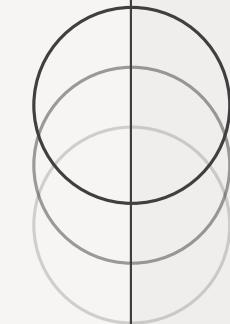




DRONES



TechnoCognition'25

DISASTER RESPONSE DRONE

FOR REMOTE AREAS

SKY HAWK

PS CATEGORY- AEROCIRCUITRY

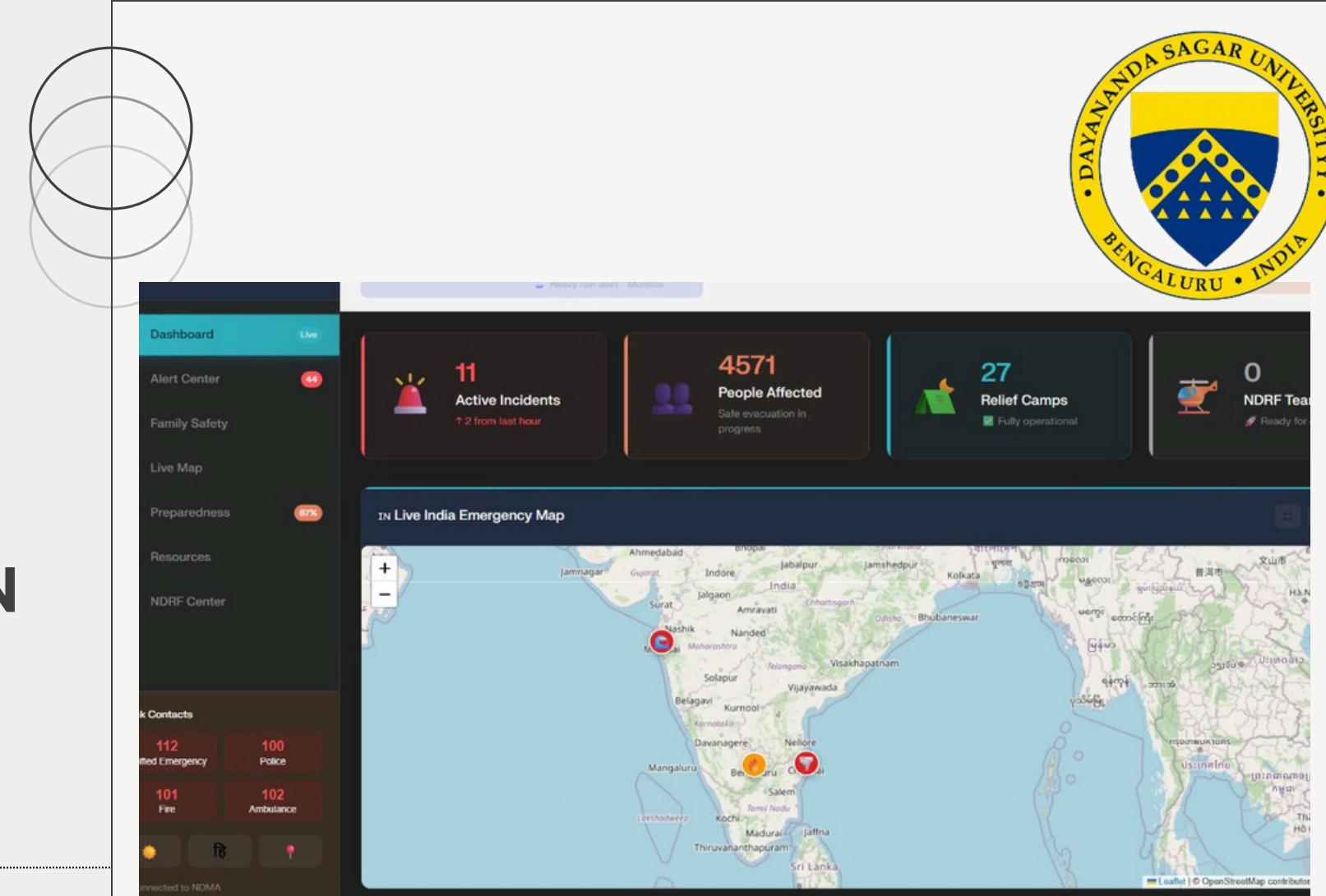
NOV 2025

ROBOTICS

Proposed Solution

DETAILED EXPLANATION OF THE PROPOSED SOLUTION

The solution uses a distributed multi-drone system where a scout drone performs real-time survivor detection and communication. In contrast, a delivery drone ensures precise payload drops, all coordinated through a centralised control system.



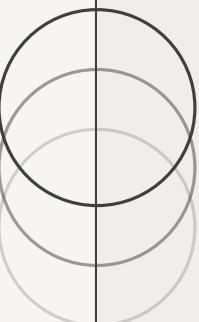
INNOVATION AND UNIQUENESS OF THE SOLUTION

The unique integration of thermal imaging, real-time communication, and precision delivery within a coordinated multi-drone architecture makes it both innovative and highly effective for disaster response.

HOW IT ADDRESSES THE PROBLEM

This system overcomes challenges of accessibility, communication failure, and time-critical rescue by enabling rapid area coverage, accurate survivor geotagging, and autonomous delivery in disaster-hit regions.

