

Circuit Theory and Electronics Fundamentals

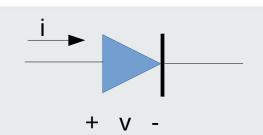
Lecture 12: Non-Linear Components: piecewise linear and incremental models

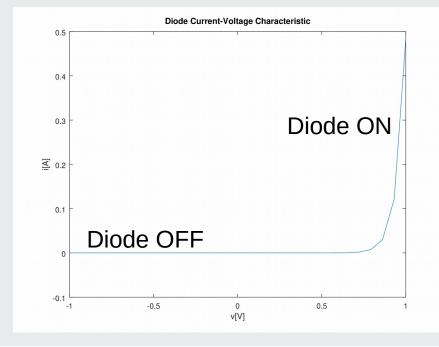
- Ideal diode model
- Voltage source diode model
- Voltage source plus resistor diode model
- Piecewise linear diode model
- Incremental analysis
- Incremental diode model
- Exercise

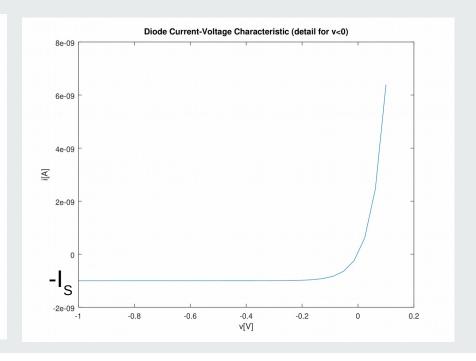


Diode I-V Plots

$$i=I_S(e^{\frac{v}{\eta V_T}}-1)$$
 $I_S=1nA$
 $\eta=2$ (Silicon)

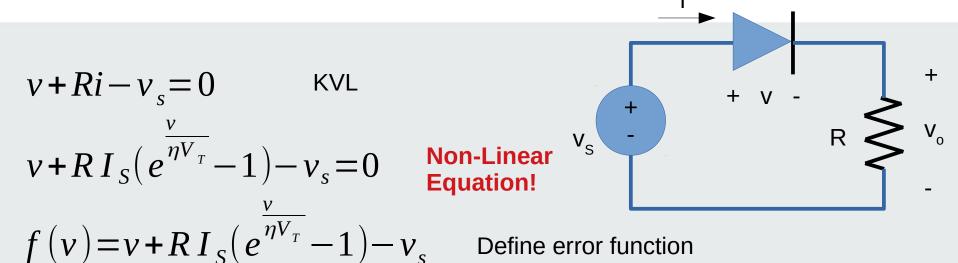








Example diode circuit



$$f(v)=0$$

$$x_{n+1}=x_n-\frac{f(x_n)}{f'(x_n)}$$

$$|x_{n+1}-x_n|<\delta$$

Solve non-linear equation for v

Use Newton Raphson's iterative method

Stop condition: δ is the desired error

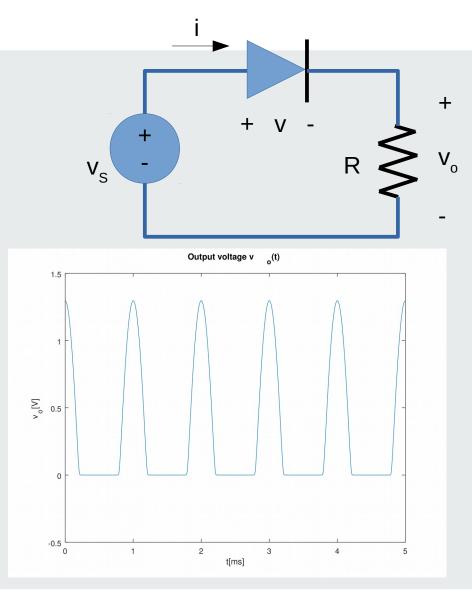


Example diode circuit solution

$$\begin{split} &v_s(t) \!=\! 2\cos\left(2\,\pi f\,t\right)\\ &I_S \!=\! 1\,nA\\ &R \!=\! 1\,k\,\Omega\\ &f \!=\! 1\,kHz\\ &v_o \!=\! v_s \!-\! v\,; v_o \!=\! 0\\ &i \!=\! \frac{v_o}{R}; i \!=\! 0 \end{split} \tag{ON; OFF)}$$

