

Kinetic Particle Model

Kinetic particle model = atomic theory.

- All matter made of tiny moving particles
e.g. atoms or molecules
- Particles move in straight lines
- Elastically collide with each other and walls of container
so KE is conserved
- As a gas, the distance between particles are large compared to their size
- Average Particle velocity (i.e. KE) is proportional to temperature

(Boiling vs. Evaporation)

Evap. = slow process. Boiling quick.

(Fig 10.5 BBB) Increasing T, avg speed increases

also, Increasing T, larger spread of molecule KE

Heat and Temperature

$$\text{Internal Energy} = \text{KE} + \text{PE}$$

↑
 $\Delta \text{Temp.}$

Phase diagram (Fig 10.15): E used to break inter-molecular bonds instead of increasing KE @ boiling point.

Zeroth Law of Thermodynamics

If object A has the same temperature as object B and object C has the same temperature as object C then object A is the same temperature.

but we do not object with finding law of new law of thermodynamics of heat and work of relation of relation on it. **First Law of Thermodynamics** is given that Energy cannot be created or destroyed in an isolated system.

$$\text{fully filled room temperature} - Q_{lost} = Q_{gained}$$

Answer with (Types of systems) closed, open and isolated.

Open: Energy / mass can enter and exit the system.

Closed: Mass stays same but energy can enter and exit.

Isolated: Neither energy nor mass can enter or exit.

Second Law of Thermodynamics

The entropy of an isolated system always increases.

be done in K.

mas (Entropy) \rightarrow $\Delta S \geq 0$ must exist

Entropy is the measure of the disorder in a system.

Third Law of Thermodynamics

Entropy approaches a constant value as temperature approaches absolute zero.

Absolute zero

Absolute zero is the theoretical temperature where there is no internal energy. It is equal to -273.15°C .

To cool something, there needs to be an object that is colder for the heat to flow into. However, when cooling an object to absolute zero, there is no colder temperature than -273.15°C . Thus, it is theoretically impossible to achieve absolute zero temperatures.

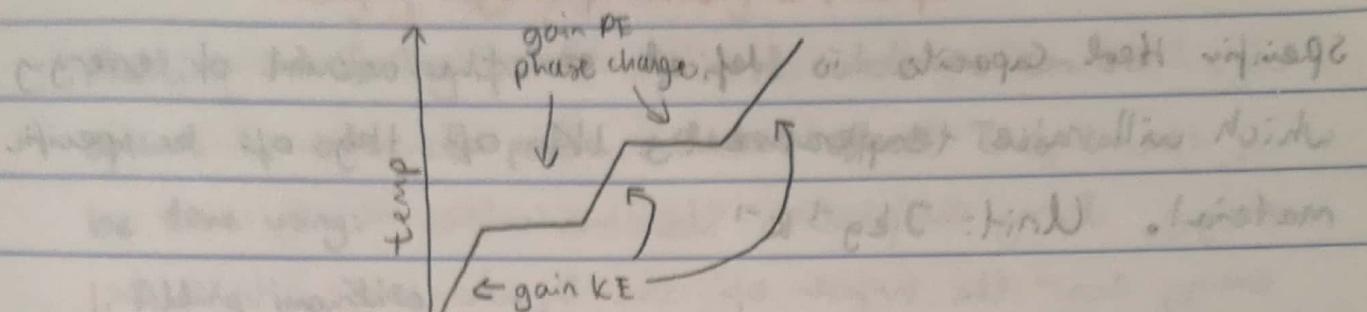
(Celsius and Kelvin)

C and K share the same magnitude of their units (i.e. $+1^{\circ}\text{C} = +1\text{K}$). Converting between them requires the formula: $\text{C} = \text{K} - 273$.

$$\text{K} = ^{\circ}\text{C} + 273$$

$$^{\circ}\text{C} = \text{K} - 273$$

This means 0K is at absolute zero.



* melting point times of energy applied \rightarrow $c_{H_2O} < c_{LiCl}$

so same relation to $c_{H_2O} > c_{LiCl}$

(bathtub vs. Teacup) = $c_{H_2O} > c_{LiCl}$

which has more energy, a fully filled 40°C bathtub or a fully filled 100°C teacup?

Answer: bathtub, because there are more molecules inside the bathtub compared to the cup even though for one molecule, the kinetic energy in the cup is higher than in the bathtub.

(Use Kelvin, not Celsius)

When comparing temperatures of substances, calculations must be done in K.

opposite effect on melting point

Substances at different temperatures have different solubilities.

lowerer temp melting rule you know

heat to heat melting change sol. capacity

low temp solubility not (S.A) solubility, \downarrow)

(S.A) water, \downarrow) nitrogen to heat freeze

, expand wrong as no big pit \rightarrow

Specific Heat Capacity

Specific Heat Capacity is defined as the amount of energy which will raise temperature by 1K of 1kg of a specific material. Unit: $J \text{ kg}^{-1} \text{ K}^{-1}$

Table 10.1 lists specific heat capacities.

$$Q = m c \Delta T$$

where Q is energy (J),
 m is mass (kg),
specific heat capacity ($\text{J kg}^{-1} \text{ K}^{-1}$)
 ΔT is change in temperature (K)

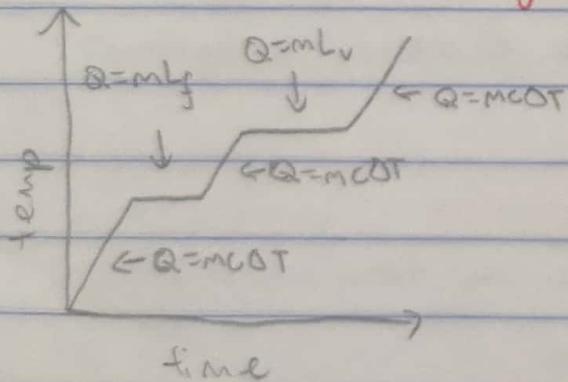
Process of Calorimetry

Use First Law of Thermodynamics:

$$-(Q_{\text{lost}}) = Q_{\text{gained}}$$

$$-(m_1 c_1 \Delta T_1) = m_2 c_2 \Delta T_2$$

Change of State



We cannot use specific heat capacity to calculate energy use when potential energy increases/changes. Use specific latent heat of fusion (L_f , table 10.2) for solid \leftrightarrow liquid and latent heat of vapourisation (L_v , table 10.2) for liquid \leftrightarrow gas phase changes.

Changing Melting & Boiling Points

Melting and boiling points of most substances can be changed affected in order to produce a desired effect. This can all be done using the solution of impurities present in pure.

1. Adding impurities (impurities to water or sea water)

- ↓ melting point of water → ↑ boiling point of water

e.g. saline solution to

e.g. cook pasta in

→ de-ice windows more easily in salty water (quicker)

2. Increasing pressure (for no water and melting salt no)

- If liquid expands when freezing, • If liquid contracts when freezing:
↓ melting point law. (↓) of T_m melting point law →

and because: P pressure pushes molecules closer together.

Then If (↓) contracts, increases T_m where T molecules

attract & solidify. at about 0°C and 100°C

- P boiling point be ↑ boiling and ↑ refrigeration

e.g. pressure cookers do start to boil and ↑ fast cooking. Substances that dissolve well with water

removing impurities (or decreasing pressure) has the opposite effect on melting and boiling points. all ↓

consider that the sun often helps get rid of water

contrary to what people think are melting and

boiling points which are all the same

If the water is refrigerated at different times

↑ of cooling time the differences will be ↓

the insulation will be reduced the water will be ↓

cooling of insulating all of which is a negative

Evaporation

Liquids can change state without boiling. All molecules in the liquid do not contain the same kinetic energy; during evaporation, the molecules with greater energy near the surface of the liquid change state to gaseous form. The slower molecules get left behind.

Evaporation does not occur in a closed container as the system has reached an equilibrium where the rate of evaporation is equal to the rate of condensation. (Fig 10.16)

The Kinetic Model of Gases

Assumptions are made to simplify the motion of gas particles.

1. Gas particles are in constant random motion. They move at high speeds in straight lines unless they elastically collide (no loss in KE) with the walls and of the container or other gas particles.
 - Explains why gases readily mix and fill containers.
2. Gas particles are separated by large distances compared with the particles' diameter, which is assumed to be negligible in size.
 - Explain compressibility and small density of gases
3. Intermolecular attraction is negligible \therefore distance.
4. Temperature is a measure of the average KE of the gas,

Pressure (Pressure)

Pressure is defined as the force per unit area, or

$$P = \frac{F}{A} \quad (\text{Force} \text{ is applied over area } A)$$

where P is pressure (N m^{-2}) or (Pa)

F is force (N)

A is area (m^2) of rectangular area

The Combined Gas Equation

since (i) applying the law of total effect we have

$$V \propto \frac{1}{P} \quad (\text{Boyle's Law}, P_1 V_1 = P_2 V_2), \quad T$$

$$V \propto T \quad (\text{Charles' Law}, \frac{V_1}{T_1} = \frac{V_2}{T_2}), \quad \text{or}$$

and $P \propto T$ (Amonton's Law)

Then:

$$\text{Under } \frac{T}{P} \text{ is constant, } \frac{P_1 V_1}{T_1} = \frac{P_2 V_2}{T_2} \quad \text{and this is called}$$

where P and V can be given any unit as long as it is consistent

it is consistent, but the law is 'adhering to

T has to be measured in Kelvins. $1 \text{ L} = 10^{-3} \text{ m}^3$

$\therefore T$ is in Kelvin, at room temperature $1000 \text{ K} = 1000 \text{ K}$

The Ideal Gas Equation

Because $P \propto N$ where N is the number of gas particles,

$$PV = kNT$$

where k is Boltzmann's constant, $k = 1.38 \times 10^{-23} \text{ J K}^{-1} \text{ molecule}^{-1}$

If N is changed to number of moles (n), then

$$\text{so change of } PV = nRT \text{ get standard formula}$$

where R is the Universal Gas constant, $R = 8.31 \text{ Pa m}^3 \text{ mol}^{-1} \text{ K}^{-1}$

All variables are in standard units.

