Model Complexity and Regularization Machine Learning

Overview

- Overfitting.
- Complexity and capacity of a hypothesis class.
- Complexity, bias and variance of a hypothesis.
- Bias-variance decomposition.
- Regularization.
- Qualitative Effects of Regularization on Bias-Variance and Overfitting.
- **O** Example: ℓ_2 (Ridge) Regularization for Linear Regression
- **1** Example: ℓ_1 (LASSO) Regularization for Linear Regression

Overfitting

Definition (Overfitting)

- Qualitatively: When model performs much better on training data than on arbitrary data points drawn from the distribution (simulated by test data).
- Quantitatively: When "overfitting gap" $L_{\mu}(h) L_{s_{\text{train}}}(h)$ is large.

Example (Memorizing)

A hypothesis h which "memorizes" training data and outputs ∞ elsewhere:

$$h(x) = \begin{cases} y & (x, y) \in s_{\text{train}} \\ \infty & x \notin s_{\text{train};X} \end{cases}$$

Gets all training data exactly right but everything else infinitely wrong. Hence $L_{s_{\text{train}}}(h)$ minimized, $L_{\mu}(h)$ maximized, "overfitting gap" maximized.

Hypothesis Class Quality

- Say we have a hypothesis class \mathcal{H} (given by a particular ML algorithm).
- We want to quantify the suitability of \mathcal{H} for our problem.
- Occam's Razor: All else being equal, the lowest-complexity solution is best.
- But there are trivially low-complexity hypothesis classes, which suck at fitting the data.
- For example, $\mathcal{H} = \{x \mapsto 0\}$ is bad at fitting nonzero outputs.
- So we want to quantify how good \mathcal{H} can be at fitting the data.
- Two related notions: complexity and capacity.

Hypothesis Class Complexity

- Hard to discuss non-parametric hypothesis class complexity, as there is less structure.
- It is safe to say hypothesis classes with very diverse hypotheses are high-complexity.
- Correspondingly, hypothesis classes with a lot of structure are low-complexity.
- For parametric hypothesis classes of the form

$$\mathcal{H} = \{h_{\theta} : \theta \in \Theta\}$$

We can be significantly more quantitative/clear.

ullet One idea is to count the number of independent parameters ("degrees of freedom") in Θ :

$$DF(\mathcal{H}) = dim(\Theta)$$
.

This works pretty well and for lots of algorithms it is obvious or well-known.

Hypothesis Class Complexity

Example (Linear Regression Hypothesis Classes)

The "naive" linear regression hypothesis class looks like

$$\mathcal{H}_{\text{dumb}} = \left\{ x \mapsto \theta^* x : \theta \in \mathbb{R}^{d \times k} \right\}.$$

In this case $DF(\mathcal{H}_{dumb}) = dk$.

That's not quite the end of the story. Remembering the least squares solution,

$$\widehat{\theta} = \left(X_{\text{train}}^* X_{\text{train}}\right)^{-1} X_{\text{train}} Y_{\text{train}}$$

so the hypothesis class looks more like

$$\mathcal{H}_{\text{smart}} = \left\{ x \mapsto \left(\left(X_{\text{train}}^* X_{\text{train}} \right)^{-1} X_{\text{train}}^* Y_{\text{train}} \right)^* x \colon \begin{array}{l} X_{\text{train}} \in \mathbb{R}^{n \times d} & \text{rank}(X_{\text{train}}) = d \\ Y_{\text{train}} \in \mathbb{R}^{n \times k} & \end{array} \right\}$$

This has $DF(\mathcal{H}_{smart}) \ll dk$, so linear regression isn't too complex.