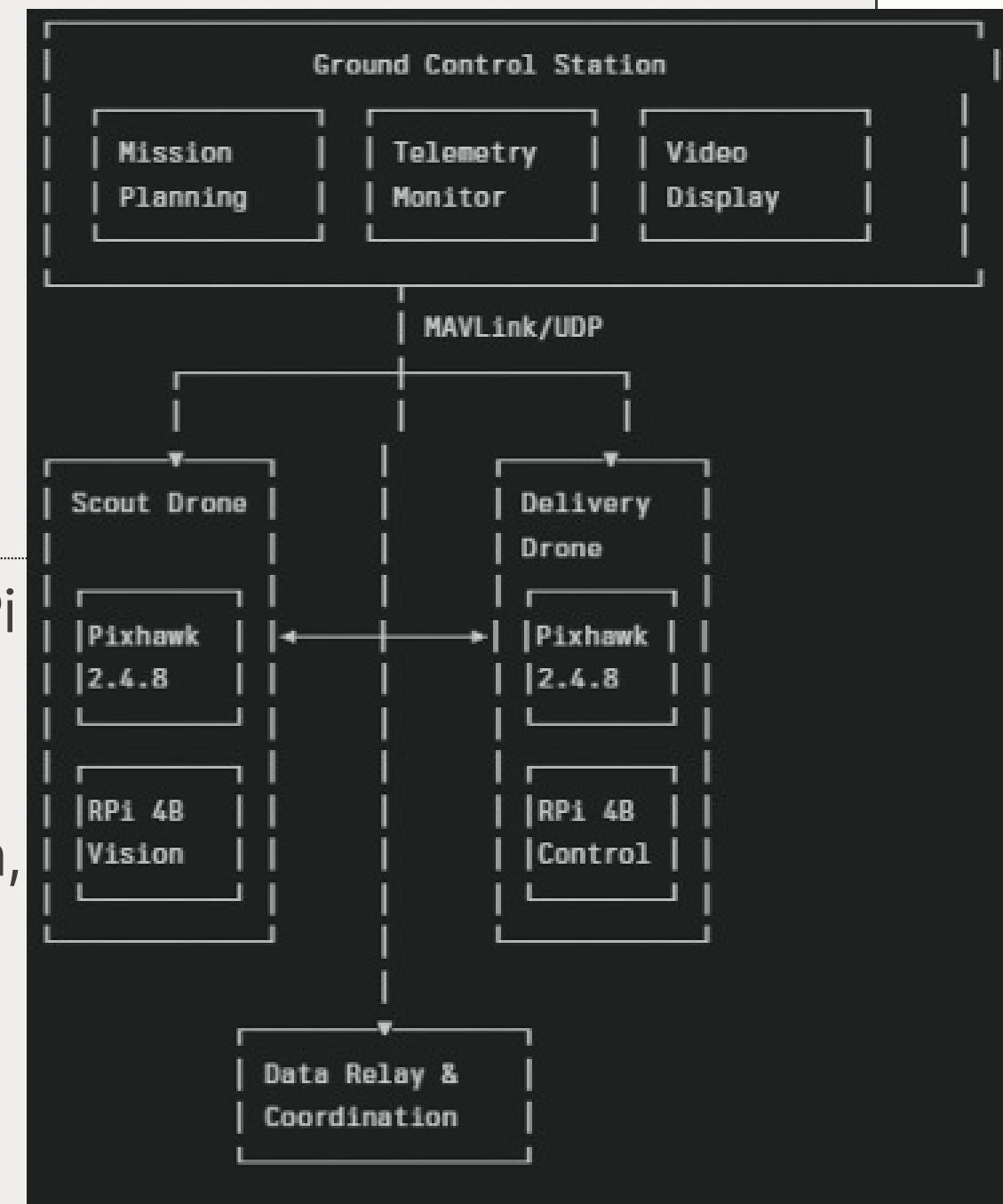
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0	0	0 person	0.825111	12.6608	77.4493	487	156	514	213
0	0	0 person	0.7905935	12.6608	77.4493	482	105	505	160
0	0	0 person	0.7833960	12.6608	77.4493	221	216	248	284
0	0	0 person	0.7540534	12.6608	77.4493	249	150	274	207
0	0	0 person	0.7488513	12.6608	77.4493	597	47	616	91
0	0	0 person	0.7363725	12.6608	77.4493	379	316	414	360
0	0	0 person	0.7135884	12.6608	77.4493	86	145	108	204
0	0	0 person	0.6844931	12.6608	77.4493	400	42	418	89
0	0	0 person	0.68168	12.6608	77.4493	235	80	255	128
0	0	0 person	0.6614385	12.6608	77.4493	469	234	508	296
0	0	0 bird	0.6575972	12.6608	77.4493	10	263	46	329
0	0	0 person	0.6439860	12.6608	77.4493	66	14	87	53
0	0	0 bird	0.6185749	12.6608	77.4493	379	168	404	218
0	0	0 person	0.6175292	12.6608	77.4493	363	15	377	49
0	0	0 person	0.6038966	12.6608	77.4493	562	25	594	95
0	0	0 person	0.6037327	12.6608	77.4493	297	31	310	70
0	0	0 person	0.5972894	12.6608	77.4493	189	85	210	135
0	0	0 person	0.5897072	12.6608	77.4493	558	3	575	46
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0	0	0 person	0.569304	12.6608	77.4493	266	25	281	68
0	0	0 person	0.56666302	12.6608	77.4493	537	5	551	42
0	0	0 person	0.5597180	12.6608	77.4493	30	43	48	84
0	0	0 person	0.5325279	12.6608	77.4493	308	58	326	102
0	0	0 person	0.5155848	12.6608	77.4493	241	0	257	36
0	0	0 person	0.4588032	12.6608	77.4493	114	0	134	46
0	0	0 person	0.4195566	12.6608	77.4493	526	6	539	40
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0	0	0 person	0.3641164	12.6608	77.4493	434	3	448	36
0	0	0 person	0.3620387	12.6608	77.4493	633	32	639	66
0	0	0 person	0.3563854	12.6608	77.4493	527	5	545	41
0	0	0 person	0.3480006	12.6608	77.4493	379	168	404	218



TECHNICAL APPROACH

Technologies to be utilized (e.g., programming languages, frameworks, hardware)

The system utilizes Pixhawk 2.4.8 flight controllers, Raspberry Pi 4B companion computers, FLIR thermal cameras, GPS modules, and brushless motors, operating with ArduCopter firmware and custom Python applications for mission control, computer vision, and communication.





