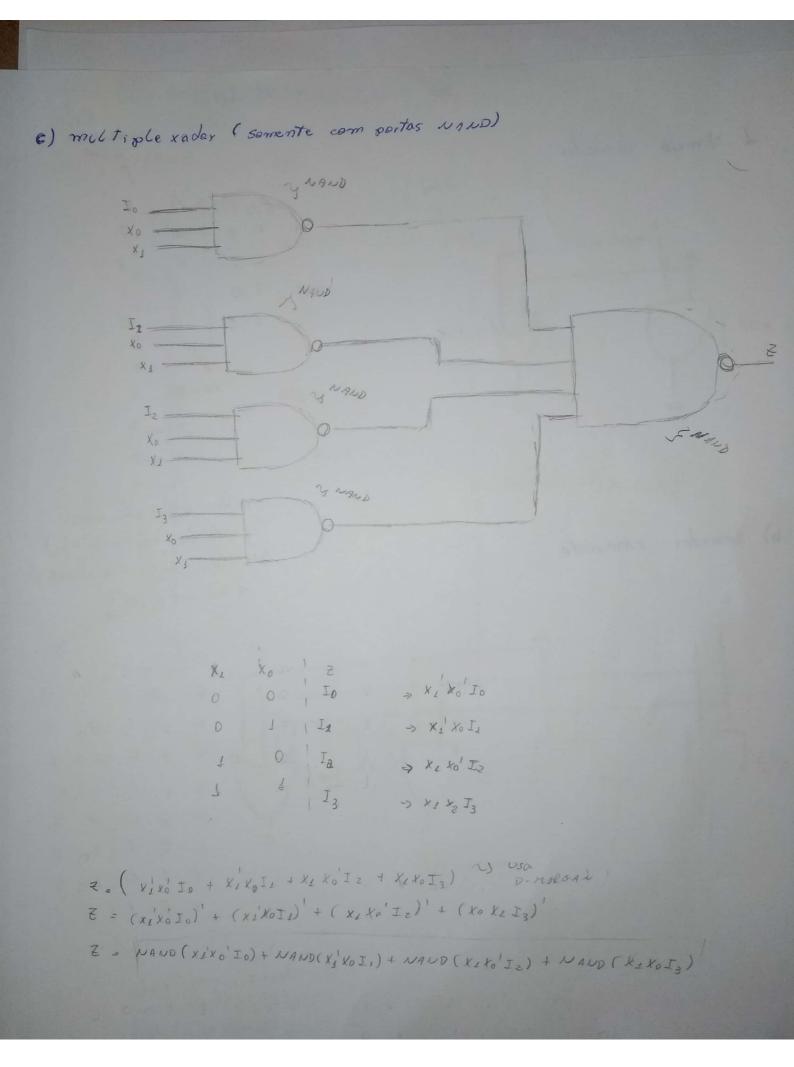


Digitalizado com CamScanner



/-> F(X3, X2, X1, X0). TM(0,2,3,7,10,13,15) 2.0) mux 16x1 f(x) = TM (0,2,3,7,10,13,15) = Em (1, 4,5,6, 8,9,11,12, 14) 1 _ 1 0- 2 0-3 MUX 1 3 - F (X3 X2, X1, X0) 1 8 1-19 0_10 1_11 1 12 0-113 0-15 C3 C2 C4 C0

MUX Bx1 X3 X2 X1 X0 { = xo 0 MUX -F(X3,X2,X1,X0) 14,1110 IM (0,2,3,7,10,13,15)