Octave script l11.m solves 1 non-linear equation for v, for each time instant t

HALF WAVE RECTIFIER CIRCUIT

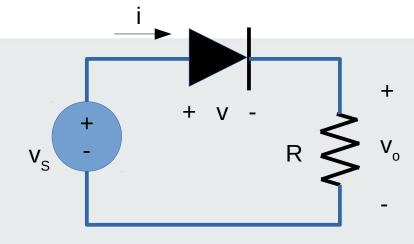


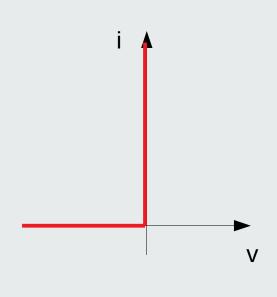


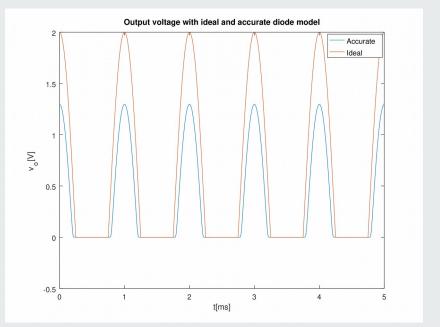
Ideal diode model

$$\begin{cases} i=0, & v<0 \\ v=0, & i\geq 0 \end{cases}$$

$$\begin{cases} v_o = 0, & v_s < 0 \\ v_o = v_s, & v_s \ge 0 \end{cases}$$





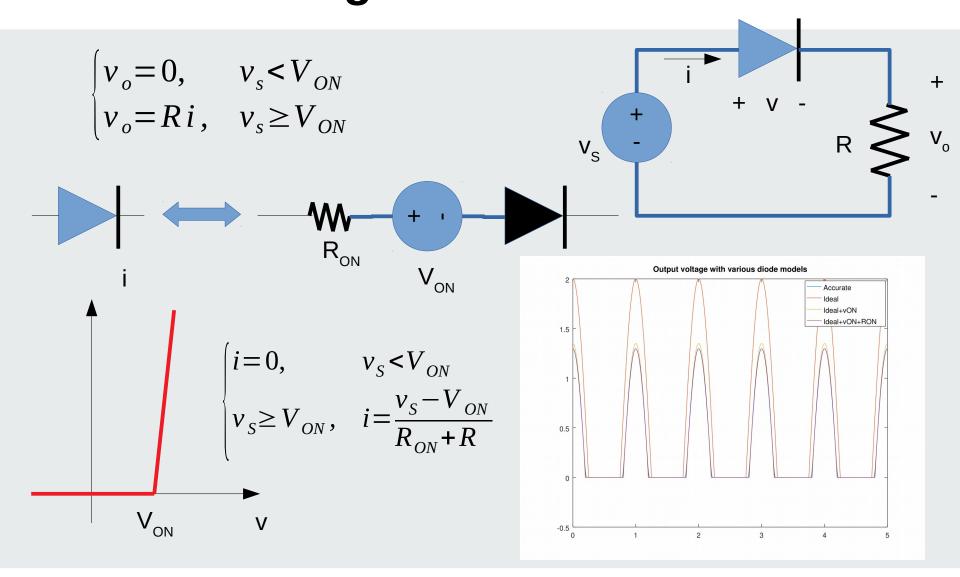




Diode model with ideal diode+voltage source

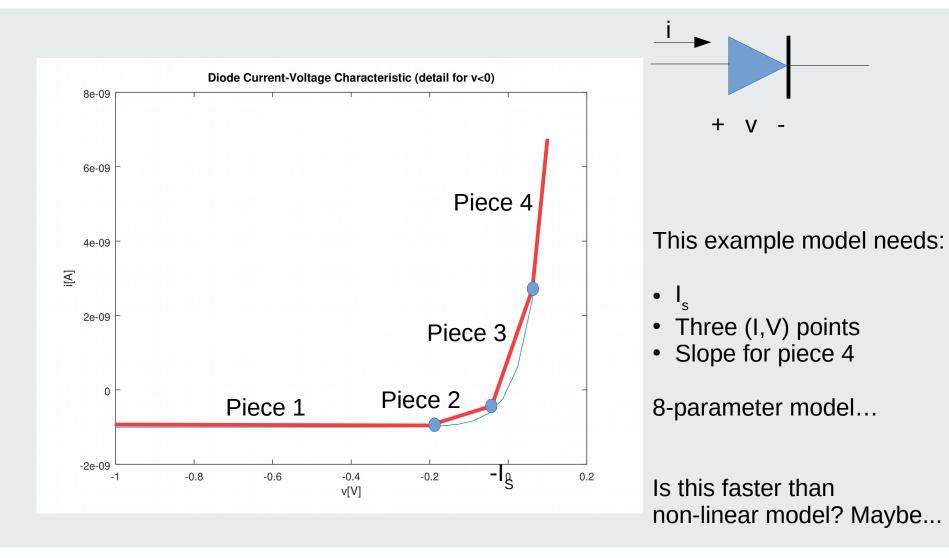


Diode model with ideal diode + voltage source + resistor





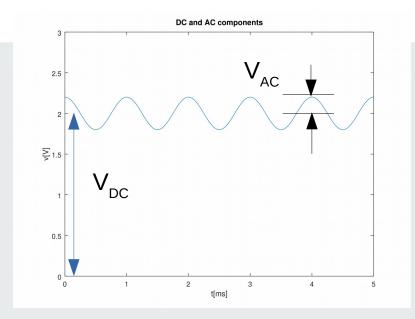
Piece-Wise Linear Diode Model





Incremental Analysis

- In many practical situations, the input voltage has a DC component and an AC component
- The DC component dictates the circuit operating point
- The AC component contains the energy or information (the message) delivered
- If the DC component has no information, only the AC component needs to be analysed