(converting N to n)

Use $n = \frac{N}{N_A}$ to convert n to N .
 N_A is Avogadro's Constant, $N_A = 6.02 \times 10^{23}$

Temperature and Kinetic Energy

use this equation to find E_k about T

or vice versa. $\text{pressure}^2 (P = \frac{1}{3} \rho U^2)$

$$\overline{E}_k = \frac{3}{2} kT$$

where \overline{E}_k is the total E_k for all particles (J)

T is temperature (K)

k is Boltzmann's Constant (J/K) $T \propto V$

(and $c = nRT$) $T \propto \frac{1}{V}$

(Real Gases)

Gases in real life are often not ideal (ideal: consisting of single atoms only). Assumptions were made that each gas particles' size and attractive force is negligible.

However, in real life, $P \neq \frac{F}{A}$ vs the molecules

are pushed closer together, attractive F is

greater and V of particles is significant compared to

V of gas. (a volume of n molecules is nV)

Under of the conditions of low temperatures or high pressures, a real gas deviates from the behavior indicated by the ideal gas equations

Thermal Expansion of Solids

Linear thermal expansion: application p265 bottom

$$\Delta L = L_i \alpha \Delta T$$

where ΔL is change in length (m)

L_i is original length (m)

α is the coefficient of linear expansion ($m K^{-1}$)

ΔT is change in temperature (K)

ΔL of 1m of substance due to 1K ΔT

(Table II.1)

Thermal Expansion of Liquids

Liquid thermal expansion: heat transfer (W)

$$\Delta V = V_i \beta, \Delta T$$

where ΔV is change in volume (L)

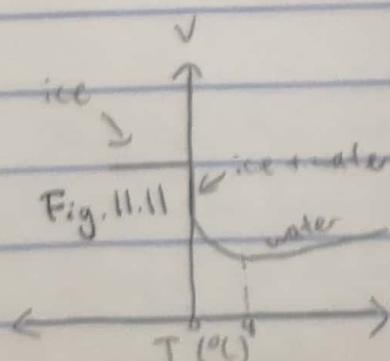
V_i is initial volume (L)

β is the coefficient of volume expansion ($m^3 L K^{-1}$)

ΔT is change in temperature (K)

(Table II.2)

Abnormal Expansion of Water



Between 0°C and 4°C , water expands as T decreases. When it freezes at 0°C it undergoes considerable expansion.

Conduction

Metal feels colder than fabric because it is more thermally conductive. Similarly, a down blanket feels warmer than a polyester blanket because the air between the feathers is less thermally conductive.

Heat can only be conducted through a medium where there are particles i.e. s, l and g. Vacuum environments cannot conduct heat.

$$R = \frac{k|T_2 - T_1|A}{d}$$

where R is the rate of heat transfer (W)

$\rightarrow R$ is the thermal conductivity ($\text{W m}^{-1} \text{K}^{-1}$)

$|T_2 - T_1|$ is the difference in temperature ($^{\circ}\text{C}$ or K)

Table 12-1 A is the area (m^2)

d is the thickness (m)

Conduction - contact between two objects where energy transfer occurs

Magnetism & Electromagnetism

Diamagnetic - most common, weakly repelled by magnets

e.g. glass, Cu, Au and bismuthate with ni

Paramagnetic - weakly attracted by magnets

e.g. Mn, Al and Pt

Ferromagnetic - strongly attracted to magnets

e.g. Fe, Ni, Co best examples (T) and (C)

soft, hard etc

Field Lines - Arrows from N to S

- Do not cross

- More closer together \rightarrow stronger field at point

softer harder at strong areas

(Magnetised?)

During crystallisation, metals that are magnetised have their magnetic domains oriented (Fig 25.5 R). Unmagnetised materials have randomly oriented magnetic domains, resulting in a net magnetic charge of zero.

(Soft vs. Hard)

Difficult to induce but retains magnetism \rightarrow magnetically hard

Easy to induce but quickly loses magnetism \rightarrow magnetically soft

(Demagnetisation)

Demagnetisation occurs with soft/hard magnets when -

- heated to Curie Temperature (unique to every material)
- dropped or hammered

(Cause of Magnetism) mechanism

Magnetism is caused by the spin of the electrons in the atoms.

strength of field in the air - air gap

Magnetic Fields / A, nT, pG

The magnetic field strength, (B), measured in Teslas (T), is shown by the density of the field lines.

2 at N many lines = concentrated

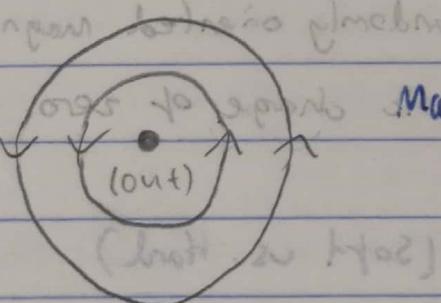
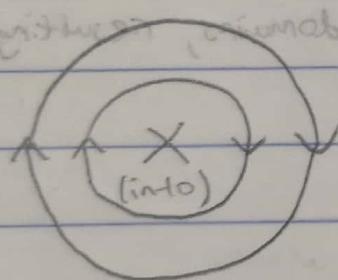
(conventional current) \rightarrow tan θ -

Conventional current describes current flow from excess positive to excess negative.

(Electricity)

Magnetic Field in a Wire

Field lines travel clockwise radially to the wire end



Maxwell's Screw rule

Point thumb (RH) parallel to wire. Direction to fingers

H = direction of field lines. (Thumb = current, curl = field)

- Field lines are concentric

- $B \propto \frac{I}{r}$ - current
- radius

- Current reversed, field direction reversed

(bottom page of engine) strongest field at bottom -

longest to biggest -

~~rotational properties not covered~~

$$B = \frac{k I}{r}$$

(law of solenoids or current loop)

where B is magnetic field strength (T) half credit limit

where k is magnetic constant, $k = 2 \times 10^{-7} \text{ N A}^{-2} \text{ m}^2 \text{ rad}^2$ (rad)

I is current (A)

r is distance from centre of wire (m)

The total magnetic field along the axis of a long solenoid is

Magnetic field / Solenoids / Multi-turn Coils

Inside coil, field lines add up through middle of coil.

Outside, field lines cancel out. $I B = ?$

$$(U) B = \frac{2\pi k N I}{L}$$

(T) Length of coil L

where N is number of turns (turns/m) and I

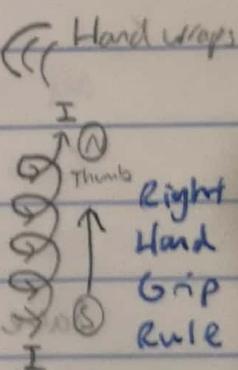
L is coil length (m) if not wire length

To find direction of field: (RH Grip)

Point fingers along each coil wire in direction of current

Thumb will point N, direction of field

now what about solenoids? direction of field along axis?



... so to show, $\frac{\pi d}{2} = \theta$ (angle)

area of end of solenoid = πr^2

$\frac{\pi d}{2} = \theta$ next

Forces on Current-Carrying Conductors

Use the right hand motor rule:

Point thumb in direction of current

Point fingers flat in field direction (external)

Force directed on wire away from palm



RH Motor Rule

or Motor principle

Force $F = B I L \sin \theta$

Where F is the EMF on the wire (N)

B is the field strength (T)

I is the current (A)

θ is the angle of the wire to the field

Parallel: attractive force btwn. wires

Same direction of current: attractive force btwn. wires

Opposite direction of current: repulsive force btwn. wires

Recall $B = \frac{\mu I}{r}$, field of a CCL

Let $r =$ distance btwn. two wires

Then $B = \frac{\mu I}{r}$

Force experienced by I_1 : $F_1 = B_2 I_1 L \sin \theta$ (in field)

Then: $F = \frac{k I_1 I_2 L}{d}$

Where F is the force on both parallel wires (N)

Coils in Magnetic Fields

The total torque acting on a coil within a T.M.F is if given by magnetic field is given by:

$$\tau = B A I N \cos \theta$$

where τ is the torque (Nm)

A is the CSA (m^2) (area) facing to either a \rightarrow or \leftarrow field

N is the number of turns

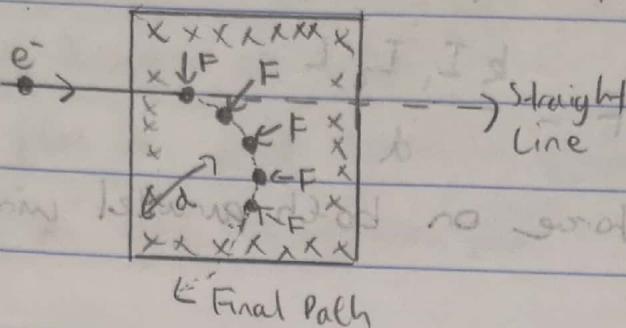
θ is the angle (0° to 180°)

Important note: you need current flowing through the coil for it to experience a torque. Current flowing in opposite directions will cancel each other out (transformation at 90 degrees). Through left hand rule - if left

To calculate self inductance we go from H to B and then $\mu_0 N^2 / l$ where N is the number of turns.