Hypothesis Class Capacity

- We don't want our hypothesis class to be too complicated.
- But we also want the hypotheses in the class to have some predictive power.
- A hypothesis class with a low-dimensional (or even finite) parameter space ⊕ has low complexity, but is probably not very good at fitting the data.
- Measures of capacity of a hypothesis class \mathcal{H} :
 - VC dimension for binary classification ($\mathcal{Y} = \{1, 2\}$): size of largest set of points s such that, for every assignment $f: \mathcal{X} \to \mathcal{Y}$, there is $h \in \mathcal{H}$ such that $f|_{s} = h|_{s}$.
 - Rademacher complexity with respect to an integer n and distribution ν over Z:

$$\mathsf{Rad}_{\nu,n}(\mathcal{H}) = \frac{1}{n} \underset{\substack{s \sim \nu^n \\ \sigma \sim \mathsf{Uni}\left(\{\pm 1\}^n\right)}}{\mathbb{E}} \left[\sup_{h \in \mathcal{H}} \sum_{i=1}^n \sigma_i \ell_h(z_i) \right]$$

Possible to get bounds on Rademacher complexity analytically, even for complex models such as neural networks.

• In general, capacity is hard to compute, but easy to give a qualitative/asymptotic estimate.

Model Complexity/Capacity Tradeoff

- Highly complex hypothesis classes can model arbitrarily complex functions.
- Thus, we expect complexity and capacity to be very correlated.
- We would like to maximize capacity and minimize complexity, which is a difficult problem.
- Each algorithm has a different complexity-capacity balance, so we pick one that works for our use-cases.

Complexity of a Hypothesis

- We can also talk about complexity of a hypothesis.
- (Capacity isn't a very useful notion since a hypothesis can model exactly one function.)
- We would like low-complexity hypotheses; those that are smooth and don't have very high curvature at every point. Possible complexity functional:

$$R(h) = \mathbb{E}_{x} \left[\det(\operatorname{Hessian}(h(x)))^{2} \right].$$

- Easier/more concrete for parametric hypotheses.
- Larger coefficients ⇒ probably overly complex hypothesis. (Occam's Razor again.)
- Possible complexity functionals:

$$R(h_{\theta}) = \lambda \begin{cases} \|\theta\|_1 = \text{sum of absolute values of entries of } \theta \\ \|\theta\|_2^2 = \text{sum of squares of entries of } \theta \\ \|\theta\|_{\infty} = |\text{largest entry of } \theta| \\ \|\theta\|_0 = \text{\# of nonzero entries of } \theta \end{cases}$$

Bias and Variance of an Algorithm

- Some analogous properties of "capacity" and "complexity" for a hypothesis class are bias and variance for an algorithm.
- Bias: measures the difference between the "systematic" (non-random) parts of the output, and the hypothesis given by the algorithm.
- Variance: measures the variability of the hypothesis given by the algorithm.
- How to measure distance? Loss function!

Bias and Variance of an Algorithm

- Let the algorithm's output be $h = A(s_{\text{train}})$.
- The *optimal prediction* is that which minimizes the loss pointwise:

$$y_*(x) = \underset{u \in \mathcal{Y}}{\operatorname{argmin}} \mathbb{E}[\ell(y, u) \mid x].$$

Note: This is the rule we would use if we knew $\mu_{Y|X}$, but we don't.

• The main prediction is that which minimizes the loss on the dataset:

$$\widehat{y}(x) = \underset{u \in \mathcal{Y}}{\operatorname{argmin}} \mathbb{E}_{s_{\text{train}}} [\ell(h(x), u) \mid x].$$

• It represents the "central tendency" of *A* around *y*.

Bias and Variance of an Algorithm

- The **bias** of an algorithm A on an example x is $Bias(A; x) = \ell(\widehat{y}(x), y_*(x))$.
 - It represents the systemic loss incurred by *A*.
- The **variance** of an algorithm A on an example x is $Var(A; x) = \mathbb{E}_{S_{train}}[\ell(h(x), \widehat{y}(x))].$
 - It represents the fluctuations of A due to the varying samples.
- The **noise** of an algorithm A on an example x is $\operatorname{noise}(A; x) = \mathbb{E}_y[\ell(y, \widehat{y}(x)) \mid x]$.
 - It represents the irreducible error regardless of the choice of *A* and sample.
- We can also talk about average bias/variance/noise:

$$\operatorname{Bias}(A) = \underset{x}{\mathbb{E}} \Big[\operatorname{Bias}(A; x) \Big] \qquad \operatorname{Var}(A) = \underset{x}{\mathbb{E}} \Big[\operatorname{Var}(A; x) \Big] \qquad \operatorname{noise}(A) = \underset{x}{\mathbb{E}} \Big[\operatorname{noise}(A; x) \Big]$$

