

✕ MessageNotUnderstood: UndefinedObject>>adaptToPoint:ar

UndefinedObject(Object)>>doesNotUnderstand: #adaptToPoint:andSend
Point>>*
Bot>>positionIfGo:
Bot>>go:
Bot>>pattern

Proceed Restart Into Over Through Full Stack Where

go: distance
"make the receiver goes forward from a given distance"
self goTo: (self positionIfGo: distance)

self all inst vars bounds	thisContext all temp vars distance
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