Moving Charges in Magnetic Fields

Once $I = I_d$ $\Rightarrow B = \mu_0 I / 2\pi r$ becomes zero



Final Path

$$F = qvB$$

where F is EMF causing e^- to turn (N) \rightarrow right hand rule

q is charge of e^- (C)

v is velocity ($m s^{-1}$)

$$r = \frac{mv}{qB}$$

where r is radius of path (m)

(Right or Left Hand?)

All rules to do with hands have been using the right hand.

This is because the RH thumb points in the direction of conventional current (opposite to e^- movement).

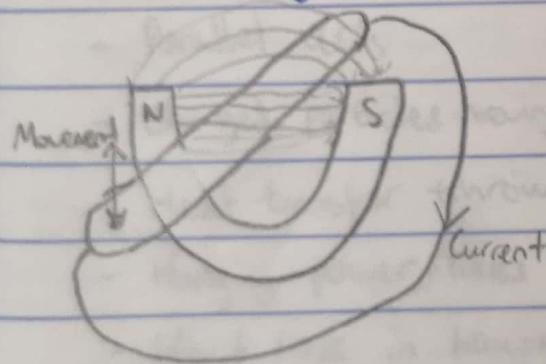
The LH can be used instead to find the direction of e^- flow. All hand rules are compatible.

Electromagnetic Induction

Faraday's Law states that when a magnetic field in the region of a conductor changes, an EMF is induced across the ends of the conductor. If the conductor is made part of a complete circuit then an induced current will flow.

Lenz's Law states that when an EMF is generated by a change in magnetic flux, according to Faraday's Law, the polarity of the induced EMF is such that it produces a current whose magnetic field opposes the change which produces it.

$$\text{Faraday's Law} \quad \text{work} \quad \text{F} = B A v \quad \text{EMF} = B L v \sin \theta$$



Where EMF is induced voltage

L is length of conductor in field

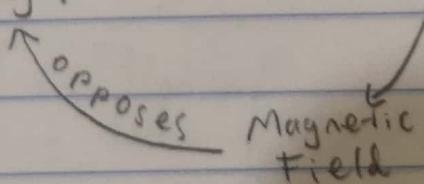
v is relative velocity

Lenz's Law

Magnetic flow in a conductor, in a closed circuit, gives current.

Mag. flux \rightarrow EMF \rightarrow Current

Magnetic flow in a conductor, in an open circuit, gives EMF across the conductor.



Transformers

When, with $\frac{V_p}{V_s} = \frac{N_p}{N_s}$ ratio kept, voltage and current
EMF are proportional to no. of turns.

Where V_p is AC across primary coil also called primary voltage.

V_s is AC across secondary coil also called secondary voltage.

N_p is number of primary turns also called no. of turns.

N_s is number of secondary turns.

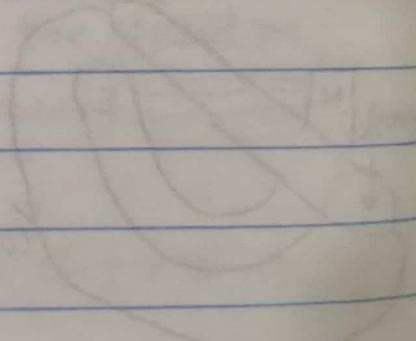
If $N_p > N_s$, transformer is step-down (reduce AC voltage).

If $N_s > N_p$, transformer is step-up (increase AC voltage).

The current changes along with the voltage as energy is not created nor destroyed.

$$V_p I_p = V_s I_s$$

This equation derived in EMF section
Method of derivation of EMF will be discussed later.



Example - Transformer with 200 turns

Primary
Secondary

Paper A

Term I Exam Content

8 marks

Recall & Explain (Part A) KCU 1

- defn. - Field Lines N-S - 1st, 2nd laws of Thermodynamics defn.
rel. - Mag. domains, diam., ferro-, paramag. - Thermal Expansion - defn.
rel - Current, mag. fields, movement - Thermal Energy, E_k , E_p , temperature rel.

Very in-depth explanation required
Summary of content to be appropriate

Compare & Explain (Part A) KCU 2

- Magnet attracting iron
- Liquid \leftrightarrow gas energy change
- Compare galvanometer & electric motor
- (Compare temp. change & phase changes)

Conclude & Recommend (Part A) EC 2

- Parallel AC's
 - Charged particles moving through fields
 - Heat transfer through windows
 - Hanging power lines
 - Heat loss in houses
 - Transformers
- to conclude, remember to justify your recommendations. justify mathematically and assume, compare values.

Paper B

Term I

Exam Content Old & New

Apply & Calculate (Part B) KCUZ (A 2019) - included in notes

- Field strength of wire, $B = \frac{\mu_0 I}{r}$ kg

- Find c to identify substance $Q = mc\Delta T$, with elements, pH

- Field strength of a solenoid $B = \frac{2\pi k N I}{l}$

- P, V, T relationships $P_1V_1 = P_2V_2$, $\frac{V_1}{T_1} = \frac{V_2}{T_2}$

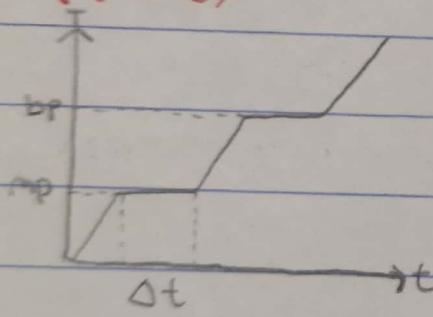
- Field strength at a point due to 2 wires

- Calorimetry with phase changes $Q_{lost} = Q_{gain}$

- Force on conductor in magnetic field ($F = BIL \sin \theta$)

- Calorimetry with ice

IP (Part B)



Can find: m_p , b_p , c (w) power, mass & ΔT

L_f , L_v (w/ power, mass)

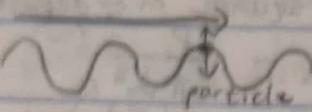
- Charles' law experiment $\frac{V_1}{T_1} = \frac{V_2}{T_2}$
- Electromagnet - vary N or I, measure F or t, repeat for 3 trials

unit newton C.G.S.H -
newton m. 2201 H.S.H -
Joule/m²/s

Basics of Sound

Types of waves: wave propagates this way (wavy line) \rightarrow longitudinal

Transverse



particle moves this way

- Particles move \perp to wave's movement

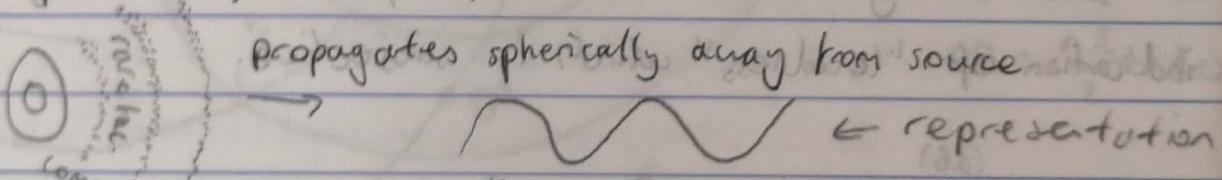
e.g. water waves, skipping ropes

Longitudinal

Particles move || to wave's movement

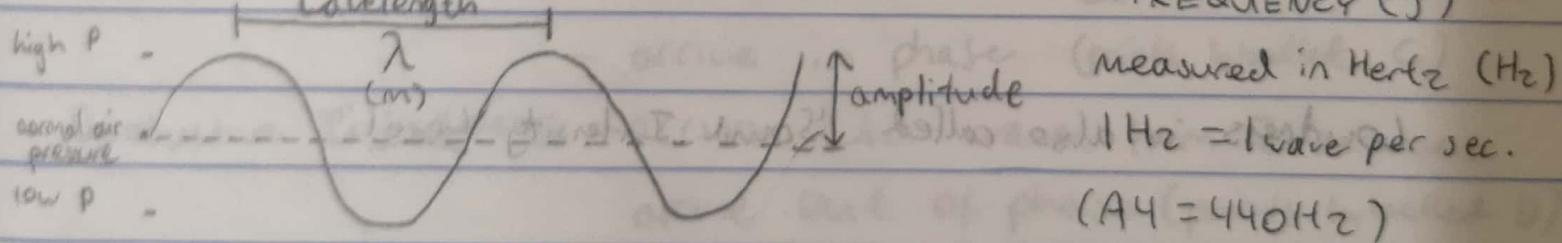
e.g. sound, air expands/contracts at ends of waves

Sound is made of alternating bands of high pressure
air (compressions) and low pressure air (rarefactions).



