

```

/*
*File: LCD.c
* Se tomo y se adaptaron las librerias de Ligo
George
* de la pagina www.electrosome.com
* Pagina: https://electrosome.com/lcd-pic-
mplab-xc8/
*/

#include "LCD.h"

void Lcd_Port(char a) {
    if (a & 1)
        D0 = 1;
    else
        D0 = 0;

    if (a & 2)
        D1 = 1;
    else
        D1 = 0;

    if (a & 4)
        D2 = 1;
    else
        D2 = 0;

    if (a & 8)
        D3 = 1;
    else
        D3 = 0;

    if (a & 16)
        D4 = 1;
    else
        D4 = 0;

    if (a & 32)
        D5 = 1;
    else
        D5 = 0;

    if (a & 64)
        D6 = 1;
    else
        D6 = 0;

    if (a & 128)
        D7 = 1;
    else
        D7 = 0;
}

void Lcd_Cmd(char a) {
    RS = 0;

    Lcd_Port (a);

    EN = 1;

```

```

    __delay_ms(5);
    EN = 0;
}

```

```

void Lcd_Clear(void) {
    Lcd_Cmd(0);
    Lcd_Cmd(1);
}

```

```

void Lcd_Init(void) {
    Lcd_Port(0x00);
    __delay_ms(30);
    Lcd_Cmd (0x30);
    __delay_ms(6);
    Lcd_Cmd (0x30);
    __delay_ms(15);
    Lcd_Cmd (0x30);

```

```

////////////////////////////////////
////////////////////////////////////

```

```

    Lcd_Cmd (0x08);
    Lcd_Cmd (0x01);
    Lcd_Cmd (0x08);
    Lcd_Cmd (0x06);
}

```

```

void Lcd_Set_Cursor(char a, char b) {
    char temp, z, y;
    if (a == 1) {
        temp = 0x80 + b - 1;

```

```

        z = temp >> 4;
        y = temp & 0x0F;
        Lcd_Cmd(z);
        Lcd_Cmd (y);
    }else if (a == 2) {
        temp = 0xC0 + b - 1;
        z = temp >> 4;
        y = temp & 0x0F;
        Lcd_Cmd(z);
        Lcd_Cmd (y);
    }
}

```

```

void Lcd_Write_Char(char a){
    char temp;
    RS = 1;
    Lcd_Port(temp);
    EN = 1;
    __delay_us(40);
    EN = 0;
}

```

```

void Lcd_Write_String(char *a){
    int i;
    for (i = 0; a[i] != '\0'; i++)
        Lcd_Write_Char(a[i]);
}

```

```

/*
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mplab-xc8/

*/

#ifndef LCD_H
#define LCD_H

#endif

#ifndef _XTAL_FREQ
#define _XTAL_FREQ 8000000
#endif

#ifndef RS
#define RS PORTAbits.RA0
#endif

#ifndef RW
#define RW PORTAbits.RA1
#endif

#ifndef EN
#define EN PORTAbits.RA2

#endif

#endif

#endif

#define D0 PORTDbits.RD0
#endif

#define D1 PORTDbits.RD1
#endif

#define D2 PORTDbits.RD2
#endif

#define D3 PORTDbits.RD3
#endif

#define D4 PORTDbits.RD4
#endif

#define D5 PORTDbits.RD5
#endif

#define D6 PORTDbits.RD6
#endif

```

```

#ifndef D7

#define D7 PORTDbits.RD7

#endif


#include <xc.h>


void Lcd_Port (char a);
void Lcd_Cmd (char a);
void Lcd_Clear (void);
void Lcd_Set_Cursor (char a, char b);
void Lcd_Init (void);
void Lcd_Write_Char (char a);
void Lcd_Write_String (char *a);
void Lcd_Shift_Right (void);
void Lcd_Shift_Left (void);

```

```

*****
*****
*
* File:  mainTemplate.c
* Author: Mariandree Rivera
* Carnet: 18178
* Archivo template
*
* Created on February 08, 2021,

```

```

/*****
*****
**
*/

//*****

// Importacion de librerias

//*****

#include <xc.h>

#include <stdint.h>

#include "LCD.h"


//*****

// Palabra de configuracion

//*****


// CONFIG1

#pragma config FOSC = XT      // Oscillator
Selection bits (XT oscillator: Crystal/resonator
on RA6/OSC2/CLKOUT and RA7/OSC1/CLKIN)

#pragma config WDTE = OFF     // Watchdog
Timer Enable bit (WDT disabled and can be
enabled by SWDTEN bit of the WDTCON
register)

#pragma config PWRTE = OFF    // Power-up
Timer Enable bit (PWRT disabled)

#pragma config MCLRE = OFF    // RE3/MCLR
pin function select bit (RE3/MCLR pin function is
digital input, MCLR internally tied to VDD)

#pragma config CP = OFF       // Code
Protection bit (Program memory code
protection is disabled)

#pragma config CPD = OFF      // Data Code
Protection bit (Data memory code protection is
disabled)

