

C++部署_fastdeploy

FastDeploy面向AI模型产业落地，帮助开发者简单几步即可完成AI模型在对应硬件上的部署，降低部署难度、压缩部署时间成本。支持40多个主流的AI模型在8大类常见硬件上的部署能力。

参考文档：

```
https://www.paddlepaddle.org.cn/  
https://www.paddlepaddle.org.cn/fastdeploy
```

参考代码：

```
https://github.com/PaddlePaddle/FastDeploy
```

一、工控机基本环境安装

可参考《ubuntu装机》

nvidia驱动安装：

注意：系统重启后可能会出现nvidia驱动出现问题，可能是由于系统内核升级造成的。开发快速解决办法：重新安装驱动。 `sudo ./NVIDIA-Linux-x86_64-525.116.04.run`；部署解决办法：避免系统内核升级，锁定内核版本。

```
cat /proc/version #20.04  
# 显卡：3060  
# 安装nvidia 驱动 https://blog.csdn.net/weixin\_48506823/article/details/123127186  
报错解决办法：  
https://www.cnblogs.com/xiaohuidi/p/14326784.html
```

cuda 安装：

https://blog.csdn.net/weixin_44857882/article/details/124108458

https://blog.csdn.net/weixin_37926734/article/details/123033286

```
wget  
https://developer.download.nvidia.com/compute/cuda/11.6.0/local\_installers/cuda\_11.6.0\_510.39.01\_linux.run  
sudo sh cuda_11.6.0_510.39.01_linux.run  
# continue->accept->取消driver安装后install  
#配置环境变量 gedit ~/.bashrc
```

```
.bashrc
83 alias l='ls -CF'
84
85 # Alias definitions.
86 # You may want to put all your additions into a separate file like
87 # ~/.bash_aliases, instead of adding them here directly.
88 # See /usr/share/doc/bash-doc/examples in the bash-doc package.
89
90 if [ -f ~/.bash_aliases ]; then
91     . ~/.bash_aliases
92 fi
93
94 # enable programmable completion features (you don't need to enable
95 # this, if it's already enabled in /etc/bash.bashrc and /etc/profile
96 # sources /etc/bash.bashrc).
97 #if [ -f /etc/bash_completion ] && ! shopt -oq posix; then
98 #    . /etc/bash_completion
99 #fi
100
101 export MVMCAM_SDK_PATH=/opt/MVS
102
103 export MVMCAM_COMMON_RUNENV=/opt/MVS/lib
104 export LD_LIBRARY_PATH=/opt/MVS/lib/64:/opt/MVS/lib/32 /usr/local/cuda-11.6/-
lib64:$LD_LIBRARY_PATH
105
106 export PATH=/usr/local/cuda-11.6/bin${PATH:+:${PATH}}
107 export LD_LIBRARY_PATH=/home/hayao/fastdeploy-linux-x64-gpu-1.0.4/lib:/home/hayao/fastdeploy-
linux-x64-gpu-1.0.4/third_libs/install/onnxruntime/lib:/home/hayao/fastdeploy-linux-x64-
gpu-1.0.4/third_libs/install/paddle_inference/paddle/lib:/home/hayao/fastdeploy-linux-x64-
gpu-1.0.4/third_libs/install/openvino/runtime/lib:/home/hayao/fastdeploy-linux-x64-gpu-1.0.4/-
third_libs/install/openvino/runtime/3rdparty/omp/lib:/home/hayao/fastdeploy-linux-x64-
gpu-1.0.4/third_libs/install/tensorrt/lib:/home/hayao/fastdeploy-linux-x64-gpu-1.0.4/-
third_libs/install/opencv/lib64:/home/hayao/fastdeploy-linux-x64-gpu-1.0.4/third_libs/install/-
fast_tokenizer/lib:/home/hayao/fastdeploy-linux-x64-gpu-1.0.4/third_libs/install/paddle2onnx/-
lib:/home/hayao/conda/lib/python3.10/site-packages/torch/lib${LD_LIBRARY_PATH:+:$
{LD_LIBRARY_PATH}}
108
109
```

cuda安装:

<https://developer.nvidia.com/rdp/cudnn-download> 官网注册账号下载对应版本 (cuda11.*)