(In air) $\text{P}_{\text{air}} \propto \frac{1}{r^2}$ \rightarrow molecular view

However, sometimes sound is represented as a transverse
wave to make it easier to visualize.



Velocity of a wave: $v = f\lambda$ (measured and now formula)

In air, $v_s \approx 340 \text{ m}^{-1}$ (at 0°C , 331 m^{-1} ; at 20°C , 344 m^{-1})

Formula for v_s of air @ T: $v_T = 331 \sqrt{\frac{T}{273} + 1}$

v_s depends on density; metals $\uparrow v_s$ than soft fluids

Period (T)

measured in (s)
time for a wave
to move past a point

When waves travel through different surfaces, its frequency remains the same but its wavelength changes.

$$T = \frac{1}{f}$$

How Loud Things Are

Intensity: $I (\text{Wm}^{-2}) \rightarrow$ energy per second \leftarrow Power (P)
per square m \leftarrow depends on dist.

$$\text{SA}_{\text{sphere}} = 4\pi r^2 \therefore I = \frac{P}{4\pi d^2}$$

spherical propagation
away from source

inverse-square
relationship

$I_0 = 10^{-12} \text{ Wm}^{-2}$ is the lowest intensity sound the human ear is able to detect. Changes in intensity can be picked up more easily at lower intensity levels than high.

Sound intensity is objective. However, it is not a good indication of "loudness" which is subjective.

(dB)

Loudness: $L = 10 \log \left(\frac{I}{I_0} \right)$ where L is loudness (decibels, dB)

L compares the intensity logarithmically to the lower threshold of the ear.

(dB) start of hearing

Loudness is also called "Sound Intensity Level!"

(SIOPP = PA)

Humans can hear between 20Hz to 20000Hz

(min 20, max 20000 Hz)

(T) bone

$10 \log \left(\frac{I}{I_0} \right) = L$ T \oplus L \oplus I

(e) human

present at: centre + left + right + nose + mouth

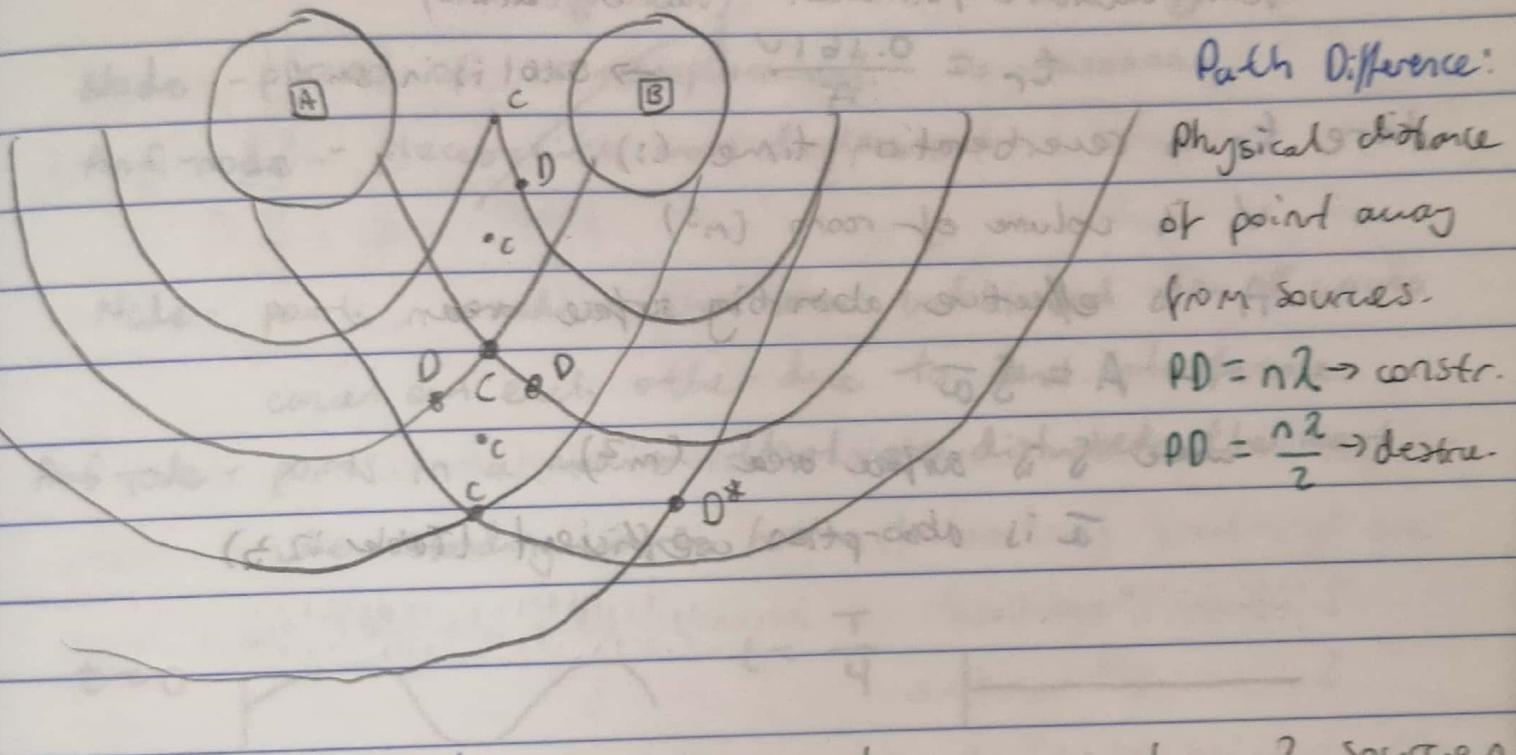
regions appearance at last come with pain

Interference & Reflection

Hard surfaces reflect waves in the same phase, as the ~~as~~ home particles in the rigid surface do not move.

Soft surfaces reflect waves out of phase, switching decompressions and rarefactions about

(almost) nothing (return of sound)



Constructive Interference occurs when waves from 2 sources arrive in phase (points labelled C)

Destructive Interference occurs when waves from 2 sources arrive out of phase (points labelled D)

Reverberation Wub-Wub

Reverberation Time is the time that it takes from birth of a note to end of its echoes cannot be heard (usually < 60 dB).

Depends on size, shape and nature of surfaces.

Semi-accurate formula: (Sabine's Formula)

$$t_r = \frac{0.161V}{A} \rightarrow 0.161 \text{ is in } \text{sm}^{-1}$$

where t_r is reverberation time (s)

V is volume of room (m^3)

A is effective absorbing surface area

$$A = S\bar{\alpha}$$

where S is surface area (m^2)

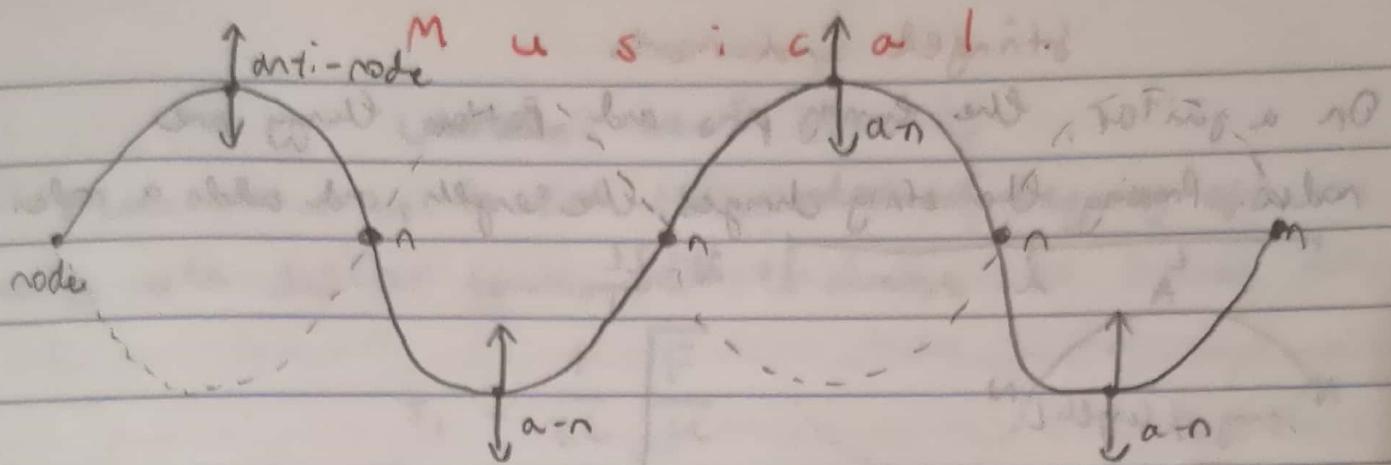
$\bar{\alpha}$ is absorption coefficient (Table 17.3)

to compare the intensity logarithmically to the mean

absorbing surfaces with zero absorption coefficient
(perfectly reflecting) nearly no sound

perfectly absorbing, zero absorption coefficient
(perfectly solid) nearly no sound

