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Rayleigh-Ritz theorem

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Let $A \in \mathbf{C}^{n \times n}$ be a Hermitian matrix. Then its eigenvectors are the critical points (vectors) of the "Rayleigh quotient", which is the real function $R : \mathbf{C}^n \setminus \{\mathbf{0}\} \rightarrow \mathbb{R}$

$$R(\mathbf{x}) = \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}, \|\mathbf{x}\| \neq 0$$

and its eigenvalues are its values at such critical points.

As a consequence, we have:

$$\lambda_{max} = \max_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$$

and

$$\lambda_{min} = \min_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$$

Proof:

First of all, let's observe that for a hermitian matrix, the number $\mathbf{x}^H A \mathbf{x}$ is a real one (actually, $\langle \mathbf{x}, A \mathbf{x} \rangle = \mathbf{x}^H A \mathbf{x} = (A^H \mathbf{x})^H \mathbf{x} = (A \mathbf{x})^H \mathbf{x} = \langle A \mathbf{x}, \mathbf{x} \rangle = \langle \mathbf{x}, A \mathbf{x} \rangle^*$, whence $\langle \mathbf{x}, A \mathbf{x} \rangle = \mathbf{x}^H A \mathbf{x}$ is real), so that the Rayleigh quotient is real as well.

Let's now compute the critical points $\bar{\mathbf{x}}$ of the Rayleigh quotient, i.e. let's solve the equations system $\frac{dR(\bar{\mathbf{x}})}{d\mathbf{x}} = \mathbf{0}^T$. Let's write $\mathbf{x} = \mathbf{x}^{(R)} + j\mathbf{x}^{(I)}$, $\mathbf{x}^{(R)}$ and $\mathbf{x}^{(I)}$ being respectively the real and imaginary part of \mathbf{x} . We have:

$$\frac{dR(\mathbf{x})}{d\mathbf{x}} = \frac{dR(\mathbf{x})}{d\mathbf{x}^{(R)}} + j \frac{dR(\mathbf{x})}{d\mathbf{x}^{(I)}}$$

so that we must have:

$$\frac{dR(\bar{\mathbf{x}})}{d\mathbf{x}^{(R)}} = \frac{dR(\bar{\mathbf{x}})}{d\mathbf{x}^{(I)}} = \mathbf{0}^T$$

Using derivatives rules, we obtain:

$$\frac{dR(\mathbf{x})}{d\mathbf{x}^{(R)}} = \frac{d}{d\mathbf{x}^{(R)}} \left(\frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}} \right) = \frac{\frac{d(\mathbf{x}^H A \mathbf{x})}{d\mathbf{x}^{(R)}} \mathbf{x}^H \mathbf{x} - \mathbf{x}^H A \mathbf{x} \frac{d(\mathbf{x}^H \mathbf{x})}{d\mathbf{x}^{(R)}}}{(\mathbf{x}^H \mathbf{x})^2} = \frac{\frac{d(\mathbf{x}^H A \mathbf{x})}{d\mathbf{x}^{(R)}} - R(\mathbf{x}) \frac{d(\mathbf{x}^H \mathbf{x})}{d\mathbf{x}^{(R)}}}{\mathbf{x}^H \mathbf{x}}.$$

Applying matrix calculus rules, we find:

$$\frac{d(\mathbf{x}^H A \mathbf{x})}{d\mathbf{x}^{(R)}} = \mathbf{x}^H A \frac{d\mathbf{x}}{d\mathbf{x}^{(R)}} + \mathbf{x}^T A^T \frac{d\mathbf{x}^*}{d\mathbf{x}^{(R)}} = \mathbf{x}^H A + \mathbf{x}^T A^T = \mathbf{x}^H A + (\mathbf{x}^H A^H)^* =$$

and since $A = A^H$,

$$= \mathbf{x}^H A + (\mathbf{x}^H A)^* = 2\Re(\mathbf{x}^H A).$$

In a similar way, we get:

$$\frac{d(\mathbf{x}^H \mathbf{x})}{d\mathbf{x}^{(R)}} = 2\Re(\mathbf{x}^H).$$

Substituting, we obtain:

$$\frac{dR(\mathbf{x})}{d\mathbf{x}^{(R)}} = 2 \frac{\Re(\mathbf{x}^H A) - R(\mathbf{x})\Re(\mathbf{x}^H)}{\mathbf{x}^H \mathbf{x}}$$

and, after a transposition, equating to the null column vector,

$$\begin{aligned} \mathbf{0} &= (\Re(\bar{\mathbf{x}}^H A) - R(\bar{\mathbf{x}})\Re(\bar{\mathbf{x}}^H))^T = \\ &= \Re(A^T \bar{\mathbf{x}}^*) - R(\bar{\mathbf{x}})\Re(\bar{\mathbf{x}}^*) = \Re((A^H \bar{\mathbf{x}})^*) - R(\bar{\mathbf{x}})\Re(\bar{\mathbf{x}}^*) = \\ &= \Re((A\bar{\mathbf{x}})^*) - R(\bar{\mathbf{x}})\Re(\bar{\mathbf{x}}^*) = \Re(A\bar{\mathbf{x}}) - R(\bar{\mathbf{x}})\Re(\bar{\mathbf{x}}) \end{aligned}$$

and, since $R(\mathbf{x})$ is real,

$$\Re(A\bar{\mathbf{x}} - R(\bar{\mathbf{x}})\bar{\mathbf{x}}) = \mathbf{0}$$

Let's then evaluate $\frac{dR(\mathbf{x})}{d\mathbf{x}^{(I)}}$:

$$\frac{dR(\mathbf{x})}{d\mathbf{x}^{(I)}} = \frac{d}{d\mathbf{x}^{(I)}} \left(\frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}} \right) = \frac{\frac{d(\mathbf{x}^H A \mathbf{x})}{d\mathbf{x}^{(I)}} \mathbf{x}^H \mathbf{x} - \mathbf{x}^H A \mathbf{x} \frac{d(\mathbf{x}^H \mathbf{x})}{d\mathbf{x}^{(I)}}}{(\mathbf{x}^H \mathbf{x})^2} = \frac{\frac{d(\mathbf{x}^H A \mathbf{x})}{d\mathbf{x}^{(I)}} - R(\mathbf{x}) \frac{d(\mathbf{x}^H \mathbf{x})}{d\mathbf{x}^{(I)}}}{\mathbf{x}^H \mathbf{x}}.$$

Applying again matrix calculus rules, we find:

$$\frac{d(\mathbf{x}^H A \mathbf{x})}{d\mathbf{x}^{(I)}} = \mathbf{x}^H A \frac{d\mathbf{x}}{d\mathbf{x}^{(I)}} + \mathbf{x}^T A^T \frac{d\mathbf{x}^*}{d\mathbf{x}^{(I)}} = j\mathbf{x}^H A - j\mathbf{x}^T A^T = j(\mathbf{x}^H A - (\mathbf{x}^H A^H)^*) =$$

and since $A = A^H$,

$$= j(\mathbf{x}^H A - (\mathbf{x}^H A)^*) = j(2j\Im(\mathbf{x}^H A)) = -2\Im(\mathbf{x}^H A).$$

In a similar way, we get:

$$\frac{d(\mathbf{x}^H \mathbf{x})}{d\mathbf{x}^{(I)}} = j\mathbf{x}^H - j\mathbf{x}^T = j(\mathbf{x}^H - (\mathbf{x}^H)^*) = j(2j\Im(\mathbf{x}^H)) = -2\Im(\mathbf{x}^H).$$

