

```
In [51]: 1 !pip install time
          2 !pip install tqdm
```

```
ERROR: Could not find a version that satisfies the requirement time
(from versions: none)
ERROR: No matching distribution found for time
Collecting tqdm
  Downloading tqdm-4.64.0-py2.py3-none-any.whl (78 kB)
    78.4/78.4 kB 795.0 kB/s
eta 0:00:00.31m 1.5 MB/s eta 0:00:01m
Installing collected packages: tqdm
Successfully installed tqdm-4.64.0
```

```
In [1]: 1 import tensorflow as tf
        2 print("TensorFlow version:", tf.__version__)
```

```
2022-07-13 08:09:56.547867: W tensorflow/stream_executor/platform/d
efault/dso_loader.cc:64] Could not load dynamic library 'libcudart.
so.11.0'; dlerror: libcudart.so.11.0: cannot open shared object fil
e: No such file or directory
2022-07-13 08:09:56.547890: I tensorflow/stream_executor/cuda/cudar
t_stub.cc:29] Ignore above cudart dlerror if you do not have a GPU
set up on your machine.
```

```
TensorFlow version: 2.9.1
```

```
In [54]: 1 import numpy as np
        2 import pandas as pd
        3 import matplotlib.pyplot as plt
        4 import seaborn as sns
        5 import time
        6 from tqdm import tqdm
```

```
In [410]: 1 data = pd.read_csv('data/handtyped_nn/train.csv')
          2 label = data['label']
```

```
In [411]: 1 data /= 254
          2 data['label'] = label
```

```
In [412]: 1 data.head()
```

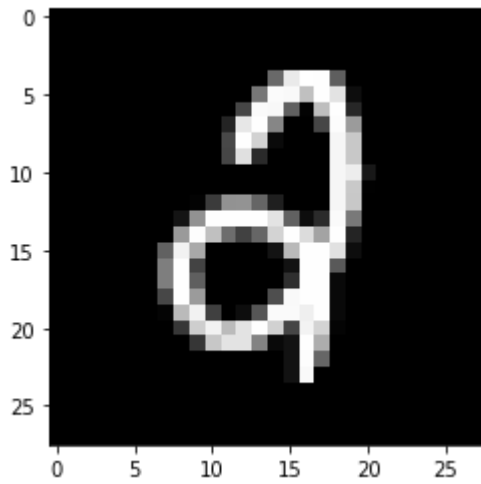
```
Out[412]:
```

	label	pixel0	pixel1	pixel2	pixel3	pixel4	pixel5	pixel6	pixel7	pixel8	...	pixel774	pixel775
0	1	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	...	0.0	0.0
1	0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	...	0.0	0.0
2	1	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	...	0.0	0.0
3	4	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	...	0.0	0.0
4	0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	0.0	...	0.0	0.0

```
5 rows x 785 columns
```

```
In [413]: 1 plt.imshow(data.values[10000][1:].reshape(28, 28), cmap='gray')
```

```
Out[413]: <matplotlib.image.AxesImage at 0x7fb71ea7ff40>
```

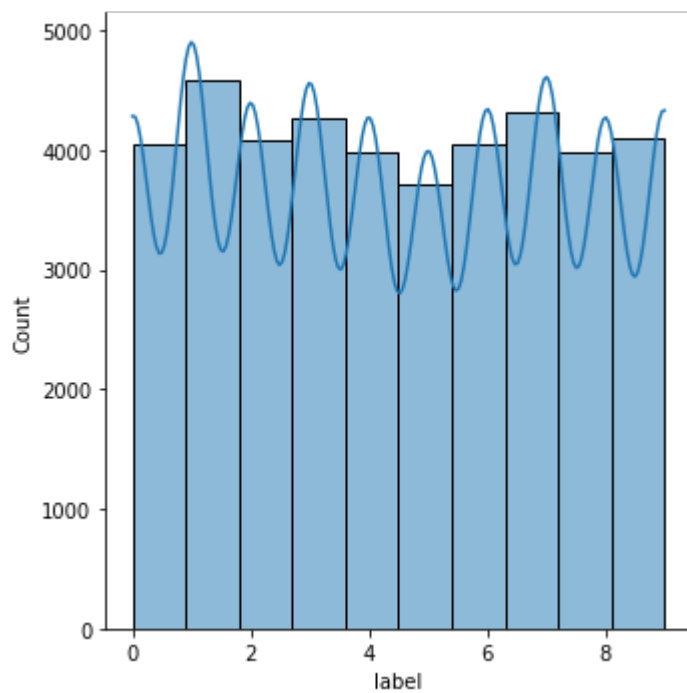
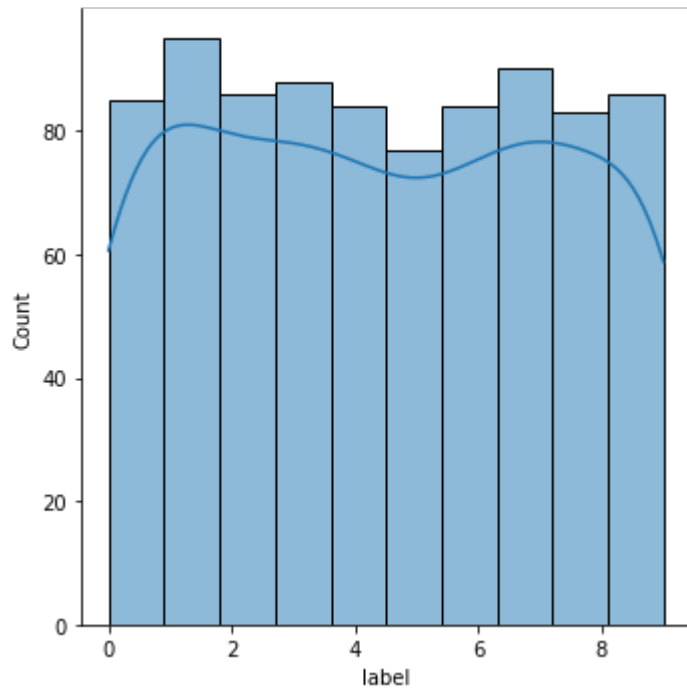


```
In [414]: 1 data.values[10000][1:].reshape(28, 28)
```

