

Data Driven Models for Engineering Problems

1st Assignment

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The most important chunks of code used in our simulation can be found in the Appendix, or even within the main body, rather scarcely. A Jupyter notebook with the complete code has also been included in our submission, separately from this text.

EXERCISE A

Number of terms retained justification: By the Karhunen-Loeve theorem, we can decompose each realization as

$$\begin{aligned} X(t, \omega) &= \sum_{n=1}^{\infty} \sqrt{\lambda_n} \phi_n(t) \xi_n(\omega) \\ &= \sum_{n=1}^M \sqrt{\lambda_n} \phi_n(t) \xi_n(\omega) + \sum_{n=M+1}^{\infty} \sqrt{\lambda_n} \phi_n(t) \xi_n(\omega), \end{aligned}$$

where $(\xi_n)_n$ is an i.i.d. sequence of standard normal distributions. Let $\tilde{X}(t, \omega) = \sum_{n=1}^M \sqrt{\lambda_n} \phi_n(t) \xi_n$ denote the part of the sum that we will actually simulate and $e_M(t, \omega) = \sum_{n=M+1}^{\infty} \sqrt{\lambda_n} \phi_n(t) \xi_n(\omega)$ denote the error part. Our estimation \tilde{X} for X has the property that $\|\tilde{X} - X\|_2 = \|e_M\|_2$, so in order for \tilde{X} to be close to X , we need to pick an M large enough so that the $\|e_M\|_2$ will be acceptably small.

Since \tilde{X} is created using the random variables $(\xi_n)_{n=1}^M$, there is an additional potential source of error: If we are unlucky and the ξ_n 's are relatively large for large values of n , then the same may hold for $\|e_M\|_2$ regardless of our initial choice for M . However, given how fast $(\lambda_n)_n$ converges to zero, obtaining such large values for ξ_n 's is rather unlikely. Thus, although we cannot assure that $\|e_M\|_2$ will always be acceptably small, we can assure that it will be small with high probability. So we may rephrase our goal as follows:

Problem 1. For any given $\delta, \varepsilon > 0$ find an $M \in \mathbb{N}$ such that $\|e_M\|_2 < \delta$ with probability at least $1 - \varepsilon$.

For the probabilistic aspect of our problem, we will rely on the Laurent-Massart Lemma, which provides

concentration bounds for linear combinations of chi-squared distributions:

Lemma 2. [LM00, Lemma 1] Let Y_1, \dots, Y_D be i.i.d. standard normal random variables and $(a_i)_{i=1}^D$ be non-negative real numbers. For the random variable $Z = \sum_{i=1}^D a_i(Y_i^2 - 1)$ the following inequalities hold for any $x > 0$:

$$\begin{aligned} P(X \geq 2\|a\|_2 \sqrt{x} + 2\|a\|_{\infty} x) &\leq e^{-x}, \\ P(X \leq -2\|a\|_2 \sqrt{x}) &\leq e^{-x}. \end{aligned}$$

Combining the last two inequalities, we also obtain that

$$P(|X| \geq 2\|a\|_2 \sqrt{x} + 2\|a\|_{\infty} x) \leq 2e^{-x}. \quad (1)$$

Proposition 3. Consider a zero-mean stationary Gaussian field on $D = [-a, a]$ with correlation function $C(t, s) = e^{\frac{|t-s|}{b}}$. Then, for every $\delta, \varepsilon > 0$, we have that $\|e_M\|_2^2 < \delta$ with probability at least $1 - \varepsilon$ for every $M \geq \left(\frac{2a^2}{3b\pi^2} \frac{2\sqrt{-\ln(\varepsilon/2)} - 2\ln(\varepsilon/2) + 1}{\delta} \right)^{1/3} + 1$.