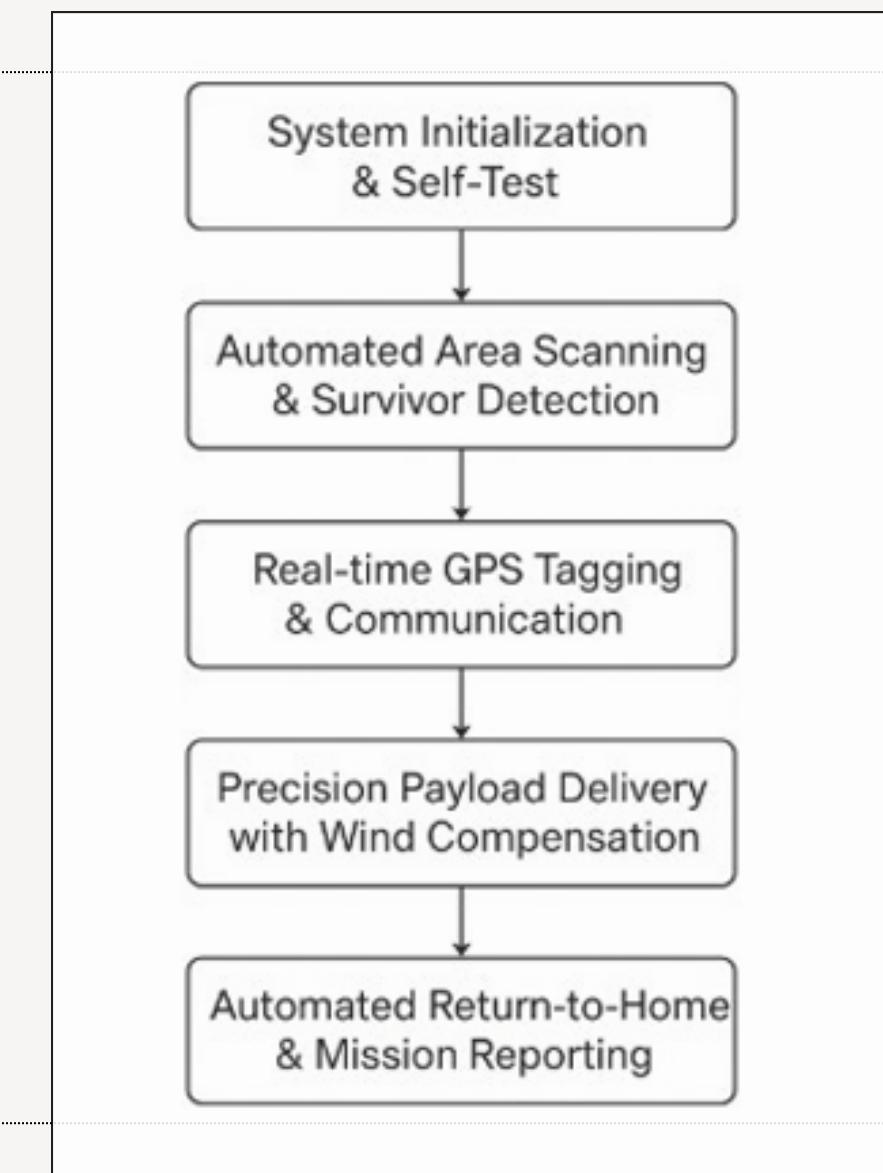
IMPORTANT INSTRUCTIONS

METHODOLOGY AND IMPLEMENTATION PROCESS (FLOW CHARTS/IMAGES/PROTOTYPE)

The implementation involves a multi-phase process, including:

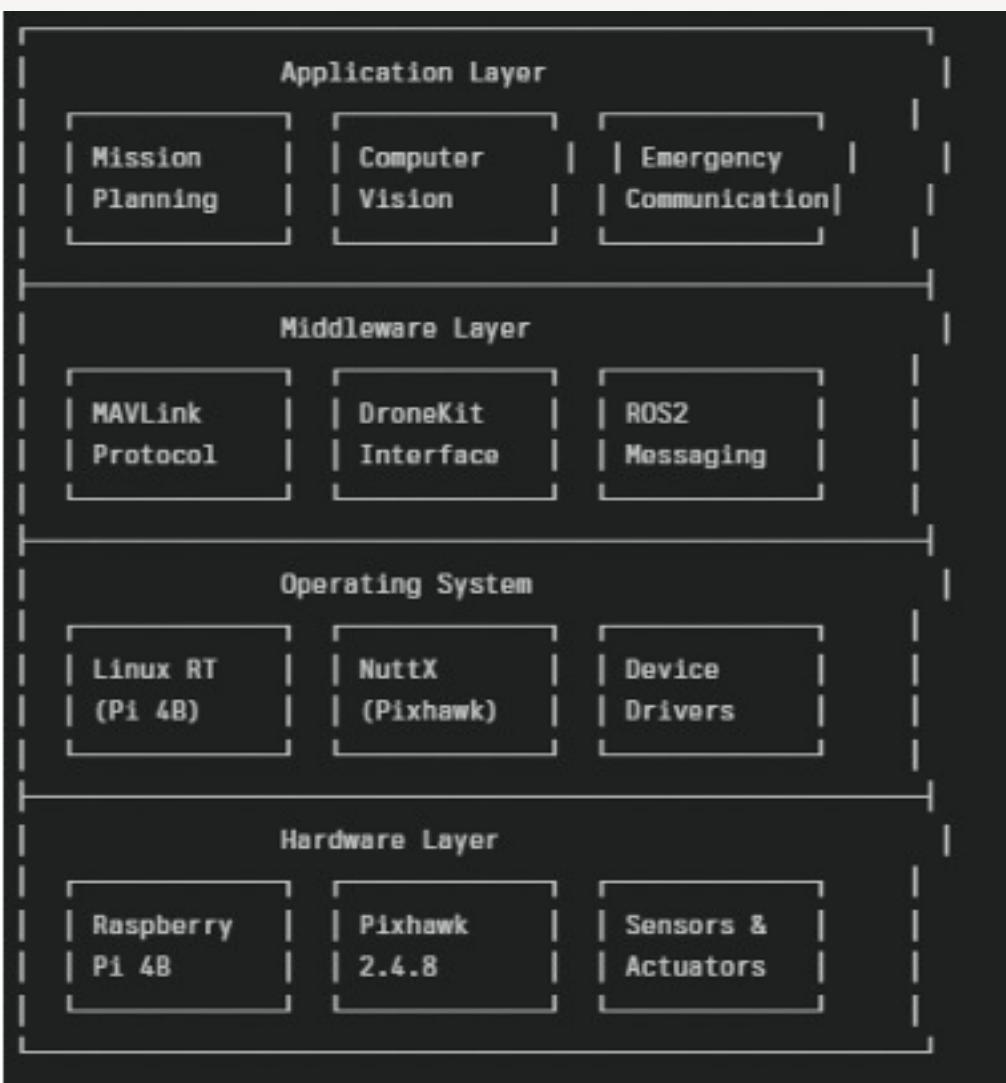
- System initialization and self-tests
- Automated search with real-time survivor detection
- Precision payload delivery using wind-compensated navigation

