# **COMPSCI 371D Homework 6**

## Part 1: Automatic Differentiation

#### **Automatic Differentiation Basics**

```
In [1]: names = {}
        def reset auto diff(name=None):
            global names
            if name is None:
                names = {}
            else:
                _names.pop(name, None)
In [2]: class Node:
            def __init__(self, value, gradient=None, name=None, variables=None):
                self.value = value
                self.gradient = gradient
                self.name = name
                self.variables = variables
In [3]: class Internal(Node):
            def init (self, value, gradient, variables):
                super(Internal, self).__init__(value, gradient=gradient, name=None,
                                               variables=variables)
            def str (self):
                grad string = 'Gradient wrt {}:\n{}'.format(self.variables, self.gradient)
                return '{}\n{}'.format(self.value, grad_string)
In [4]: class Variable(Node):
            def __init__(self, value, name):
                assert name not in _names, 'Different independent variables must have diffe
        rent name'
                assert isinstance(value, int) or isinstance(value, float), 'Variables must
        be scalars'
                value = float(value)
                names[name] = name
                gradient = [1.0]
                super(Variable, self). init (value, gradient=gradient, name=name, variabl
        es=[name])
            def __str__(self):
                return '{}:\n{}'.format(self.name, self.value)
In [5]: def print variables(*args, **keywords):
                print(keywords['title'])
            except KeyError:
                pass
            print(*args, sep='\n\n', end='\n\n')
```

```
In [6]: def scale_list(sequence, factor):
    return [factor * item in sequence]
```

### A Botched Implementation of times

```
In [7]: def bad times(a, b):
           assert isinstance(a, Node) and isinstance(b, Node)
            value = a.value * b.value
            a_gradient = scale_list(a.gradient, b.value)
            b_gradient = scale_list(b.gradient, a.value)
            # The following two + are list concatenation operators
            gradient = a_gradient + b_gradient
            variables = a.variables + b.variables
            return Internal(value, gradient, variables)
In [8]: reset_auto_diff()
        u = Variable(2.0, 'u')
        v = Variable(4.0, 'v')
        print variables(u, v)
        p = bad_times(u, v)
        print_variables(p, title='product')
        s = bad times(u, u)
        print_variables(s, title='square')
        u:
        2.0
        v:
        4.0
        product
        8.0
        Gradient wrt ['u', 'v']:
        [4.0, 2.0]
        square
        4.0
        Gradient wrt ['u', 'u']:
        [2.0, 2.0]
```

### Problem 1.1

### **Solution**

```
In [9]: def merge(*partials):
             derivatives = {}
             for p in partials:
                 values = p[0]
                 keys = p[1]
                 for i in range(len(keys)):
                     v = values[i]
                     k = keys[i]
                     if k in derivatives.keys():
                         v = v + derivatives[k]
                     derivatives.update({k: v})
             return list(derivatives.values()), list(derivatives.keys())
In [10]: def times(a, b):
             assert isinstance(a, Node) and isinstance(b, Node)
             value = a.value * b.value
             a_gradient = scale_list(a.gradient, b.value)
             b_gradient = scale_list(b.gradient, a.value)
             gradient, variables = merge((a gradient, a.variables), (b gradient, b.variable
             return Internal(value, gradient, variables)
In [11]: reset_auto_diff()
         u = Variable(2.0, 'u')
         v = Variable(4.0, 'v')
         print_variables(u, v)
         p = times(u, v)
         print_variables(p, title='product')
         s = times(u, u)
         print variables(s, title='square')
         u:
         2.0
         v:
         4.0
         product
         8.0
         Gradient wrt ['u', 'v']:
         [4.0, 2.0]
         square
         Gradient wrt ['u']:
         [4.0]
```

