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$O(2)$

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still being written

An elementary example of a Lie group is afforded by $O(2)$, the orthogonal group in two dimensions. This is the set of transformations of the plane which fix the origin and preserve the distance between points. It may be shown that a transform has this property if and only if it is of the form

$$\begin{pmatrix} x \\ y \end{pmatrix} \mapsto M \begin{pmatrix} x \\ y \end{pmatrix},$$

where M is a 2×2 matrix such that $M^T M = I$. (Such a matrix is called orthogonal.)

It is easy enough to check that this is a group. To see that it is a Lie group, we first need to make sure that it is a manifold. To that end, we will parameterize it. Calling the entries of the matrix a, b, c, d , the condition becomes

$$\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}^T \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a^2 + c^2 & ab + cd \\ ab + cd & b^2 + d^2 \end{pmatrix}$$

which is equivalent to the following system of equations:

$$\begin{aligned} a^2 + c^2 &= 1 \\ ab + cd &= 0 \\ b^2 + d^2 &= 1 \end{aligned}$$

The first of these equations can be solved by introducing a parameter θ and writing $a = \cos \theta$ and $c = \sin \theta$. Then the second equation becomes $b \cos \theta + d \sin \theta = 0$, which can be solved by introducing a parameter r :

$$\begin{aligned} b &= -r \sin \theta \\ d &= r \cos \theta \end{aligned}$$

Substituting this into the third equation results in $r^2 = 1$, so $r = -1$ or $r = +1$. This means we have two matrices for each value of θ :

$$\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$$

Since more than one value of θ will produce the same matrix, we must restrict the range in order to obtain a bona fide coordinate. Thus, we may

cover $O(2)$ with an atlas consisting of four neighborhoods:

$$\begin{aligned} & \left\{ \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \mid -\frac{3}{4}\pi < \theta < \frac{3}{4}\pi \right\} \\ & \left\{ \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \mid \frac{1}{4}\pi < \theta < \frac{7}{4}\pi \right\} \\ & \left\{ \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \mid -\frac{3}{4}\pi < \theta < \frac{3}{4}\pi \right\} \\ & \left\{ \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix} \mid \frac{1}{4}\pi < \theta < \frac{7}{4}\pi \right\} \end{aligned}$$

Every element of $O(2)$ must belong to at least one of these neighborhoods. It is trivial to check that the transition functions between overlapping coordinate patches are