Automated recovery with mission data reporting.

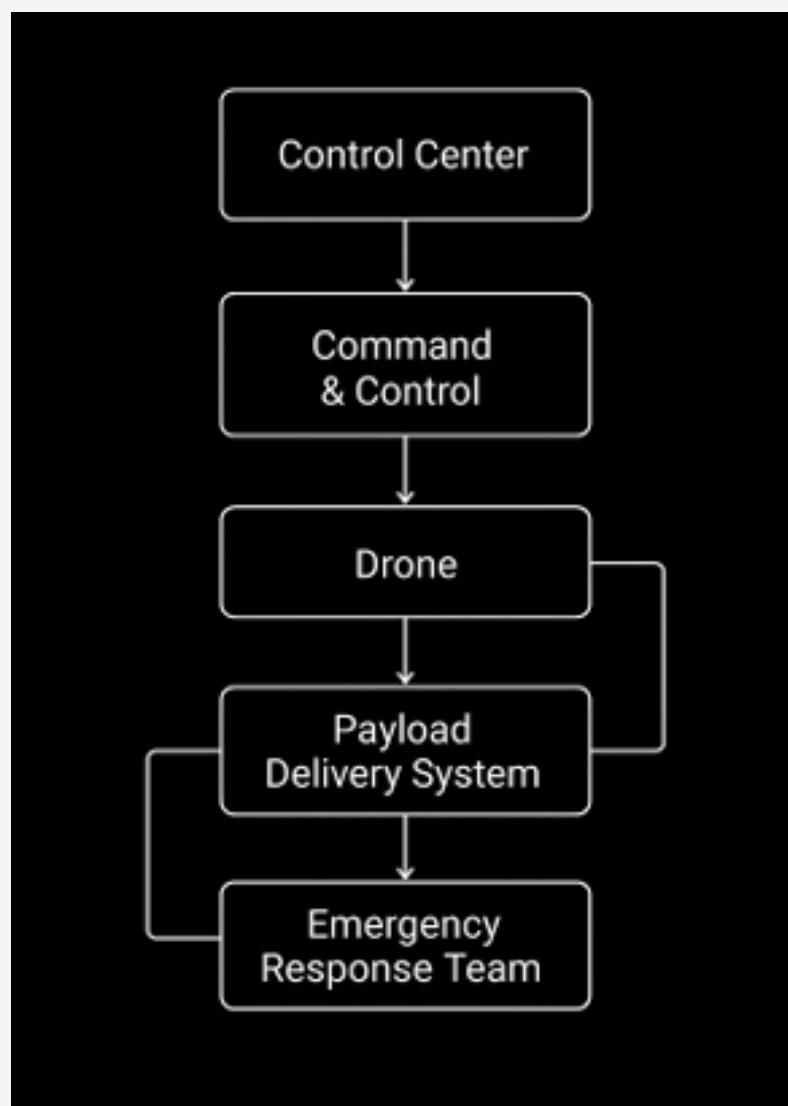
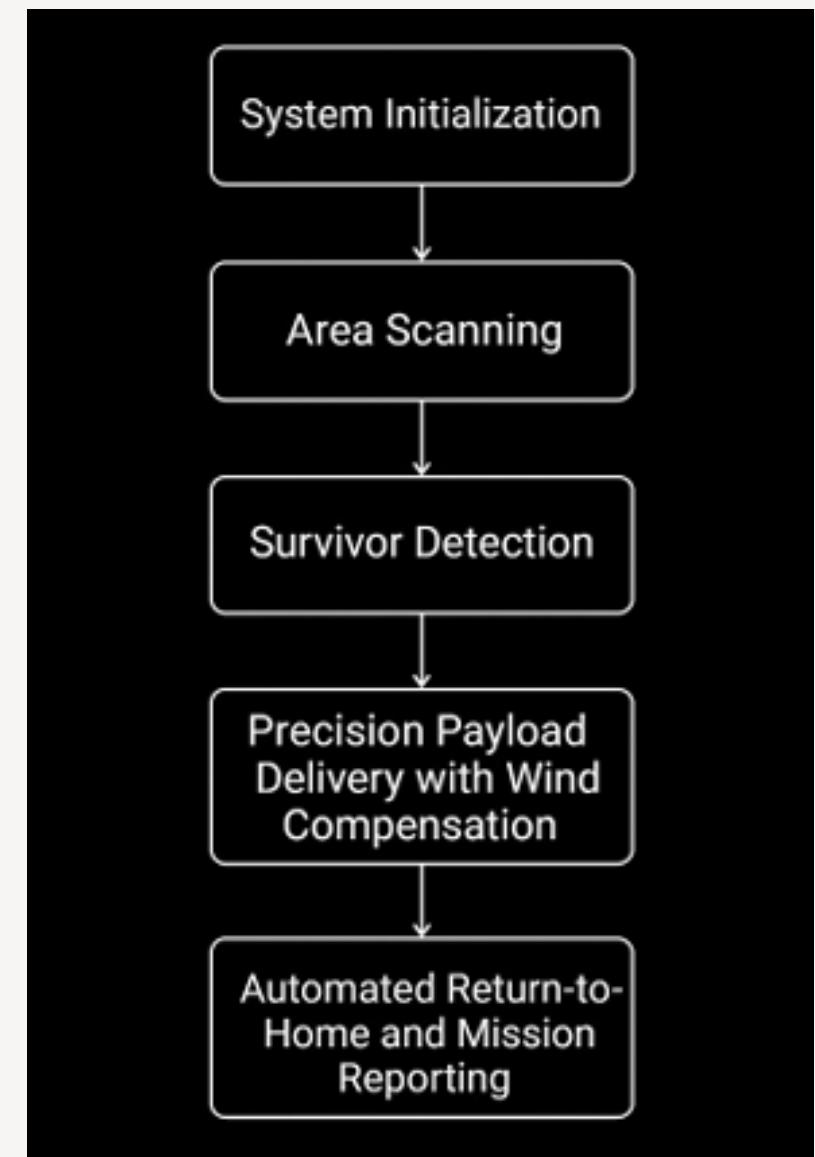