解压安装:

```
cp lib/* /usr/local/cuda-11.6/lib64/
cp include/* /usr/local/cuda-11.6/include/
```

python 环境安装:

```

apt update

apt install build-essential zlib1g-dev libncurses5-dev libgdbm-dev libnss3-dev
libssl-dev libreadline-dev libffi-dev libsqlite3-dev wget libbz2-dev

wget https://www.python.org/ftp/python/3.10.8/Python-3.10.8.tgz
tar -xf Python-3.10.*.tgz
cd Python-3.10.*/

./configure --enable-optimizations --prefix=/usr/local/python

make -j8
make install

```

PyTorch安装:

```

apt install python3-pip
# CUDA 11.6 python_base:3.8
pip3 install torch==1.12.1+cu116 torchvision==0.13.1+cu116 torchaudio==0.12.1 --
extra-index-url https://download.pytorch.org/whl/cu116

```

yolov5 测试显卡调用:

```

git clone https://github.com/ultralytics/yolov5

# -i https://pypi.tuna.tsinghua.edu.cn/simple
pip install -r requirements.txt

python3 detect.py --weights yolov5s.pt --source data/images/bus.jpg --device 0

```

Cmake 安装:

```

# https://cmake.org/download/
wget https://github.com/Kitware/CMake/releases/download/v3.25.3/cmake-3.25.3.tar.gz

tar -zxvf cmake-3.25.3.tar.gz

apt install g++
apt install build-essential
apt install libssl-dev

cd cmake-3.25.3
./bootstrap

make -j8
make install

```

opencv安装配置:

```
apt-get install build-essential

# libgtk2.0-dev 失败
apt-get install libgtk2.0-dev pkg-config libavcodec-dev libavformat-dev libswscale-dev

apt-get install python-dev python-numpy libtbb2 libtbb-dev libjpeg-dev libpng-dev libtiff-dev libdc1394-22-dev

wget -O opencv-4.6.0.zip
https://github.com/opencv/opencv/archive/refs/tags/4.6.0.zip

cd opencv-4.6.0

mkdir -p build && cd build
cmake ..
make -j8
make install
```

spdlog 和 nlohmann:

```
git clone https://github.com/gabime/spdlog.git
cd spdlog && mkdir build && cd build
cmake ..
make
make install

git clone https://github.com/nlohmann/json.git
mkdir build && cd build
cmake ..
make
make install
```

fastdeploy:

```
wget https://bj.bcebos.com/fastdeploy/release/cpp/fastdeploy-linux-x64-gpu-1.0.4.tgz
tar xvf fastdeploy-linux-x64-gpu-1.0.4.tgz
# 不需要编译
# c++ 推理代码: cpp_info
mkdir build
cd build
cmake ..
make

./infer_demo /home/hayao/hayao_algo/config_source /home/hayao/hayao_algo/images # 报错: error while loading shared libraries: libonnxruntime.so.1.12.0: cannot open shared object file: No such file or directory
```

```
source /root/fastdeploy-linux-x64-gpu-1.0.4/fastdeploy_init.sh 再执行, 报错
libcudart.so.11.0: cannot open shared object file: No such file or directory
```

解决 在 ~/.bashrc 中添加环境变量 再 source

```
export LD_LIBRARY_PATH=/home/hayao/fastdeploy-linux-x64-gpu-
1.0.4/lib:/home/hayao/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/onnxruntime/lib:/home/hayao/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/paddle_inference/paddle/lib:/home/hayao/fastdeploy-linux-
x64-gpu-1.0.4/third_libs/install/opencvino/runtime/lib:/home/hayao/fastdeploy-linux-
x64-gpu-
1.0.4/third_libs/install/opencvino/runtime/3rdparty/omp/lib:/home/hayao/fastdeploy-
linux-x64-gpu-1.0.4/third_libs/install/tensorrt/lib:/home/hayao/fastdeploy-linux-
x64-gpu-1.0.4/third_libs/install/opencv/lib64:/home/hayao/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/fast_tokenizer/lib:/home/hayao/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/paddle2onnx/lib:/home/hayao/conda/lib/python3.10/site-
packages/torch/lib
```

测试:

```
./infer_demo /home/hayao/hayao_algo/config_source /home/hayao/hayao_algo/images--
[ok]
```

