayName', 'Accepted y-Data')
plot(znew(:,1),'-o', 'DisplayName', 'Accepted z-Data')
plot(xtarget*ones(length(p_x),1), 'DisplayName','Target x,y-Location', ...
    'LineWidth',3)
plot(ztarget*ones(length(p_z),1), 'DisplayName','Target z-Location', ...
    'LineWidth',3)
legend('Location','bestoutside')
xlabel('Incriments')
ylabel('meters')
title('X,Y, & Z Accepted Data')
```