### Problem 1.2

### Solution

```
In [12]: def plus(a, b):
             assert isinstance(a, Node) and isinstance(b, Node)
             value = a.value + b.value
             a_gradient = scale_list(a.gradient, 1)
             b_gradient = scale_list(b.gradient, 1)
             gradient, variables = merge((a gradient, a.variables), (b gradient, b.variable
         s))
             return Internal(value, gradient, variables)
In [13]: reset_auto_diff()
         u = Variable(2.0, 'u')
         v = Variable(4.0, 'v')
         print variables(u, v)
         z = plus(u, v)
         print_variables(z, title='sum')
         twice = plus(u, u)
         print variables(twice, title='twice')
         u:
         2.0
         v:
         4.0
         sum
         6.0
         Gradient wrt ['u', 'v']:
         [1.0, 1.0]
         twice
         4.0
         Gradient wrt ['u']:
         [2.0]
```

### Problem 1.3

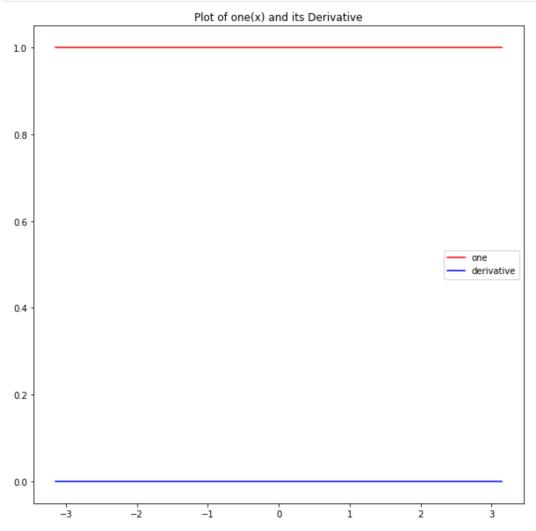
### **Solution**

```
In [14]: import numpy as np
   import matplotlib.pyplot as plt
   import math as math
   %matplotlib inline

In [15]: def cosine(x):
       assert isinstance(x, Node)
       value = math.cos(x.value)
       gradient = scale_list(x.gradient, -math.sin(x.value))
       return Internal(value, gradient, x.variables)
```

```
In [16]: def sine(x):
            assert isinstance(x, Node)
             value = math.sin(x.value)
             gradient = scale_list(x.gradient, math.cos(x.value))
             return Internal(value, gradient, x.variables)
In [17]: def one(x):
             assert isinstance(x, Node)
             return plus(times(cosine(x), cosine(x)), times(sine(x), sine(x)))
In [18]: def derivative(a, name):
             assert isinstance(a, Node)
             if name not in a.variables:
             index = a.variables.index(name)
             return a.gradient[index]
In [19]: reset_auto_diff()
         domain = np.linspace(-math.pi, math.pi, endpoint = True)
         one_range = []
         deriv range = []
         for d in domain:
            v = Variable(d, str(d))
             result = one(v)
             one_range.append(result.value)
             deriv range.append(derivative(result, v.variables))
```

```
In [20]: plt.figure(figsize = (10,10))
    plt.title("Plot of one(x) and its Derivative")
    plt.plot(domain, one_range, '-r', label = 'one')
    plt.plot(domain, deriv_range, '-b', label = 'derivative')
    x = plt.legend(loc = 'best')
```