Proof. Recall that for some fixed orbit, $e_M(t) = \sum_{n=M+1}^{\infty} \sqrt{\lambda_n} \phi_n(t) \xi_n$ where the eigenvalues λ_n and eigenfunctions $\phi_n(t)$ are described in [PG18, p. 33] and the ξ_i 's are realizations of independent standard normal random variables. The L_2 -norm of e_M is equal to

$$\begin{aligned} \|e_M\|_2^2 &= \sum_{n=M+1}^{\infty} \lambda_n \xi_n^2 \\ &= \sum_{n=M+1}^{\infty} (\lambda_n \xi_n^2 - 1) + \sum_{n=M+1}^{\infty} \lambda_n. \end{aligned}$$

Let λ denote the sequence $\lambda = (\lambda_{M+1}, \lambda_{M+2}, \dots)$. By the Laurent-Massart Lemma,¹ we have that

$$P(\|e_M\|_2^2 \geq 2\|\lambda\|_2 \sqrt{x} + 2\|\lambda\|_{\infty} x + \|\lambda\|_1) \leq 2e^{-x}$$

¹Here our sequence of scalars $(\lambda_n)_n$ is not finite, but $\|\lambda_n\|_2 \rightarrow \|\lambda\|_2$ and it is easy to see that inequality (1) still holds using a simple limit argument.

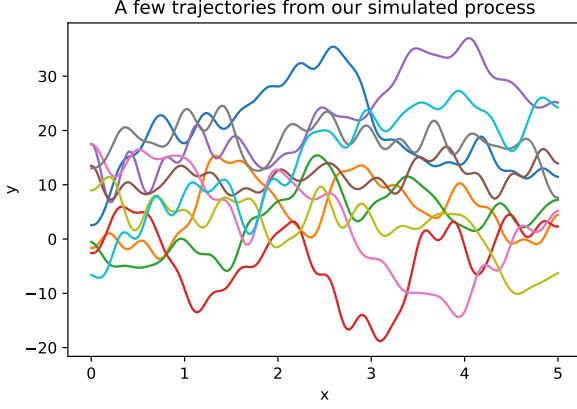


Figure 1. Sample trajectories from the stochastic field $E(x) = 10(1 + f(x))$.

for every $x > 0$. In particular, since the ℓ_1 -norm always dominates the rest of the ℓ_p -norms, we obtain that

$$P(\|e_M\|^2 \geq \|\lambda\|_1(2\sqrt{x} + 2x + 1)) \leq 2e^{-x} \quad (2)$$

for every $x > 0$.

What is left to be done, is to determine an upper bound for $\|\lambda\|_1$ as an expression involving M . Notice that for every n , the value of ω_n is always larger than or equal to $\frac{(n-1)\pi}{a}$. Since $\lambda_n = \frac{2b}{1+\omega_n^2 b^2}$, this implies that

$$\lambda_n \leq \frac{2a^2}{\pi^2 b} \frac{1}{(n-1)^2}, \quad (3)$$

so

$$\begin{aligned} \|\lambda\|_1 &\leq \frac{2a^2}{b\pi^2} \sum_{n=M+1}^{\infty} \frac{1}{(n-1)^2} = \frac{2a^2}{b\pi^2} \sum_{n=M}^{\infty} \frac{1}{n^2} \\ &\leq \frac{2a^2}{b\pi^2} \int_{M-1}^{\infty} \frac{1}{x^2} dx \\ &= \frac{2a^2}{b\pi^2} \frac{1}{3(M-1)^3} := C_M. \end{aligned} \quad (4)$$

Therefore,

$$P(\|e_M\|^2 \geq C_M(2\sqrt{x} + 2x + 1)) \leq 2e^{-x} \quad (5)$$

also holds for every $x > 0$. The requirement that the probability of error should be less than ε implies that $2e^{-x} \leq \varepsilon$, so $x \geq -\ln \frac{\varepsilon}{2}$. We substitute this value of x in (5) to obtain:

$$P\left(\|e_M\|^2 \geq C_M\left(2\sqrt{-\ln \frac{\varepsilon}{2}} - 2\ln \frac{\varepsilon}{2} + 1\right)\right) \leq \varepsilon. \quad (6)$$

The last relation holds for any choice of M . We finish the proof by choosing an M such that $C_M(2\sqrt{-\ln \frac{\varepsilon}{2}} - 2\ln \frac{\varepsilon}{2} + 1) < \delta$, namely any integer M larger than

$$M \geq \left(\frac{2a^2}{3b\delta\pi^2} \left(2\sqrt{-\ln \frac{\varepsilon}{2}} - 2\ln \frac{\varepsilon}{2} + 1\right)\right)^{1/3} + 1 \quad (7)$$