[illegible]

```
In [415]: 1 def split_data_1to50(data):
2         test = data.sort_values(by=['label'])[:49]
3         train = pd.concat([data, test]).drop_duplicates(keep=False)
4         sns.displot(test['label'], bins=10, kde=True);
5         sns.displot(train['label'], bins=10, kde=True);
6         return test, train
```

```
In [417]: 1 test, train = split_data_1to50(data)
```



```
In [ ]: 1
```

```
In [ ]: 1
```

```
In [ ]: 1
```

```
In [425]: 1 class MyNN:
2         def __init__(self):
3             self.learn_rate = 0.01
4
5             self._weights0 = np.random.rand(10, 16)-0.5
6             self._weights1 = np.random.rand(16, 49)-0.5
7             self._weights2 = np.random.rand(49, 784)-0.5
```

```

8
9     self._input = np.zeros([10])
10    self._layer1 = np.zeros([16])
11    self._layer2 = np.zeros([49])
12    self._output = np.zeros([784])
13
14    self._correction_0 = np.zeros([10, 16])
15    self._correction_1 = np.zeros([16, 49])
16    self._correction_2 = np.zeros([49, 784])
17
18    self._activation0 = self.act_relu
19    self._activation1 = self.act_relu
20    self._activation2 = self.act_relu
21
22    self._der_act_0 = self.der_act_relu
23    self._der_act_1 = self.der_act_relu
24    self._der_act_2 = self.der_act_relu
25
26    def zero(self):
27        self._input = np.zeros([10])
28        self._layer1 = np.zeros([16])
29        self._layer2 = np.zeros([49])
30        self._output = np.zeros([784])
31
32    def act_sigmoid(self, layer):
33        return np.array([1/(1+np.exp(-x)) for x in layer])
34
35    def act_relu(self, layer):
36        return np.array([x if x > 0 else 0 for x in layer])
37
38    def act_softplus(self, layer):
39        return np.array([np.log(1+np.exp(x)) for x in layer])
40
41    def der_act_sigmoid(self, l):
42        _exp = np.exp(-l)
43        return _exp / (1+_exp)**2
44
45    def der_act_relu(self, l):
46        if l > 0:
47            return 1
48        else:
49            return 0
50
51    def der_act_softplus(self, l):
52        return 1 / (1+np.exp(-l))
53
54    def predict(self, num):
55        self.zero()
56        self._input = np.array([100 if k == num[0] else 0 for k in range(10)])
57        #print(num, self._input)
58
59        self._layer1 = np.dot(self._input, self._weights0)
60        self._layer1 = self._activation0(self._layer1)
61        #print(" ", self._layer1)
62
63
64        self._layer2 = np.dot(self._layer1, self._weights1)
65        self._layer2 = self._activation1(self._layer2)
66
67        self._output = np.dot(self._layer2, self._weights2)

```

```

68         self._output = self._activation2(self._output)
69
70         return self._output
71
72     def learn(self, labels):
73
74         main_delta = self._output - labels
75         delta_output = main_delta * [self._der_act_2(x) for x in self._output]
76         delta_w_2 = np.dot(delta_output.reshape(len(delta_output), 1),
77                             self._layer2.reshape(1, len(self._layer2)))
78
79         delta_layer2 = np.dot(self._weights2, delta_output) * [self._der_act_2(x) for x in self._output]
80         delta_w_1 = np.dot(delta_layer2.reshape(len(delta_layer2), 1),
81                             self._layer1.reshape(1, len(self._layer1)))
82
83         delta_layer1 = np.dot(self._weights1, delta_layer2) * [self._der_act_2(x) for x in self._output]
84         delta_w_0 = np.dot(delta_layer1.reshape(len(delta_layer1), 1),
85                             self._input.reshape(1, len(self._input)))
86
87         self._correction_0 += np.transpose(delta_w_0)
88         self._correction_1 += np.transpose(delta_w_1)
89         self._correction_2 += np.transpose(delta_w_2)
90
91     def update(self):
92         self._weights0 = self._weights0 - self.learn_rate * self._correction_0
93         self._weights1 = self._weights1 - self.learn_rate * self._correction_1
94         self._weights2 = self._weights2 - self.learn_rate * self._correction_2
95
96         self._correction_0 = np.zeros([10, 16])
97         self._correction_1 = np.zeros([16, 49])
98         self._correction_2 = np.zeros([49, 784])
99

```

In [426]:

```

1 NN = MyNN()
2
3 NN._activation0 = NN.act_sigmoid
4 NN._activation1 = NN.act_sigmoid
5 NN._activation2 = NN.act_sigmoid
6
7 NN._der_act_0 = NN.der_act_sigmoid
8 NN._der_act_1 = NN.der_act_sigmoid
9 NN._der_act_2 = NN.der_act_sigmoid
10

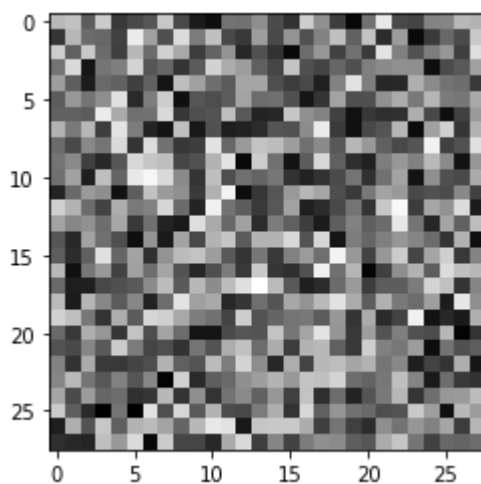
```

In []:

1

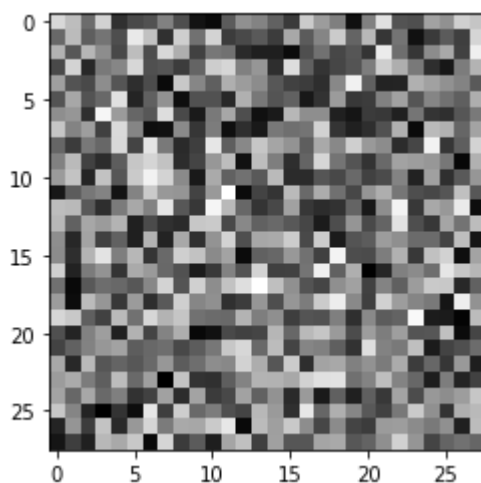
```
In [427]: 1 res = NN.predict([0])
          2 plt.imshow(res.reshape(28, 28), cmap='gray')
```