## Problem 1.4

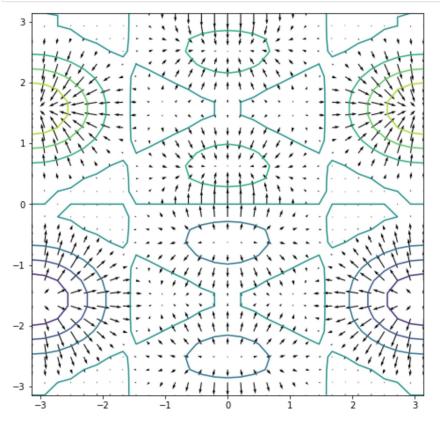
## **Solution**

```
In [21]: import numpy as np
         import matplotlib.pyplot as plt
         %matplotlib inline
         def plot_gradient(f, trange=(-np.pi, np.pi), samples=31):
             t = np.linspace(trange[0], trange[1], samples)
             x_values, y_values = np.meshgrid(t, t)
             z_values = np.zeros_like(x_values)
             g x = np.zeros((samples, samples))
             g y = np.zeros((samples, samples))
             reset_auto_diff(name='pg_x')
             reset_auto_diff(name='pg_y')
             x = Variable(0.0, 'pg_x')
             y = Variable(0.0, 'pg y')
             for i in range(samples):
                 for j in range(samples):
                     x.value, y.value = x_values[i, j], y_values[i, j]
                     z = f(x, y)
                     z_values[i, j] = z.value
                     g_x[i, j], g_y[i, j] = derivative(z, 'pg_x'), derivative(z, 'pg_y')
             plt.figure(figsize=(8, 8))
             plt.contour(t, t, z_values)
             plt.quiver(t, t, g_x, g_y)
             plt.show()
```

```
In [22]: def trig(x, y):
    return times(times(cosine(x), sine(y)), plus(cosine(x), cosine(times(two, y))))
```

```
In [23]: reset_auto_diff()
    two = Variable(2.0, 'two')

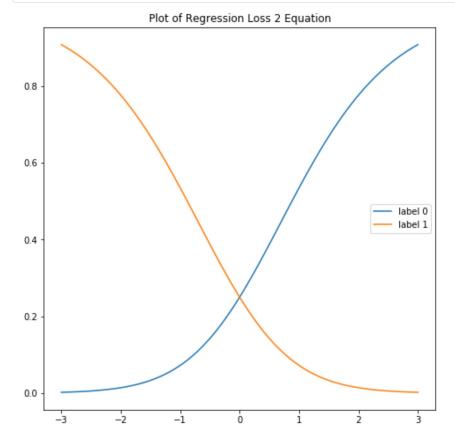
plot_gradient(trig)
```



# Part 2: Loss and Convexity

### Problem 2.1

### **Solution**



# Problem 2.2 (Exam-Style)

### **Solution**

By substituting in 0 and  $\alpha$  into our  $r_2$  equation, we get  $\rho(\alpha)=r_2(0,\alpha)=\ell_2(0,s(\alpha))=p^2$ .

Then 
$$p^2 = ((1 + e^{-\alpha})^{-1})^2 = (1 + e^{-\alpha})^{-2}$$
.

 $\rho(\alpha)$  is continuous and differentiable everywhere, so we can find the first derivative:

$$ho'(lpha)=rac{2e^{-lpha}}{(1+e^{-lpha})^3}$$

This is also continuous and differentiable everywhere, so we can find the second derivative:

$$\rho''(\alpha)=\frac{2e^{-2\alpha}(-e^\alpha+2)}{(1+e^{-\alpha})^4}$$

This second derivative is not postive for all of  $\alpha$  because at  $\alpha \geq ln(2)$ , the  $e^{\alpha}$  becomes  $\geq 2$  which makes the function negative, so  $\rho(\alpha)$  is not convex.

# Part 3: Logistic Regression and Regularization

```
In [26]: import autograd.numpy as np
    from autograd import grad, jacobian

In [27]: def logistic(x, v):
        alpha = v[0] + v[1:] * x
        return 1.0 / (1.0 + np.exp(-alpha))

In [28]: import pickle
    with open('data.pickle', 'rb') as file:
        T = pickle.load(file)
```

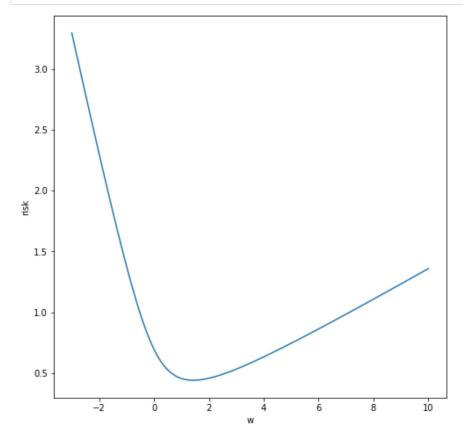
### **Problem 3.1**

#### Solution

```
In [29]: def risk(v, T):
             x = T['x']
             [] = q
             small = 1.e-8
             for point in x:
                 p.append(logistic(point, v))
             y = T['y']
             risk = []
             for w in range(len(v[1:])):
                 total loss = 0
                  for i in range(len(y)):
                      \verb|score| = np.minimum(1.0 - small, np.maximum(small, p[i][w]))|
                      loss = -y[i] * np.log(score) - (1 - y[i]) * np.log(1 - score)
                      total loss += loss
                  risk.append(total_loss/len(y))
             return np.array(risk)
```

```
In [30]: def plot_risks(T, risk=risk):
    bw = []
    bw.append(0)
    for w in np.linspace(-3,10,101):
        bw.append(w)
    v = np.array(bw)
    j = risk(v, T)
    fig = plt.figure(figsize = (8,8))
    plt.plot(bw[1:], j)
    plt.xlabel('w')
    plt.ylabel('risk')
```

