COMSM1302 Overview of Computer Architecture

Lecture 13
Advanced Math Operations

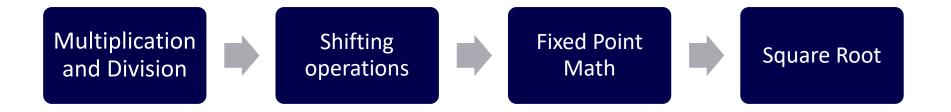


In the previous lecture

- General introduction to ARM architecture.
- Conditional code flags and conditional execution.
- Data processing instructions
 - Arithmetic and logical operations.
 - Comparisons (no results just set condition codes)
 - Data movement between registers.
- Branching instructions.



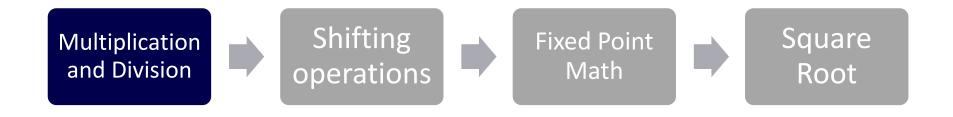
In this lecture



- At the end of this lecture:
 - Solve problems that require multiplication and division.
 - Use shifting operations to do efficient calculations.
 - Use fixed point math to do accurate calculations.









Multiplication Instructions

- Multiply
 - MUL{cond}{S} Rd, Rm, Rs

$$- Rd = Rm * Rs$$

$$32 * 32$$

Usually, we need a 64 bits register to store the multiplication of two 33 bits value. Rd only stores the 32 LSB.

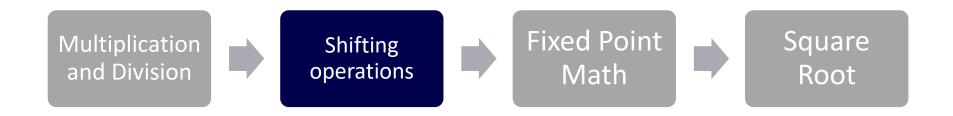
- Multiply Accumulate
 - Does addition for free
 - MLA(cond)(S) Rd, Rm, Rs, Rn
 - -Rd = (Rm * Rs) + Rn



Division Instructions

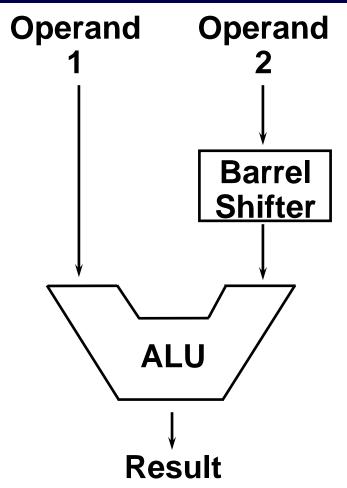
- Unsigned integer division
 - UDIV{cond} Rd, Rm, Rs; Rd = Rm / Rs 9/2 = 4
- Signed integer division
 - SDIV{cond} Rd, Rm, Rs ; Rd = Rm / Rs

Advance Math Operations





The Barrel Shifter



very quick, no need for a clock phase, can be done during any data processing instruction.



Barrel Shifter – Logical Left Shift

- Shifts left by the specified amount (multiplies by powers of two) e.g.
 - LSL{cond}{S} Rd, Rm, Rs
 - LSL{cond}{S} Rd, Rm, #sh

Corry Flag

CF

Destination

- Shifts right by the specified amount (divides by powers of two) e.g.
 - LSR{cond}{S} Rd, Rm, Rs
 - LSR{cond}{S} Rd, Rm, #sh
 - -MOV r1, r0, LSR #1
 - -LSR r1, r0, #1



 Shifts right (divides by powers of two) and preserves the sign bit, for 2's complement operations.

- ASR{cond}{S} Rd, Rm, Rs
- ASR{cond}{S} Rd, Rm, #sh
- -MOV r1, r0, ASR #1

- ASR r1, r0, #1

$$r_0 = -6$$
 $r_1 = -3$

/O10 -> 1/01

 $r_2 = -3$



CF

Destination

Sign bit shifted in

Barrel Shifter – Shift Operations

- Logical Shift Left: LSL
- Logical Shift Right: LSR
- Arithmetic Shift Right: ASR

 Why do not we have Arithmetic Shift Left (ARL)?

Because there will be a carryout in the left



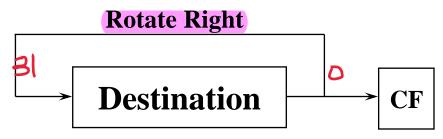
Barrel Shifter - Rotations

Rotate Right (ROR)

- Similar to an ASR but the bits wrap around as they leave the LSB and appear as the MSB.
 - ROR{cond}{S} Rd, Rm, Rs

No ROS, because it can be achieved by ROR

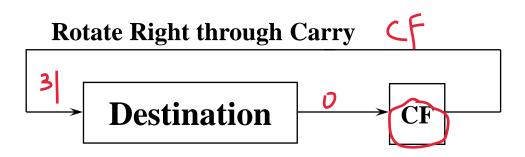
- ROR{cond}{S} Rd, Rm, #sh
- -MOV r1, r0, ROR #1
- -ROR r1, r0, #1



Barrel Shifter - Rotations

Rotate Right Extended (RRX) by one bit.

- This operation uses the CPSR C flag as a 33rd bit.
 - RRX{cond}{S} Rd, Rm
 - -MOV r1, r0, RRX
 - -RRX r1, r0



Using a Shifted Register

• Multiplications by a constant equal to a ((power of 2) \pm 1) can be done in one cycle.

