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diagonalization

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Let V be a finite-dimensional linear space over a field K , and $T : V \rightarrow V$ a linear transformation. To *diagonalize* T is to find a basis of V that consists of eigenvectors. The transformation is called *diagonalizable* if such a basis exists. The choice of terminology reflects the fact that the matrix of a linear transformation relative to a given basis is diagonal if and only if that basis consists of eigenvectors.

Next, we give necessary and sufficient conditions for T to be diagonalizable. For $\lambda \in K$ set

$$E_\lambda = \{u \in V : Tu = \lambda u\}.$$

It isn't hard to show that E_λ is a subspace of V , and that this subspace is non-trivial if and only if λ is an *eigenvalue* of T . In that case, E_λ is called the eigenspace associated to λ .

Proposition 1 *A transformation is diagonalizable if and only if*

$$\dim V = \sum_{\lambda} \dim E_{\lambda},$$

where the sum is taken over all eigenvalues of the transformation.

The Matrix Approach. As was already mentioned, the term “diagonalize” comes from a matrix-based perspective. Let M be a <http://planetmath.org/matrixmatrix> representation of T relative to some basis B . Let

$$P = [v_1, \dots, v_n], \quad n = \dim V,$$

be a matrix whose column vectors are eigenvectors expressed relative to B . Thus,

$$Mv_i = \lambda_i v_i, \quad i = 1, \dots, n$$

where λ_i is the eigenvalue associated to v_i . The above n equations are more succinctly as the matrix equation

$$MP = PD,$$

where D is the diagonal matrix with λ_i in the i -th position. Now the eigenvectors in question form a basis, if and only if P is invertible. In that case, we may write

$$M = PDP^{-1}. \tag{1}$$

Thus in the matrix-based approach, to “diagonalize” a matrix M is to find an invertible matrix P and a diagonal matrix D such that equation (1) is satisfied.

Subtleties. There are two fundamental reasons why a transformation T can fail to be diagonalizable.

1. The characteristic polynomial of T does not factor into linear factors over K .
2. There exists an eigenvalue λ , such that the kernel of $(T - \lambda I)^2$ is strictly greater than the kernel of $(T - \lambda I)$. Equivalently, there exists an invariant subspace where T acts as a nilpotent transformation plus some multiple of the identity. Such subspaces manifest as non-trivial Jordan blocks in the Jordan canonical form of the transformation.