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dual homomorphism of the derivative

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Owner	rmilson (146)
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Author	rmilson (146)
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Let \mathcal{P}_n denote the vector space of real polynomials of degree n or less, and let $D_n : \mathcal{P}_n \rightarrow \mathcal{P}_{n-1}$ denote the ordinary derivative. Linear forms on \mathcal{P}_n can be given in terms of evaluations, and so we introduce the following notation. For every scalar $k \in \mathbb{R}$, let $\text{Ev}_k^{(n)} \in (\mathcal{P}_n)^*$ denote the evaluation functional

$$\text{Ev}_k^{(n)} : p \mapsto p(k), \quad p \in \mathcal{P}_n.$$

Note: the degree superscript matters! For example:

$$\text{Ev}_2^{(1)} = 2 \text{Ev}_1^{(1)} - \text{Ev}_0^{(1)},$$

whereas $\text{Ev}_0^{(2)}, \text{Ev}_1^{(2)}, \text{Ev}_2^{(2)}$ are linearly independent. Let us consider the dual homomorphism D_2^* , i.e. the adjoint of D_2 . We have the following relations:

$$\begin{aligned} D_2^* \left(\text{Ev}_0^{(1)} \right) &= -\frac{3}{2} \text{Ev}_0^{(2)} + 2 \text{Ev}_1^{(2)} - \frac{1}{2} \text{Ev}_2^{(2)}, \\ D_2^* \left(\text{Ev}_1^{(1)} \right) &= -\frac{1}{2} \text{Ev}_0^{(2)} + \frac{1}{2} \text{Ev}_2^{(2)}. \end{aligned}$$

In other words, taking $\text{Ev}_0^{(1)}, \text{Ev}_1^{(1)}$ as the basis of $(\mathcal{P}_1)^*$ and $\text{Ev}_0^{(2)}, \text{Ev}_1^{(2)}, \text{Ev}_2^{(2)}$ as the basis of $(\mathcal{P}_2)^*$, the matrix that represents D_2^* is just

$$\begin{pmatrix} -\frac{3}{2} & -\frac{1}{2} \\ 2 & 0 \\ -\frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

Note the contravariant relationship between D_2 and D_2^* . The former turns second degree polynomials into first degree polynomials, where as the latter turns first degree evaluations into second degree evaluations. The matrix of D_2^* has 2 columns and 3 rows precisely because D_2^* is a homomorphism from a 2-dimensional vector space to a 3-dimensional vector space.

By contrast, D_2 will be represented by a 2×3 matrix. The dual basis of \mathcal{P}_1 is

$$-x + 1, \quad x$$

and the dual basis of \mathcal{P}_2 is

$$\frac{1}{2}(x-1)(x-2), \quad x(2-x), \quad \frac{1}{2}x(x-1).$$

Relative to these bases, D_2 is represented by the transpose of the matrix for D_2^* , namely

$$\begin{pmatrix} -\frac{3}{2} & 2 & -\frac{1}{2} \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{pmatrix}$$

This corresponds to the following three relations:

$$\begin{array}{rcl} D_2 \left[\frac{1}{2}(x-1)(x-2) \right] & = & -\frac{3}{2}(-x+1) - \frac{1}{2}x \\ D_2 [x(2-x)] & = & 2(-x+1) + 0x \\ D_2 \left[\frac{1}{2}x(x-1) \right] & = & -\frac{1}{2}(-x+1) + \frac{1}{2}x \end{array}$$