In [31]: plot\_risks(T)



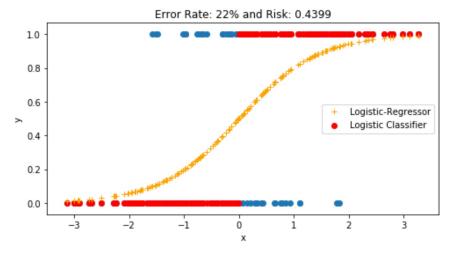
## Problem 3.2

## **Solution**

```
In [33]: def performance(v, T):
    x = T['x']
    h = classifier(x, v)
    y = T['y']
    loss = 0
    for i in range(len(y)):
        if y[i] != h[i]:
            loss+=1
    error = loss/len(y) * 100
    return error, risk(v, T)
```

```
In [34]: def plot_logistic_regressor(v, T):
    fig = plt.figure(figsize = (8,4))
    x = T['x']
    y = T['y']
    plt.scatter(x, y)
    regressor = logistic(x, v)
    plt.plot(x, regressor, '+', color='orange', label='Logistic-Regressor')
    log_classifier = classifier(x, v)
    plt.scatter(x, log_classifier, color='red', label='Logistic Classifier')
    error, risk = performance(v, T)
    plt.xlabel('x')
    plt.ylabel('y')
    plt.ylabel('y')
    plt.title('Error Rate: %.0f%% and Risk: %.4f' %(error, risk[0]))
    plt.legend(loc='best')
```





## Problem 3.3

### Solution

```
In [36]: from scipy.optimize import minimize
         def learn_logistic_regressor(T, lambda_reg=0.0):
             risk_T = lambda v: risk(v, T) + lambda_reg * np.inner(v, v)
             gradient = grad(risk_T)
             hessian = jacobian(gradient)
             v = np.array((0,0))
             result = minimize(risk T, v 0, method='Newton-CG', jac=gradient, hess=hessian)
             if result.success:
                 v = result.x
                 print("b = %.4f \nw = %.4f \nlambda reg = %0.f \nIterations = %0.f"
                       %(v[0], v[1], lambda reg, result.nit))
                 return result
             else:
                 print(result.message)
                 return None
In [37]: v_star = learn_logistic_regressor(T)
         b = -0.0095
         w = 1.4299
         lambda_reg = 0
         Iterations = 6
```

### Problem 3.4

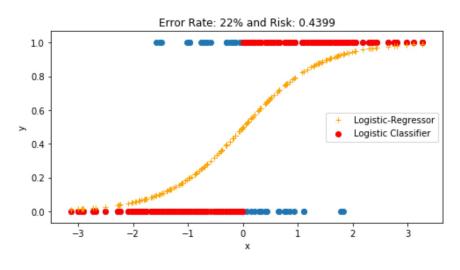
#### Solution

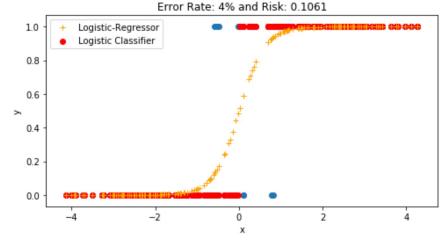
```
In [38]: def spread data(T, spread=0.0):
             x, y = T['x'].copy(), T['y'].copy()
             T s = \{ \}
             x_s = []
             for i in range(len(y)):
                adjust = -1
                 if y[i] == 1:
                    adjust = 1
                 x_s.append(x[i] + adjust*spread)
             T_s['y'] = y
             T s['x'] = x s
             return T s
In [39]: def spread_experiment(lambda_reg):
             for spread in [0.0, 1.0, 10.0]:
                 T_s = spread_data(T, spread=spread)
                 result = learn logistic regressor(T s)
                 print("Spread Value = %.f" %spread)
                 print("----")
                 plot_logistic_regressor(result.x, T_s)
```

