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**every  $\epsilon$ -automaton is equivalent to an automaton**

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In this entry, we show that an automaton with <http://planetmath.org/EpsilonTransition>  $\epsilon$ -transitions is no more powerful than one without. Having  $\epsilon$ -transitions is purely a matter of convenience.

**Proposition 1.** *Every <http://planetmath.org/EpsilonAutomaton>  $\epsilon$ -automaton is equivalent to an automaton.*

For the proof, we use the following setup (see the parent entry for more detail):

- $E = (S, \Sigma, \delta, I, F, \epsilon)$  is an  $\epsilon$ -automaton, and  $E_\epsilon$  is the automaton associated with  $E$ ,
- $h : (\Sigma \cup \{\epsilon\})^* \rightarrow \Sigma^*$  is the homomorphism that erases  $\epsilon$  (it takes  $\epsilon$  to the empty word, also denoted by  $\epsilon$ ). From the parent entry,  $L(E) := h(L(E_\epsilon))$ .

*Proof.* Define a function  $\delta_1 : S \times \Sigma \rightarrow P(S)$ , as follows: for each pair  $(s, a) \in S \times \Sigma$ , let

$$\delta_1(s, a) = \bigcup \{ \delta(s, u) \mid h(u) = a \}.$$

In other words,  $\delta_1(s, a)$  is the set of all states reachable from  $s$  by words of the form  $\epsilon^m a \epsilon^n$ . As usual, we extend  $\delta_1$  so its domain is  $S \times \Sigma^*$ . By abuse of notation, we use  $\delta_1$  again for this extension. First, we set  $\delta_1(s, \epsilon) := \{s\}$ .

Then we inductively define  $\delta_1(s, ua) = \delta_1(\delta_1(s, u), a)$ . Using induction,

$$\begin{aligned}
\delta_1(s, ua) &= \delta_1(\delta_1(s, u), a) \\
&= \delta_1\left(\bigcup_{h(v)=u} \delta(s, v), a\right) \\
&= \bigcup_{h(v)=u} \delta_1(\delta(s, v), a) \\
&= \bigcup_{h(v)=u} \bigcup_{t \in \delta(s, v)} \delta_1(t, a) \\
&= \bigcup_{h(v)=u} \bigcup_{t \in \delta(s, v)} \bigcup_{h(w)=a} \delta(t, w) \\
&= \bigcup_{h(v)=u} \bigcup_{h(w)=a} \bigcup_{t \in \delta(s, v)} \delta(t, w) \\
&= \bigcup_{h(v)=u} \bigcup_{h(w)=a} \delta(\delta(s, v), w) \\
&= \bigcup_{h(v)=u} \bigcup_{h(w)=a} \delta(s, vw) \\
&= \bigcup \{ \delta(s, vw) \mid h(v) = u \text{ and } h(w) = a \} \\
&= \bigcup \{ \delta(s, x) \mid h(x) = ua \}
\end{aligned}$$

So for any non-empty word  $u$ , we have the following equation:

$$\delta_1(s, u) = \bigcup \{ \delta(s, v) \mid h(v) = u \}. \quad (1)$$

In other words, if  $u = a_1 a_2 \cdots a_n$ , then  $\delta_1(s, u)$  is the set of all states reachable from  $s$  by words of the form

$$\epsilon^{i_0} a_1 \epsilon^{i_1} a_2 \epsilon^{i_2} \cdots \epsilon^{i_{n-1}} a_n \epsilon^{i_n}. \quad (2)$$

Now, define  $A$  to be the automaton  $(S, \Sigma, \delta_1, I, F)$ . Then, from equation (1) above, a word

$$u = a_1 a_2 \cdots a_n$$

is accepted by  $A$  iff some word  $v$  of the form (2) is accepted by  $E_\epsilon$  iff  $u = h(v)$  is accepted by  $E$ , proving the proposition.  $\square$

**Remark.** Another approach is to use the concept of <http://planetmath.org/EpsilonClosure> closure. The proof is very similar to the one given above, and the resulting equivalent automaton is a DFA.