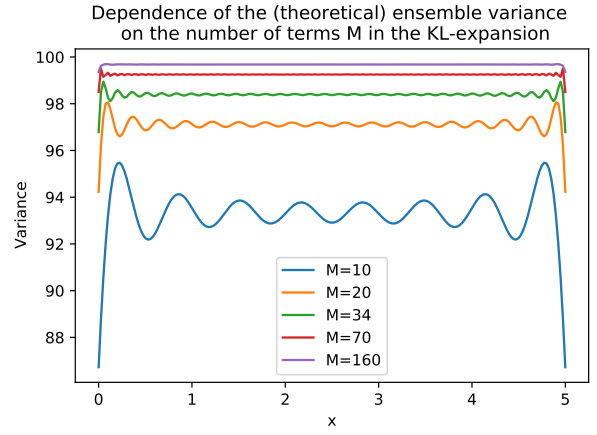


Figure 2. The theoretical ensemble variance $V[X(t)] = v_M(t) = \sum_{n=1}^M \lambda_n \phi_n(t-2.5)^2$ for various values of M . As M increases, v_M converges to the constant function $v_{\infty} \equiv 100$.

will suffice. \square

Simulation: In order to simulate from the field $E(t) = 10(1 + f(t))$ for $t \in [0, 5]$, we initially simulate from $f(t)$ for $t \in (-2.5, 2.5)$ using the relevant theory. Then, each simulated orbit $X(t, \omega)$, $t \in [-2.5, 2.5]$, can be easily transformed into $Y(t, \omega) = 10 + 10X(t - 2.5, \omega)$ for $t \in [0, 5]$ which is then a realization from the desired stochastic field $E(t)$.

Applying Proposition 3 to our exercise for $a = 2.5$, $b = 2$ and for a choice of $\varepsilon = 10^{-4}$ and $\delta = 0.01$, we obtain that $M \geq 34$. It is worth stressing out that the previous bound is by no means a sharp one, and one could potentially achieve the same result with a smaller M .

```
def M_estimate(a, b, d, e):
    return(((2 * np.sqrt(-np.log(e/2)) -
              2 * np.log(e/2) + 1) *
              2 * a**2/(3 * d * b *
              np.pi**2))**(1. / 3.) + 1)
```

```
M_estimate(2.5, 2, 0.01, 0.01)
> 7.99
```

```
M_estimate(2.5, 2, 0.0001, 0.01)
> 33.45
```

We proceeded with the simulation, first simulating from $f(t)$ using $M = 34$ terms in the KL-expansion, and then translating the results so as to obtain the orbits of $E(x)$. In Figure 1 we depict a few orbits from our simulated processes.

Theoretical ensemble average and variance: In the general setting, each simulated trajectory has the form $X(t) = \sum_{n=1}^M \sqrt{\lambda_n} \phi_n(t) \xi_n$, where $(\xi_n)_n$ are i.i.d. standard

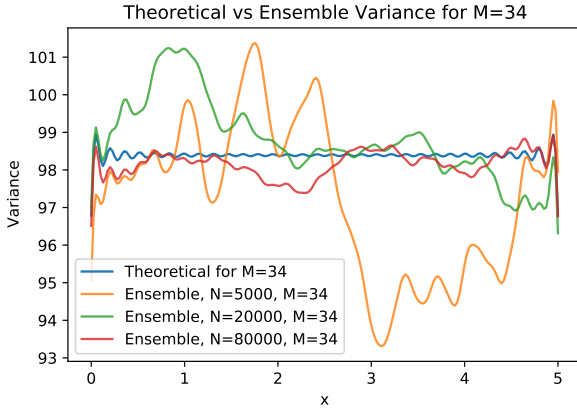


Figure 3. The ensemble variance converges a.s. to $v_{34}(t) = \sum_{n=1}^{34} \lambda_n \phi_n(t-2.5)^2$ as N increases.

normal. From this formula we can immediately compute the expectation and the variance of $X(t)$ for each $t \in [-a, a]$:

$$\mathbb{E}[X(t)] = \sum_{n=1}^M \sqrt{\lambda_n} \phi_n(t) \mathbb{E}[\xi_n] = 0 \quad (8)$$

$$\begin{aligned} \text{Var}[X(t)] &= \sum_{n=1}^M \lambda_n \phi_n(t)^2 \text{Var}(\xi_n) \\ &= \sum_{n=1}^M \lambda_n \phi_n(t)^2. \end{aligned} \quad (9)$$