Out[427]: <matplotlib.image.AxesImage at 0x7fb71fa89190>



```
In [428]: 1 res = NN.predict([1])
          2 plt.imshow(res.reshape(28, 28), cmap='gray')
```

Out[428]: <matplotlib.image.AxesImage at 0x7fb71f0f4250>



```
In [429]: 1 def print_predictions(nn):
          2     plt.figure(figsize=(10,10))
          3     for i in range(10):
          4         plt.subplot(5,5,i+1)
          5         plt.xticks([])
          6         plt.yticks([])
          7         plt.grid(False)
          8         res = nn.predict([i])
          9         plt.imshow(res.reshape(28, 28), cmap='gray')
         10         plt.xlabel(i)
         11     plt.show()
         12
```

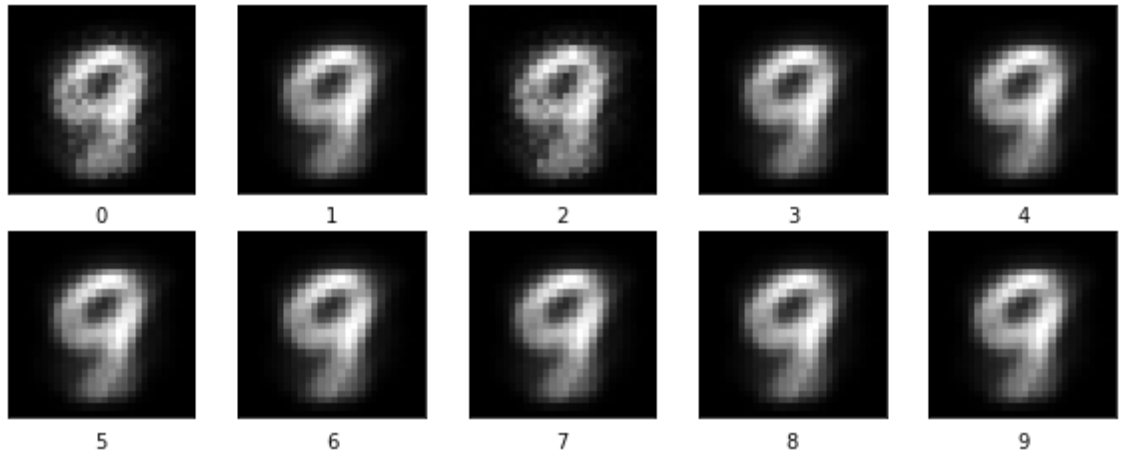
```
In [430]: 1 #data = data.sort_values(by=['label'])
          2
```

```
In [431]: 1 epohs = 100
          2 uprate = 5
```

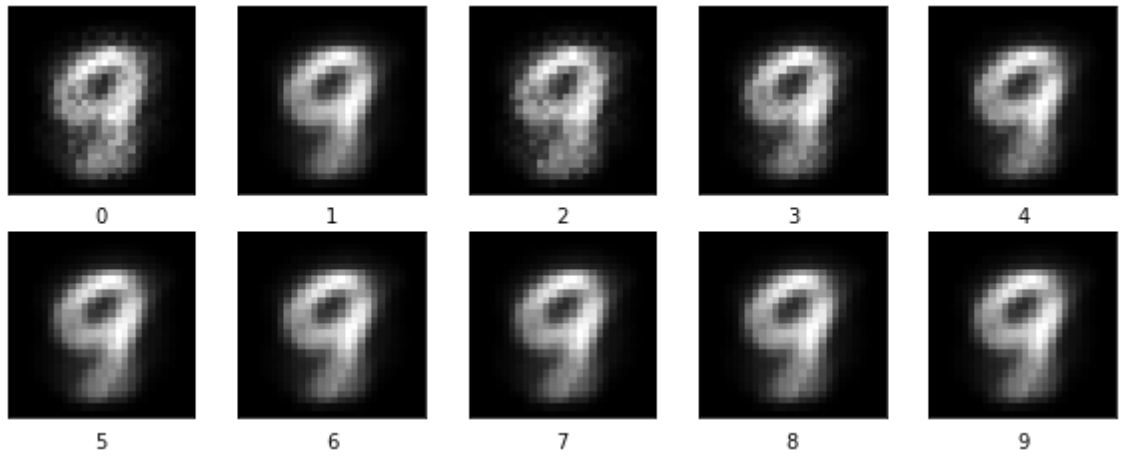
E: 0

100% |

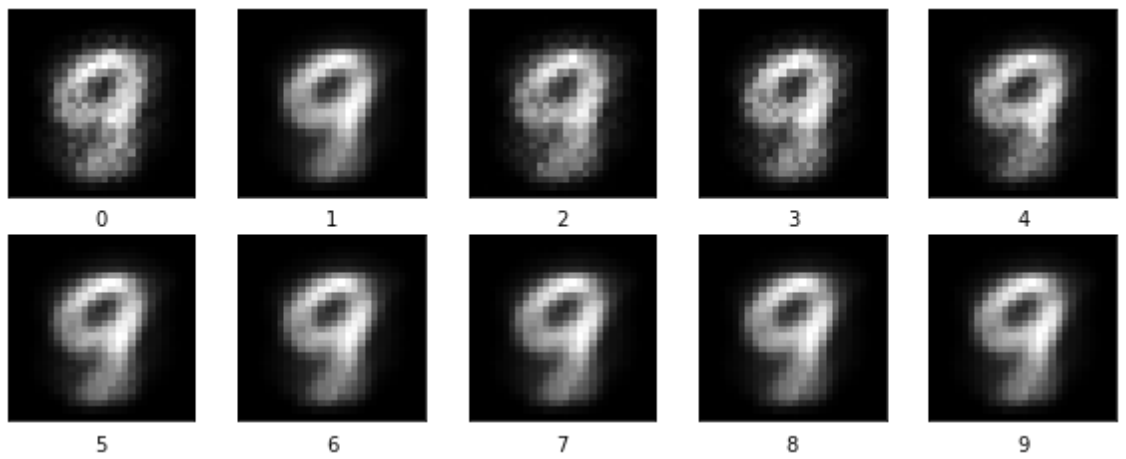
```
0it/s]
```



E: 3

[illegible]

