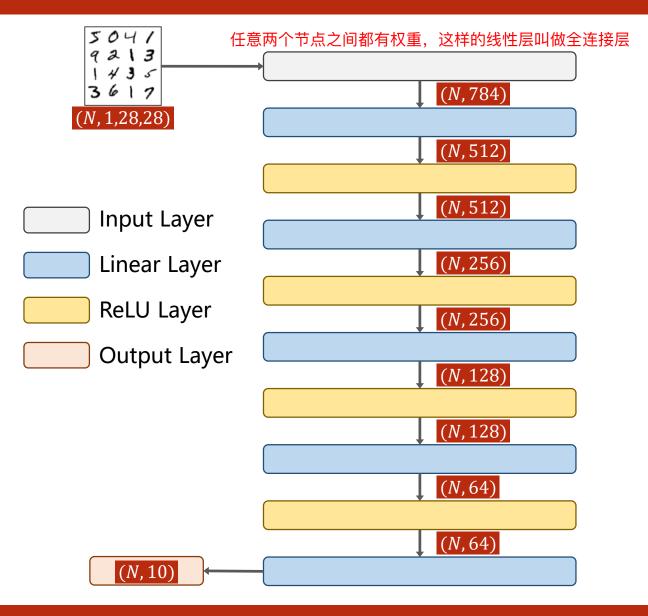


PyTorch Tutorial

10. Basic CNN

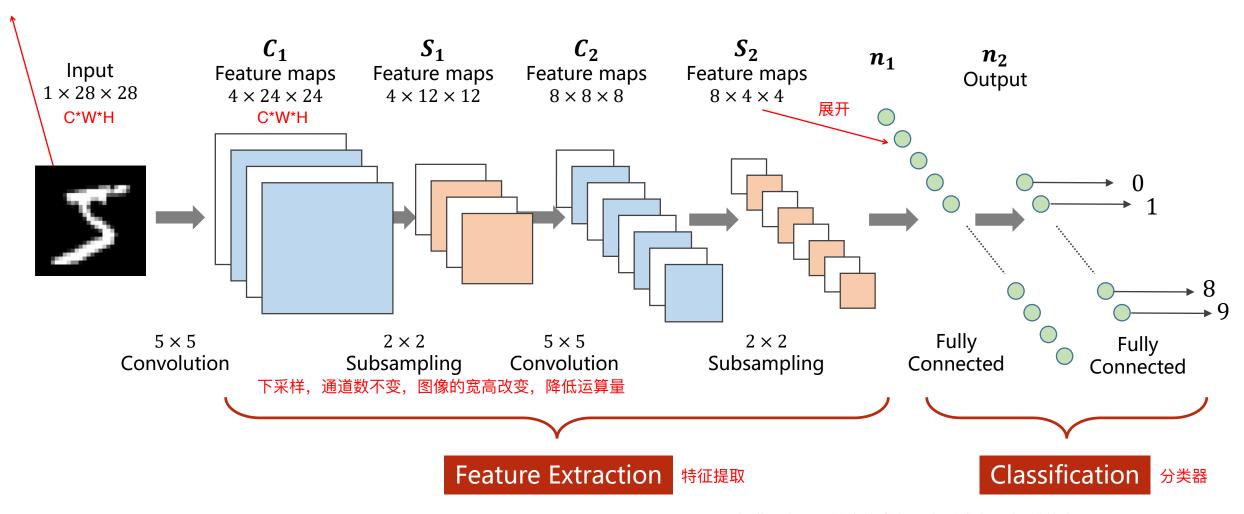
Revision: Fully Connected Neural Network



```
class Net(torch.nn.Module):
    def init (self):
         super(Net, self).__init__()
         self. 11 = \text{torch. nn. Linear}(784, 512)
         self. 12 = torch. nn. Linear (512, 256)
         self. 13 = torch. nn. Linear (256, 128)
         self. 14 = torch. nn. Linear (128, 64)
         self. 15 = \text{torch. nn. Linear} (64, 10)
    def forward(self, x):
         x = x. view(-1, 784)
         x = F. relu(self. 11(x))
         x = F. relu(self. 12(x))
         x = F. relu(self. 13(x))
         x = F. relu(self. 14(x))
         return self. 15(x)
model = Net()
```

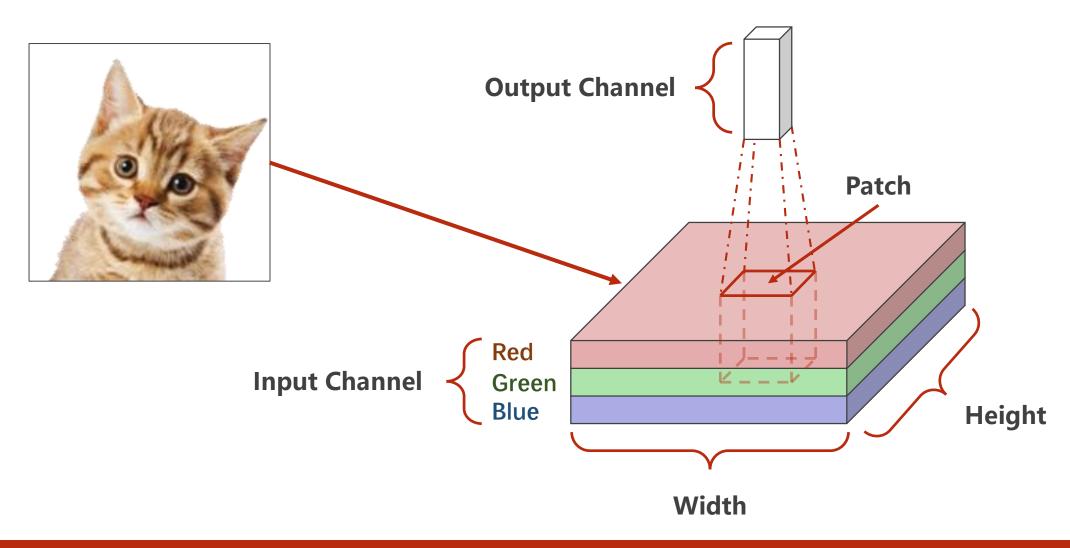
Convolutional Neural Network

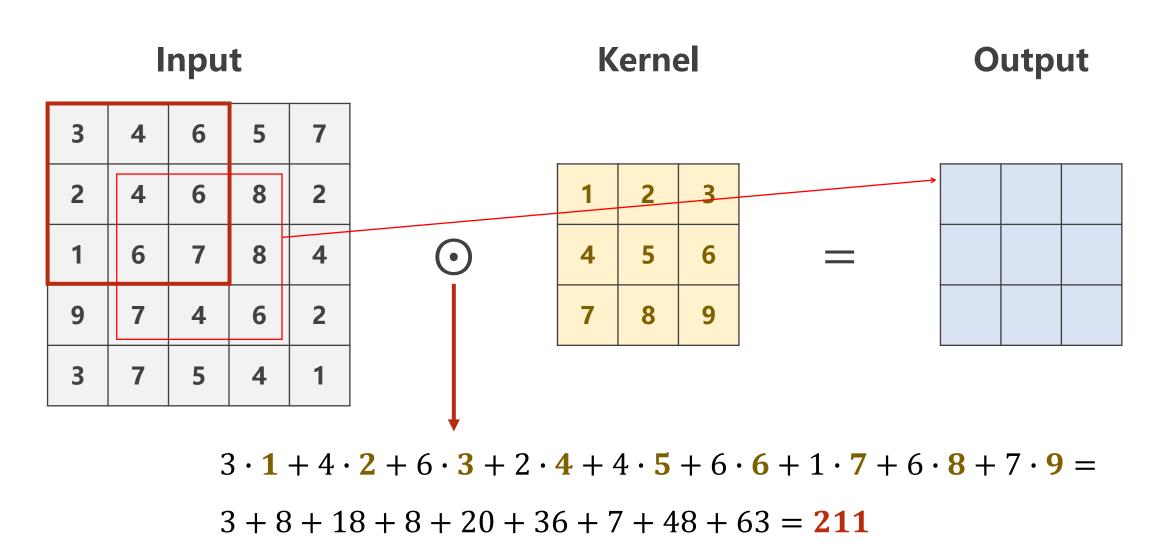
之前用全连接做预测时,将图像所有像素直接变为一维向量,这个过程会丧失部分像素之间的位置关联。