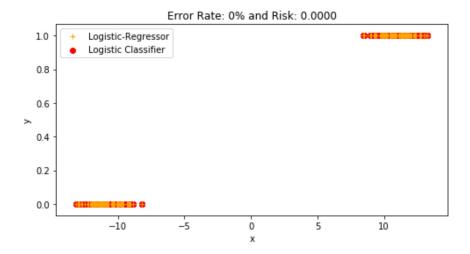
In [40]: spread\_experiment(0.0)

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```
b = -0.0095
w = 1.4299
lambda_reg = 0
Iterations = 6
Spread Value = 0
-----
b = -0.0070
w = 3.2812
lambda_reg = 0
Iterations = 9
Spread Value = 1
-----
b = -0.0017
w = 1.4882
lambda reg = 0
Iterations = 15
Spread Value = 10
```

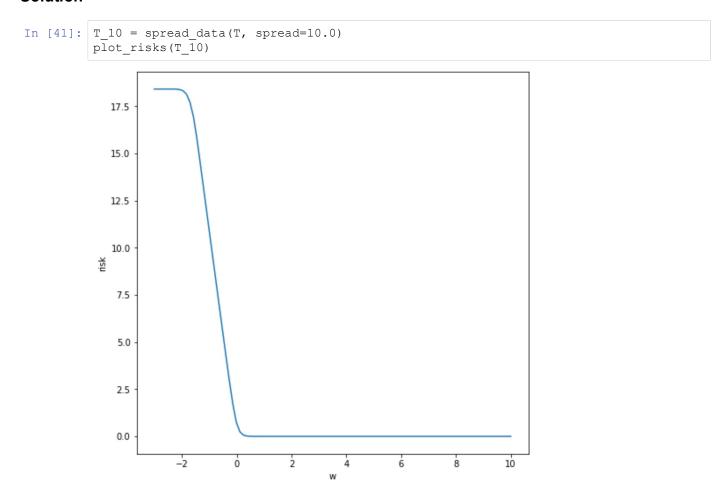






# Problem 3.5

# Solution



# Problem 3.6 (Exam-Style)

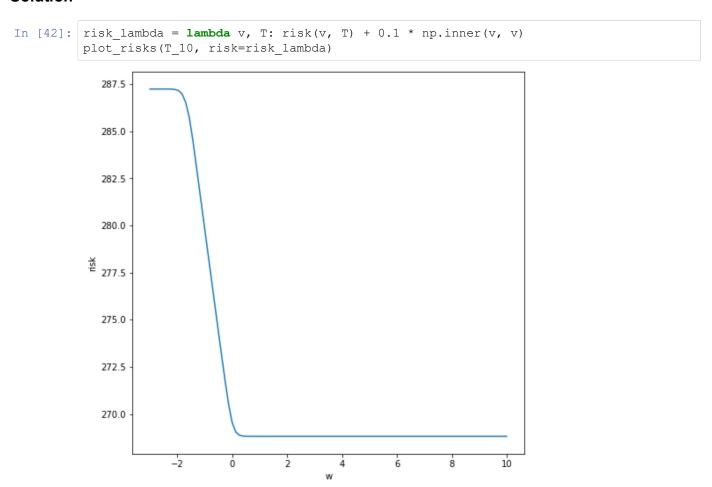
## **Solution**

If b is zero, as w increases, this will cause the rise of the logistic-regressor function to be sharper. Since the set is separable,  $\hat{w}$  is the value at which the logistic-regression function will perfectly separate the set. So any value of w beyond  $\hat{w}$  will not reduce the loss, since at  $\hat{w}$  the loss is at 0.

This can be seen in the graph of problem 3.5, at w=1.48, the risk is 0, and stays zero after that.

### Problem 3.7

### **Solution**



The regularization term causes the risk to significantly increase the risk of the function. Before, at  $w=\hat{w}$ , the risk was 0, but now its 270.