二、yolov5服务器环境配置【容器】

服务器yolov5开发容器环境 <https://hub.docker.com/r/ultralytics/yolov5/tags>

```
docker pull ultralytics/yolov5:latest
```

```
docker run -dit --name hayao -p 5322:22 -p 5330-5399:5330-5399 -v
/etc/localtime:/etc/localtime -v /etc/machine-id:/etc/machine-id -v
/data01/hayao:/tmp/project -v /dev/shm:/dev/shm --gpus all --privileged
ultralytics/yolov5:latest /bin/bash
```

测试 python 3.10

```
python detect.py --weights yolov5s.pt --source data/images/bus.jpg --device 0
找不到有效gpu
```

```
pip uninstall torch*
```

<https://pytorch.org/get-started/previous-versions/>

#如果速度慢, 考虑换源

```
conda config --add channels https://mirrors.ustc.edu.cn/anaconda/pkgsg/free/
```

```
conda config --add channels https://mirrors.ustc.edu.cn/anaconda/pkgsg/main/
```

#下面两个非常重要, 从清华源下载速度非一般

```
conda config --add channels
```

```
https://mirrors.tuna.tsinghua.edu.cn/anaconda/cloud/pytorch/
```

```
conda config --add channels
```

```
https://mirrors.tuna.tsinghua.edu.cn/anaconda/cloud/conda-forge/
```

#查看是否添加成功

```
conda config --show-sources
```

```

conda install pytorch==1.12.1 torchvision==0.13.1 torchaudio==0.12.1
cudatoolkit=10.2 -c pytorch # 失败 docker run 加上 --gpus all 重试 OK

# 安装yolov5
git clone https://github.com/ultralytics/yolov5

# 环境包安装
pip install -r requirements.txt

# 测试成功
python detect.py --weights yolov5s.pt --source data/images/bus.jpg --device 0

#使用vscode远程连接docker开发

# 宿主机与docker数据传输：创建docker时挂载目录，同步 /data01/hayao:/tmp/project

# 数据集配置 wood_test.yaml
# 模型配置 wood_yolov5s.yaml
# 训练 https://github.com/wudashuo/yolov5
python train.py --data data/wood_test.yaml --cfg models/wood_yolov5s.yaml --weight
pretrained/yolov5s.pt --epochs 50 --batch-size 16 --device 2,3
# 训练结果保存目录 ./runs/train/exp
python train.py --data data/hayao.yaml --cfg models/hayao_yolov5s.yaml --weight
pretrained/yolov5s.pt --epochs 100 --batch-size 16 --device 2,3
# 训练结果保存目录 ./runs/train/exp2

# 训练结果测试
python detect.py --weights /root/yolov5/runs/train/exp/weights/best.pt --source
/tmp/project/getech/yolov5_test/data/images/test/00342.jpg --device 0
# 测试结果保存目录： ./runs/detect/exp2
python detect.py --weights /root/yolov5/runs/train/exp2/weights/best.pt --source
/tmp/project/demo_data/dataset/images/val/Image_20230310173745647.bmp --device 0
# 测试结果保存目录： ./runs/detect/exp3

# 导出onnx 参数opset改为12
python export.py --data data/wood_test.yaml --weights runs/train/exp/weights/best.pt
--include onnx --device 0

python export.py --data data/hayao.yaml --weights runs/train/exp2/weights/best.pt --
include onnx --device 0

/root/yolov5/runs/train/exp2/weights/best.onnx

```

三、服务器Fastdeploy部署环境【容器】

<https://github.com/PaddlePaddle/FastDeploy/tree/develop/examples/vision/detection/yolov5>

```
docker run -dit --name yolov5_deploy -p 8322:22 -p 8330-8399:8330-8399 -v
/etc/localtime:/etc/localtime -v /etc/machine-id:/etc/machine-id -v
/data01/hayao:/tmp/project -v /dev/shm:/dev/shm --gpus all --privileged
ultralytics/yolov5:latest /bin/bash

# 训练： 指标误检较高
python train.py --data data/hayao.yaml --cfg models/hayao_yolov5s.yaml --weight
pretrained/yolov5s.pt --epochs 100 --batch-size 16 --device 2,3

# 转onnx
python export.py --data data/hayao.yaml --weights runs/train/exp/weights/best.pt --
include onnx --device 0

# 测试 Image_20230310171432581
python detect.py --weights /root/yolov5/runs/train/exp/weights/best.pt --source
/tmp/project/demo_data/dataset/images/val/Image_20230310171432581.bmp --device 0
```

