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MSDM5004
Homework 3 (Part I)

1. Consider the equation

$$\frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2}.$$

Show that the numerical scheme

$$\frac{U_j^{n+1} - U_j^{n-1}}{2\Delta t} = \frac{U_{j+1}^n - 2U_j^n + U_{j-1}^n}{(\Delta x)^2}$$

is second order both in time and space.

2. Consider the problem

$$\begin{cases} \frac{\partial u}{\partial t} = \frac{\partial^2 u}{\partial x^2} & 0 < x < 1, \quad t > 0 \\ u(0, t) = u(1, t) = 0 & t > 0 \\ u(x, 0) = u_0(x) & 0 \leq x \leq 1 \end{cases}$$

where

$$u_0(x) = \begin{cases} 2x & 0 \leq x \leq \frac{1}{2} \\ 2 - 2x & \frac{1}{2} < x \leq 1. \end{cases}$$

(1) The analytical solution is given by

$$u(x, t) = \sum_{m=1}^{\infty} a_m e^{-(m\pi)^2 t} \sin m\pi x, \quad \text{where } a_m = 2 \int_0^1 u_0(x) \sin m\pi x dx.$$

Compute the coefficient a_m .

(2) Write a code using MATLAB (or some other software) to obtain numerical solution using the explicit scheme. Use $J = 20$, $\Delta x = 0.05$, and (i) $\Delta t = 0.0012$ (ii) $\Delta t = 0.0013$. Plot the numerical solution and the analytical solution at $t = 0, \Delta t, 25\Delta t, 50\Delta t$ (To plot the analytical solution, you can stop the summation at a large number N , when you cannot see difference in the solution curve if N is increased).

3. Write a code to solve the PDE in problem 2 using the Crank-Nicolson method.

Use $J = 20$, $\Delta x = 0.05$, and (i) $\Delta t = 0.0012$ (ii) $\Delta t = 0.0013$, (iii) $\Delta t = 0.012$. Plot the solutions at $t = 0, \Delta t, 25\Delta t, 50\Delta t$.

Ans: 1.

$$T(x_j, t_n) = \frac{u(x_j, t_{n+1}) - u(x_j, t_n)}{2\Delta t} - \frac{u(x_{j+1}, t_n) - 2u(x_j, t_n) + u(x_{j-1}, t_n))}{(\Delta x)^2}$$

$$u(x_j, t_{n+1}) = u(x_j, t_n) + \frac{\partial u}{\partial t}(x_j, t_n) \Delta t + \frac{1}{2} \frac{\partial^2 u}{\partial t^2}(x_j, t_n) (\Delta t)^2 + \frac{1}{6} \frac{\partial^3 u}{\partial t^3}(x_j, t_n) (\Delta t)^3 + o(\Delta t)^4$$

$$u(x_j, t_n) = u(x_j, t_n) - \frac{\partial u}{\partial t}(x_j, t_n) \Delta t + \frac{1}{2} \frac{\partial^2 u}{\partial t^2}(x_j, t_n) (\Delta t)^2 - \frac{1}{6} \frac{\partial^3 u}{\partial t^3}(x_j, t_n) (\Delta t)^3 + o(\Delta t)^4$$

$$\Rightarrow \frac{u(x_j, t_{n+1}) - u(x_j, t_n)}{2\Delta t} = \frac{2 \frac{\partial u}{\partial t}(x_j, t_n) \Delta t + \frac{1}{3} \frac{\partial^3 u}{\partial t^3}(x_j, t_n) (\Delta t)^3 + o(\Delta t)^4}{2\Delta t} \\ = \frac{\partial u}{\partial t}(x_j, t_n) + \frac{1}{6} \frac{\partial^3 u}{\partial t^3}(x_j, t_n) (\Delta t)^2 + o(\Delta t)^3$$

$$u(x_{j+1}, t_n) = u(x_j, t_n) + \frac{\partial u}{\partial x}(x_j, t_n) \Delta x + \frac{1}{2} \frac{\partial^2 u}{\partial x^2}(x_j, t_n) (\Delta x)^2 + \frac{1}{6} \frac{\partial^3 u}{\partial x^3}(x_j, t_n) (\Delta x)^3 \\ + \frac{1}{24} \frac{\partial^4 u}{\partial x^4}(x_j, t_n) (\Delta x)^4 + o(\Delta x)^5$$