System and work flow

SYSTEM SOFTWARE STACK



EMERGENCY DRONE SYSTEM ARCHITECTURE CHART





SKY HAWK

FEASIBILITY AND VIABILITY

ANALYSIS OF THE FEASIBILITY OF THE IDEA

The multi-drone architecture is technically feasible with proven hardware, real time processing, and autonomous operation tailored to disaster management needs.

POTENTIAL CHALLENGES AND RISKS

Risks include GPS degradation, communication failures, harsh weather, and regulatory or operational integration challenges.

STRATEGIES FOR OVERCOMING THESE CHALLENGES

The system uses sensor fusion, redundant communication links, weather compensation algorithms, modular design, and intuitive operator interfaces to mitigate these issues.





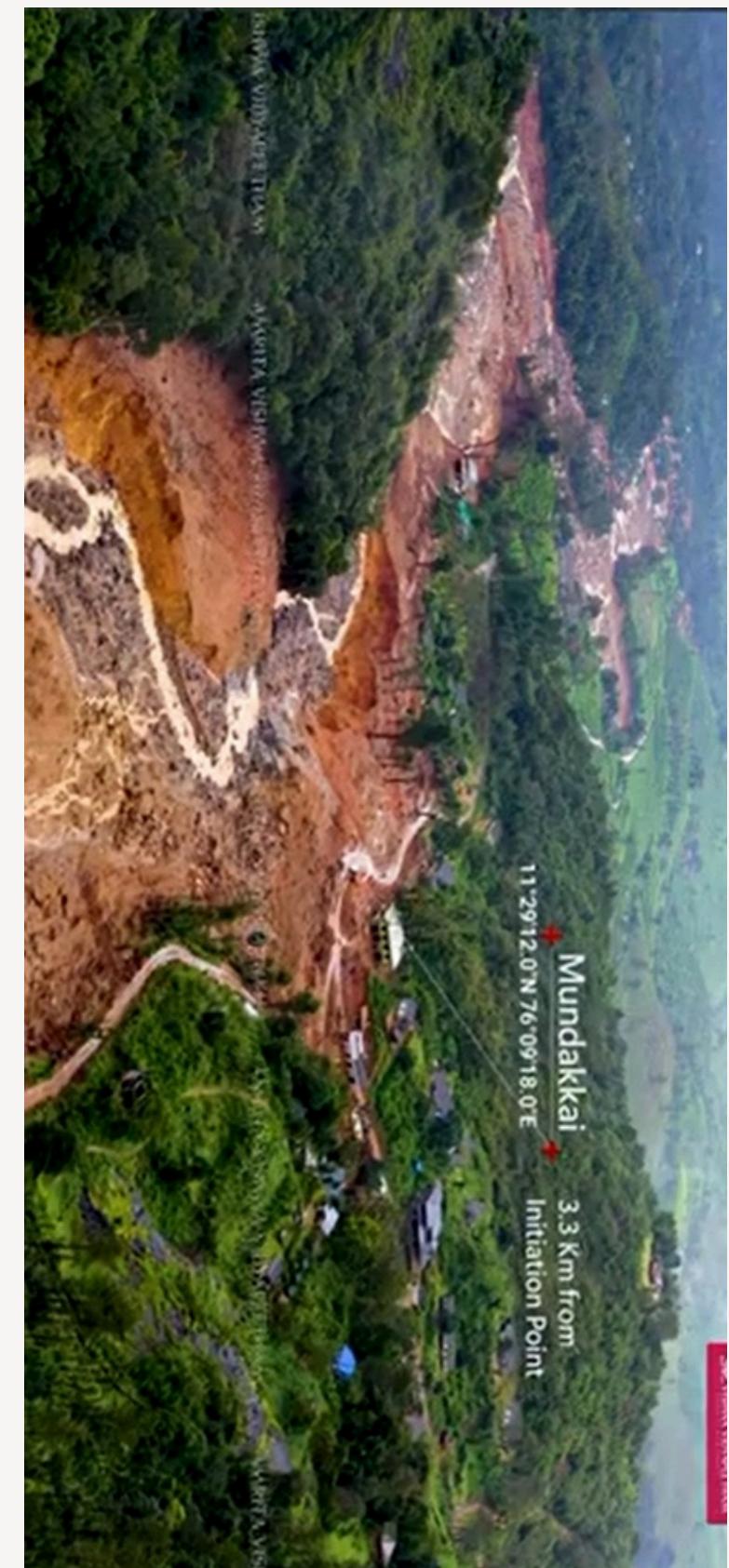
IMPACT AND BENEFITS

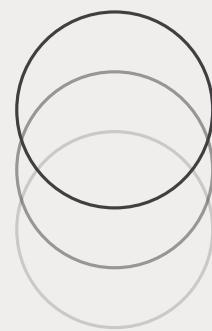
POTENTIAL IMPACT ON THE TARGET AUDIENCE

The solution supports disaster-affected populations by facilitating quick survivor detection and timely supply delivery. It improves rescue teams' efficiency through accurate geotagging and real-time situational awareness, enhancing safety and coordination for emergency responders.