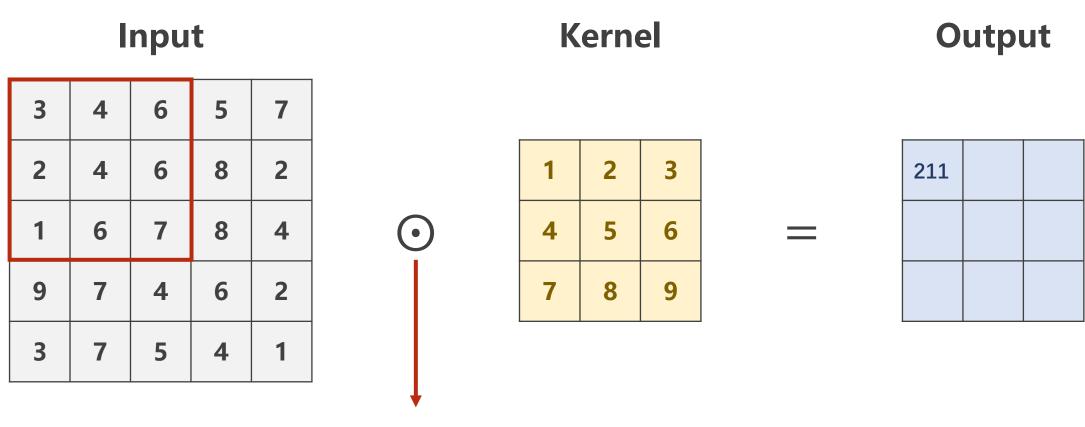


不断进行大小和维度的变化,直到成为一个1维的向量

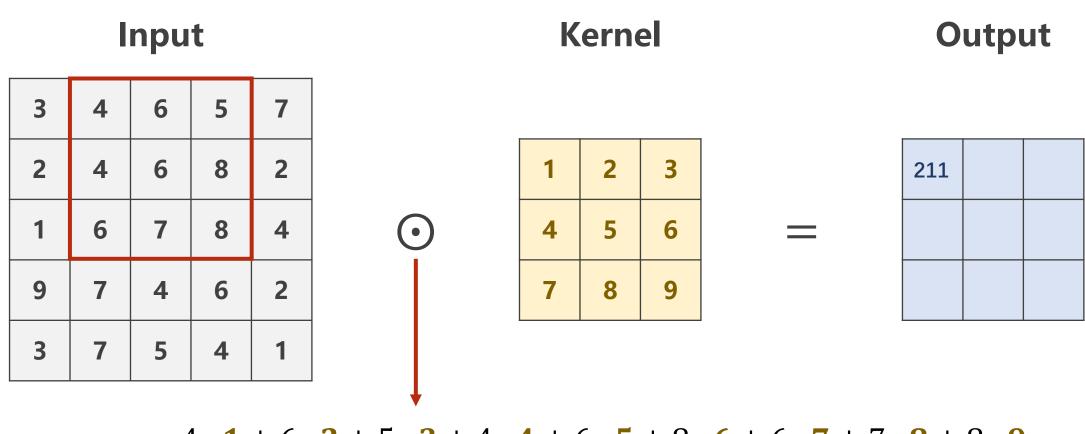
Convolution



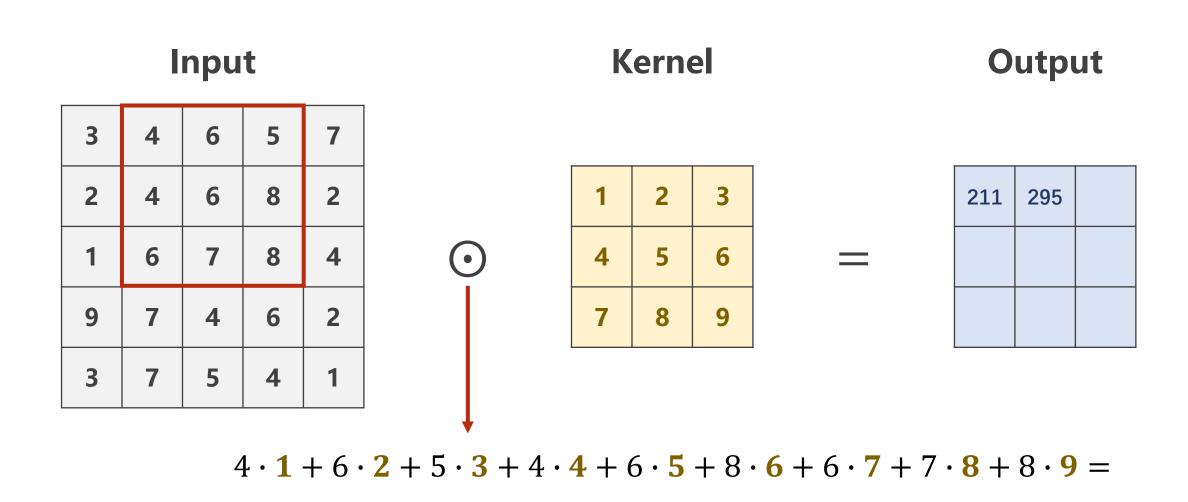




$$3 \cdot \mathbf{1} + 4 \cdot \mathbf{2} + 6 \cdot \mathbf{3} + 2 \cdot \mathbf{4} + 4 \cdot \mathbf{5} + 6 \cdot \mathbf{6} + 1 \cdot \mathbf{7} + 6 \cdot \mathbf{8} + 7 \cdot \mathbf{9} = 3 + 8 + 18 + 8 + 20 + 36 + 7 + 48 + 63 = 211$$



$$4 \cdot 1 + 6 \cdot 2 + 5 \cdot 3 + 4 \cdot 4 + 6 \cdot 5 + 8 \cdot 6 + 6 \cdot 7 + 7 \cdot 8 + 8 \cdot 9 =$$
 $4 + 12 + 15 + 16 + 30 + 48 + 42 + 56 + 72 = 295$

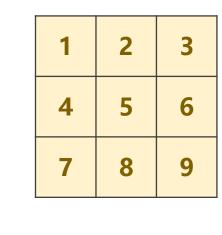


4 + 12 + 15 + 16 + 30 + 48 + 42 + 56 + 72 = 295

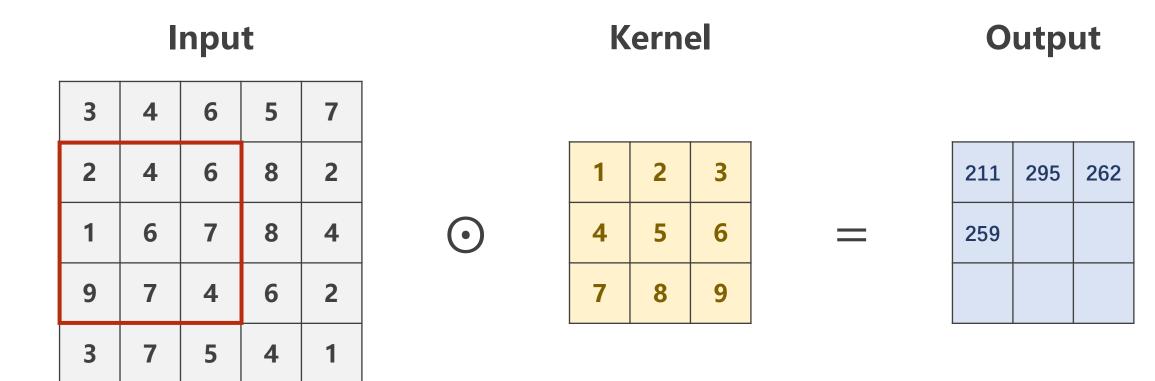


3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

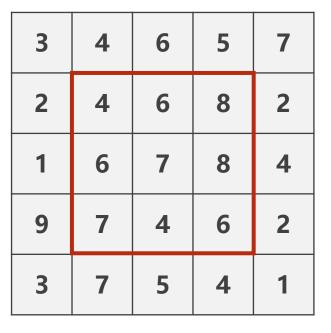
Kernel



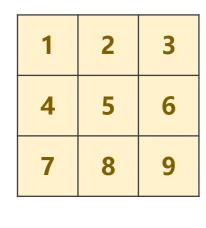
211	295	262







Kernel

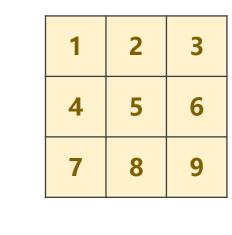


211	295	262
259	282	

Input

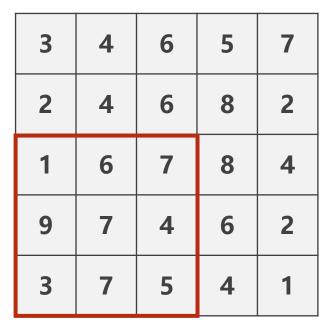
3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel

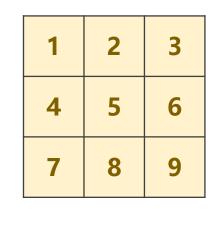


211	295	262
259	282	214

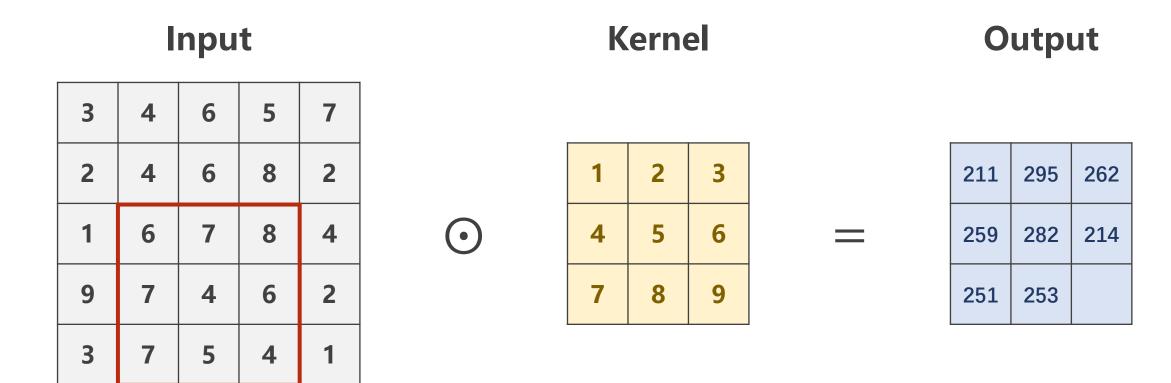
Input



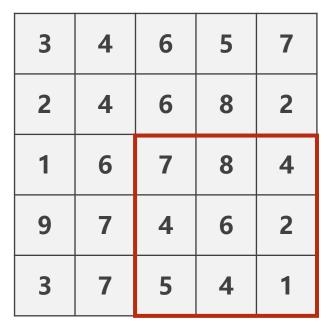
Kernel



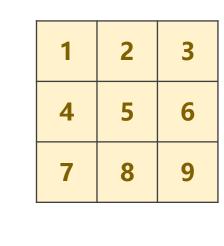
211	295	262
259	282	214
251		







Kernel



211	295	262
259	282	214
251	253	169

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1



211	295	262
259	282	214
251	253	169

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1



211	295	262
259	282	214
251	253	169

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

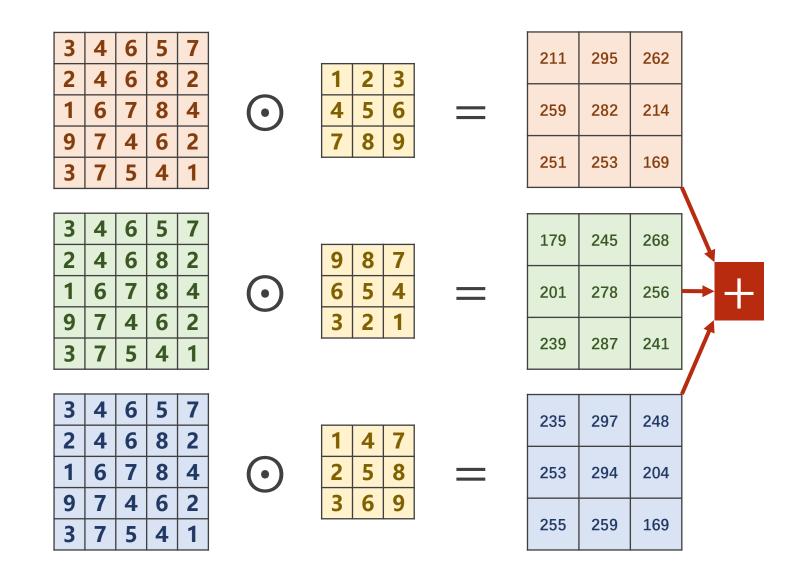
179	245	268	
201	278	256	
239	287	241	

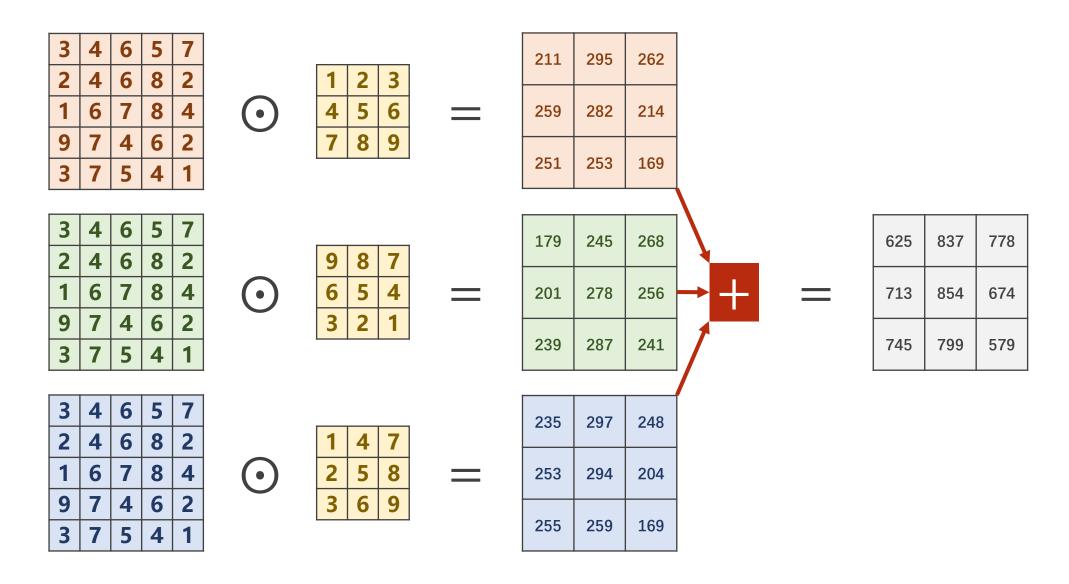
3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

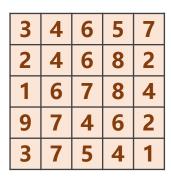
3	4	6	5	7					
2	4	6	8	2				1	1
1	6	7	8	4	(•		4	
9	7	4	6	2				7	
3	7	5	4	1					
3	4	6	5	7			_		
3	4	6	5	7 2			[9	
		_	_	_	(•		9	
2	4	6	8	2	(•			⊢
2	4	6 7	8	2	(•		6	
2 1 9 3	4 6 7	6 7 4 5	8 8 6 4	2 4 2	(•		6	⊢

	-					_				
7	4	6	2		7 8	9		251	252	100
7	5	4	1					251	253	169
4	6	5	7					179	245	268
4	6	8	2		9 8	7				
6	7	8	4	\odot	6 5	4	=	201	278	256
7	4	6	2		3 2	1				
7	5	4	1					239	287	241
4	6	5	7					235	297	248
4	6	8	2		1 4	7				
6	7	8	4	\odot	2 5	8	=	253	294	204
7	4	6	2		3 6	9				
7	5	4	1					255	259	169
				•						

211	295	262	
259	282	214	
251	253	169	
		-	•
179	245	268	
201	278	256	
239	287	241	
235	297	248	
253	294	204	
255	259	169	