$$u(x_{j-1}, t_n) = u(x_j, t_n) - \frac{\partial u}{\partial x}(x_j, t_n) \Delta x + \frac{1}{2} \frac{\partial^2 u}{\partial x^2}(x_j, t_n) (\Delta x)^2 - \frac{1}{6} \frac{\partial^3 u}{\partial x^3}(x_j, t_n) (\Delta x)^3 \\ + \frac{1}{24} \frac{\partial^4 u}{\partial x^4}(x_j, t_n) (\Delta x)^4 + o(\Delta x)^5$$

$$\Rightarrow \frac{u(x_{j+1}, t_n) - 2u(x_j, t_n) + u(x_{j-1}, t_n))}{(\Delta x)^2} = \frac{\frac{\partial^2 u}{\partial x^2}(x_j, t_n) (\Delta x)^2 + \frac{1}{12} \frac{\partial^4 u}{\partial x^4}(x_j, t_n) (\Delta x)^4 + o(\Delta x)^5}{(\Delta x)^2}$$

$$= \frac{\partial^2 u}{\partial x^2}(x_j, t_n) + \frac{1}{12} \frac{\partial^4 u}{\partial x^4}(x_j, t_n) (\Delta x)^2 + O(\Delta x^3)$$

$$\begin{aligned} \Rightarrow T(x_j, t_n) &= \left(\frac{\partial u}{\partial t}(x_j, t_n) - \frac{\partial^2 u}{\partial x^2}(x_j, t_n) \right) \\ &+ \frac{1}{6} \frac{\partial^3 u}{\partial t^3}(x_j, t_n) (\Delta t)^2 + O(\Delta t^3) - \frac{1}{12} \frac{\partial^4 u}{\partial x^4}(x_j, t_n) (\Delta x)^2 + O(\Delta x^3) \\ &= \frac{1}{6} \frac{\partial^3 u}{\partial t^3}(x_j, t_n) \cdot (\Delta t)^2 - \frac{1}{12} \frac{\partial^4 u}{\partial x^4}(x_j, t_n) (\Delta x)^2 \\ &\quad + O(\Delta t^3) + O(\Delta x^3) \\ &= O(\Delta t^2) + O(\Delta x^2) \end{aligned}$$

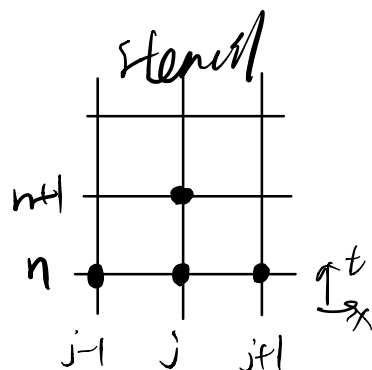
\Rightarrow second order both in time and space.

2.

$$\begin{aligned} (1) a_m &= 2 \int_0^{\frac{1}{2}} 2x \sin m\pi x dx + 2 \int_{\frac{1}{2}}^1 (2-2x) \sin m\pi x dx \\ &= 4 \left[-\frac{1}{m\pi} x \cos m\pi x \right]_0^{\frac{1}{2}} - 4 \int_0^{\frac{1}{2}} \frac{1}{m\pi} \cos m\pi x dx \\ &\quad + 4 \left[\frac{1}{m\pi} (x-1) \cos m\pi x \right]_{\frac{1}{2}}^1 - 4 \int_{\frac{1}{2}}^1 \frac{1}{m\pi} \cos m\pi x dx \\ &= -\frac{2}{m\pi} \cos \frac{m\pi}{2} + \frac{4}{(m\pi)^2} \sin \frac{m\pi}{2} + \frac{2}{m\pi} \cos \frac{m\pi}{2} + \frac{4}{(m\pi)^2} \sin \frac{m\pi}{2} \\ &= \frac{8}{(m\pi)^2} \sin \frac{m\pi}{2} \end{aligned}$$