Bias and Variance

Example (Squared-Error Loss)

Suppose if ℓ is squared error loss (so $\ell(y, y') = ||y - y'||_2^2$), then

$$y_*(x) = \underset{u \in \mathcal{Y}}{\operatorname{argmin}} \mathbb{E}_{y} \left[\|y - u\|_{2}^{2} \, \middle| \, x \right] = \mathbb{E}_{y} [y \, | \, x]$$
$$\widehat{y}(x) = \underset{u \in \mathcal{Y}}{\operatorname{argmin}} \mathbb{E}_{s_{\text{train}}} \left[\|h(x) - u\|_{2}^{2} \, \middle| \, x \right] = \mathbb{E}_{s_{\text{train}}} [h(x) \, | \, x].$$

Bias-Variance Decomposition

We can decompose loss at a point:

Loss(A; x) =
$$\mathbb{E}_{s_{\text{train}}} \left[\mathbb{E}[\ell(y, h(x)) | x] \right]$$

into functions of Bias(A; x), Var(A; x), and noise(A; x).

Example (Squared-Error Loss)

$$Loss(A; x) = Bias(A; x) + Var(A; x) + noise(A; x).$$

Want low-bias and low-variance, but they are correlated, so we have to make a tradeoff. Different algorithms have different bias-variance tradeoffs.

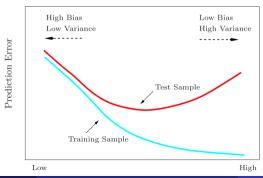
Regularization

- Idea: to get a good tradeoff, we do the following three step process:
 - Pick an algorithm family with low bias.
 - Change the loss function to penalize high-variance algorithms and complex hypotheses.
 - Pick the best algorithm and run it on the training set to get a good hypothesis.
- Regularized loss function:

$$\ell_h^{\text{reg}}(z) = \ell_h(z) + R(h).$$

Regularization, Bias, Variance, and Overfitting

- Our hypotheses are lower complexity, because we are more willing to sacrifice loss on the training set to get reduced hypothesis complexity.
- This means that regularized algorithms have:
 - Higher bias.
 - Lower variance.
 - Less overfitting.



Example: ℓ^2 -Regularized Linear Regression

Example (Ridge Regression)

Let's suppose we have the linear regression algorithm and $R(h_{\theta}) = \lambda \|\theta\|_2^2$, for $\lambda > 0$. Then we want to minimize in θ the expression

$$L_{s_{\text{train}}}^{\text{reg}}(h_{\theta}) = \|X_{\text{train}}\theta - Y_{\text{train}}\|_{2}^{2} + \lambda \|\theta\|_{2}^{2}$$

which has solution

$$\widehat{\theta}_{\lambda} = \left(X_{\text{train}}^* X_{\text{train}} + \lambda I_d\right)^{-1} X_{\text{train}}^* Y_{\text{train}}.$$

Pro: $X_{\text{train}}^* X_{\text{train}} + \lambda I_d$ is *always* invertible, and the problem is easier to optimize.

Con: we don't exactly have a line of best fit (or generalization) anymore.

Example: ℓ^1 -Regularized Linear Regression

Example (LASSO Regression)

Let's suppose we have the linear regression algorithm and $R(h_{\theta}) = \lambda \|\theta\|_1$, for $\lambda > 0$. Then we want to minimize in θ the expression

$$L_{s_{\text{train}}}^{\text{reg}}(h_{\theta}) = \|X_{\text{train}}\theta - Y_{\text{train}}\|_{2}^{2} + \lambda \|\theta\|_{1}$$

which has no easy closed-form solution.

Pro: ℓ^1 -regularization promotes *sparsity*, so # of nonzero entries in θ will be high (depending on λ). This is a form of *feature selection*: features with coefficient 0 in $\widehat{\theta}_{\lambda}$ are considered insignificant and can be tossed out in the final model.

Con: we don't exactly have a line of best fit (or generalization) anymore.