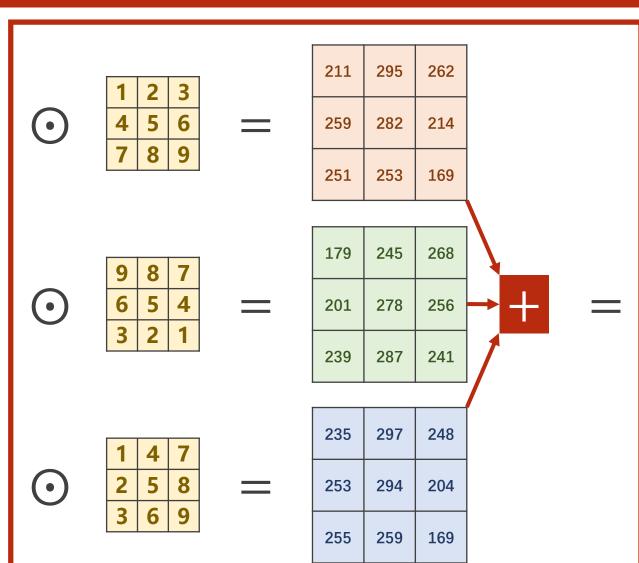






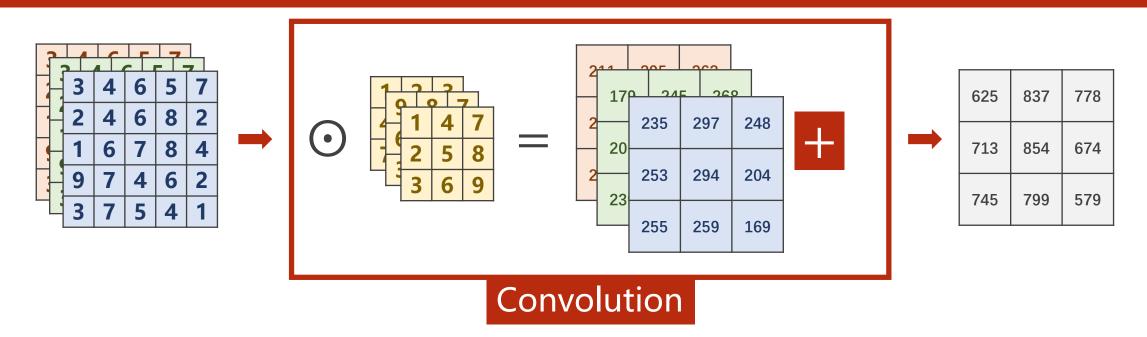
3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

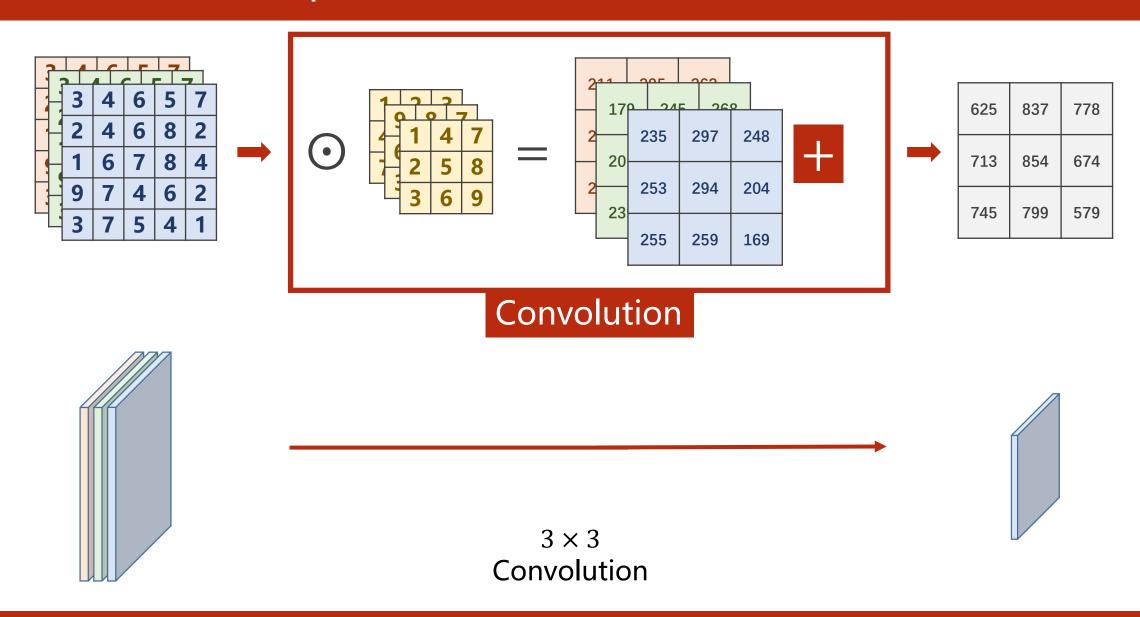
3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