- If the amplitude of the AC component is small, the distortion caused by nonlinear components such as diodes is small ...
- This is incremental analysis

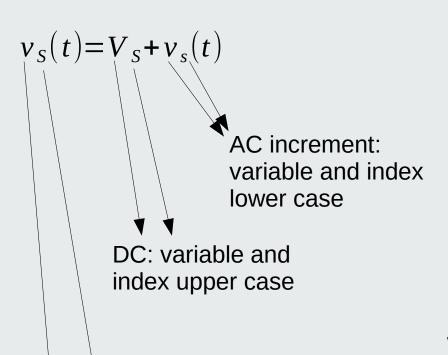


$$\begin{aligned} v_S(t) &= V_{DC} + V_{AC} \cos(2 \, \pi f \, t) \\ v_S(t) &= V_{DC} \cos(0 \, t) + V_{AC} \cos(2 \, \pi f \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{AC} \cos(2 \, \pi f \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{AC} \cos(2 \, \pi f \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{AC} \cos(2 \, \pi f \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{AC} \cos(2 \, \pi f \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{AC} \cos(2 \, \pi f \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) + V_{DC} \cos(0 \, t) \\ V_{DC} &= V_{DC}$$

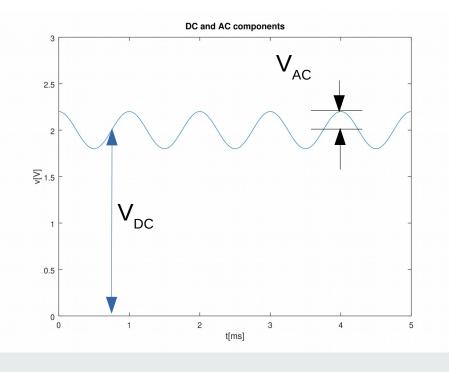


Incremental Analysis Notation





Total DC+increment: variable lower case and index upper case



$$v_s = \Delta v_s$$

 v_s is considered an infinitesimal increment in incremental analysis.

DC and incremental components be analysed separately!