Substituting, we obtain:

$$\frac{dR(\mathbf{x})}{d\mathbf{x}^{(I)}} = -2 \frac{\Im(\mathbf{x}^H A) - R(\mathbf{x})\Im(\mathbf{x}^H)}{\mathbf{x}^H \mathbf{x}}$$

and, after a transposition, equating to the null column vector,

$$\begin{aligned} \mathbf{0} &= (\Im(\bar{\mathbf{x}}^H A) - R(\bar{\mathbf{x}})\Im(\bar{\mathbf{x}}^H))^T = \\ &= \Im(A^T \bar{\mathbf{x}}^*) - R(\bar{\mathbf{x}})\Im(\bar{\mathbf{x}}^*) = \Im((A^H \bar{\mathbf{x}})^*) - R(\bar{\mathbf{x}})\Im(\bar{\mathbf{x}}^*) = \\ &= \Im((A\bar{\mathbf{x}})^*) - R(\bar{\mathbf{x}})\Im(\bar{\mathbf{x}}^*) = -\Im(A\bar{\mathbf{x}}) + R(\bar{\mathbf{x}})\Im(\bar{\mathbf{x}}) \end{aligned}$$

and, since $R(\mathbf{x})$ is real,

$$\Im(A\bar{\mathbf{x}} - R(\bar{\mathbf{x}})\bar{\mathbf{x}}) = \mathbf{0}$$

In conclusion, we have that a stationary vector $\bar{\mathbf{x}}$ for the Rayleigh quotient satisfies the complex eigenvalue equation

$$A\bar{\mathbf{x}} - R(\bar{\mathbf{x}})\bar{\mathbf{x}} = \mathbf{0}$$

whence the thesis. \square

Remarks:

1) The two relations $\lambda_{\max} = \max_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$ and $\lambda_{\min} = \min_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$ can also be obtained in a simpler way. By Schur's canonical form theorem, any normal (and hence any hermitian) matrix is unitarily diagonalizable, i.e. a unitary matrix U exists such that $A = U \Lambda U^H$ with $\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$. So, since all eigenvalues of a hermitian matrix are real, it's possible to write:

$$\begin{aligned} \mathbf{x}^H A \mathbf{x} &= \mathbf{x}^H U \Lambda U^H \mathbf{x} = (U^H \mathbf{x})^H \Lambda (U^H \mathbf{x}) = \mathbf{y}^H \Lambda \mathbf{y} = \sum_{i=1}^n \lambda_i |y_i|^2 \leq \lambda_{\max} \sum_{i=1}^n |y_i|^2 = \\ &= \lambda_{\max} \mathbf{y}^H \mathbf{y} = \lambda_{\max} (U^H \mathbf{x})^H (U^H \mathbf{x}) = \lambda_{\max} (\mathbf{x}^H U U^H \mathbf{x}) = \lambda_{\max} (\mathbf{x}^H \mathbf{x}) \end{aligned}$$

whence

$$\lambda_{\max} \geq \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$$

But, having defined $A \mathbf{v}_M = \lambda_{\max} \mathbf{v}_M$, we have:

$$\frac{\mathbf{v}_M^H A \mathbf{v}_M}{\mathbf{v}_M^H \mathbf{v}_M} = \frac{\mathbf{v}_M^H \lambda_{\max} \mathbf{v}_M}{\mathbf{v}_M^H \mathbf{v}_M} = \lambda_{\max}$$

so that

$$\lambda_{\max} = \max_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$$

In a much similar way, we obtain

$$\lambda_{\min} = \min_{\|\mathbf{x}\| \neq 0} \frac{\mathbf{x}^H A \mathbf{x}}{\mathbf{x}^H \mathbf{x}}$$

2) The above relations yield the following noteworthy bounds for the diagonal entries of a hermitian matrix:

$$\lambda_{\min} \leq a_{ii} \leq \lambda_{\max}$$

In fact, having defined

$$\mathbf{e}_i = [\overbrace{0, 0, \dots, 0}^{i-1}, 1, 0, \dots, 0]^T$$

and observing that $a_{ii} = \frac{\mathbf{e}_i^H A \mathbf{e}_i}{\mathbf{e}_i^H \mathbf{e}_i} = R(\mathbf{e}_i)$, we have:

$$\lambda_{\min} = \min_{\|\mathbf{x}\| \neq 0} R(\mathbf{x}) \leq R(\mathbf{e}_i) \leq \max_{\|\mathbf{x}\| \neq 0} R(\mathbf{x}) = \lambda_{\max}.$$