

SIGNALS AND DAEMON PROCESSES

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Signals are software interrupts. Signals provide a way of handling asynchronous events: a user at a terminal typing the interrupt key to stop a program or the next program in a pipeline terminating prematurely.

Name	Description	Default action
SIGABRT	abnormal termination (<code>abort</code>)	terminate+core
SIGALRM	timer expired (<code>alarm</code>)	terminate
SIGBUS	hardware fault	terminate+core
SIGCANCEL	threads library internal use	ignore
SIGCHLD	change in status of child	ignore
SIGCONT	continue stopped process	continue/ignore
SIGEMT	hardware fault	terminate+core
SIGFPE	arithmetic exception	terminate+core
SIGFREEZE	checkpoint freeze	ignore
SIGHUP	hangup	terminate
SIGILL	illegal instruction	terminate+core
SIGINFO	status request from keyboard	ignore
SIGINT	terminal interrupt character	terminate
SIGIO	asynchronous I/O	terminate/ignore
SIGIOT	hardware fault	terminate+core
SIGKILL	termination	terminate
SIGLWP	threads library internal use	ignore
SIGPIPE	write to pipe with no readers	terminate
SIGPOLL	pollable event (<code>poll</code>)	terminate
SIGPROF	profiling time alarm (<code>setitimer</code>)	terminate

SIGPWR	power fail/restart	terminate/ignore
SIGQUIT	terminal quit character	terminate+core
SIGSEGV	invalid memory reference	terminate+core
SIGSTKFLT	coprocessor stack fault	terminate
SIGSTOP	stop	stop process
SIGSYS	invalid system call	terminate+core
SIGTERM	termination	terminate
SIGTHAW	checkpoint thaw	ignore
SIGTRAP	hardware fault	terminate+core
SIGTSTP	terminal stop character	stop process
SIGTTIN	background read from control tty	stop process
SIGTTOU	background write to control tty	stop process
SIGURG	urgent condition (sockets)	ignore
SIGUSR1	user-defined signal	terminate
SIGUSR2	user-defined signal	terminate
SIGVTALRM	virtual time alarm (<code>setitimer</code>)	terminate
SIGWAITING	threads library internal use	ignore
SIGWINCH	terminal window size change	ignore
SIGXCPU	CPU limit exceeded (<code>setrlimit</code>)	terminate+core/ignore
SIGXFSZ	file size limit exceeded (<code>setrlimit</code>)	terminate+core/ignore
SIGXRES	resource control exceeded	ignore

When a signal is sent to a process, it is pending on the process to handle it. The process can react to pending signals in one of three ways:

- Accept the **default action** of the signal, which for most signals will terminate the process.
- **Ignore the signal.** The signal will be discarded and it has no affect whatsoever on the recipient process.
- Invoke a **user-defined function.** The function is known as a signal handler routine and the signal is said to be *caught when this function is called*.

THE UNIX KERNEL SUPPORT OF SIGNALS

- When a signal is generated for a process, the kernel will set the corresponding signal flag in the process table slot of the recipient process.
- If the recipient process is asleep, the kernel will awaken the process by scheduling it.
- When the recipient process runs, the kernel will check the process U-area that contains an array of signal handling specifications.
- If array entry contains a zero value, the process will accept the default action of the signal.
- If array entry contains a 1 value, the process will ignore the signal and kernel will discard it.
- If array entry contains any other value, it is used as the function pointer for a user-defined signal handler routine.

Signals

- The function prototype of the signal API is:

```
#include <signal.h>
```

```
void (*signal(int sig_no, void (*handler)(int)))(int);
```

- The formal argument of the API are: sig_no is a signal identifier like SIGINT or SIGTERM.
- The handler argument is the function pointer of a user-defined signal handler function.

- The following example attempts to catch the SIGTERM signal, ignores the SIGINT signal, and accepts the default action of the SIGSEGV signal.
- The pause API suspends the calling process until it is interrupted by a signal and the corresponding signal handler does a return:


```
#include<iostream.h>
#include<signal.h>
/*signal handler function*/
void catch_sig(int sig_num)
{
    signal (sig_num,catch_sig);

    cout<<"catch_sig:"<<sig_num<<endl;
}

/*main function*/
int main()
{
}
signal(SIGTERM,catch_sig);
signal(SIGINT,SIG_IGN);
signal(SIGSEGV,SIG_DFL);
pause( );  /*wait for a signal interruption*/
```

- The SIG_IGN specifies a signal is to be ignored, which means that if the signal is generated to the process, it will be discarded without any interruption of the process.
- The SIG_DFL specifies to accept the default action of a signal.