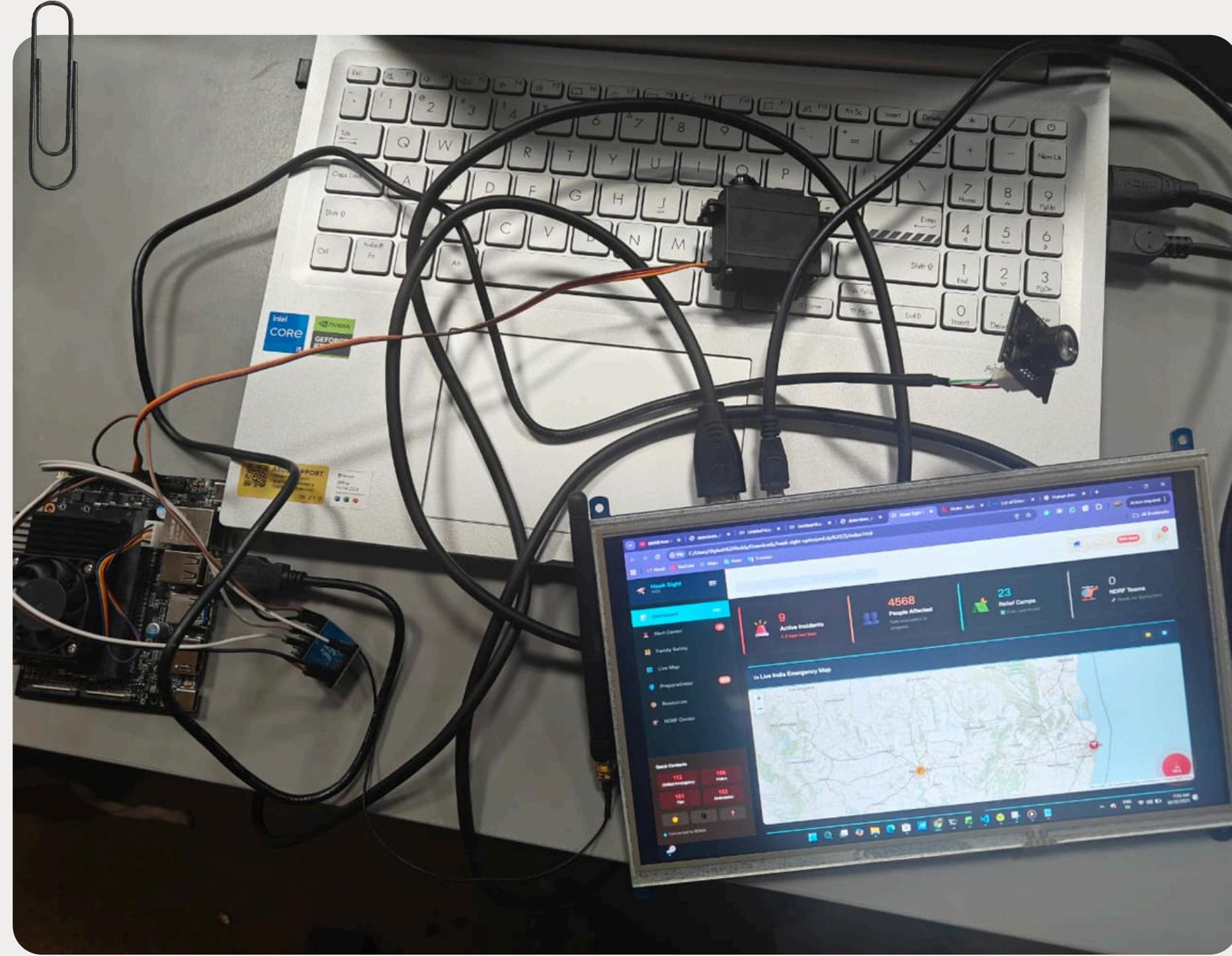
BENEFITS OF THE SOLUTION (SOCIAL, ECONOMIC, ENVIRONMENTAL, ETC.)

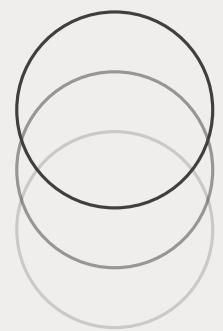
Drones improve disaster management by enhancing survival rates and communication with isolated victims, reducing operational costs and carbon footprints, and ensuring safer navigation in hazardous areas, thus promoting resilience and sustainability in response efforts.