However, the difference between them is very small

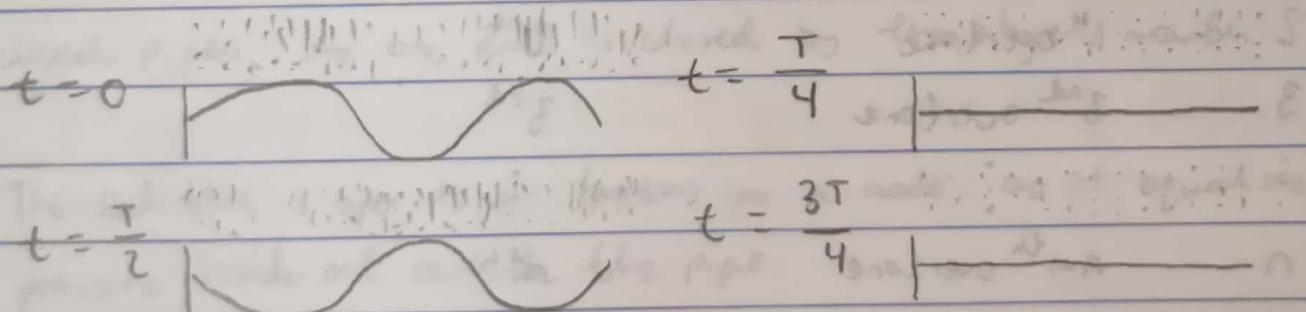


Node - places of no-displacement ha-haaaaaa

Anti-node = places with most displacement

Node - points in a medium that remain undisturbed when 2 waves cancel out each other due to dest. interference.

Anti-node - points in a medium that are disturbed the most when standing waves form.



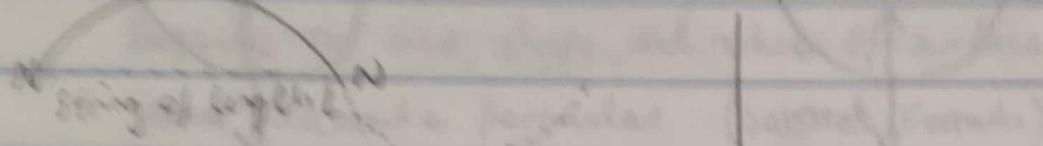
(effektiv wiedergabe)

die "Rechteck" ist etwas reicht mit, aber vereinfacht es eigentlich nicht
weil es schon die Länge des ganzen Schwingungsbereiches auf einer Seite
und die Amplitude auf der anderen Seite aufgetragen ist.

String Instruments

On a guitar, the tuning pegs and bottom string are nodes. Playing the string changes the length, and adds a node.

$$\lambda = \frac{2L}{1}$$

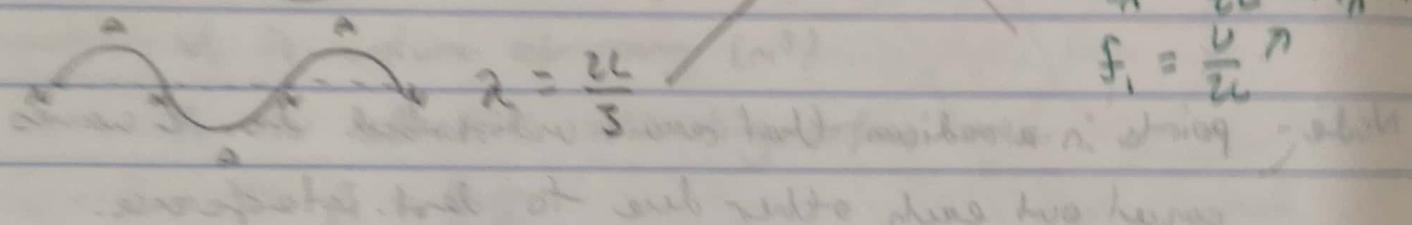


string of length L

$$\lambda = \frac{2L}{2} \quad \text{general formula: } \lambda = \frac{2L}{n}, n \in \mathbb{Z}$$

$$f_n = \frac{v}{2L} \cdot f_1 = n f_1$$

$$f_1 = \frac{v}{2L} n$$



top and bottom nodes (harmonic node) - when you pluck the string, it vibrates at all nodes along the string

1 fundamental (not overtone)

2 1st overtone

3 2nd overtone

⋮ ⋮ ⋮

n $n-1^{\text{th}}$ overtone

nth

(Harmonic Staff)

When playing a harmonic note, the finger creates a "partial" node. However, the full length of string is allowed to vibrate, creating an overtone that is louder than the fundamental tone.

(Mersenne's Law) (contd.)

This law allows us to find the fundamental frequency of two strings with different tensions and thicknesses.

$$f_1 = \frac{1}{2L} \sqrt{\frac{F}{\mu}}$$

where F is the tension in the string (N)

μ is the mass per unit length of the string (kg m^{-1})

This model $\mu = \frac{\text{mass}}{L}$ the distance would get to the

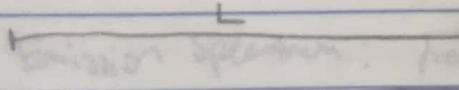
frequency of the string and spiral tubes. This would

Closed Pipes

A closed pipe is one that is sealed at one end and open at the other. Brass instruments and any instruments involving breathing are closed pipes, as one end is closed by the player's mouth.

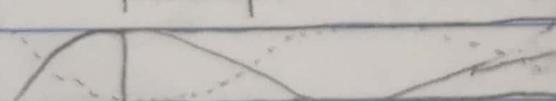
It also did not explain the frequencies of closed pipes.

The end that is open to air functions as a node, as it equalises the pressure inside and outside the pipe.

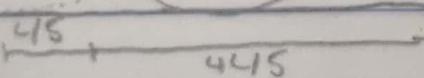


$$\lambda = 4L$$

4/3



$$\lambda = \frac{4}{3}L \quad \text{general formula: } \lambda_n = \frac{4L}{2n-1}$$



$$\lambda = \frac{4}{5}L$$

Modern Physics - History / Intro

α -particle: He^{2+} ion and its behavior with solid material
and through various impact to determine

Ernest Rutherford's gold foil experiment determined that instead of a "plum pudding" model where the electrons are interspersed in positively-charged matter, there exists a nucleus of positive matter surrounded by electrons.

This model has problems: the electrons would get to the nucleus of the atom and spiral faster. This would increase the frequency emitted, but was never observed.

Furthermore, a collision of e^- and nucleus would make the atom unstable.

It also did not explain the specific absorbed frequencies in the sunlight's absorption spectrum.

Emission spectrum: frequencies of light emitted when a gas is excited.

Absorption spectrum: frequencies of light absorbed by a gas with white light shining through. The "gaps" in the spectrum indicate the gas' composition.

Balmer's Equation

Johann Jakob Balmer created an empirical equation for the wavelengths of hydrogen's emission spectrum:

$$\frac{1}{\lambda} = R_H \left(\frac{1}{n_i^2} - \frac{1}{n_f^2} \right)$$

where λ is the wavelength (in nanometers) and

R_H is Rydberg's constant ($R_H = 1.097 \times 10^7 \text{ m}^{-1}$)

n_f is the final energy level

n_i is the initial energy level

For the Balmer series, $n_f = 2$ and $n_i = 3, 4, 5$ or 6

with the longest wavelengths corresponding with the smallest n_i .

For the Lyman series, $n_f = 1$ with n_i increasing after 1.

For the Paschen series, $n_f = 3$ with n_i increasing after 3.

Photoelectric Effect

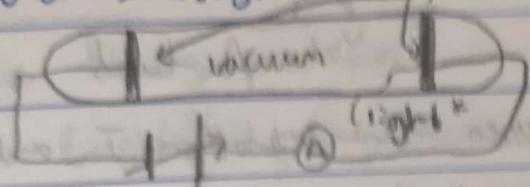
Observation: UV light in, current in collector, no current out

Double-Slit Experiment

Two slits placed in front of sodium lamp resulting in image. Light and dark bands caused by const. & destructive interference. This suggests light is a wave.

