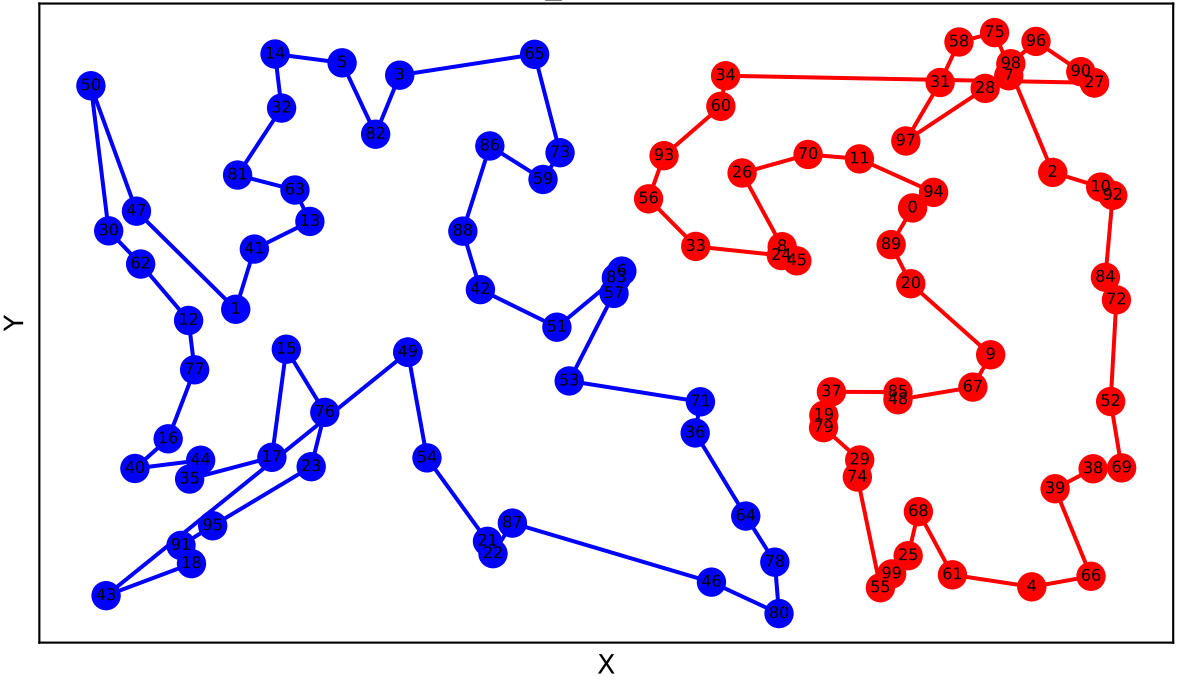solver = nearest-neighbour
cost1 = 14468
cost2 = 10760
instance = kroB100.tsp
start_vertex = 50