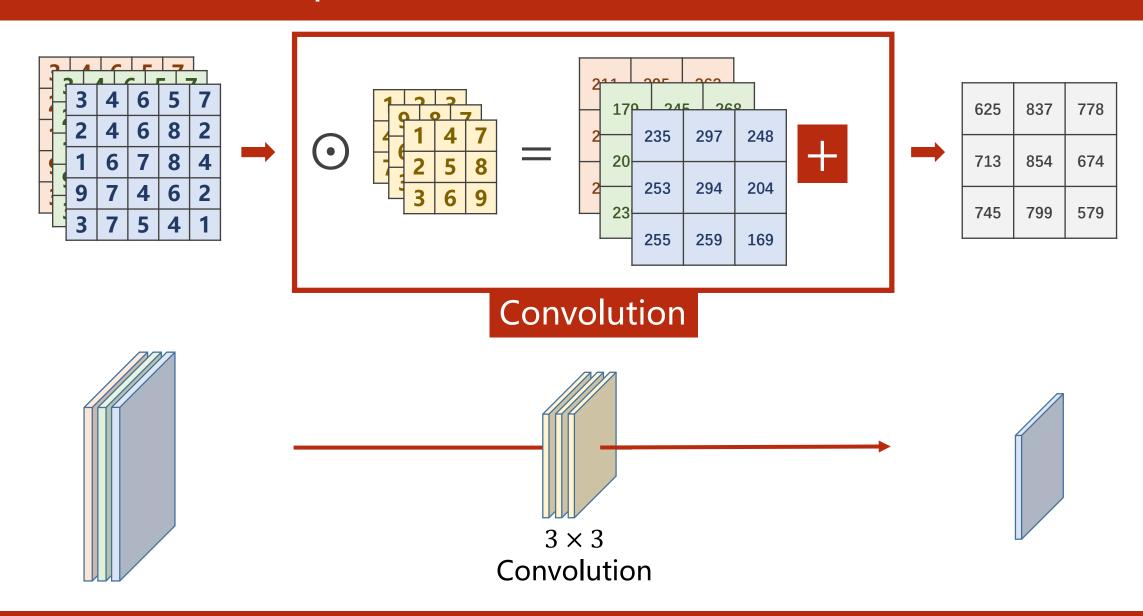


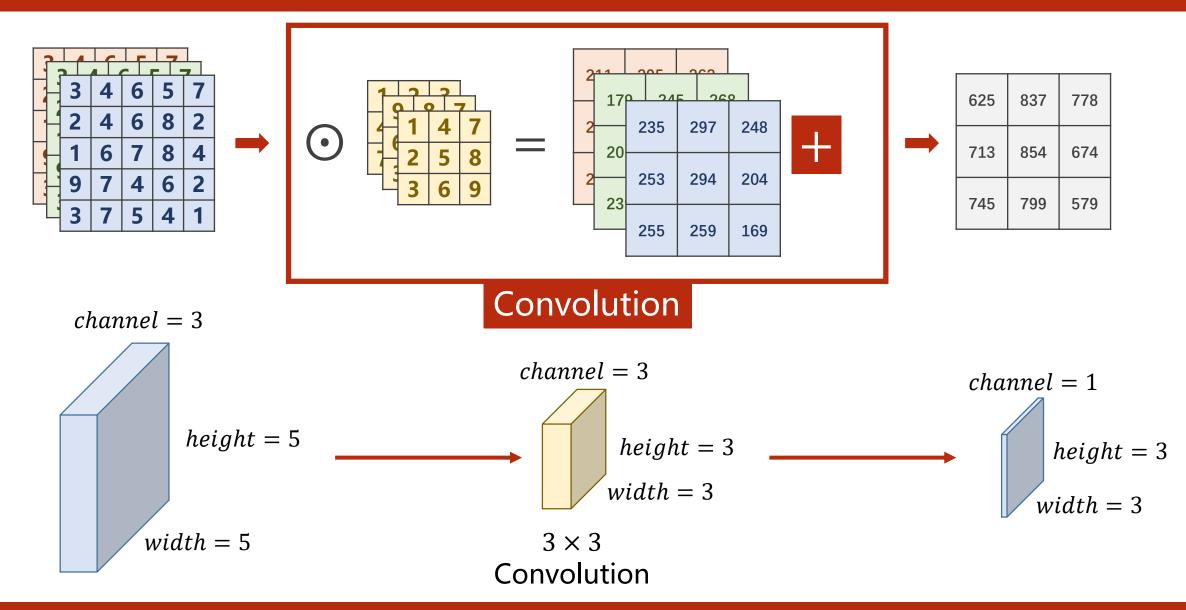
Convolution

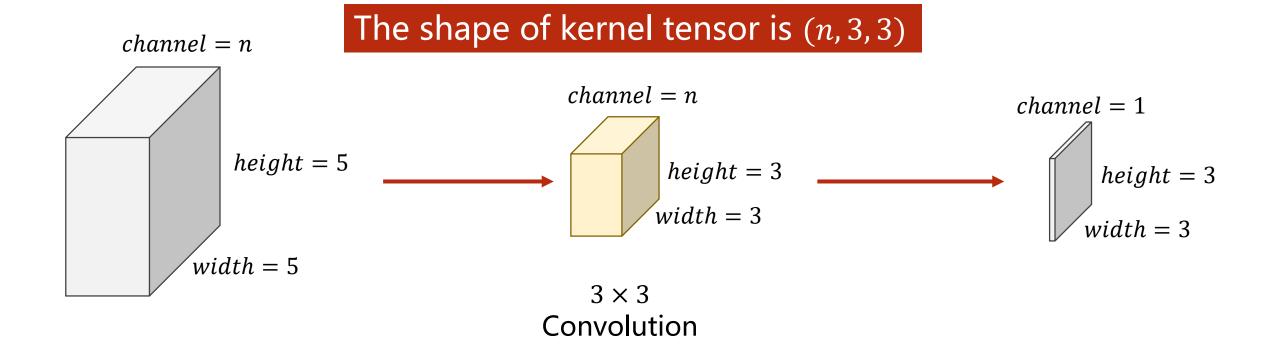
625	837	778	
713	854	674	
745	799	579	



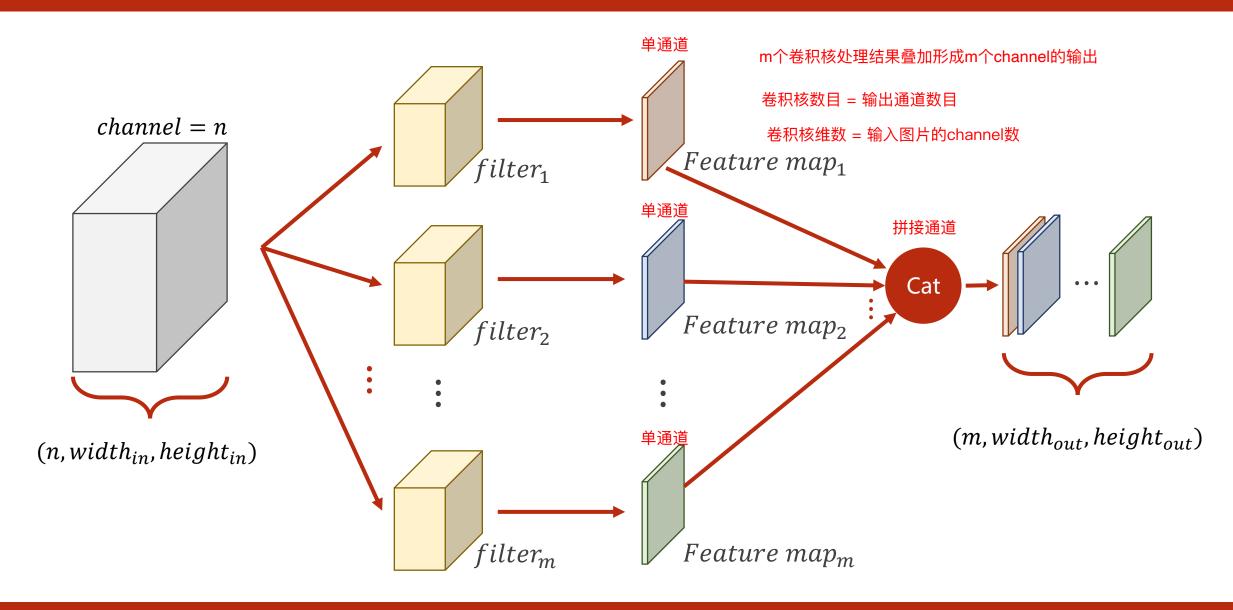


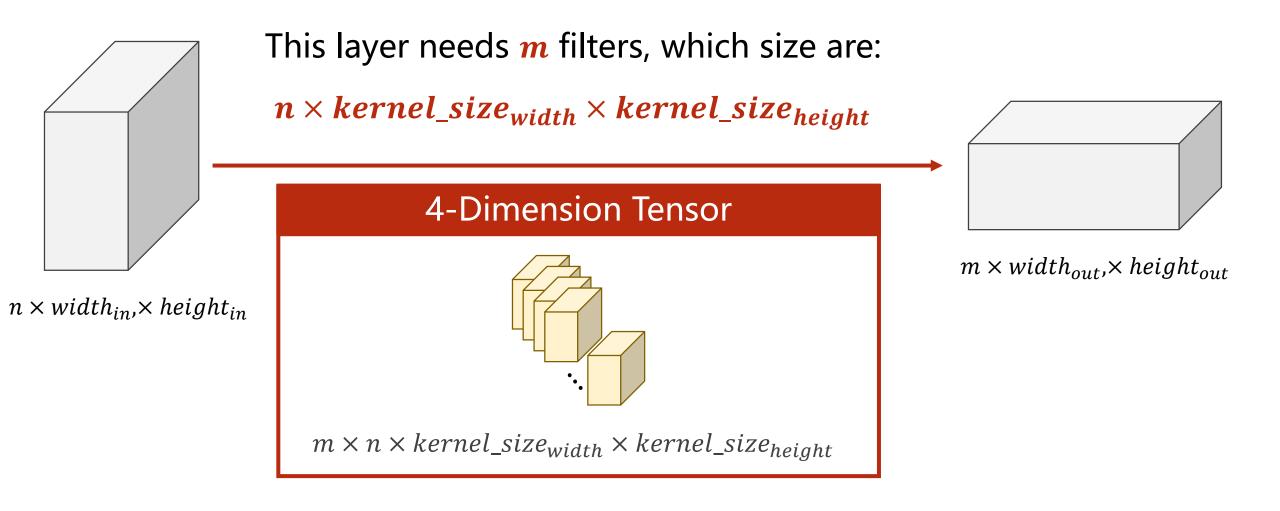






Convolution – N Input Channels and M Output Channels





```
import torch
in_channels, out_channels= 5, 10
width, height = 100, 100
kernel size = 3
batch size = 1
input = torch.randn(batch size,
                    in channels,
                    width,
                    height)
conv layer = torch.nn.Conv2d(in channels,
                              out channels,
                              kernel size=kernel size)
output = conv_layer(input)
print(input. shape)
print(output. shape)
print(conv layer.weight.shape)
```

```
import torch
in channels, out channels= 5, 10
width, height = 100, 100
kernel size = 3
batch size = 1
input = torch.randn(batch size,
                    in channels,
                    width,
                    height)
conv layer = torch.nn.Conv2d(in channels,
                              out channels,
                              kernel size=kernel size)
output = conv_layer(input)
print(input. shape)
print(output. shape)
print(conv layer.weight.shape)
```

```
import torch
in channels, out channels= 5, 10
width, height = 100, 100
kernel size = 3
batch size = 1
input = torch.randn(batch_size,
                    in channels,
                    width,
                    height)
conv_layer = torch.nn.Conv2d(in_channels,
                              out channels,
                              kernel size=kernel size)
output = conv_layer(input)
print(input. shape)
print(output. shape)
print(conv layer.weight.shape)
```

```
import torch
in channels, out channels= 5, 10
width, height = 100, 100
kernel size = 3
batch size = 1
input = torch.randn(batch size,
                    in channels,
                    width,
                    height)
conv_layer = torch.nn.Conv2d(in_channels,
                             out_channels,
                             kernel size=kernel size)
output = conv_layer(input)
print(input. shape)
print(output. shape)
print(conv layer.weight.shape)
```

```
import torch
in channels, out channels= 5, 10
width, height = 100, 100
kernel size = 3
batch size = 1
input = torch.randn(batch size,
                    in channels,
                    width,
                    height)
conv layer = torch.nn.Conv2d(in channels,
                              out channels,
                              kernel size=kernel size)
output = conv layer(input)
print(input. shape)
print(output. shape)
print(conv layer.weight.shape)
```

```
import torch
in channels, out channels= 5, 10
width, height = 100, 100
kernel size = 3
batch\_size = 1
input = torch.randn(batch_size,
                    in channels,
                    width,
                    height)
conv layer = torch.nn.Conv2d(in channels,
                             out channels,
                             kernel size=kernel size)
output = conv_layer(input)
                                  torch. Size([1, 5, 100, 100])
print(input.shape)
print(output.shape)
                                  torch. Size([1, 10, 98, 98])
print(conv_layer.weight.shape)
                                   torch. Size([10, 5, 3, 3])
```