Léonard's Investigation

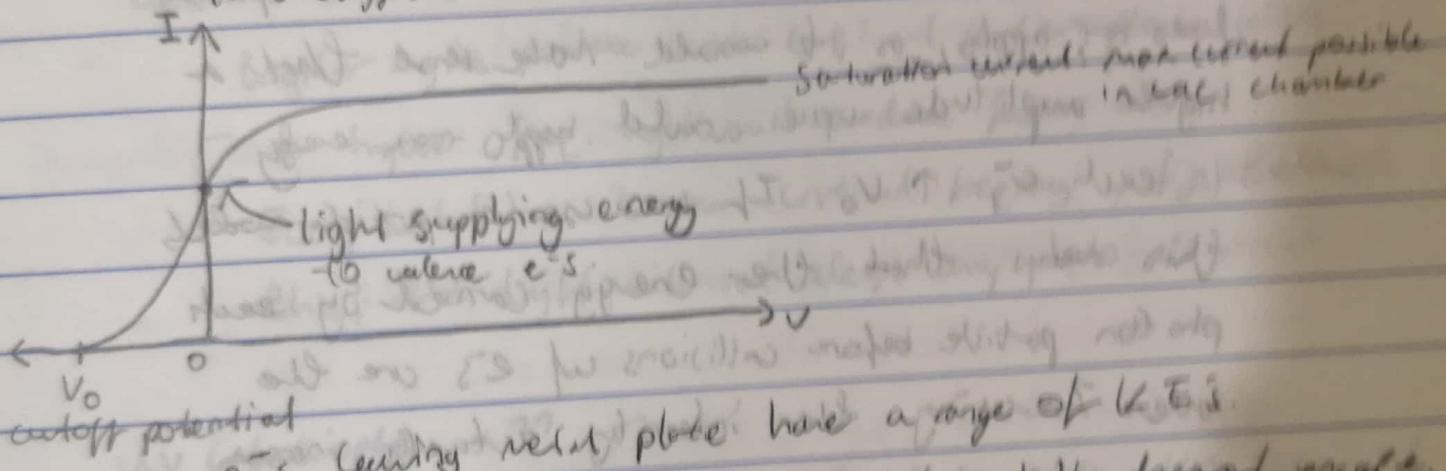
metal plate *monochromatic



Without voltage from the battery, the electrons travelled across the

vacuum chamber when a light was shone against the plate.

This suggests the light gave the e's energy



e^- hitting next plate have a range of KE.
If e^- does not have enough energy from light, doesn't escape.
 $\Rightarrow e^-$ does have energy but not enough KE, doesn't rise.
 e^- requires more KE to travel to collector plate.

$$E_p = qV \quad E_k = \frac{1}{2}mv^2$$

where E_p is electrical potential energy

q is charge

V is voltage (potential diff.)

@ cutoff potential, $qV = \frac{1}{2}mv^2$ for most energetic e^- s.

Qd.

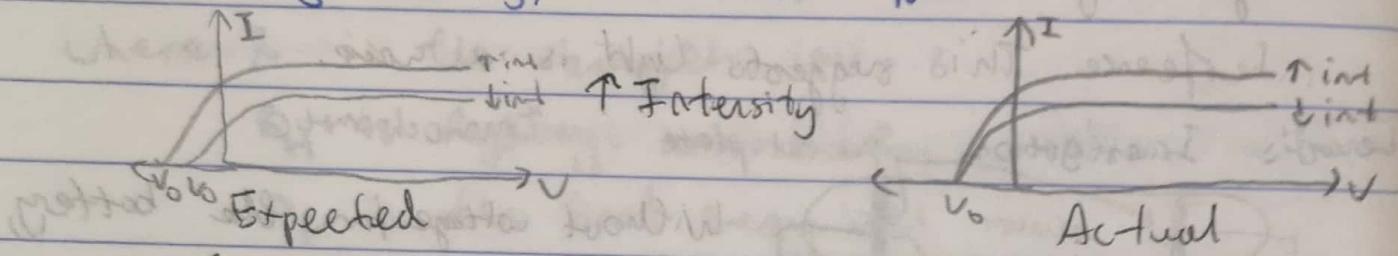
Balmer Series & Stark Effect

Qd. We can write this as: $E_{kinetic} = qV_0$ (horizontal 1:12 which
represents the energy of the electron at the end of the tube)

$$E_{kinetic} = qV_0$$

so the final speed would be dependent on the voltage applied

at changing Frequency, Intensity & Surface



Increasing the intensity increases the saturation current I_s and I_s at no voltage, but the cut-off potential stays the same.

This means the wave model for the electron plasma

does not apply, as it would make sense that a higher amplitude wave would supply more energy

to each e^- , $\uparrow V_0$. If we use a particle model,

this means that the energy carried by each photon particle before collisions w/ e^- s are the same.

Increasing the intensity actually increases

the amount of photons sent, not their individual

energies.

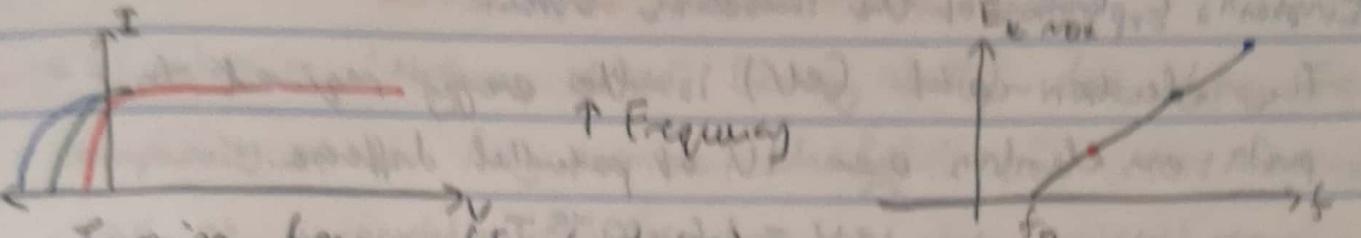
Now to go back to the theory of the cathode

emission theory, the rate of emission

depends on

(After heating) emission is proportional to

area of $\propto \text{Area}^2 = V_0^2$ (heating factor)



Increasing frequency (f of photon)

Decreasing V_p and increasing $E_{kinetic}$.

(Action summary) By now we know what happens is not as

Wave theory predicts: (a) no effect due to f

and (b) brighter lights produce more and faster photo-electrons

- A higher frequency light will not change anything

Lenard's Results show:

- Brighter lights produce more but not faster photo-electrons

~~length~~ → A higher freq. light will produce faster e⁻s.

When light has its own critical frequency, f_0 . Below this,

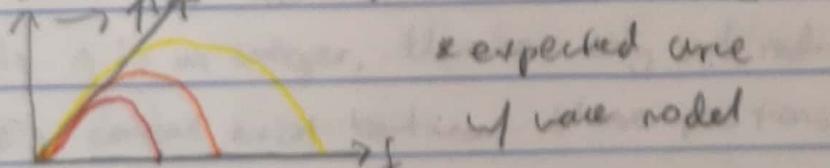
the light will not release any photo-e⁻s.

UV Catastrophe → ??

Black body: object that absorbs and re-emits all radiation it

receives.

Theory & practice for black body radiation disagree.



Planck proposed that energy was emitted in short bursts instead of one continuous stream called energy quanta.

$$E = h f$$

where h is Planck's constant, $h = 6.63 \times 10^{-34}$

f is frequency

Einstein's Explanation of the Photoelectric Effect.

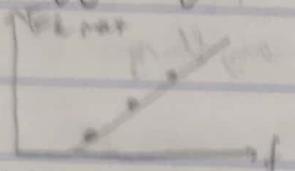
The electron-volt (eV) is the energy required to push an electron over 1V of potential difference.

$$1\text{eV} = 1.6 \times 10^{-19} \text{ J}$$

Requirements for Einstein's Model:

1. A photon gives all its energy to an e^- .
2. An e^- must take energy from one photon of energy $h\nu$.

The work function (W) is a measure of the metal's the energy required for an e^- to escape its metal's nucleus.



$$\begin{aligned} E_{k\max} &= hf - W \\ &= mx + c \end{aligned}$$

Millikan's experiments confirmed Einstein's prediction.

Applications

Common uses: photovoltaic light meters, solar panels

$$m_{e^-} = 9.109 \times 10^{-31} \text{ kg}$$



Bohr's Model of the Atom

- e⁻s exist in "stationary states" (energy shells) where they are unexplainably stable. Any permanent change in their motion must consist of a complete transition from one state to the other.
- No radiation is emitted from an atom in a stationary state. A transition between states will cause an emission/absorption of radiation (photon). The photon's frequency is ~~is~~ ~~and ultraviolet energies~~

$$\Delta E = E_1 - E_2 \text{ (in units of } J)$$

where E₁ and E₂ are the energy states.

- An e⁻ in a stationary state has an angular momentum of a multiple of $\frac{h}{2\pi}$.

Coulomb's law shows $F_C = \frac{kZ e^2}{r^2}$

where F_C is the electrostatic attractive force (N)

k is Coulomb's constant, k = $8.988 \times 10^9 \text{ Nm}^2 \text{ C}^{-2}$

Z is the atomic number of the atom

e is the fundamental charge, e = $1.6 \times 10^{-19} \text{ C}$

Radius of H energy level $r_n = n^2 \times 5.3 \times 10^{-11} \text{ m}$

As n is an integer, there are only set radii possible.

e⁻s cannot exist between these positions.