- YOLOv5 v7.0部署模型实现来自 YOLOv5 和基于COCO的预训练模型
 - (1) [官方库](#)提供的*.onnx可直接进行部署；
 - (2) 开发者基于自己数据训练的YOLOv5 v7.0模型，可使用[YOLOv5](#)中的 `export.py` 导出ONNX文件后，完成部署。

1、C++ GPU部署环境：

环境要求：

- CUDA >= 11.2
- cuDNN >= 8.0
- python >= 3.6
- OS: Linux(x64)/Windows 10(x64)

在工控机 (30系显卡) 测试 (也可以在2080服务器测试 (yolov5_deploy))：

```
docker run -dit --name yolov5_deploy -p 8322:22 -p 8330-8399:8330-8399 -v
/etc/localtime:/etc/localtime -v /etc/machine-id:/etc/machine-id -v
/home/wood:/tmp/project -v /dev/shm:/dev/shm --gpus all --privileged
ultralytics/yolov5:latest /bin/bash

# 直接使用原有环境：CUDA11.3 PyTorch 1.13.1 torchvision 0.14.1
# 安装yolov5
git clone https://github.com/ultralytics/yolov5

# 环境包安装
pip install -r requirements.txt

# 测试成功
python detect.py --weights yolov5s.pt --source data/images/bus.jpg --device 0
```

```

# 训练
python train.py --data data/hayao.yaml --cfg models/hayao_yolov5s.yaml --weight
pretrained/yolov5s.pt --epochs 100 --batch-size 16 --device 2,3

# 测试
python detect.py --weights /root/yolov5/runs/train/exp/weights/best.pt --source
/tmp/project/demo_data/dataset/images/val/Image_20230310171432581.bmp --device 0

# 转onnx
python export.py --data data/hayao.yaml --weights runs/train/exp/weights/best.pt --
include onnx --device 0

```

C++ SDK 安装:

```

wget https://bj.bcebos.com/fastdeploy/release/cpp/fastdeploy-linux-x64-gpu-1.0.4.tgz
tar xvf fastdeploy-linux-x64-gpu-1.0.4.tgz
# 先安装Cmake
# c++ 推理代码: cpp_info
mkdir build
cd build
cmake ..
make # 报错 fatal error: cuda_runtime_api.h: No such file or directory 常规/usr/local
下找不到, 这是镜像的问题, docker inspect ultralytics/yolov5:latest 查看
# 尝试重新安装 conda install pytorch==1.12.1 torchvision==0.13.1 torchaudio==0.12.1
cudatoolkit=11.6 -c pytorch -c conda-forge 还是不行
find -name cuda_runtime_api.h # ./opt/conda/include/cuda_runtime_api.h
# CMakeLists.txt 添加 include_directories(/opt/conda/include)
link_directories(/opt/conda/lib)
link_directories(/opt/conda/lib/python3.10/site-packages/torch/lib)

./infer_demo best.onnx Image_20230310171432581.bmp 1 # 报错: error while loading
shared libraries: libonnxruntime.so.1.12.0: cannot open shared object file: No such
file or directory
source /root/fastdeploy-linux-x64-gpu-1.0.4/fastdeploy_init.sh 再执行, 还是报错
libcudart.so.11.0: cannot open shared object file: No such file or directory

# 尝试解决 在 ~/.bashrc 中添加环境变量 再source
export LD_LIBRARY_PATH=/opt/conda/lib:/root/fastdeploy-linux-x64-gpu-
1.0.4/lib:/root/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/onnxruntime/lib:/root/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/paddle_inference/paddle/lib:/root/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/opencv/lib:/root/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/opencv/lib64:/root/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/tensorrt/lib:/root/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/fast_tokenizer/lib:/root/fastdeploy-linux-x64-gpu-
1.0.4/third_libs/install/paddle2onnx/lib:/opt/conda/lib/python3.10/site-
packages/torch/lib

# 测试:
./infer_demo best.onnx Image_20230310171432581.bmp 1 OK品
./infer_demo best.onnx Image_20230310170404244.bmp 1 NG品