Convolutional Layer – padding

边缘填充,扩展input大小,使output满足大小要求。 对于3*3的卷积核,如果需要output与input形态大小一样,则需要填充一圈。5*5则需要填充两圈

Input

Kernel

Output

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

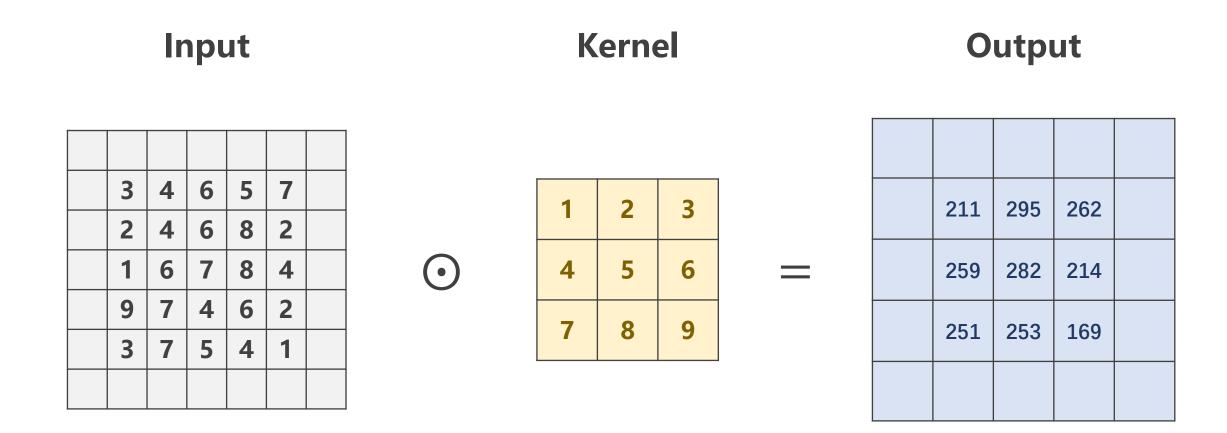
(·)

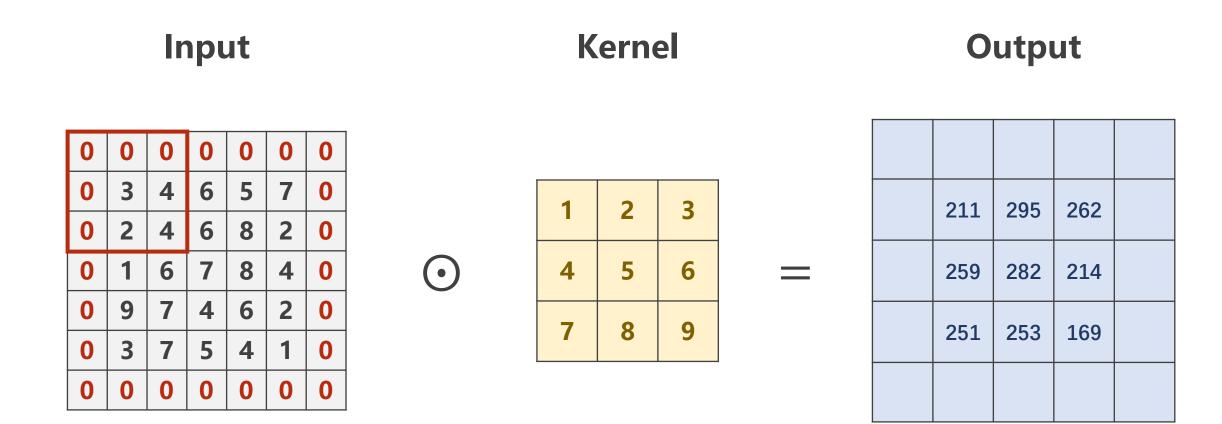
1	2	3
4	5	6
7	8	9

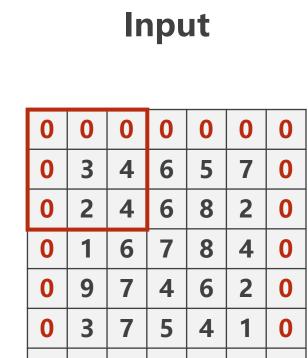
 211
 295
 262

 259
 282
 214

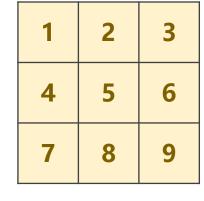
 251
 253
 169







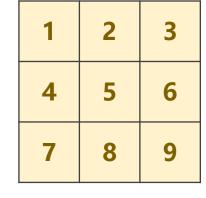
Kernel



91				
	211	295	262	
	259	282	214	
	251	253	169	



Kernel



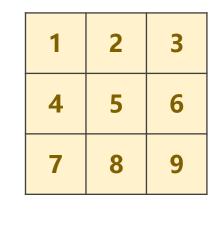
91	168	224	215	127
114	211	295	262	149
192	259	282	214	122
194	251	253	169	86
96	112	110	68	31

```
import torch
input = [3, 4, 6, 5, 7,
         2, 4, 6, 8, 2,
         1, 6, 7, 8, 4,
         9, 7, 4, 6, 2,
         [3, 7, 5, 4, 1]
input = torch. Tensor(input). view(1, 1, 5, 5)
conv_layer = torch.nn.Conv2d(1, 1, kernel_size=3, padding=1, bias=False)
kernel = torch. Tensor([1, 2, 3, 4, 5, 6, 7, 8, 9]). view(1, 1, 3, 3)
conv_layer.weight.data = kernel.data
output = conv_layer(input)
print(output)
```