(2) $J=20$

$$\frac{U_j^{n+1} - U_j^n}{\Delta t} = \frac{U_{j+1}^n - 2U_j^n + U_{j-1}^n}{(\Delta x)^2}$$



$$\Rightarrow U_j^{n+1} = U_j^n + \mu (U_{j+1}^n - 2U_j^n + U_{j-1}^n)$$

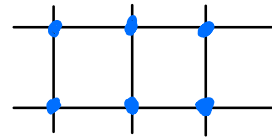
$$\mu = \frac{\Delta t}{(\Delta x)^2}$$

$$U_j^0 = u_0(x_j) = \begin{cases} 2x_j & , 0 \leq x_j \leq \frac{1}{2} \\ 2-2x_j & , \frac{1}{2} < x_j \leq 1 \end{cases}$$

$$U_0^n = U_J^n = 0$$

$$\begin{bmatrix} U_1^{n+1} \\ U_2^{n+1} \\ \vdots \\ U_{J-2}^{n+1} \\ U_{J-1}^{n+1} \end{bmatrix} = \begin{bmatrix} 1-2\mu & \mu & & & 0 \\ \mu & 1-2\mu & \mu & & \\ & \ddots & \ddots & \ddots & \\ 0 & & \mu & 1-2\mu & \mu \\ & & & \mu & 1-2\mu \end{bmatrix} \begin{bmatrix} U_1^n \\ U_2^n \\ U_3^n \\ \vdots \\ U_{J-2}^n \\ U_{J-1}^n \end{bmatrix}$$

3. Crank-Nicolson method



$$\frac{U_j^{n+1} - U_j^n}{\Delta t} = \frac{U_{j+1}^n - 2U_j^n + U_{j-1}^n}{2(\Delta x)^2} + \frac{U_{j+1}^{n+1} - 2U_j^{n+1} + U_{j-1}^{n+1}}{2(\Delta x)^2}$$

$$\Rightarrow -\frac{\mu}{2} U_{j-1}^{n+1} + (1+\mu) U_j^{n+1} - \frac{\mu}{2} U_{j+1}^{n+1} = \frac{\mu}{2} U_{j-1}^n + (1-\mu) U_j^n + \frac{\mu}{2} U_{j+1}^n$$

$$M = \frac{\Delta t}{(\Delta x)^2}$$

$$\begin{bmatrix} H\mu & -\frac{\mu}{2} & 0 & 0 \\ \frac{\mu}{2} & H\mu & -\frac{\mu}{2} & 0 \\ 0 & -\frac{\mu}{2} & H\mu & -\frac{\mu}{2} \\ & & \ddots & \ddots \\ & & & -\frac{\mu}{2} & H\mu & -\frac{\mu}{2} \\ & & & & -\frac{\mu}{2} & H\mu \end{bmatrix} \begin{bmatrix} U_1^{ntl} \\ U_2^{ntl} \\ \vdots \\ U_{J-2}^{ntl} \\ U_{J-1}^{ntl} \end{bmatrix} = \begin{bmatrix} H\mu & \frac{\mu}{2} & - & - \\ \frac{\mu}{2} & H\mu & \frac{\mu}{2} & - \\ 0 & \frac{\mu}{2} & H\mu & \frac{\mu}{2} \\ & \ddots & \ddots & \ddots \\ & & \frac{\mu}{2} & H\mu & \frac{\mu}{2} \\ & & & \frac{\mu}{2} & H\mu \end{bmatrix} \begin{bmatrix} U_1^n \\ U_2^n \\ \vdots \\ U_{J-2}^n \\ U_{J-1}^n \end{bmatrix}$$

$$H_{ii} \mu > \left| -\frac{\mu}{2} - \frac{\mu}{2} \right| = \mu \Rightarrow \text{diagonally dominant}$$

\Rightarrow Thomas algorithm is stable

Thomas algorithm $AU^{n+1} = BU^n$

$$1. \quad A = LU$$

2. solve: $Ly = BU^n$

3. solve $U \cdot U^{n+1} = y$