By the Strong Law of Large Numbers, the ensemble average and variance will converge to the functions $m(t) = 0$ and $v_M(t) = \sum_{n=1}^M \lambda_n \phi_n(t)^2$ respectively, for almost every $t \in [-a, a]$. For the stochastic field of the exercise the corresponding limits are $m(t) = 10$ and $v_M(t) = \sum_{n=1}^M \lambda_n \phi_n(t-2.5)^2$ for $t \in [0, 5]$. Since all the terms appearing in the last sum are nonnegative, $(v_M)_{M \in \mathbb{N}}$ is an increasing sequence of functions in $[0, 5]$ with $\lim_{M \rightarrow \infty} v_M(t) = \sum_{n=1}^{\infty} \lambda_n \phi_n(t-2.5)^2$. We expect the latter to be equal to $v_{\infty}(t) = 100$ for all $t \in [0, 5]$, due to the stationarity of the underlying process.

In Figure 2 we show the theoretical variance $v_M(t)$ for various values of the number of terms M retained in the Karhunen-Loeve expansion. For our simulation we chose $M = 34$. In Figure 3 we compare the variances for the simulated process to the theoretical ones for various values of the number of experiments N . We can visually confirm that for large values of N , the ensemble variance approaches the theoretical function v_M . Similarly, the ensemble average converges to the function $m(t) = 10$ as N increases (Figure 4).

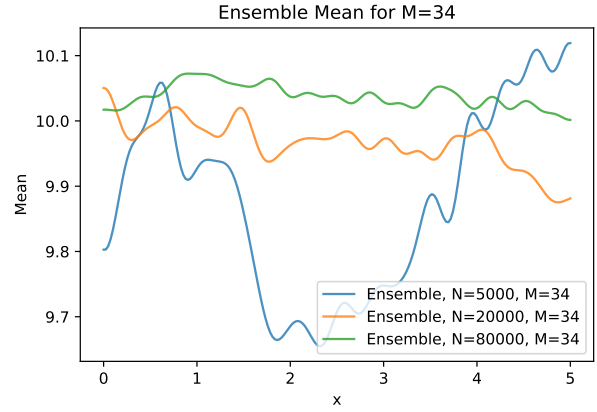


Figure 4. The ensemble mean converges a.s. to $m(t) = 10$ as N increases.

EXERCISE B

To compare the metrics of the simulated process with the theoretical ones, we first need to compute the autocorrelation function R_X using the formula $R_X(\tau) = \int_0^{\infty} G_X(\omega) d\omega$:

$$\begin{aligned} R_X(\tau) &= \int_1^2 (\omega - 1) \cos \omega \tau d\omega + \int_2^3 (3 - \omega) \cos \omega \tau d\omega \\ &= \left[\frac{\cos \omega \tau}{\tau^2} + \frac{\omega \sin \omega \tau}{\tau} \right]_1^2 - \left[\frac{\cos \omega \tau}{\tau^2} + \frac{\omega \sin \omega \tau}{\tau} \right]_2^3 + \\ &\quad + \frac{3}{\tau} [\sin \omega \tau]_2^3 - \frac{1}{\tau} [\sin \omega \tau]_1^2 \\ &= \frac{2 \cos 2\tau}{\tau^2} - \frac{\cos 3\tau}{\tau^2} - \frac{\cos \tau}{\tau^2}. \end{aligned} \quad (10)$$

The process is zero-mean, stationary and its variance is equal to

$$\begin{aligned} \text{Var}[X(t)] &= \lim_{\tau \rightarrow 0} R_X(\tau) \\ &= \lim_{\tau \rightarrow 0} \left(\frac{2 \cos 2\tau}{\tau^2} - \frac{\cos 3\tau}{\tau^2} - \frac{\cos \tau}{\tau^2} \right) \\ &= -4 + \frac{9}{2} + \frac{1}{2} \\ &= 1 \end{aligned} \quad (11)$$

for every $t \in [0, 10]$.