```

```

#pragma config BOREN = OFF    // Brown Out
Reset Selection bits (BOR disabled)

#pragma config IESO = OFF    // Internal
External Switchover bit (Internal/External
Switchover mode is disabled)

#pragma config FCMEN = OFF    // Fail-Safe
Clock Monitor Enabled bit (Fail-Safe Clock
Monitor is disabled)

#pragma config LVP = OFF    // Low Voltage
Programming Enable bit (RB3 pin has digital I/O,
HV on MCLR must be used for programming)

// CONFIG2

#pragma config BOR4V = BOR40V // Brown-
out Reset Selection bit (Brown-out Reset set to
4.0V)

#pragma config WRT = OFF    // Flash Program
Memory Self Write Enable bits (Write
protection off)

#define _XTAL_FREQ 8000000
#define RS PORTAbits.RA0
#define RW PORTAbits.RA1
#define EN PORTAbits.RA2
#define D0 PORTDbits.RD0
#define D1 PORTDbits.RD1
#define D2 PORTDbits.RD2
#define D3 PORTDbits.RD3
#define D4 PORTDbits.RD4
#define D5 PORTDbits.RD5
#define D6 PORTDbits.RD6
#define D7 PORTDbits.RD7

```

```

//*****

// Variables

//*****

char counter = 0;

//*****

// Interrupciones

//*****

void __interrupt() ISR()
{
    //esto se activara si la interrupcion viene del
    receptor en el UART

    if (PIR1bits.RCIF == 1)
    {
        //esto nos limpiara la interrupcion

        PIR1bits.RCIF = 0;

        TXREG = (RCREG + 1);

        while (TXSTAbits.TRMT == 0);

    }
}

//*****

// Prototipos de funciones

//*****

void setup(void);

void UART_Init(void);

```

```

void __interrupt() ISR();

void Lcd_Init(void);

//*****

// Ciclo principal

//*****

void main(void) {
    unsigned int a;

    setup();

    void Lcd_Init(void);
    UART_Init();

    //*****

    // Loop principal

    //*****

    while (1) {

        Lcd_Clear();

        //    if (PORTCbits.RC7 == 0) {
        Lcd_Set_Cursor(1, 1);
        Lcd_Write_String("Hola Mundo");
        //    }

        //    if (PORTCbits.RC7 == 0) {
        Lcd_Set_Cursor(2, 1);
        Lcd_Write_String("Adios Mundo");
        __delay_ms(2000);
        Lcd_Clear();
        //    }

        //    if (PORTCbits.RC7 == 0) {
        Lcd_Set_Cursor(1, 1);

```

```

        Lcd_Write_String("Developed By");
        Lcd_Set_Cursor(2, 1);
        Lcd_Write_String("electroSome");
        __delay_ms(2000);
        Lcd_Clear();
        //    }

        //    Lcd_Set_Cursor(1, 1);
        //
        Lcd_Write_String("www.electroSome.com");

        for (a = 0; a < 15; a++) {
            __delay_ms(300);
            Lcd_Shift_Left();
        }

        for (a = 0; a < 15; a++) {
            __delay_ms(300);
            Lcd_Shift_Right();
        }

        Lcd_Clear();
        Lcd_Set_Cursor(2, 1);
        Lcd_Write_Char('M');
        Lcd_Write_Char('S');
        __delay_ms(2000);
    }
}

```

```
//*****
```

```
// Configuracion
```

```
//*****
```

```
void setup(void) {
```

```
    ANSEL = 0;
```

```
    ANSELH = 0b00000001;
```

```
    TRISA = 0;
```

```
    PORTA = 0;
```

```
    TRISB = 0b00000111;
```

```
    PORTB = 0;
```

```
    TRISD = 0;
```

```
    PORTD = 0;
```

```
    TRISE = 0;
```

```
    PORTE = 0;
```

```
}
```

```
//*****
```

```
// Funciones
```

```
//*****
```

```
void UART_Init()
```

```
{
```

```
    //Seleccionara los 8bits para la transmision  
    de los datos.
```

```
    TXSTAbits.TX9 = 0;
```

```
    //habilitar la transmision
```

```
    TXSTAbits.TXEN = 1;
```

```
    //habilitacion del modo asincrono
```

```
    TXSTAbits.SYNC = 0;
```

```
    //operacion en velocidad lenta
```

```
    TXSTAbits.BRGH = 0;
```

```
    // habilita el puerto serial
```

```
    RCSTAbits.SPEN = 1;
```

```
    // habilita que constantemente se reciban  
    datos
```

```
    RCSTAbits.CREN = 1;
```

```
    //Baudrate 10417
```

```
    SPBRG = 11;
```

```
    //activacion de las interrupciones
```

```
    INTCONbits.GIE = 1;
```

```
    // habilitacion de las interrupciones  
    perifericas, ver diagrama.
```

```
    INTCONbits.PEIE = 1;
```

```
    //habilita las interrupciones del receptor.
```

```
    PIE1bits.RCIE = 1;
```

```
    // limpia el flag de la interrupcion
```

```
    PIR1bits.RCIF = 0;
```

```
}
```