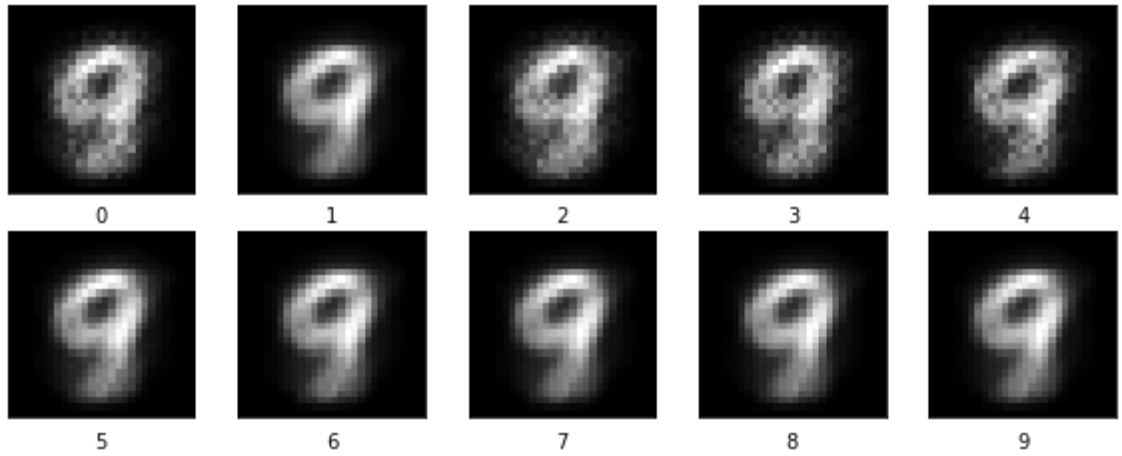
E: 4

[illegible]

E: 5

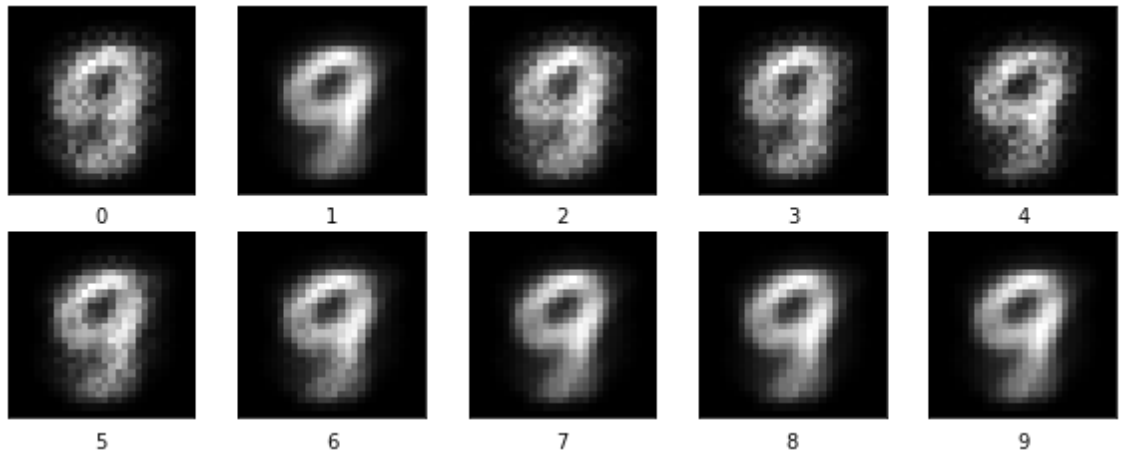
100%


```
|██████████| 858/858 [00:10<00:00, 80.3  
lit/s]
```

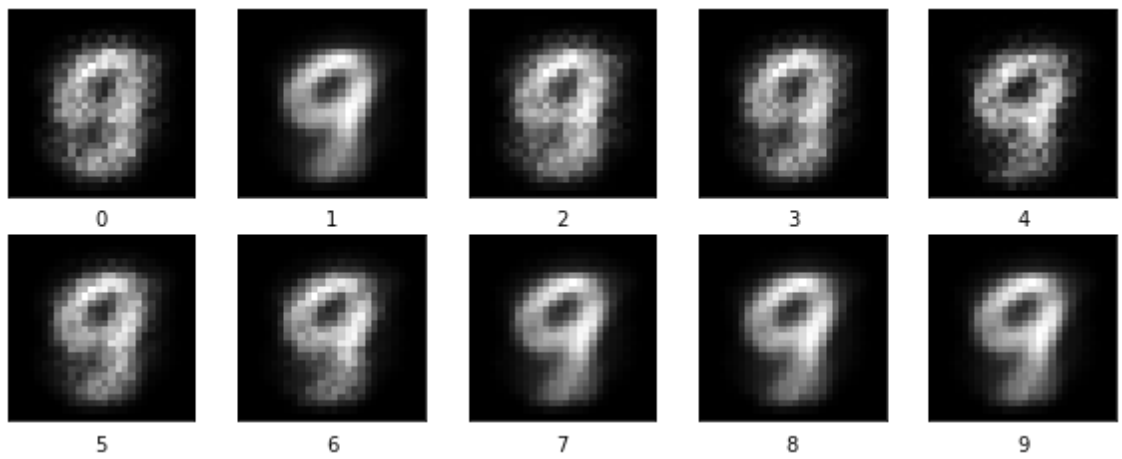


E: 6

```
100%|██████████| ██████████ | 858/858 [00:10<00:00, 82.1  
3it/s]
```



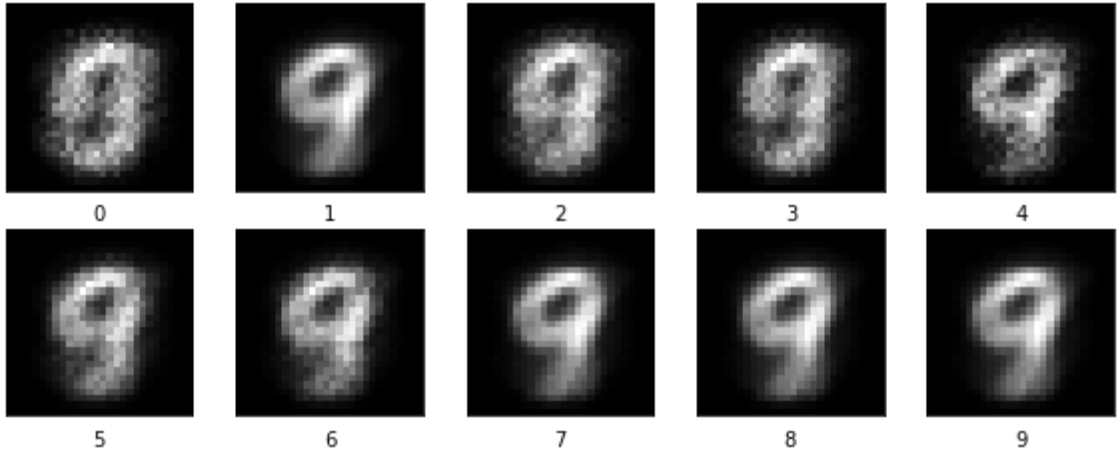
E: 7

[illegible]