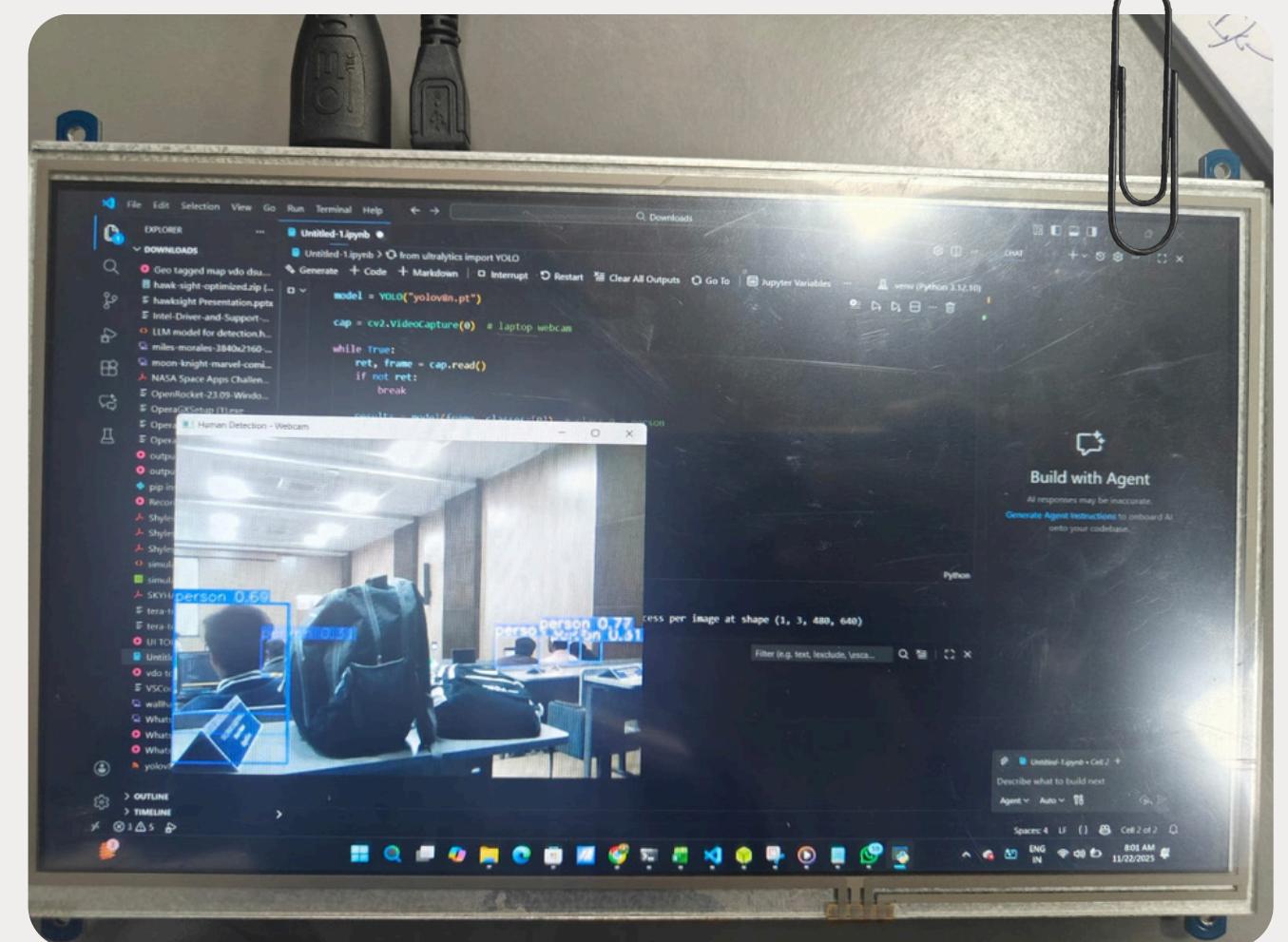
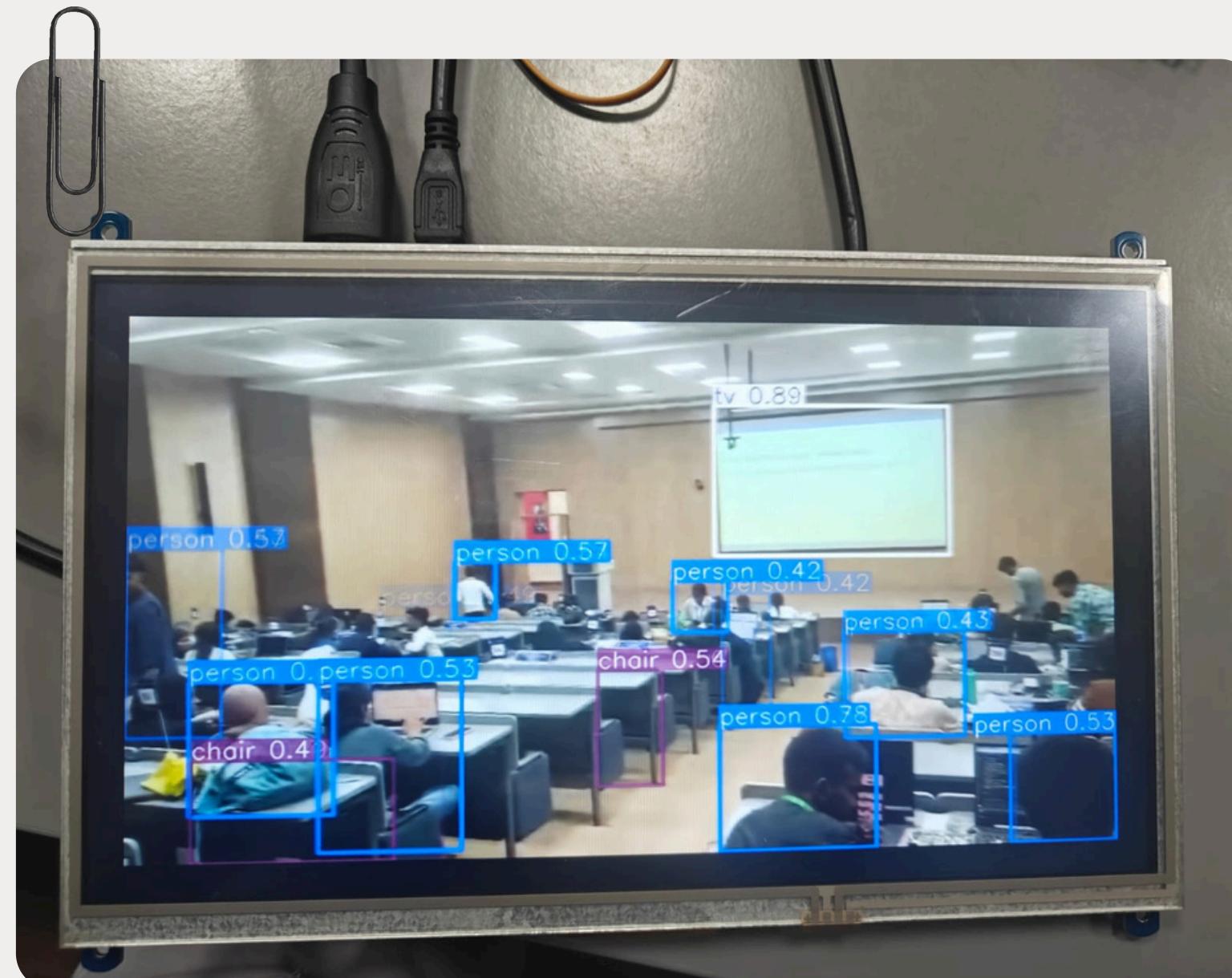