A realization of $X(t, \omega)$ can be written as

$$X(t, \omega) = \sqrt{2} \sum_{n=0}^{\infty} A_n \cos(\omega_n t + \Phi_n(\omega)), \quad (12)$$

where $(\Phi_n)_n$ are i.i.d. standard normal. When simulating such a realization, we may only keep finitely many such terms. As in the previous exercise, one can determine the theoretical ensemble mean and variance using the formula $\tilde{X}(t, \omega) = \sum_{n=0}^M A_n \cos(\omega_n t + \Phi_n(\omega))$. It is easy to see that when $\Phi_n \sim N(0, 1)$, then $\mathbb{E}[\cos(\omega_n t + \Phi_n)] = 0$ and

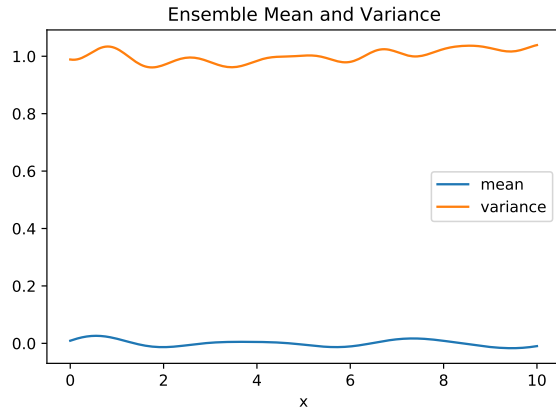


Figure 5. The ensemble mean and variance converge a.s. to $m(t) = 0$ and $v(t) = 1$ respectively as N and M increase. Our simulation was based on $N = 5000$ realizations, each one keeping $M = 500$ terms in the spectral series expansion.

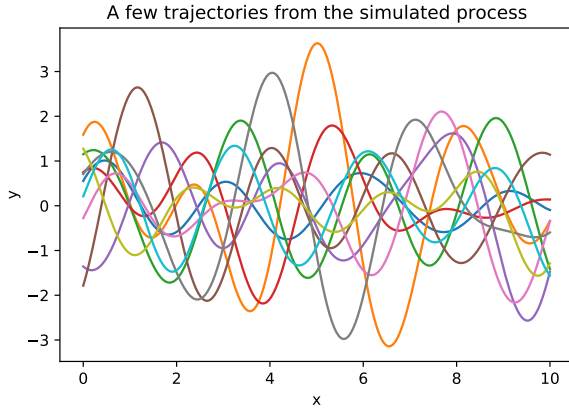


Figure 6. Some simulated trajectories from our process.

$\text{Var}[\cos(\omega_n t + \Phi_n)] = \frac{1}{2}$. By the independence of $(\Phi_n)_n$ we obtain that $\mathbb{E}[X(t)] = 0$ and $\text{Var}[X(t)] = \sum_{n=1}^M A_n^2 = \sum_{n=1}^M G_X(\omega_n) \Delta\omega$. As $M \rightarrow \infty$, the last quantity becomes the Riemman integral of G_X , which is equal to 1, as expected.

By the previous discussion, for large values of N and M^2 , the ensemble average and variance will be close to $m(t) = 0$ and $v(t) = 1$, $t \in [0, 10]$ respectively. This can be confirmed in Figure 5.

The process is also ergodic in the autocorrelation [PG18, p. 7] since it is stationary with

$$\lim_{\tau \rightarrow \infty} R_X(\tau) = \lim_{\tau \rightarrow \infty} \left(\frac{2 \cos 2\tau}{\tau^2} - \frac{\cos 3\tau}{\tau^2} - \frac{\cos \tau}{\tau^2} \right) = 0.$$

This implies that both the temporal average and variance should converge to the corresponding ensemble

²A large M allows for the sum $v_M(t) = \sum_{n=1}^M G_X(\omega_n) \Delta\omega$ to be close to the Riemman integral of G_X , whereas a large N allows for the sample variance to be close to v_M .