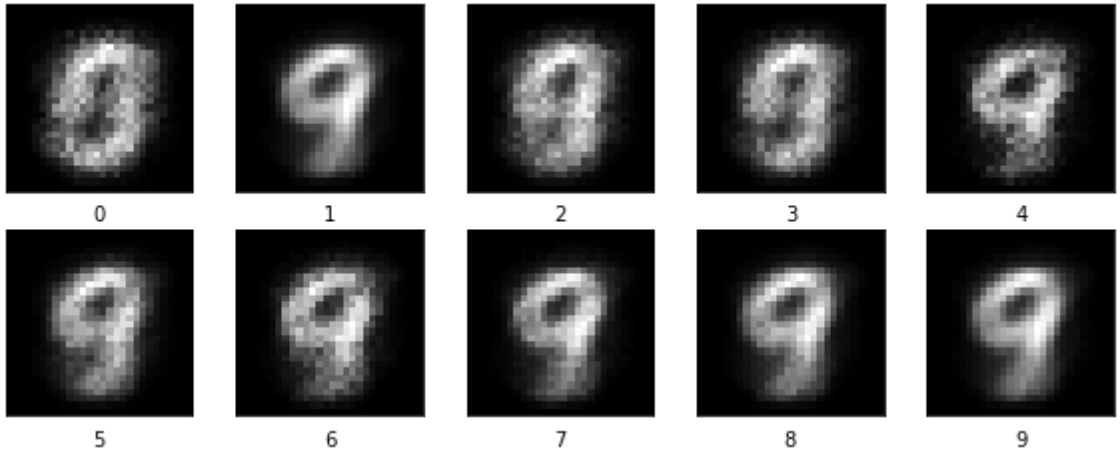
E: 8

100%|

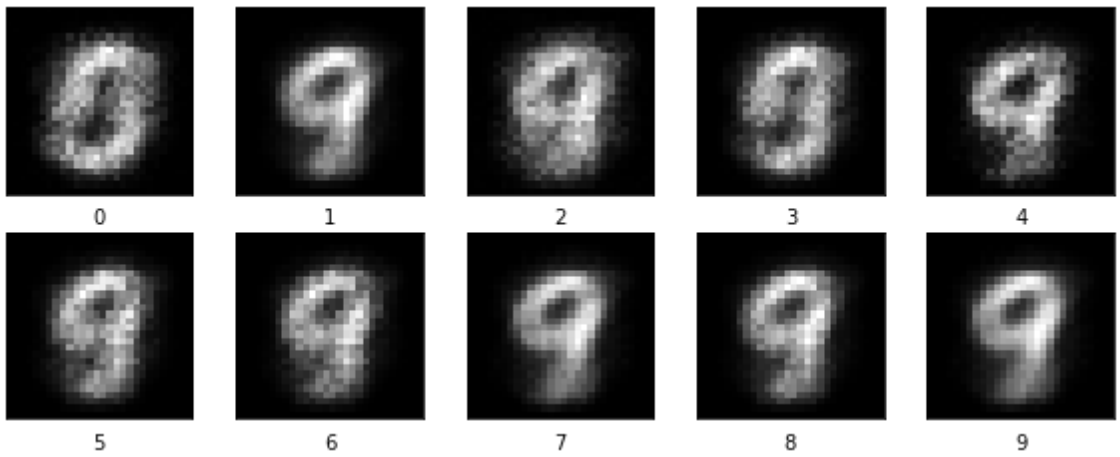
```
|██████████| 858/858 [00:10<00:00, 81.79it/s]
```



E: 9

[illegible]

E: 10

[illegible]

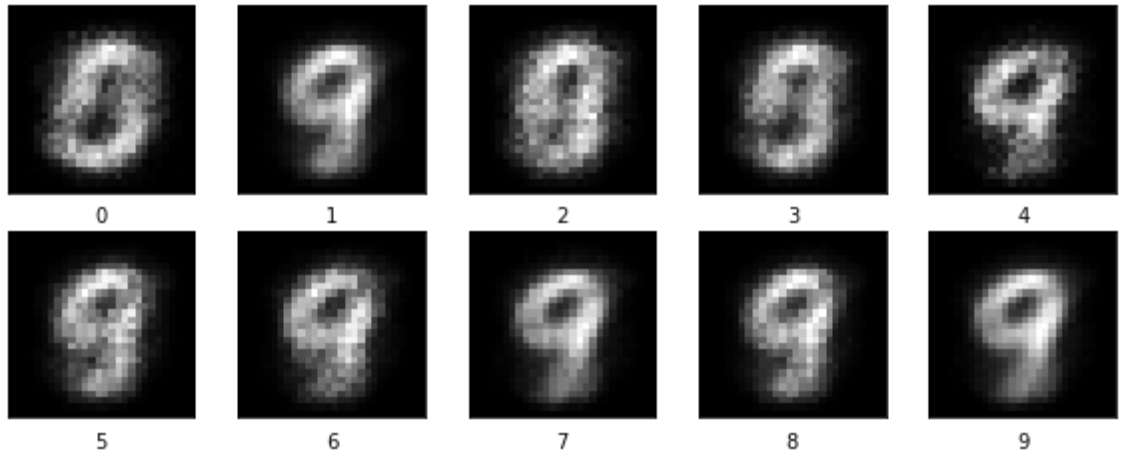
E: 11

[illegible]