Operating point

$$\begin{aligned} & v_D \! + \! R i_D \! - \! v_s \! = \! 0 & \text{KVL} \\ & \left(V_D \! + \! v_d \right) \! + \! R \left(I_D \! + \! i_d \right) \! - \! \left(V_S \! + \! v_s \right) \! = \! 0 \\ & \left(V_D \! + \! R \, I_D \! - \! V_S \right) \! + \! \left(\! v_d \! + \! R \, i_d \! - \! v_s \! \right) \! = \! 0 \end{aligned} \quad \text{S}$$

Separate DC and increments

$$v_s = 0 \Rightarrow v_d = 0$$
, $i_d = 0$ The cause of variations is $v_s = 0 \Rightarrow v_d = 0$ DC or operating point analysis

Solve non-linear equation to get V_D and I_D (DC values)

+

+

V_D

R

V_O

-



Diode incremental model

$$i_{D}(v_{D}) = I_{S}(e^{\frac{v_{D}}{\eta V_{T}}} - 1)$$

Diode equation

Taylor series expansion

$$i_D(V_D + v_d) = i_D(V_D) + \frac{1}{1!} \frac{di_D}{dv_D}(V_D) v_d + \frac{1}{2!} \frac{d^2 i_D}{dv_D^2}(V_D) v_d^2 + \dots$$

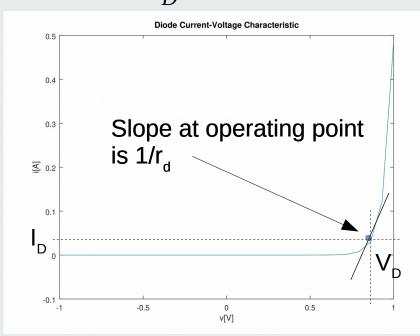
First order approximation for small v_d signal

$$I_D + i_d \approx I_D + \frac{di_D}{dv_D} (V_D) v_d$$

$$i_d \approx \frac{V_d}{r_d}$$
 The diode incremental model is approximately a resistor!

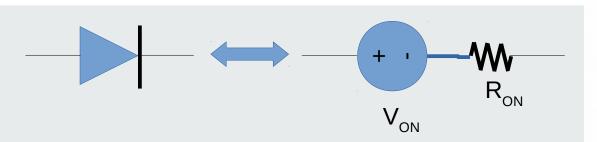
$$r_d = \frac{dv_D}{di_D} (V_D)$$

The diode incremental resistor

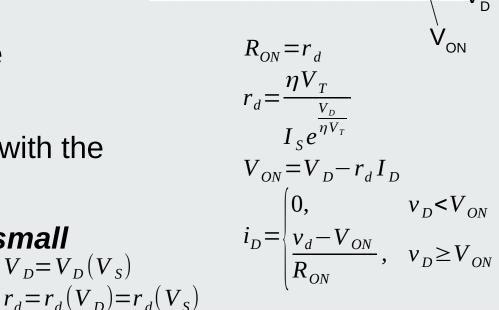




Diode complete model at given operating point



- Attention: model only valid for given operating point!
- DC voltage V_D varies with the operating point $(V_D, I_D)!$
- Incremental resistor r_d varies with the operating point!
- Model only valid for OP and **small** variations around it! $V_D = V_D$



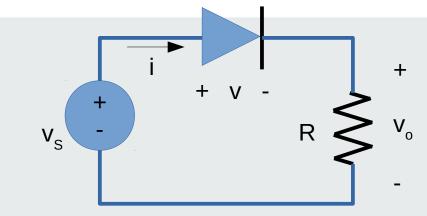
Slope at OP is 1/r_d



Exercise: operating point and incremental analysis

$$v_s(t)=2+A\cos(2\pi f t)$$

 $I_S=1nA$
 $R=1k\Omega$
 $f=1kHz$

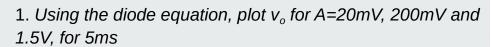


- 1. Using the diode equation, plot v_0 for A=20mV, 200mV and 1.5V, for 5ms
- 2. Using incremental analysis, plot v_0 for A=20mV, 200mV and 1.5V
- 3. Compare the plots of 1. and 2.