Energy levels of H $E_n = \frac{-1.7 \times 10^{-18}}{n^2} \text{ J}$

grand state	n = 1
1st excited state	n = 2
2nd excited state	n = 3
⋮	⋮

or

$$E_n = \frac{-13.6}{n^2} \text{ eV}$$

Ionisation energy: energy req. to remove e⁻ from atom (n = ∞)

Fundamental Forces

Gravity $F = \frac{G m_1 m_2}{r^2}$ nucleons - protons and neutrons

Electrostatic $F = \frac{k q_1 q_2}{r^2}$

Strong Nuclear force acts between nucleons in nucleus

- Force that acts over the small distance in nucleus ($\approx 10^{-15} \text{ m}$) to hold nucleons together against repulsive electrostatic forces exerted between protons.

- If protons are too far apart, electrostatic F is too small and too many neutrons overcomes strong nuclear $F \rightarrow$ nucleus breaks up.
- If nucleons are too close, strong nuclear F is too large and F has repulsive effect. Both repulsive

~~too few neutrons~~ → nucleus breaks up.

- Some number of protons and neutrons will create stable (arrange in stable shells)
- As $\# p^+$ ↑, more n^0 than p^+ required to be "stable"

Radioisotopes

- Isotopes that are unstable e.g. ^{12}C stable, ^{14}C and ^{15}C unstable

Binding Energy

- E required to overcome strong nuclear force - pull nucleus apart into separate nucleons

measured by Δ binding energy, $\Delta E = E_{\text{initial}} - E_{\text{final}}$

- $\frac{1}{12}$ of the mass of a ^{12}C nucleus

$$1 \text{ amu} = 1.661 \times 10^{-27} \text{ kg}$$

$$m_p = 1.007276 \text{ amu}$$

$$m_n = 1.008665 \text{ amu}$$

Mass Defect

- There is a difference, for example, Δm - the mass of a He^{4+} nucleus and the mass of $2\text{p}^1 + 2\text{n}^0$.

- Mass is always conserved, except now Δm

→ Mass defect is the difference between the mass of a nucleus and the mass of its nucleons.

- The binding energy needs to be added to separate atoms into nuclei. This is essentially "adding mass".

Mass-Energy Equivalence

- Binding energy is calculated with:

$$E = m_0 c^2$$

$$\frac{\Delta m}{c^2} = \frac{\text{binding E}}{(J)} = \frac{\text{mass defect}}{(kg)} = \frac{\text{speed of light}^2}{(3 \times 10^8 \text{ m/s})^2}$$

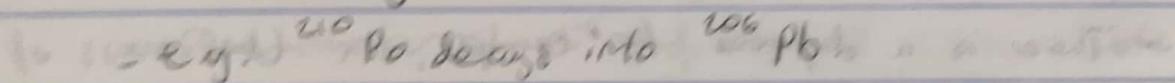
$$m_0 = 1 \text{ amu} \rightarrow E = 1.49 \times 10^{-10} \text{ J} = 931 \text{ MeV}$$

Binding Energy per Nucleon

- Binding E \propto no. of nucleons
- Nuclei with mass no. ≈ 60 are most stable as they have greatest avg. binding E per nucleon
- Mass no. $> 60 \rightarrow$ avg. binding E per nucleon decreases

Radioactive Decay

- Occurs when nuclei of radionuclides break down into smaller nuclei releasing radiation.
- The resulting atom formed is called a "decay product" or "daughter nucleus".



Decay Chain / Series

- Sequence of elements formed during radioactive decay

Half-life $t_{1/2}$

- Time taken for half of the atoms in a sample to undergo radioactive decay.

- Decay equation:

$$\frac{\text{no. sample left}}{\text{Original sample amt}} = \frac{1}{2^n}$$

where n is no. of elapsed half-lives

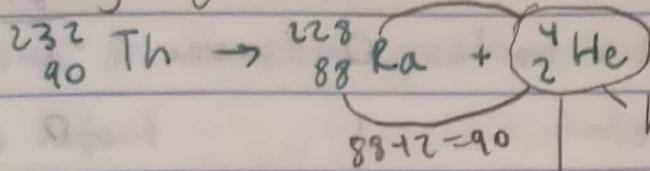
$$\text{of: } N = N_0 e^{-\lambda t} \quad \text{decay constant, } \lambda = \frac{\ln 2}{t_{1/2}}$$

(kg/no. of nuclei) Original mass / unit nuclei

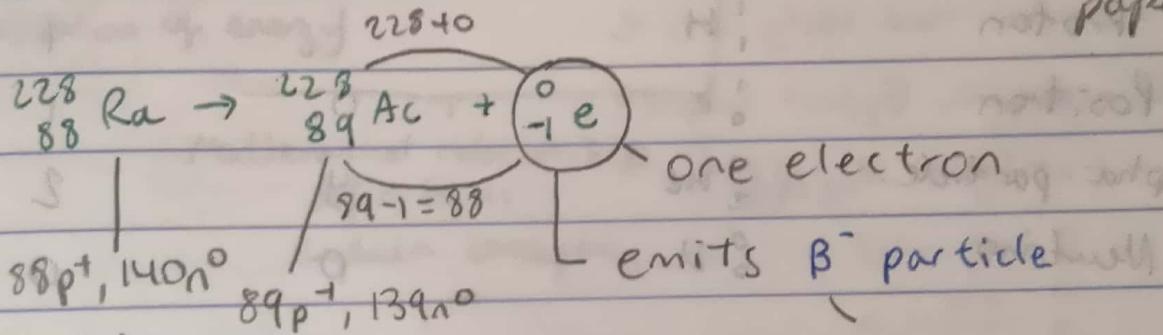
$$\lambda = \ln 2 / t_{1/2} \quad (\text{kg/no. of nuclei})$$

Radiation

Example decay equation: $^{228}\text{Th} \rightarrow ^{228}\text{Ra} + ^4_2\text{He}$



helium nucleus stopped by
emits α particle 1 sheet of
paper



one electron

emits β^- particle

One neutron has turned into a proton by emitting its negative charge (emits β^-)

β^+ particle - positron ($^0_{+1}\text{e}$)

When β^- and β^+ come into contact, they annihilate each other and emit photons.

γ particle - high-energy photon

Transmutation Process

<u>Particle</u>	<u>Symbol</u>	<u>Mass</u>	<u>Charge</u>
Electron/beta particle	e^-	0	-1
Neutron	n	0	0
Photon/gamma ray	γ	0	0
Proton	1H	1	1
Positron	e^+	0	1
Alpha particle	4_2He	4	2
Neutrino	ν	0	0

EEI Ideas

- Sound
- Electromagnetism
- Thermal (but easily influenced by ext factors)
- Light (Learn next term)

K&A 1 - Reproduce and Interpret

- emission & absorption spectrum & sound intensity, intensity level & loudness
 - mass defect
 - half-life & decay constant
 - quantisation of energy
- Mathematical relationships
definitions
explain concepts
- 3.0 points from each category

K&A 2 - Comparison & Explanation

- Lenard's results in photoelectric experiment
 - Fundamental forces
 - mass before/after fission
 - penetrating & ionizing power
 - isotopes vs. ions
- explain phenomena
- 2 A's, 2 B's, 4 C's, 2 D's

Paper B

Brom content Test 2 (6th), 20 min

A 20g

IGAP 3 - Analysis and Identification

and all other plants choose ONE and set a time limit to 20 mins.

very strict & up to 20 mins

Two datasets:

1. Concentration - Depth graph

- Graphs, most likely L & E

2. Photoelectric Effect Results

- f or light, v_0 , E_{kmax}

- $E = hf = W$

$$\frac{h}{\text{m}} \frac{\text{J}}{\text{s}} \frac{\text{eV}}{\text{s}}$$

Identifying relationships
noting patterns
noting refraction to data
trends
errors
anomalies

Calculate constants,

then compare to
accepted val.

$$e.g. F_g = \frac{G m_1 m_2}{r^2}$$

F_g	m_1	m_2	r	$\frac{m_1 m_2}{r^2}$
?	?	?	?	?
?	?	?	?	?
?	?	?	?	?

Work with multiple results from one

dataset, how to bring it together

then scatterplot

$$\text{Slope} \text{ gradient} = mx$$

$$y = mx + c$$

$$\text{many lines? } \frac{M_1 M_2}{r^2} - G = \text{grad}$$

$$\text{obtained gradient; best fit}$$

$$\text{rel. error} = \frac{G - \text{grad}}{G}$$

EC2 - Exploration & Recommendation

same criteria as EC Chemistry

Choose ONE stimulus. — 5min

1. p 577-582, "Who will pay for a nuclear future?"

