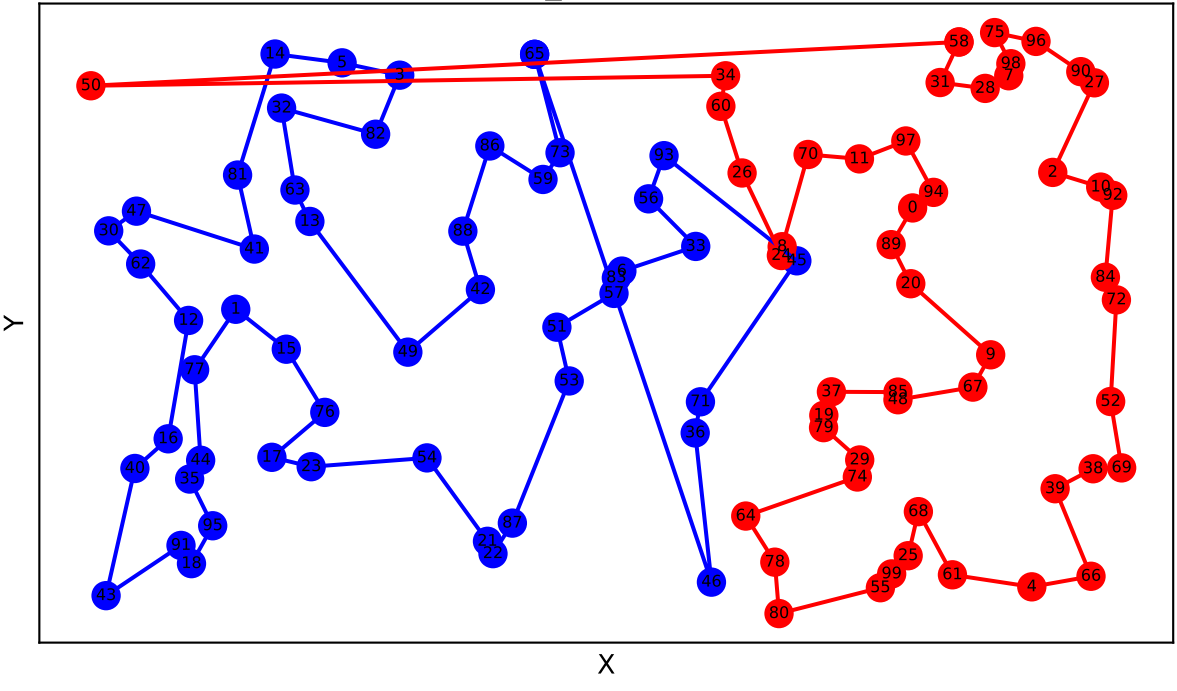solver = nearest-neighbour
cost1 = 15141
cost2 = 14654
instance = kroB100.tsp
start_vertex = 50