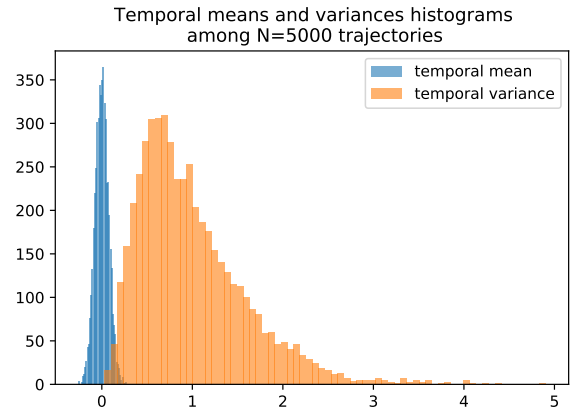


Figure 7. The distribution of the temporal mean and variance for our drawn sample.

ones, namely to $m = 0$ and $v = 1$. We computed the temporal means and variances for each of the $N = 5000$ simulated trajectories and we can see their distribution in Figure 7. Their respective means are $\bar{\mu} = 0.000686$ and $\bar{v} = 0.996004$ which are very close to 0 and 1, as we expected.

REFERENCES

- [AB06] C. ALIPRANTIS, K. BORDER, *Infinite Dimensional Analysis: A Hitchhiker's Guide*, Springer, 3rd ed., 2006. DOI: [10.1007/978-3-662-03004-2](https://doi.org/10.1007/978-3-662-03004-2)
- [LM00] B. LAURENT, P. MASSART, Adaptive estimation of a quadratic functional by model selection, *The Annals of Statistics*, **28** (5), pp. 1302–1338, 2000. DOI: [10.1214/aos/1015957395](https://doi.org/10.1214/aos/1015957395) Cited on p. 1
- [PG18] V. PAPADOPOULOS, D. GIOVANIS, *Stochastic finite element methods*, Springer, 2018. ISBN: [9783319645278](https://www.springer.com/9783319645278) Cited on p. 1, 4

APPENDIX

Exercise A

Importing packages:

```
import numpy as np
import pandas as pd
from scipy import optimize
import scipy.stats as stats
import matplotlib.pyplot as plt
from google.colab import files
from google.colab import drive
import os
```

The two equations which need to be solved so as to compute the ω_n 's:

```
def eq_odd(x, a=2.5, b=2):
    return 1/b - x*np.tan(a*x)

def eq_even(x, a=2.5, b=2):
    return (1/b)*np.tan(a*x) + x
```

The corresponding eigenvalues λ_n 's and the eigenfunctions ϕ_n 's:

```
def lam(w, a=2.5, b=2):
    return 2*b/(1 + w**2 * b**2)

def ell(w, a=2.5):
    return 1/np.sqrt(a - np.sin(2*w*a)/(2*w))

def c(w, a=2.5):
    return 1/np.sqrt(a + np.sin(2*w*a)/(2*w))

def phi_odd(w, t, a=2.5):
    return c(w, a)*np.cos(w*t)

def phi_even(w, t, a=2.5):
    return ell(w, a)*np.sin(w*t)
```

Computes the first n solutions of the previously defined equations:

```
def new_odd_omega(a=2.5, b=2, n=10):
    result = []
    count = 1
    for k in range(1, n):
        result.append(optimize.fsolve(eq_odd,
            (count-0.5)*np.pi/a - 0.1/count))
        result = [float(x) for x in result]
        count = count + 1
    return result

def new_even_omega(a=2.5, b=2, n=10):
    result = []
    count = 1
    for k in range(1, n):
        result.append(optimize.fsolve(eq_even,
            (count-0.5)*np.pi/a + 0.1/count))
        count = count + 1
        result = [float(x) for x in result]
    return result
```

Simulates N trajectories keeping M terms in the KL-expansion:

```
def simulate(a=2.5, b=2, points=200, N=5000, M=17):
    xx = np.linspace(-a, a, points)
    omega_odd = new_odd_omega(a, b, M)
    omega_even = new_even_omega(a, b, M)
    M_odd = len(omega_odd)
    M_even = len(omega_even)
    simulation_results = np.zeros((N, points))
    for j in range(N):
        ran_sample_odd = np.random.normal(size = M_odd)
        ran_sample_even = np.random.normal(size = M_even)
        summand = np.zeros((M_odd, points))
        for i in range(M_odd):
            summand[i, :] = np.sqrt(lam(omega_odd[i]))*
                phi_odd(omega_odd[i], xx)*ran_sample_odd[i]
        my_sum = np.sum(summand, axis = 0)
        summand = np.zeros((M_even, points))
        for k in range(M_even):
            summand[k, :] = np.sqrt(lam(omega_even[k]))*
                phi_even(omega_even[k], xx)*ran_sample_even[k]
        my_sum = my_sum + np.sum(summand, axis = 0)
        simulation_results[j, :] = my_sum
    return(simulation_results)
```