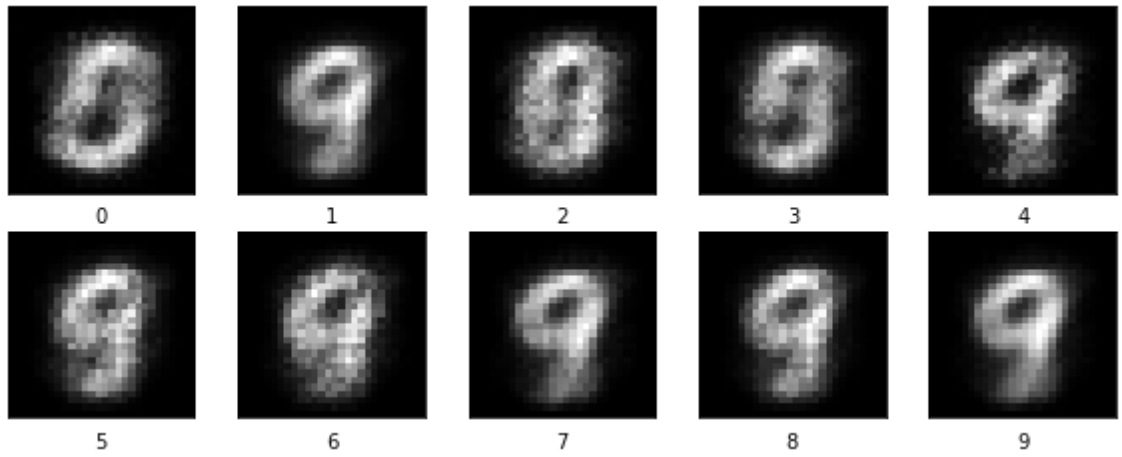
```

[REDACTED] | 858/858 [00:10<00:00, 82.3
lit/s]

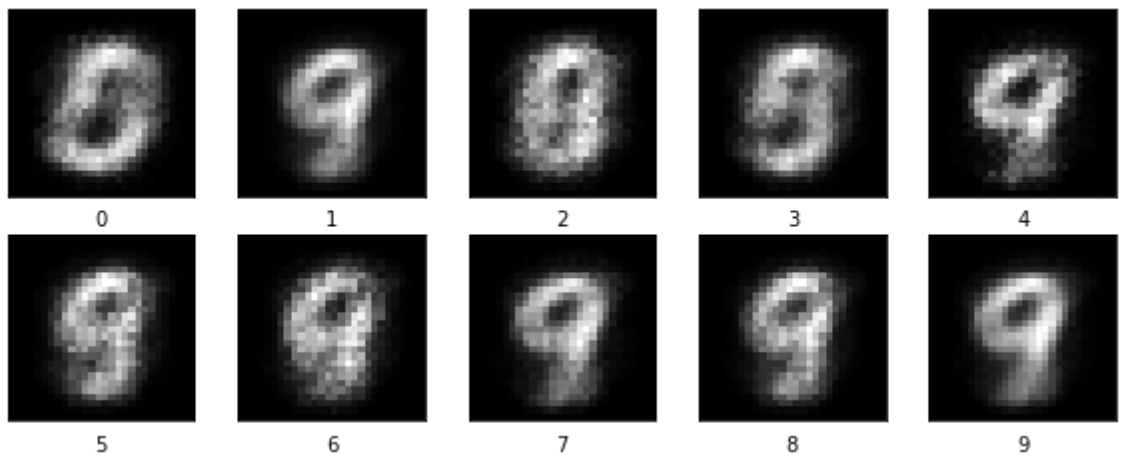
```



E: 12



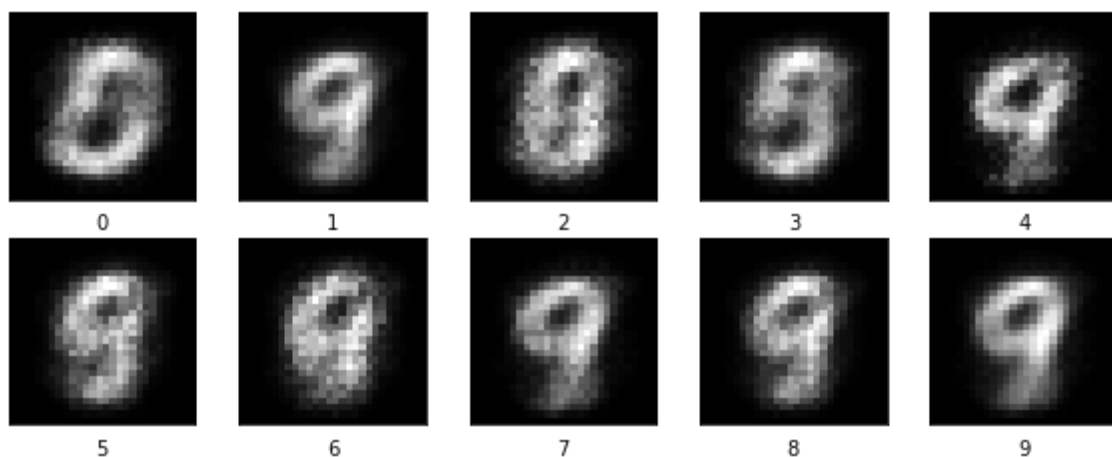
E: 13



E: 14

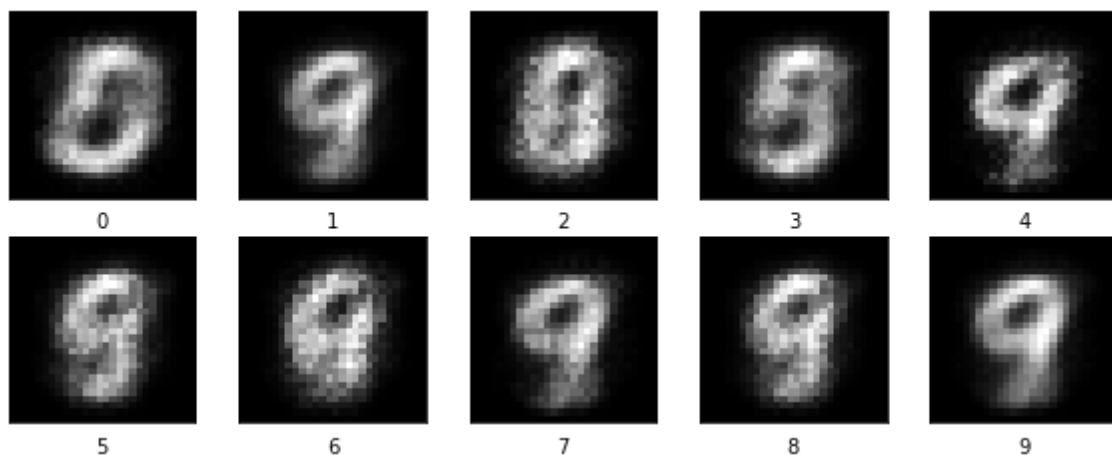
100%|

858/858 [00:10<00:00, 82.0
3it/s]



