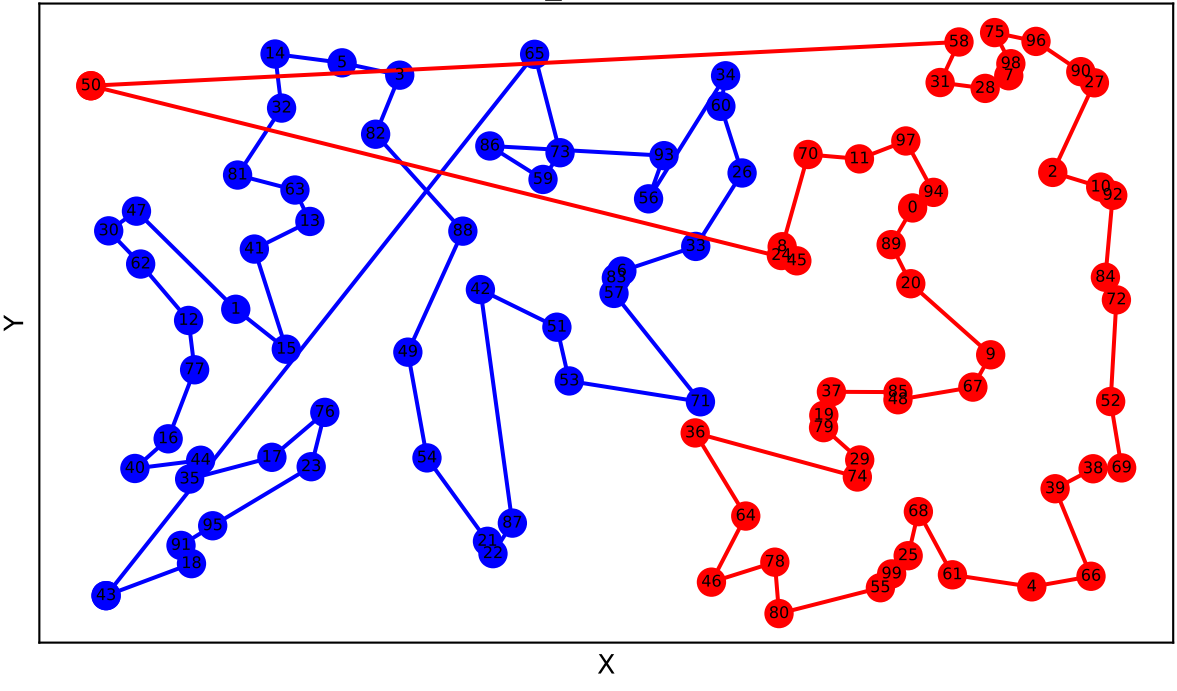solver = nearest-neighbour
cost1 = 15755
cost2 = 15240
instance = kroB100.tsp
start_vertex = 15