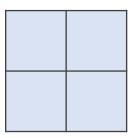
Input

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel



Output

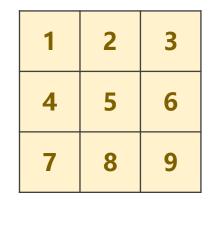


Lecture 10-42

Input

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel

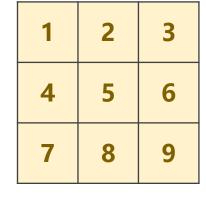




Input

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel

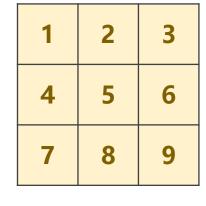


211	

Input

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel

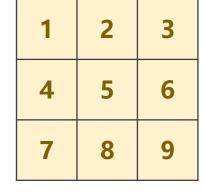


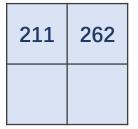
211	262

Input

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel

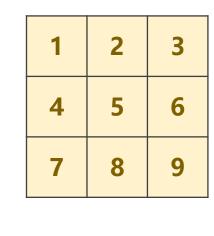




Input

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel

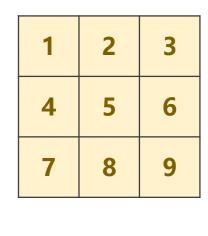


211	262
251	

Input

3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

Kernel

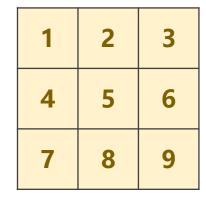


211	262
251	



3	4	6	5	7
2	4	6	8	2
1	6	7	8	4
9	7	4	6	2
3	7	5	4	1

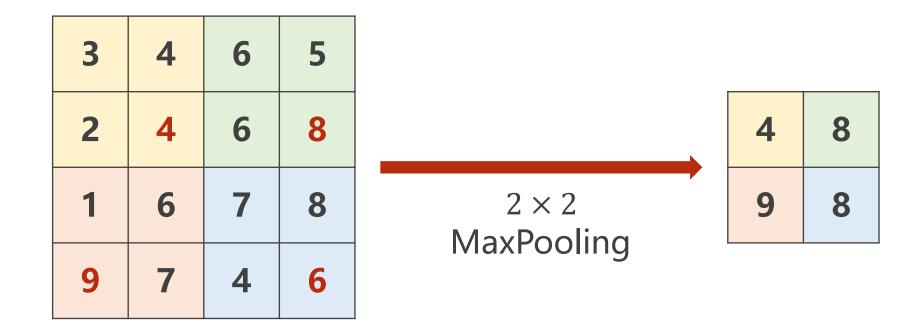
Kernel



211	262
251	169

```
import torch
input = [3, 4, 6, 5, 7,
         2, 4, 6, 8, 2,
         1, 6, 7, 8, 4,
         9, 7, 4, 6, 2,
         3, 7, 5, 4, 1
input = torch. Tensor(input). view(1, 1, 5, 5)
conv_layer = torch.nn.Conv2d(1, 1, kernel_size=3, stride=2, bias=False)
kernel = torch. Tensor([1, 2, 3, 4, 5, 6, 7, 8, 9]). view(1, 1, 3, 3)
conv layer. weight. data = kernel. data
output = conv layer(input)
print(output)
```

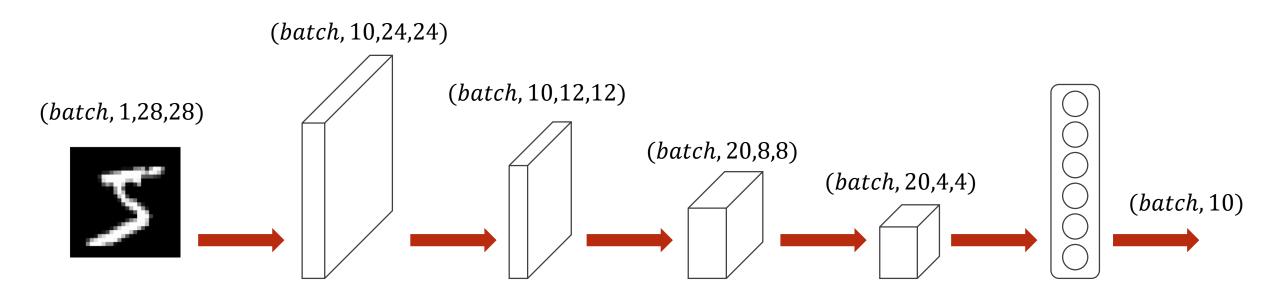
Max Pooling Layer



Max Pooling Layer

```
import torch
input = [3, 4, 6, 5,
         2, 4, 6, 8,
         1, 6, 7, 8,
         9, 7, 4, 6,
input = torch. Tensor(input). view(1, 1, 4, 4)
maxpooling_layer = torch.nn.MaxPool2d(kernel_size=2)
output = maxpooling_layer(input)
print(output)
```

A Simple Convolutional Neural Network



Conv2d Layer $filter: 5 \times 5$

 C_{in} : 1

 C_{out} : 10

Pooling Layer

filter: 2×2

Conv2d Layer

filter: 5×5

 C_{in} : 10

 C_{out} : 20

Pooling Layer

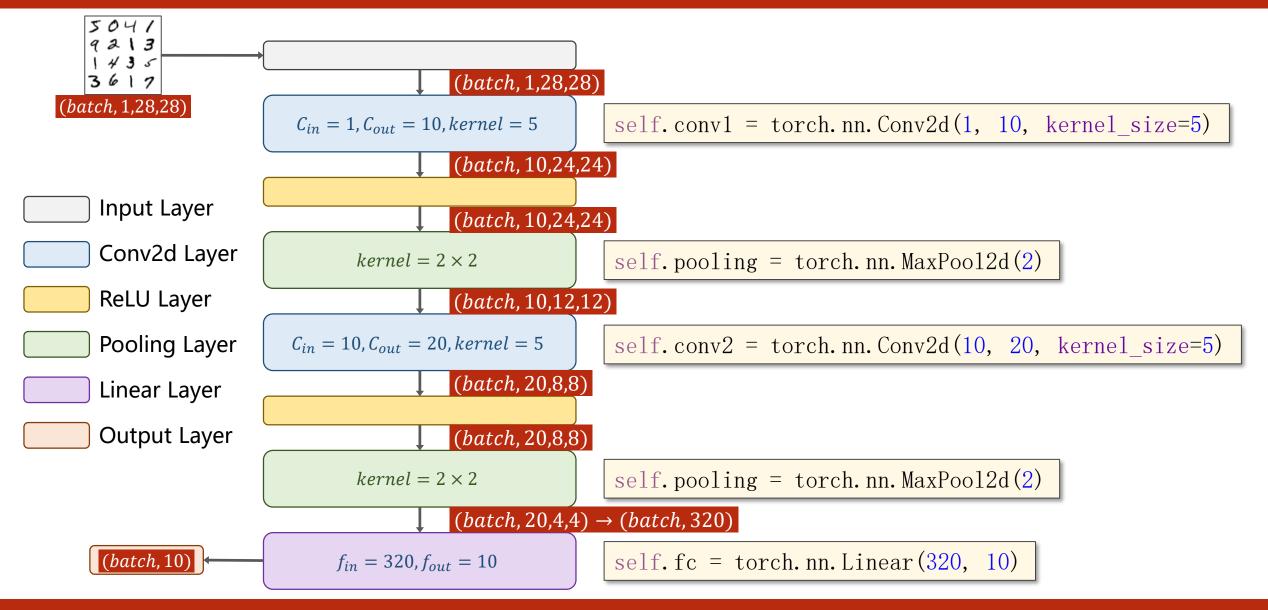
 $filter: 2 \times 2$

Linear Layer

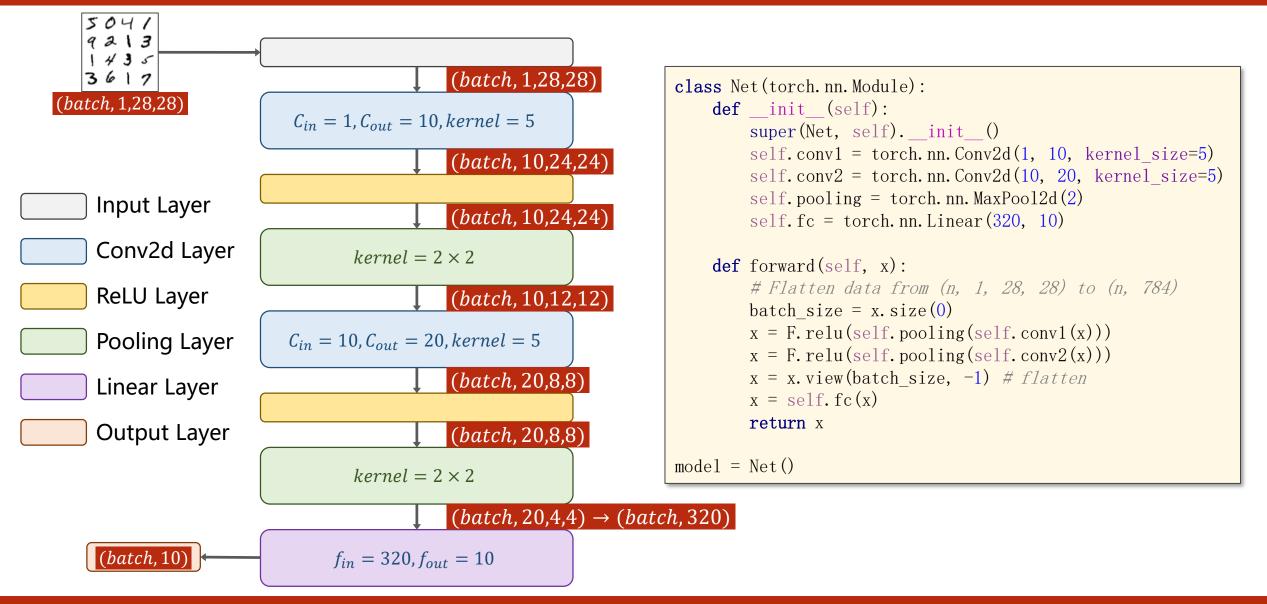
 C_{in} : 320

 C_{out} : 10

Revision: Fully Connected Neural Network



Revision: Fully Connected Neural Network



How to use GPU – 1. Move Model to GPU

```
class Net(torch.nn.Module):
    def __init__(self):
        super(Net, self). init ()
        self. conv1 = torch. nn. Conv2d(1, 10, kernel_size=5)
        self.conv2 = torch.nn.Conv2d(10, 20, kernel_size=5)
        self. pooling = torch. nn. MaxPool2d(2)
        self. fc = torch. nn. Linear (320, 10)
    def forward(self, x):
        # Flatten data from (n, 1, 28, 28) to (n, 784)
        batch size = x. size(0)
        x = F. relu(self. pooling(self. conv1(x)))
        x = F. relu(self. pooling(self. conv2(x)))
        x = x. view(batch size, -1) # flatten
        x = self. fc(x)
        return x
model = Net()
```

