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state-output machine

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## Definition

A *state-output machine* can be thought of as state machine with an output feature: when a word is fed into the machine as input, the machine goes through a series of internal “states” where certain translations take place, and finally a set of words are produced as outputs.

Formally, a *state-output machine*  $M$  is a five-tuple  $(S, \Sigma, \Delta, \delta, \lambda)$  where

1.  $(S, \Sigma, \delta)$  is a state machine (or semiautomaton),
2.  $\Delta$  is a non-empty set whose elements are called *output symbols*, and
3.  $\lambda : S \times \Sigma \rightarrow P(\Delta)$  is a function called the *output function*.

The sets  $S, \Sigma$ , and  $\Delta$  are generally considered to be finite. In the literature, a finite state-output machine is also known as *transducer*.

Note that there is no restrictions on the sizes of  $\lambda(s, a)$  and  $\delta(s, a)$ . Various classifications based on the cardinalities of  $\lambda(s, a)$  and  $\delta(s, a)$  are possible: for all  $(s, a) \in S \times \Sigma$ ,

- $M$  is *complete* if  $|\lambda(s, a)| \geq 1$  and  $|\delta(s, a)| \geq 1$ ; otherwise, it is *incomplete*;
- $M$  is *sequential* if  $|\lambda(s, a)| \leq 1$  and  $|\delta(s, a)| \leq 1$ .

Both  $\delta$  and  $\lambda$  can be extended so its first component takes on a set  $T$  of states:

$$\delta(T, a) := \bigcup \{\delta(t, a) \mid t \in T\} \quad \text{and} \quad \lambda(T, a) := \bigcup \{\lambda(t, a) \mid t \in T\}.$$

Note that  $\delta(\emptyset, a) = \lambda(\emptyset, a) = \emptyset$  for any input symbol  $a \in \Sigma$ .

## Words as Input

The transition and the output functions of a state-output machine  $M$  are defined to work only over individual symbols in  $\Sigma$  as inputs. However, finite strings of symbols over  $\Sigma$ , or words, are usually fed to the  $M$ , instead of individual symbols. Therefore, we would like modify  $\delta$  and  $\lambda$  in order to handle finite strings as well.

**Extending  $\delta$ .** When a machine  $M$  receives an input word  $u$ , it reads  $u$  one symbol at a time, starting from the left, until the last symbol is read. After reading each symbol, the machine goes into a next state, dictated by the transition function  $\delta$ . If  $M$  is at state  $s$  upon receiving  $u$ , we define a next state as a state that  $M$  enters after reading the last symbol of  $u$ .

Based on the above discussion, we are ready to extend  $\delta$  so it takes on words over  $\Sigma$ . This is done inductively:

- $\delta'(s, \epsilon) := \{s\}$ , where  $\epsilon$  is the empty word, and  $s$  is any state;
- $\delta'(s, ua) := \delta(\delta'(s, u), a)$ , where  $a \in \Sigma$  and  $u \in \Sigma^*$ .

It is easy to see that  $\delta'(s, uv) = \delta'(\delta'(s, u), v)$ .

**Extending  $\lambda$ .** There are in general two ways to view output(s) for a given input word:

1. The first, more common, approach, is to view outputs as being produced after the last symbol of the input word is processed:
  - $\lambda'(s, \epsilon) := \emptyset$ , and
  - $\lambda'(s, ua) := \lambda(\delta'(s, u), a)$ , where  $u$  is a word over  $\Sigma$ .

If  $\lambda$  does not depend on input symbols, say  $\lambda(s, a) = \beta(s)$  for all  $(s, a) \in S \times \Sigma$ , the above definition may be modified so that non-empty output(s) may be produced by the empty input word  $\epsilon$ :

- $\lambda'(s, u) := \beta(\delta'(s, u))$ , where  $u$  is any word over  $\Sigma$ .

It is easy to see that  $\lambda(s, \epsilon) = \beta(s)$ . Note that this is not a true extension of the original output function, because the new output function now depends on inputs.

2. Alternatively, outputs may be produced each time a transition occurs. In other words, outputs are words over  $\Delta$ . Thus, outputs are inductively as follows:
  - $\lambda'(s, \epsilon) := \{\epsilon\}$ , where  $\epsilon$  is the empty word, and
  - $\lambda'(s, ua) := \lambda'(s, u)\lambda(\delta'(s, u), a)$ , where  $a \in \Sigma$  and  $u \in \Sigma^*$ .

When there is no confusion, we may continue to denote  $\lambda$  and  $\delta$  as the extensions of the original next-state and output functions.

Given  $M$ , define an *input configuration* as a pair  $(s, u)$  for some  $s \in S$  and  $u \in \Sigma^*$ , and an *output configuration* as a pair  $(t, v)$  for some  $t \in S$  and  $v \in \Delta^*$ . The set of output configurations for a given input configuration  $(s, u)$  is given by  $\delta(s, u) \times \lambda(s, u)$ .

## Generator and Acceptor

One may treat a state-output machine  $M = (S, \Sigma, \Delta, \delta, \lambda)$  as either a *language generator* or a *language acceptor*. The idea is that a set of states and a set of words need to be specified as initial conditions, so that words can either be generated or accepted from these initial conditions. The way this works is as follows:

**$M$  as a generator.** Fix a non-empty set  $I \subseteq S$  of *starting states*, and a non-empty set  $G \subseteq \Sigma^*$ . The triple  $(M, I, G)$  is called a *generator*. A string  $b \in \Delta^*$  is *generated by*  $(M, I, G)$  if  $b \in \lambda(s, a)$  for some  $(s, a) \in I \times G$ . The set of all strings generated by  $(M, I, G)$  is also denoted by  $L(M, I, G)$ .

A typical example of a generator is a Post system: a state machine where the output alphabet is the input alphabet, and the set of states and the state function is suppressed ( $S$  may be taken as a singleton).

**$M$  as an acceptor.** Dually, fix a non-empty set  $F \subseteq S$  called the *final states*, and a non-empty set  $A \subseteq \Delta^*$ . The triple  $(M, F, A)$  is called an *acceptor*. A string  $a \in \Sigma^*$  is said to be *accepted by*  $(M, F, A)$  if  $\delta(s, a) \in F$  and  $\lambda(s, a) \in A$  for some state  $s \in S$ . The set of all strings accepted by  $(M, F, A)$  is denoted by  $L(M, F, A)$ .

A typical example of an acceptor is an automaton: a state machine where the output alphabet and the output function are not essential ( $\Delta^*$  may be taken as a singleton).

**Remark.** Observe that the functions  $\delta$  and  $\lambda$  can be combined to form a single function  $\tau : S \times \Sigma \rightarrow P(S) \times P(\Delta)$  such that  $\tau = (\delta, \lambda)$ . One can generalize this so that  $\tau$  is a function from  $S \times \Sigma$  to  $P(S \times \Delta)$ , or more generally, to  $P(S \times \Delta^*)$ . The resulting construct is commonly known as a *generalized sequential machine*.

## References

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