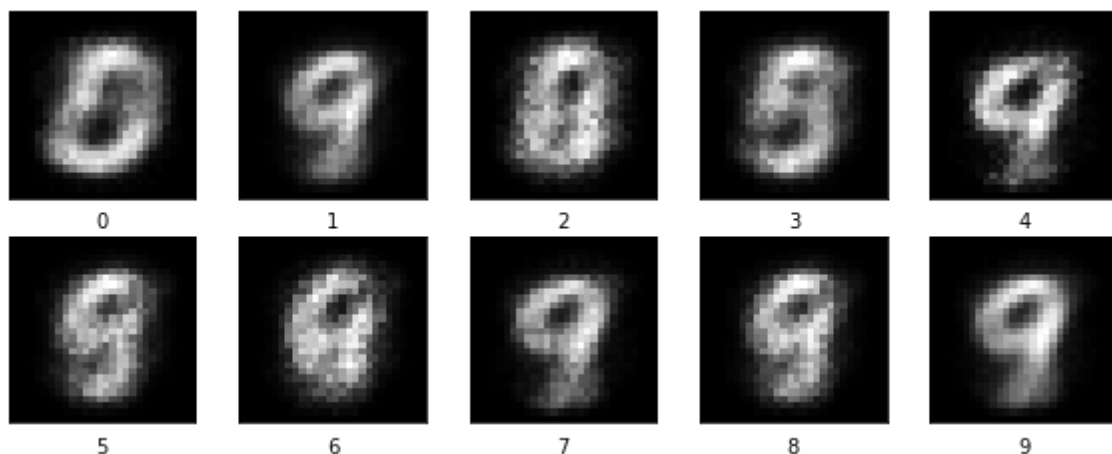
E: 15

100%| 858/858 [00:10<00:00, 80.7
7it/s]



E: 16

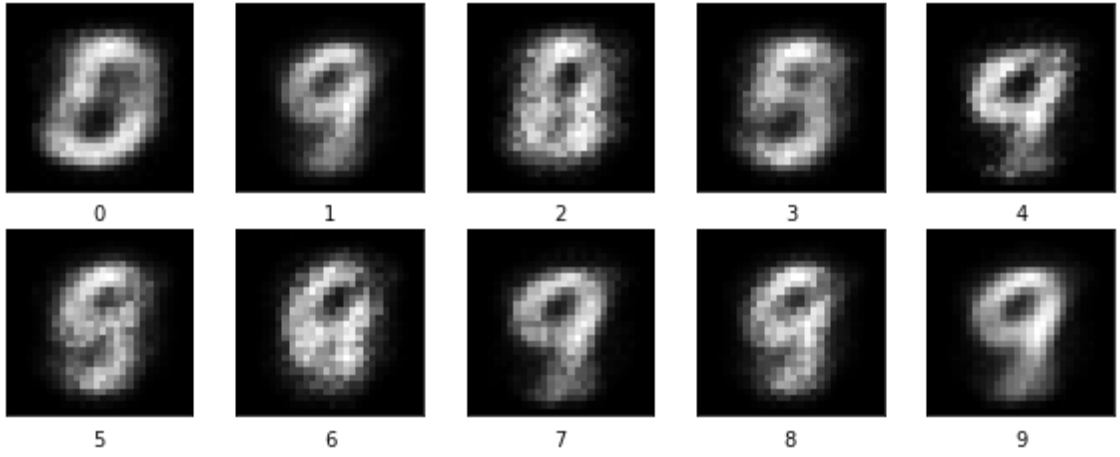
100%| 858/858 [00:10<00:00, 81.1
5it/s]