```


Cmake 安装:

```
# https://cmake.org/download/
wget https://github.com/Kitware/CMake/releases/download/v3.25.3/cmake-3.25.3.tar.gz

tar -zxvf cmake-3.25.3.tar.gz

apt install g++
apt install build-essential
apt install libssl-dev

cd cmake-3.24.1
./bootstrap

make -j8
make install
```

Opencv配置:

参考 https://blog.csdn.net/qg_51022848/article/details/128095476

```
apt-get install build-essential
apt-get install libgtk2.0-dev pkg-config libavcodec-dev libavformat-dev libswscale-dev
apt-get install python-dev python-numpy libtbb2 libtbb-dev libjpeg-dev libpng-dev libtiff-dev libdc1394-22-dev

wget -O opencv-4.6.0.zip
https://github.com/opencv/opencv/archive/refs/tags/4.6.0.zip

wget -O opencv_contrib-4.6.0.zip
https://github.com/opencv/opencv_contrib/archive/refs/tags/4.6.0.zip

cp -r opencv_contrib-4.6.0 ./opencv-4.6.0

cd opencv-4.6.0
mkdir -p build && cd build

cmake -DCMAKE_BUILD_TYPE=Release -DOPENCV_GENERATE_PKGCONFIG=ON -
DCMAKE_INSTALL_PREFIX=/usr/local OPENCV_EXTRA_MODULES_PATH=./opencv_contrib-
4.6.0/modules .. # 编译失败

# 先只编译opencv
mkdir -p build && cd build
cmake ..
# 报错:
runtime library [libpng16.so.16] in /usr/lib/x86_64-linux-gnu may be hidden by
files in:
/opt/conda/lib
```

```
runtime library [libz.so.1] in /usr/lib/x86_64-linux-gnu may be hidden by files
in:
/opt/conda/lib
runtime library [libtiff.so.5] in /usr/lib/x86_64-linux-gnu may be hidden by
files in:
/opt/conda/lib
# mv /opt/conda/lib 冲突

make -j32
make install
```

spdlog/spdlog.h 配置:

```
git clone https://github.com/gabime/spdlog.git
cd spdlog && mkdir build && cd build
cmake ..
make
make install

# nlohmann json
# 用法: https://github.com/nlohmann/json
# https://blog.csdn.net/gdizcm/article/details/121280329
git clone https://github.com/nlohmann/json.git
mkdir build && cd build
cmake ..
make
make install
```

java环境配置:

```
# jdk存放目录
/usr/local/java/jdk1.8.0_202

# 环境变量
vim /etc/profile 或者 vim ~/.bashrc
export JAVA_HOME=/usr/local/java/jdk1.8.0_202
export JRE_HOME=${JAVA_HOME}/jre
export CLASSPATH=.:${JAVA_HOME}/lib:${JRE_HOME}/lib
export PATH=${JAVA_HOME}/bin:$PATH

# 测试 java -version
```

常见国内镜像源:

清华: <https://pypi.tuna.tsinghua.edu.cn/simple>

阿里云: <http://mirrors.aliyun.com/pypi/simple/>

中国科技大学 <https://pypi.mirrors.ustc.edu.cn/simple/>

华中理工大学: <http://pypi.hustunique.com/>

山东理工大学: <http://pypi.sdutlinux.org/>

豆瓣: <http://pypi.douban.com/simple/>

2、C++ CPU部署环境:

环境要求:

- python >= 3.6
- OS: Linux(x64/aarch64)/Windows 10 x64/Mac OSX(x86/aarm64)

(可在T4服务器 yolov5_deploy容器测试)

四、接口调用方式

示例: jni 调用 c++ 接口调试 bull_vic->common_demo->paddle fastdeploy部署方式

```
# jbytearray 转 cvMat: https://www.saoniuhuo.com/question/detail-2440173.html
```

1、c++ -> jni调用方式

算法设计完成后, 需要生成动态链接库提供给系统使用, 接口设计参考如下:

算法需要提供:

- 推理使用的模型;
- 推理使用的配置文件;
- 推理额外参数;

推理类提供模型测试和推理接口, 系统端根据算法人员提供的配置文件信息, 实例化推理类。推理只有一个方法,

推理类说明:

c++ 头文件(inference.h)如下:

```
#ifndef _Included_inference_h
#define _Included_inference_h

#include "tracv_infer.h"
#include "det_infer.h"
#include "cls_infer.h"
#include "reg_infer.h"

class Inference
{
public:
    Inference(const string &config_dir);
    json run(std::vector<cv::Mat> & src_imgs, string &extra_info);
    ~Inference();

private:
    TracvInfer * tracv_inf = nullptr;
    DetInfer * det_inf = nullptr;
    ClsInfer * cls_inf = nullptr;
    RegInfer * reg_inf = nullptr;
};

#endif
```