How to use GPU – 1. Move Model to GPU

```
class Net(torch.nn.Module):
    def __init__(self):
        super(Net, self). init ()
        self. conv1 = torch. nn. Conv2d(1, 10, kernel size=5)
        self.conv2 = torch.nn.Conv2d(10, 20, kernel_size=5)
        self. pooling = torch. nn. MaxPool2d(2)
        self. fc = torch. nn. Linear (320, 10)
    def forward(self, x):
        # Flatten data from (n, 1, 28, 28) to (n, 784)
        batch size = x. size(0)
        x = F. relu(self. pooling(self. conv1(x)))
        x = F. relu(self. pooling(self. conv2(x)))
        x = x.view(batch)
                         Define device as the first visible cuda
        x = self.fc(x)
        return x
                         device if we have CUDA available.
model = Net()
device = torch.device("cuda:0" if torch.cuda.is available() else "cpu")
```

How to use GPU – 1. Move Model to GPU

```
class Net(torch.nn.Module):
    def __init__(self):
        super(Net, self). init ()
        self. conv1 = torch. nn. Conv2d(1, 10, kernel size=5)
        self.conv2 = torch.nn.Conv2d(10, 20, kernel_size=5)
        self. pooling = torch. nn. MaxPool2d(2)
        self. fc = torch. nn. Linear (320, 10)
    def forward(self, x):
        # Flatten data from (n, 1, 28, 28) to (n, 784)
        batch size = x. size(0)
        x = F. relu(self. pooling(self. conv1(x)))
        x = F. relu(self. pooling(self. conv2(x)))
        x = x. view(batch size, -1) # flatten
        x = self. fc(x)
                       Convert parameters and buffers of all
        return x
                       modules to CUDA Tensor.
model = Net()
device = torch. device ("cuda:0" if torch. cuda. is available() else "cpu")
model.to(device)
```

```
def train(epoch):
   running loss = 0.0
   for batch idx, data in enumerate(train loader, 0):
        inputs, target = data
        optimizer.zero_grad()
        # forward + backward + update
        outputs = model(inputs)
        loss = criterion(outputs, target)
        loss. backward()
        optimizer.step()
        running_loss += loss.item()
        if batch idx % 300 == 299:
            print('[%d, %5d] loss: %.3f' % (epoch + 1, batch_idx + 1, running_loss / 2000))
            running loss = 0.0
```

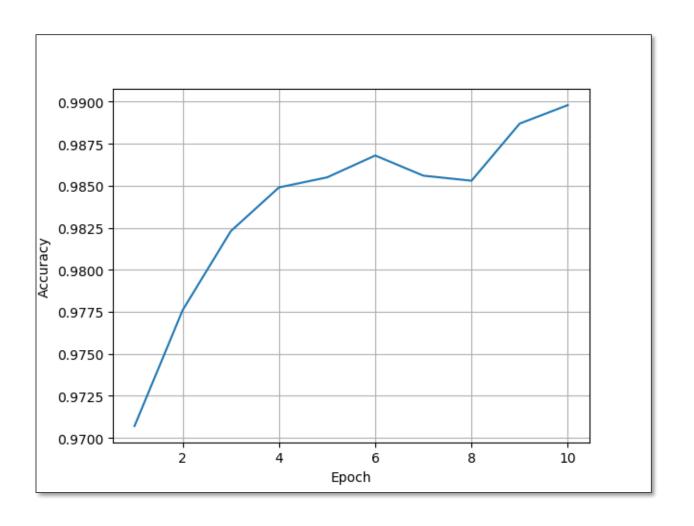
```
def train(epoch):
   running loss = 0.0
   for batch idx, data in enumerate(train loader, 0):
        inputs, target = data
        inputs, target = inputs.to(device), target.to(device)
        optimizer.zero grad()
                                             Send the inputs and targets at every
        # forward + backward + update
        outputs = model(inputs)
                                             step to the GPU.
        loss = criterion(outputs, target)
        loss, backward()
       optimizer.step()
       running loss += loss.item()
        if batch idx % 300 == 299:
            print('[%d, %5d] loss: %.3f' % (epoch + 1, batch idx + 1, running loss / 2000))
           running_loss = 0.0
```

```
def test():
    correct = 0
    total = 0
    with torch.no_grad():
        for data in test_loader:
            inputs, target = data
            outputs = model(inputs)
            _, predicted = torch.max(outputs.data, dim=1)
            total += target.size(0)
            correct += (predicted == target).sum().item()
    print('Accuracy on test set: %d %% [%d/%d]' % (100 * correct / total, correct, total))
```

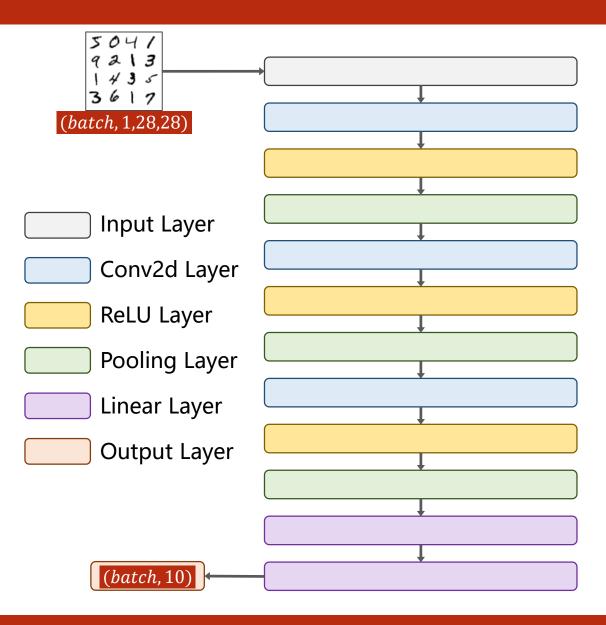
```
def test():
    correct = 0
    total = 0
    with torch.no_grad():
        for data in test_loader:
            inputs, target = data
            inputs, target = inputs.to(device), target.to(device)
            outputs = model(inputs)
            _, predicted = torch.max(outputs.data, dim=1)
            total += target.size(0)
            correct += (predicted == target).sum().item()
            print('Accuracy on test set: %d %% [%d/%d]' % (100 * correct / total, correct, total))
```

Results

```
Accuracy on test set: 6 % [637/10000]
   300] loss: 0.098
    600] loss: 0.035
   900] loss: 0.025
Accuracy on test set: 96 % [9605/10000]
   300] loss: 0.021
   600] loss: 0.017
[2, 900] loss: 0.015
Accuracy on test set: 97 % [9709/10000]
   300] loss: 0.006
   600] loss: 0.006
[9, 900] loss: 0.007
Accuracy on test set: 98 % [9857/10000]
[10, 300] loss: 0.006
     600] loss: 0.006
[10, 900] loss: 0.006
Accuracy on test set: 98 % [9869/10000]
```



Exercise 10-1



- Try a more complex CNN:
 - Conv2d Layer *3
 - ReLU Layer * 3
 - MaxPooling Layer * 3
 - Linear Layer * 3
- Try different configuration of this CNN:
 - Compare their performance.



PyTorch Tutorial

10. Basic CNN