Dimensionality Reduction Machine Learning

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- Other dimensionality reduction algorithms.

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- Generalization of diagonalization for non-square matrices.



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This is the **outer product form of SVD** for M (since $u_i v_i^* = u_i \otimes v_i$).

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How does it work for least squares?

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Argument is mostly the same, though a bit linear algebraically complicated, for least-norm.

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• Idea: can get covariance in direction v (unit vector) by $\langle \operatorname{Cov}_x(x) \, v, v \rangle$ or $\Big(\widehat{\Sigma} v, v \Big)$.

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• But these are just the eigenvectors of $\widehat{\Sigma}$, ordered by their eigenvalues! Called **principal components** of the data. For data matrix X we first de-mean X feature-by-feature, then compute $X = U \Sigma V^*$, then use columns of V.

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PCA

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\begin{aligned} & \text{procedure } \mathsf{TRAIN}(s_{\mathsf{train}}) \\ & \widehat{\mu} \leftarrow \frac{1}{|s_{\mathsf{train}}|} \sum_{i=1}^n x_i \\ & \widehat{\Sigma} \leftarrow \frac{1}{|s_{\mathsf{train}}|} \sum_{i=1}^n \left(x_i - \widehat{\mu}\right) \left(x_i - \widehat{\mu}\right)^* \\ & V \leftarrow \mathsf{Eigenvectors}(\widehat{\Sigma}) \\ & V_k \leftarrow V[:,:k] \\ & \text{procedure } \mathsf{INFERENCE}(x) \\ & \text{return } V_{b}^* x \end{aligned}
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Theorem (Eckart-Young-Mirsky Theorem)

SVD gives the best t-rank approximation to X, for all t.

To be precise, define the **truncated SVD** $X_t = \sum_{i=1}^t \sigma_i u_i v_i^*$ (equivalently taking first t columns, like compact SVD but with t instead of r). Then

$$||X - X_t||_2 = \inf_{\substack{Y \in \mathbb{C}^{n \times d} \\ \text{rank}(Y) \le t}} ||X - Y||_2.$$

Furthermore, the approximation is also true in the operator norm $\|X\|_{op}$ which is the maximum singular value of X:

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By no means an exhaustive list:

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- TDA: embeds to make sure point clouds maintain their form.
- Autoencoders: embeds using neural networks to maximize information usable by the network.