Images of the prototype





Images of the model training and testing



RESEARCH AND REFERENCES

Disaster response drone architectures: Multi-vehicle coordination and real-time survivor detection
(DFI/MeitY NIDAR Guidelines, 2025)

Pixhawk-based autonomous quadcopters: System integration and flight algorithms
[ArduPilot Documentation, 2025]

Thermal imaging for human detection in flood scenarios: FLIR Lepton 3.5 technical papers
[FLIR Lepton Product Documentation]

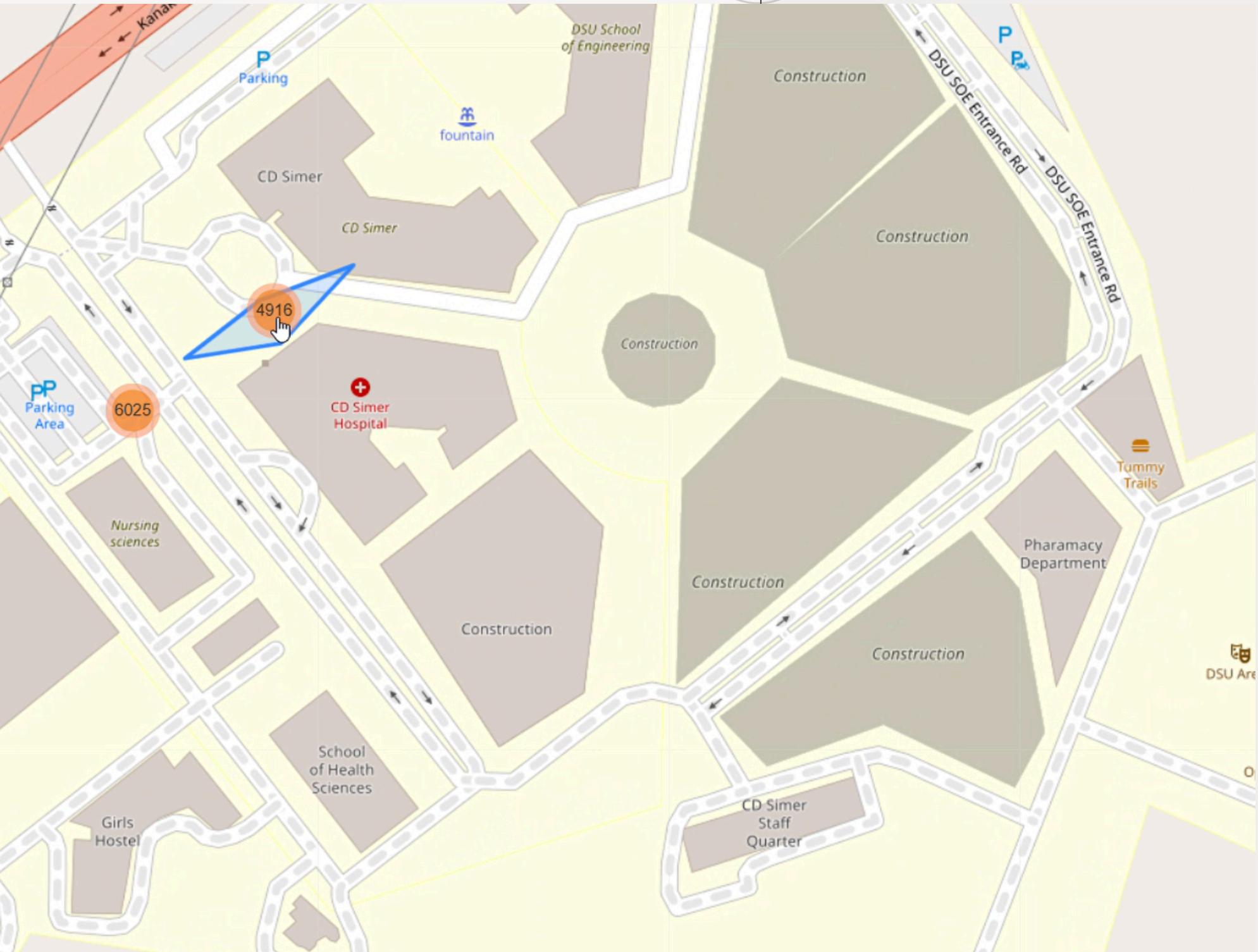
GPS/INS sensor fusion and visual odometry for GNSS-challenged environments
[IEEE Transactions on Navigation, 2024]

Efficient payload delivery and mechanical release accuracy: Servo integration studies
[RC Servo Integration Whitepaper, 2024]

Emergency communication protocols over drone platforms for disaster zones
[NIDAR Disaster Management Handbook, 2025]



SKY HAWK



THANKYOU

CHARAN RAJ R
VRINDA KATAVKAR
ARSHIA KHAN