The theoretical ensemble variance:

```
def target_variance(a=2.5, b=2, points=200, M=17):
    xx = np.linspace(-a, a, points)
    omega_odd = new_odd_omega(a, b, M)
    omega_even = new_even_omega(a, b, M)
    M_odd = len(omega_odd)
    M_even = len(omega_even)
    summand = np.zeros((M_odd, len(xx)))
    for i in range(M_odd):
        summand[i, :] = lam(omega_odd[i]) *
            phi_odd(omega_odd[i], xx)**2
    my_sum = np.sum(summand, axis = 0)
    summand2 = np.zeros((M_even, len(xx)))
    for k in range(M_even):
        summand2[k, :] = lam(omega_even[k]) *
            phi_even(omega_even[k], xx)**2
    my_sum = my_sum + np.sum(summand2, axis = 0)
    return my_sum
```

Simulating the trajectories and computing the ensemble variance.

```
bro80k = simulate(N=80000)
bro20k = simulate(N=20000)
bro5k = simulate(N=5000)

mu5k = np.mean(10 + 10*bro5k, axis = 0)
var5k = np.var(10 + 10*bro5k, axis = 0)

mu20k = np.mean(10 + 10*bro20k, axis = 0)
var20k = np.var(10 + 10*bro20k, axis = 0)

mu80k = np.mean(10 + 10*bro80k, axis = 0)
var80k = np.var(10 + 10*bro80k, axis = 0)

x = np.linspace(0, 5, 200)
plt.plot(x, 100*target_variance(M=17),
    label='Theoretical for M=34')
plt.plot(x, var5k, label="Ensemble, N=5000, M=34",
    alpha=0.8)
plt.plot(x, var20k, label="Ensemble, N=20000, M=34",
    alpha=0.8)
plt.plot(x, var80k, label="Ensemble, N=80000, M=34",
    alpha=0.8)
plt.legend()
plt.title('Theoretical vs Ensemble Variance for M=34')
plt.xlabel('x')
plt.ylabel('Variance')
```

Exercise B

```
def f1(w):
    # The first part of the power spectrum.
    return w-1

def f2(w):
    # The second part of the power spectrum.
    return 3-w

def simulation_B(w_u=3, lower=0, upper=10, points=200,
```

```

N=5000, M=100):
# Simulates N trajectories from the process using M terms
# omega_n in its spectral representation.

M2 = int(M/2)
Delta_w = w_u/M
omega = np.linspace(0, 3*(M-1)/M, M)
omega1 = []
omega2 = []
for i in range(len(omega)):
    if (omega[i]<2 and omega[i]>=1):
        omega1.append(omega[i])
    elif (omega[i]>=2 and omega[i]<=3):
        omega2.append(omega[i])
M_omega1 = len(omega1)
M_omega2 = len(omega2)
pp = np.linspace(lower, upper, points)

simulation_results = np.zeros((N, points))
for j in range(N):
    unif1 = np.random.uniform(low=0.0,
    high=2*np.pi, size=M2)
    unif2 = np.random.uniform(low=0.0,
    high=2*np.pi, size=M2)
    summand1 = np.zeros((M2, points))
    for i in range(M_omega1):
        summand1[i,:] = np.sqrt(2) * np.sqrt(f1(omega1[i]) *
        Delta_w) * np.cos(omega1[i]*pp + unif1[i])
    my_sum1 = np.sum(summand1, axis = 0)
    summand2 = np.zeros((M2, points))
    for k in range(M_omega2):
        summand2[k,:] = np.sqrt(2) * np.sqrt(f2(omega2[k]) *
        Delta_w) * np.cos(omega2[k]*pp + unif2[k])
    my_sum2 = np.sum(summand2, axis = 0)
    my_sum = my_sum1 + my_sum2
    simulation_results[j, :] = my_sum
return(simulation_results)

```