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1: function NEIGHBORSLIST(pointsx, pointsy, src, dest)
2:   for i=0 to pointsx length do
3:     if check[i] == 0 then
4:        $a \leftarrow \text{pointsx}[i] - x[src]$ 
5:        $b \leftarrow \text{pointsy}[i] - y[src]$ 
6:        $c \leftarrow x[dest] - x[src]$ 
7:        $d \leftarrow y[dest] - y[src]$ 
8:       if pointradius ≤ r then
9:          $\text{neighborsx} \leftarrow \text{pointsx}[i]$ 
10:         $\text{neighborsy} \leftarrow \text{pointsy}[i]$ 
11:         $\text{distance} \leftarrow \text{pointradius}$ 
12:         $N\text{mapping} \leftarrow 0$ 
13:      end if
14:    end if
15:  end for
16:  if neighborsx length == 0 then
17:    Source node has no neighbours hence no Route
18:  end if
19:  for i=0 to distanceLength do
20:    if distance[i] == 0 then
21:      Dest found in its tr region itself
22:    end if
23:  end for
24:   $\text{cnt} \leftarrow 0$ 
25:  if neighborsLength == presize then
26:    for i=0 to nighborsLength do
27:      if Nmapping[i] == 1 then
28:         $\text{cnt}++$ 
29:      end if
30:    end for
31:    if  $\text{cnt} == N\text{mappingLength}$  then
32:      No neighbors
33:    end if
34:    Call BestNode()
35:  end if
36: end function

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