2. Attached ⁱⁿ email

KCAI - Linking & Application

BGS, 4B's, 2A's

- intensity w/ power
- threshold freq. given W
- string length, frequency
- energy/mass comparisons
- Intensity level w/ intensity
- $E = hf$
- fundamental freq.
- Nuclear eqn's α emission
- Reverb time
- $E = mc^2$
- time takes to travel & come back
- Balmer's eqn

$$\text{e.g. } v_s = 300 \text{ m/s}, t_{\text{true}} = 5 \text{ sec}$$
$$\text{sound travels } \approx 1500 \text{ m}$$
$$\text{distance} = 750 \text{ m}$$

Term 4

Medical Physics

Ultrasound - high frequency sound waves (around 3-5 MHz) - 3000000 Hz = about 3000 waves per second

IMAGING "is another reason a lot more info" , 587-552 g

Ultrasound - looking for echoes or reflections (about A)

- transmit pulses of sound in air at every change (mirror)
- transmitter is also receiver in medium
- No known adverse effects - picks up reflected waves wavelength change ($v = f\lambda$)

X-Ray W looking for shadow away from transmitter =

modern X-Rays pass through body part after 0.752 =

and hit detectors (not film) for less contrast

- leaves "shadow" exposing film (darker) -
detector =

Doppler Ultrasound - detects blood flow direction

- bunches up reflections indicating blood flow towards transmitter
- spaced out reflections indicate blood flow away transmitter

For an object to be detected via ultrasound, the wavelength needs to be shorter than the object. Otherwise, resolution too small.

$\downarrow 2 \text{ mean } T_f: 20 \text{ kHz} \rightarrow 75 \text{ mm}$, too small.

$1.2 \text{ MHz} \rightarrow 1.2 \text{ mm}$, $3.5 \text{ MHz} \rightarrow 0.43 \text{ mm}$ resolution.

old.

ultrasound

However, because $E = hf \rightarrow f \propto E$, too high frequency could result in cell death so frequency is limited. Additionally, because (with a high frequency) the waves have to distinguish between different groups of cells, more of the sound is absorbed which leads to a shorter penetration depth. However, the area that is penetrated has a higher resolution.

Scans of reproductive organs are always ultrasound to minimize the risk of altered meiosis inside gametes due to X-ray radiation.

Placing the transmitter close to the skin with ~~or a~~ ~~an~~ air gap creates a large echo off the skin because of the difference in density and acoustic properties between both mediums. Thus, a gel with similar acoustic properties (impedance) to skin is applied so the transition can be eased.

Acoustic Impedance

The acoustic impedance (Z) of a material measures how readily sound will pass through it.

$$(kgm^{-2}s^{-1}) \quad (kgm^{-3}) \quad (m s^{-1})$$

$$Z = \rho v$$

where Z is acoustic impedance ($kgm^{-2}s^{-1}$)

ρ is density of the medium (kgm^{-3})

v is the velocity of sound in material ($m s^{-1}$)

Table 23.2 lists ρ and v for different materials.

Reflection of Ultrasound

The acoustic impedances of two adjoining tissues are used to calculate the intensity of the reflected pulse compared with that of the incoming one.

Fraction of intensity: (larger difference in $Z \rightarrow$ larger reflection)

$$\frac{\text{intensity of pulse reflected}}{\text{intensity of pulse incident}} = \frac{I_r}{I_0} = \frac{(Z_f - Z_i)^2}{(Z_f + Z_i)^2}$$

initial medium $\rightarrow Z$
final medium $\rightarrow Z$

($kgm^{-2}s^{-1}$)

Intensity of Ultrasound

Power levels of ultrasound imaging must be kept between 0.01 to 20 Wcm^{-2} to avoid cellular death. $1 Wcm^{-2}$ is used to heat tissues for therapy and $10^3 Wcm^{-2}$ is used to destroy tissue. Multiple sources of ultrasound can be layered so that constructive interference is generated at the target location.

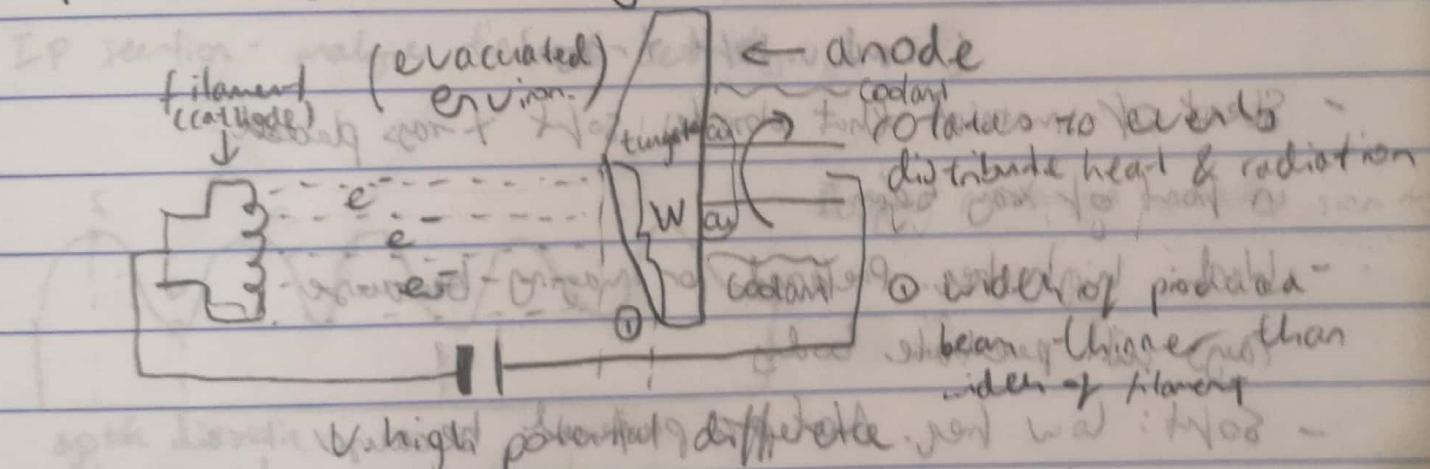
Topic 4: Emission & Ionization

$^{91}_{41} \text{Molybdenum} \xrightarrow{\text{heat}} \text{Molybdenum}^{90} + \gamma$. γ radiation along w -
 $^{90m}_{43} \text{Mo} \rightarrow \text{Mo}^{90} + \gamma$. γ radiation along w -
 - emitted from cathode at certain heat -

$N = N_0 e^{-\lambda t}$ - no below vs with quantity of time passed

$\Delta N = N_0$ (Intensity X-Rays) \propto time t , area A -

- Electromagnetic waves w/ very short wavelength $\approx 10^{-10} \text{ m}$
- When passing through body, radiation absorbed and intensity reduced. \propto mass \propto scatterer
- Produced by cathode ray tube. \propto heat



- W emits γ -rays when struck by e^- . Melting point high enough (3400°C). However, W heats up about 100 times less (91% energy used converted into heat), 99% left converted to heat.

- * due to electron (quantal - one) specific jumps from top shell to bottom shell produces γ -ray. The rest do not carry enough energy (multiple jumps).

Bremsstrahlung (braking radiation) radiation incoming -

e^- knocks out e^- in inner shell; difference in E emitted. If knocks out low level, γ -ray produced as ΔE is high. See next page

- W mode surrounded by Cu (conductor) and cooled via coolant circulation pump.
 - Anode rotates to distribute heat and radiation which prolongs life of anode.
- * Also, Bremsstrahlung (Braking) radiation generates X-rays: e⁻s slowed down by target (W) atoms. Some of e⁻s KE converted to electromagnetic radiation \rightarrow X-ray. Difference in energy produces different f X-rays. (Hard v. soft X-rays)

- Sheet of material that absorbs soft X-rays placed in front of X-ray beam.
 - Hard: high freq. Preferred for imaging because rays will penetrate body
 - Soft: low freq. Not preferred because rays will be absorbed, increasing dose over time W -
 - X-rays, after absorbed, ionize e⁻s (creating free radicals) in body. Will damage DNA sequence; possibly transmitted to children if & gametes damaged
- ~~more quanta & strings (kV & mAs) particles at each \uparrow kV \rightarrow emitting more & \uparrow mAs less \downarrow~~
- More energy to e⁻s \rightarrow more e⁻s emitted
 - more penetrating rays \rightarrow higher resolution image
 - used for deeper parts of body \rightarrow too absorb to penetrate \rightarrow here is a trade off between \uparrow kV setting & mAs setting

Term 4 Exam Formulas Required

$$v = f\lambda$$

$$Z = \rho v$$

$$\frac{I_c}{I_0} = \frac{(z_f - z_i)^2}{(z_f + z_i)^2}$$

$$N = N_0 \left(\frac{1}{2}\right)^n \rightarrow n = \log_{1/2} \left(\frac{N}{N_0}\right) \quad n \text{ is no. of } t_{1/2} \text{ s elapsed}$$

$$\rightarrow N = N_0 e^{-\lambda t}, \quad \lambda = \frac{\ln 2}{t_{1/2}}$$

$$\text{Activity } A = \frac{\lambda}{2} N, \quad A \text{ (Bq) decays s}^{-1}$$

$$\rightarrow A = A_0 e^{-\lambda t}, \quad \lambda = \frac{\ln 2}{t_{1/2}} \quad (\rightarrow \ln \frac{A}{A_0} = -\lambda t)$$

$$E = hf$$

IP section - analyse time & activity