构造函数参数说明:

```
Inference(const string &config_dir);
```

config_dir: 推理使用的配置文件目录。-- 算法人员提供配置文件的时候需要指明配置文件在config_dir目录下如何存放, 是否有特殊子目录。配置文件可能是json或者yaml文件, 里面包含如模型路径、过滤参数、产品规格信息等。例如以下路径:

```
/** 构造函数: json/yaml文件目录
- config_dir
--- traditioncv
----- inference.json
--- classification
----- inference.yaml
--- detection
----- inference.yaml
...
*/
```

启动推理函数参数说明：

```
json run(std::vector<cv::Mat> & src_imgs, string &extra_info);
```

src_imgs: 图片数组。

extra_info: 推理参数字典, 如果需要特殊参数需要和系统商量, 让系统将参数填入extra_info中, 否则系统传一个空字符串。

算法返回值：

算法返回值需要按照json格式返回, 按照传输的图片顺序返回图片信息。

coord: 推理结果位置信息, 不同算法 (如分类/目标检测/分割/传统cv测量不一致, 此处需要项目中算法与系统对接)。

conf: 置信度信息。

label: 返回标签信息, 比如具体缺陷名称。

status: 状态信息, 正常推理算法返回为 "OK"; 如果推理异常算法返回为 "NG"。

```
[
  [""], //第一张图结果, 表示为无缺陷。
  [{
    "conf": 0.9462416768074036,
    "coord": {
      "x_max": 1009,
      "x_min": 595,
      "y_max": 894,
      "y_min": 537
    },
    "label": "stomium",
    "status": "OK"
  }, {
    "conf": 0.85,
    "coord": {
      "x_max": 2005,
      "x_min": 564,
      "y_max": 869,
      "y_min": 452
    },
    "label": "abnormal_ob",
    "status": "OK"
  }, {
    ...
  }
], //第二张图结果, {}里面包含图里面缺陷名信息label, 得分信息conf, 位置信息coord, 状态信息
status, 默认为OK
  ...
]
```

2、jni C++代码封装

```
#include "cn_getech_poros_algorithm_NativeFunction.h"
#include "inference.h"
#include "logger.h"
#include <algorithm>
#include <string>
#include <iostream>

//Inference类的实例化：完成模型初始化
extern "C" JNIEXPORT jlong JNICALL
Java_cn_getech_poros_algorithm_NativeFunction_init(
    JNIEnv *env, jobject thiz, jstring j_model_dir) {
    //...
    //...
    return reinterpret_cast<jlong>(infer);
}

//调用Inference类的run()方法对图片推理
extern "C" JNIEXPORT jstring JNICALL
Java_cn_getech_poros_algorithm_NativeFunction_forward(
    JNIEnv *env, jobject thiz, jlong java_pointer, jbyteArray data, jint jw, jint
jh, jint jc) {
    //...
    //...
    return cpp_string_to_jstring(env, str);
}

//内存释放
extern "C" JNIEXPORT void JNICALL
Java_cn_getech_poros_algorithm_NativeFunction_release(
    JNIEnv *env, jobject thiz, jlong java_pointer) {
    if (java_pointer == 0) {
        return;
    }
    Inference *ppredictor =
        (Inference *)java_pointer;
    delete ppredictor;
}
```

3、镜像与调试代码

镜像位置：服务器

镜像名称：common_algo

容器启动example(以下为示例，注意名字，端口，挂载路径)：

```
docker run -dit --name commom_algo_inf -p 5322:22 -p 5330-5399:5330-5399 -v  
/etc/localtime:/etc/localtime -v /etc/machine-id:/etc/machine-id -v  
/home/wood:/tmp/project -v /dev/shm:/dev/shm --gpus all --privileged  
common_algo:latest /bin/bash
```

可自己启动一个新容器，也可直接在 commom_algo_inf 容器中测试代码：

```
# 例子参考：fastdeploy方式部署yolov5 v7.0  
/root/cpp_inf/common_algo
```