Exercise resolution (1)

$$v_s(t)=2+A\cos(2\pi f t)$$
 $I_S=1nA$
 $R=1k\Omega$
 $f=1kHz$

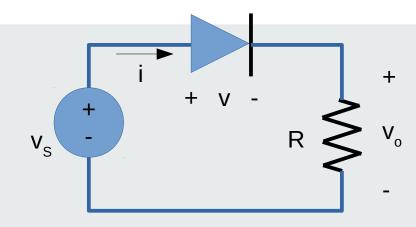


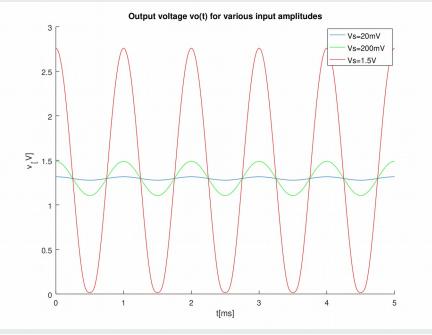
The diode equation was taught in Lecture 11. Using the same Octave functions, the $v_{\rm o}$ is plotted for the 3 values of A (see Octave script l12_exercise.m)

For A=1.5V the distortion is visible (maxima sharper than minima)

For A=200mV distortion is not visible but it is there. Spectral analysis would reveal it.

For A=20mV the distortion is very low and the waveform is almost a pure tone.







TÉCNICO Exercise resolution (2)

$$v_s(t)=2+A\cos(2\pi f t)$$

 $I_S=1nA, R=1k\Omega, f=1kHz$

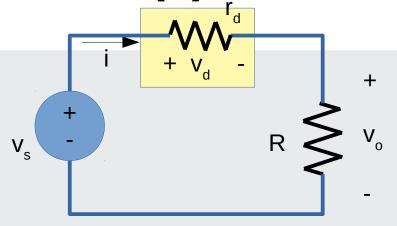
$$v_o = \frac{R}{R + r_d} v_s$$

Incremental output voltage

$$V_O = RI_D$$

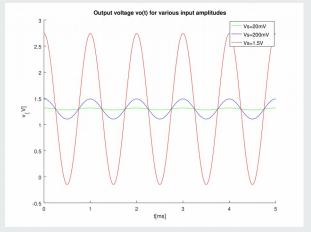
 $v_0 = V_0 + v_0$

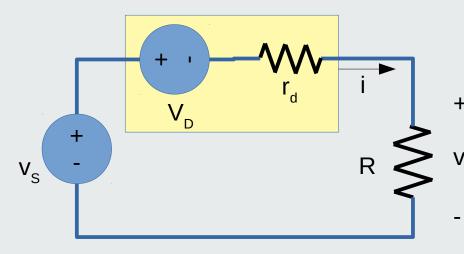
 $V_O = RI_D$ DC output voltage



Incremental circuit model: LINEAR!

Total output voltage

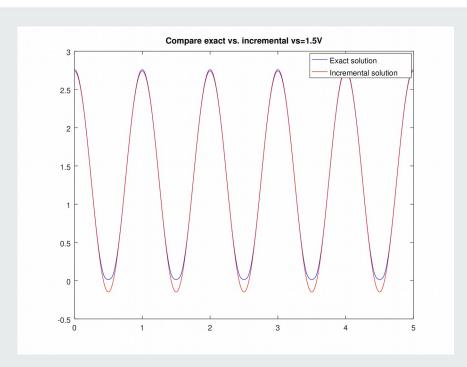


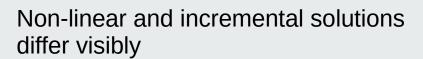


Complete circuit model via incremental analysis: LINEAR!

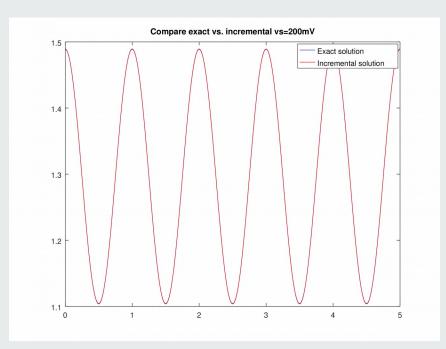


Exercise resolution (3)





Incremental solution bad for large signals!



Exact and incremental solutions differ little

Incremental solution good for small signals!

Even better for v_s=20mV though not shown



Conclusion

- Ideal diode model
- Voltage source diode model
- Voltage source plus resistor diode model
- Piecewise linear diode model
- Incremental diode model
- Exercise