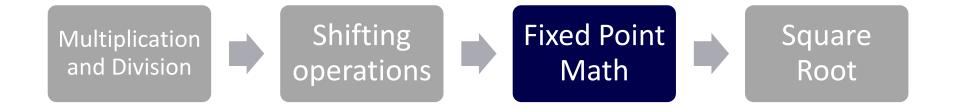


Using a Shifted Register -2

```
    Example: r2 = r3 * 105
    = r3 * 15 * 7
    = r3 * (16 - 1) * (8 - 1)
```

```
RSB r2, r3, r3, LSL #4 ; r2 = r3 * 15
RSB r2, r2, r2, LSL #3 ; r2 = r2 * 7
```

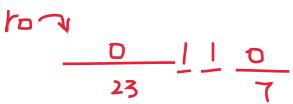
Advance Math Operations





Fixed Point Math

- We will use first 8 bits for the fraction and the last 24 bits for the integer part.
- What is r0 value that represent the value
 1.5



Fixed point

Choose the location of the point carefully, considering

- What range do you need?
 - from <smallest number> to <largest number>
- What precision do you need?
 - What is the required distance between successive numbers?

	2-4	2-3	2-2	2-1	2 0	21	2 ²	23
Base 10	0.0625	0.125	0.25	0.5	1	2	4	8
0.6875	1	1	0	1	0	0	0	0
8.5	0	0	0	1	0	0	0	1



OMSM1302 - Computer Architecture – Kerstin Edo



Multiplication with Fixed Point Math

 Multiplication of two fixed point registers cause lose in integer precision.

When calculating the mul, do not calculate integer and fraction seperately



Division with Fixed Point Math

 Division of two fixed point registers cause loss in fractional precision.

$$-@16.16 / @24.8 = @16.8$$

$$3/2 = 1.5$$

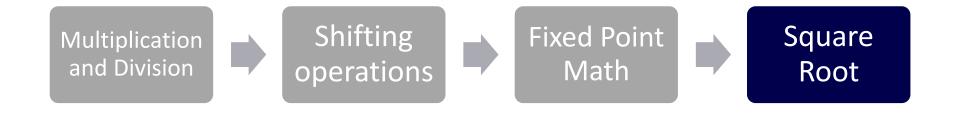
$$0x300 + 0x200$$

$$0x30000 + 0x200$$

$$180$$



Advance Math Operations





Square Root Algorithm -1/3

Newton-Raphson's Method (Numerical).

•
$$y_{n+1} = \left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$$

n	W	y_n	$\frac{w}{y_n}$	$\left(y_n + \frac{w}{y_n}\right)$	$\left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$
0	4	4	1	5	2.5
1	4				
2	4				

Square Root Algorithm -2/3

Newton-Raphson's Method (Numerical).

•
$$y_{n+1} = \left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$$

n	W	y_n	$\frac{w}{y_n}$	$\left(y_n + \frac{w}{y_n}\right)$	$\left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$
0	4	4	1	5	2.5
1	4	2.5	1.6	4.1	2.05
2	4				

Square Root Algorithm -3/3

Newton-Raphson's Method (Numerical).

•
$$y_{n+1} = \left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$$

n	w	y_n	$\frac{w}{y_n}$	$\left(y_n + \frac{w}{y_n}\right)$	$\left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$
0	4	4	1	5	2.5
1	4	2.5	1.6	4.1	2.05
2	4	2.05	1.951	4.001	2.0006



n	W	y_n	$\frac{w}{y_n}$	$\left(y_n + \frac{w}{y_n}\right)$	$\left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$
0	4	4	1	5	2.5
1	4	2.5	1.6	4.1	2.05
2	4	2.05	1.951	4.001	2.0006



Square Root Code -2/4

```
MOV r0,#4

MOV r1,r0

_loop:
UDIV r2,r0,r1

ADD r3,r1,r2

MOV r4,r3, lsr #1

MOV r1,r4

B _loop

infinite loop
```

	Yo	r.	_2	Y 3	ry
n	w	y_n	$\frac{w}{y_n}$	$\left(y_n + \frac{w}{y_n}\right)$	$\left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$
0	4	4	1	5	2.5
1	4	2.5	1.6	4.1	2.05
2	4	2.05	1.951	4.001	2.0006



Square Root Code -3/4

Consider precision
When yn - final result < 0.001, program will end.

hash is needed and 0.001 is illegal

	Yo	Y.	Y ₂	Y 3	r ₄
n	W	y_n	$\frac{w}{y_n}$	$\left(y_n + \frac{w}{y_n}\right)$	$\left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$
0	4	4	1	5	2.5
1	4	2.5	1.6	4.1	2.05
2	4	2.05	1.951	4.001	2.0006

Square Root Code -4/4

```
MOV r0, #4
                               B loop
                               end: b end
MOV r1, r0
MOV r0, r0, lsl #16 @16.16
MOV r1, r1, lsl #8 @24.8
loop:
UDIV r2, r0, r1 @16.8
ADD r3, r1, r2 @24.8
MOV r4, r3, lsr #1 @24.8
                             W
                                y_n
SUB r5, r1, r4 @24.8
CMP r5,#1 @24.8
                                          5
                                4
                                    1
                            4
BLT end
                                2.5
                                    1.6
                                          4.1
                          1
                             4
MOV r1, r4 @24.8
```



2

4

2.05

1.951

4.001

 $\left(y_n + \frac{w}{y_n}\right) * \frac{1}{2}$

2.5

2.05

2.0006

Summary

- 1. Multiplication and division instructions.
- 2. Shifting operations.
- 3. Fixed point math.
- 4. Example: Newton and Raphson's method

