Parallel Computing Project 2

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Abstract—This phase of the practical work aims to assess students ability to develop programs that explore parallelism with the main objective of reducing the execution time of the program.

Index Terms—optimization, parallelism, performance, execution time, k-means

I. Introduction

As a second assignment for the PC - Parallel Computing - subject, we were now proposed to analyse the first version of the program (sequential k-means algorithm) and improve it to a parallel version via **OMP** primitives.

II. CODE ANALYSIS

As seen in project 1 and presented in **Fig.1**, the functions with the highest computational load are *cluster_points* (**Fig.2**) followed by *reevaluate_centers* (**Fig.3**).

Since *reevaluate_centers* does not seem to present any problems in terms of parallelization, we will focus the analysis on *cluster_points*, the most problematic function. As we can see, this is very likely to generate race conditions in the last two lines, since if several threads calculate the same cluster_id, they will access and write at the same time in shared memory.

To deal with this problem, two solutions were considered. The first would be to treat the zone as critical and use the **omp critical** directive, which would make this zone accessible by only one thread at a time. As expected, this solution would greatly harm the execution time the greater the number of threads.

Therefore, we opted for the second option. This consisted of slightly changing the data structure according to the number of threads. The idea here is that each thread contains its own memory space so that there are no reading and writing conflicts between threads, thus allowing greater flexibility in terms of scalability.

III. CODE ALTERATIONS

A. Algorithm

In terms of changes made to the algorithm, since the stopping criterion became a maximum number of 20 iterations, the functions that checked whether the clusters had already converged and also the one that maintained the previous positions of the clusters were removed, since its uses were no longer justified.

B. Data Structure

Regarding the data structure (**Fig.4**), as previously mentioned, the field related to the previous position of the cluster was removed from struct **Cluster**. Three global variables corresponding to the number of samples, clusters and threads were added. Finally, the **clusters** variable was changed, and now it represents a pointer to a set of clusters, simulating a TxK matrix (T threads and K clusters).

Changing the **clusters** variable will now allow each thread to maintain the state of all clusters individually. Take as an example a case where T=2 and K=4, so we will have a list of 8 clusters where thread 0 is responsible for the first block of 4 clusters and thread 1 for the remaining 4.

C. Parallel Implementation

Fig.5 shows the implementation of the parallel version of the *cluster_points* function. For this, the **omp parallel for** directive was used, which will allow the code inside the loop to be distributed and executed by the threads. As these iterations are performed on the points, it was necessary to pay attention to their distribution among the threads. Thus, to maintain the order in which the points are worked, we chose to use the clause **schedule(static,N/T)** (N samples and T threads) since the sum of **floats** is not associative.

To take greater advantage of parallelization, the **omp parallel for** directive was used again for the functions *reevaluate_centers* - **Fig.6** - and *update_clusters_size* - **Fig.7**. Unlike the previous one, these loops iterate over the number of clusters and the order is not relevant, thus opting for a default/static distribution.

IV. PERFORMANCE ANALYSIS

As a way of analyzing the performance of the developed program, several tests were carried out where the number of clusters (4 and 32), the number of threads (1,2,4,8,16 and 32) and the number of **CPU's** (1,20 and 40) were varied. The results can be analyzed using the graphics in figures **Fig.8**, **Fig.9** and **Fig.10**.

Its analysis allows us to conclude that the use of threads or parallelism is more efficient when the number of clusters is higher. In addition, we also realize that a greater number of **CPU's** does not always imply better performance, as can be seen in the last two graphs.

Thus, the best results achieved within the tests carried out were obtained using 20 **CPU's** and 32 threads for a sample of 10000000 points and 4 and 32 clusters. These were carried out on the provided **Shearch** machine.

ATTACHMENTS

```
Samples: 32K of event
# Samples: 32K of event 'cycles:ppp'
# Event count (approx.): 23286877137
# Overhead Command Shared Object
                                                       Symbol
     87.55% k_means
7.69% k_means
1.70% k_means
                                                       [.] cluster_points
                             k_means
                             k_means
libc-2.17.so
libc-2.17.so
                                                       [.] reevaluate_centers
                                                       [.] __random_r
                                                       [.] __random
[.] initialize
[k] 0xffffffffa1195377
       1.23%
0.59%
0.51%
                k_means
                             k_means
[unknown]
                k_means
                                                       [k] 0Xffffffffa158c48a
[k] 0Xfffffffffa158ca5b
                 k_means
                              libc-2.17.so
                             k_means
[unknown]
       0.08%
                k_means
                k_means
k_means
       0.02%
       0.01%
                              [unknown]
                 k_means
                              [unknown]
                                                             0xfffffffffa158c4ef
                k_means
       0.01%
                             [unknown]
                                                       [k] 0xffffffffa158cbc0
```

Fig. 1. Perf report

Fig. 2. Cluster_points code

```
void reevaluate_centers() {
   for (int i = 0; i < K; i++) {
      float x = 0;
      float y = 0;

      // vectorizable
      for (int j = 0; j < clusters[i].size; j++) {
            x += clusters[i].points[j].x;
            y += clusters[i].points[j].y;
      }

      clusters[i].pos.x = x / (float) clusters[i].size;
      clusters[i].pos.y = y / (float) clusters[i].size;
    }
}</pre>
```

Fig. 3. Reevaluate_centers code

Fig. 4. Data Structure

Fig. 5. Parallel cluster_points

Fig. 6. Parallel reevaluate_centers

Fig. 7. Parallel update_clusters_size

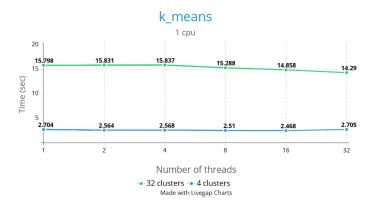


Fig. 8. Graph test with 1 CPU

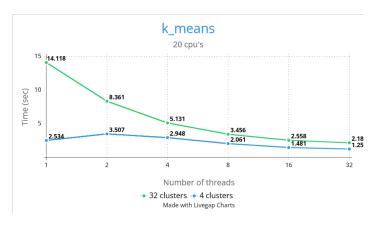


Fig. 9. Graph test with 20 CPU's

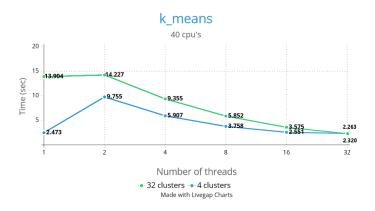


Fig. 10. Graph test with 40 CPU's