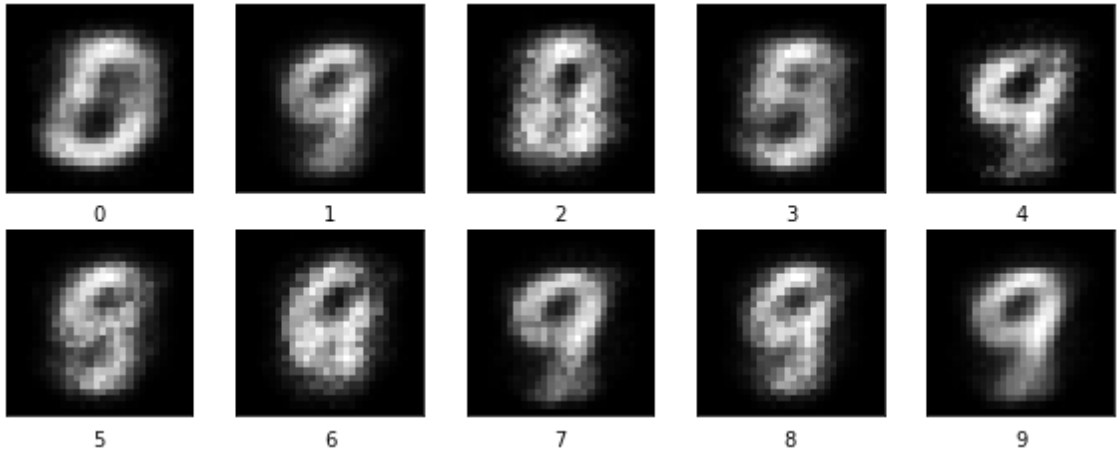
E: 17

100%|

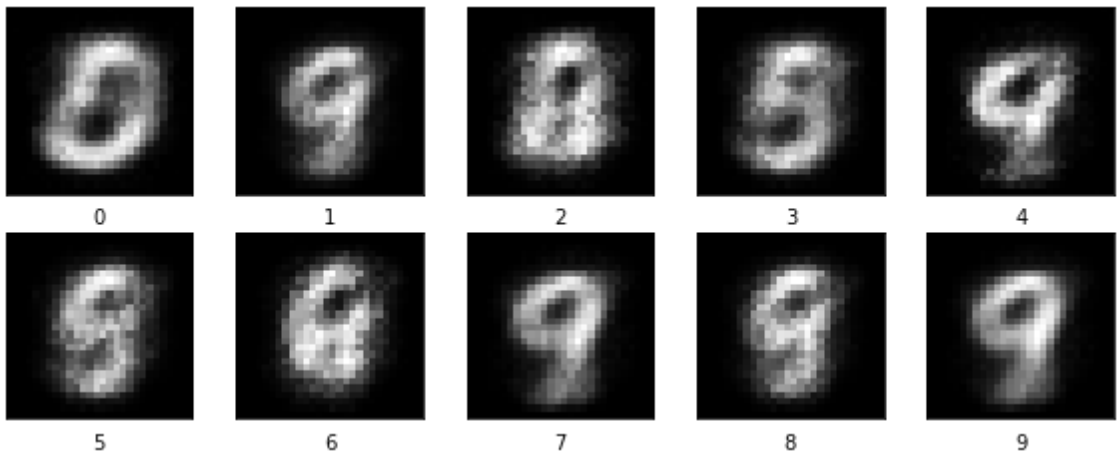
```
|██████████| 858/858 [00:10<00:00, 81.0  
9it/s]
```



E: 18

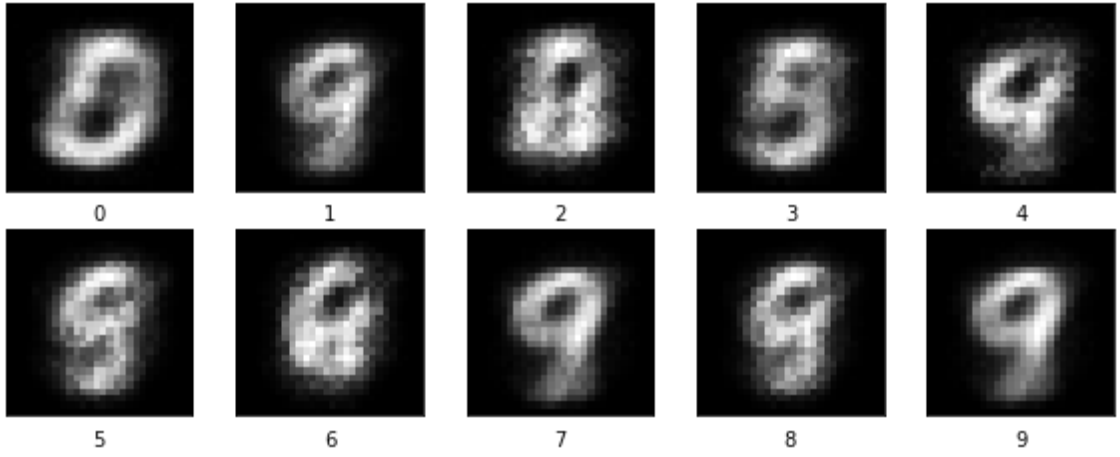
[illegible]

E: 19

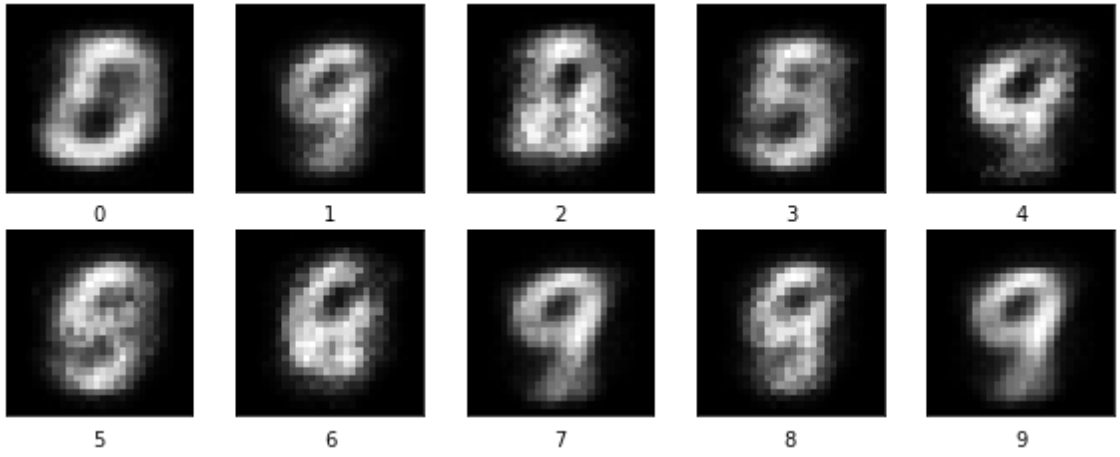
[illegible]

E: 20

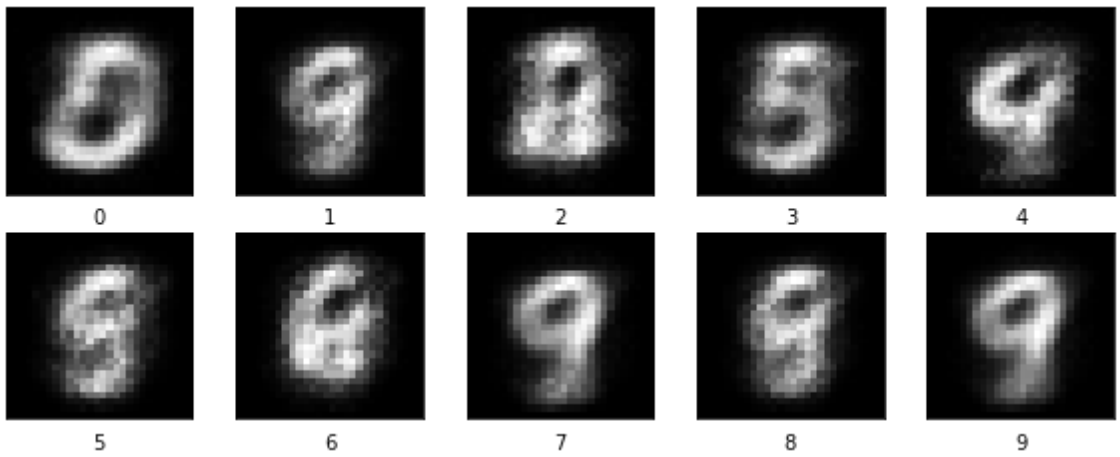
```
|██████████| 858/858 [00:10<00:00, 78.3  
9it/s]
```



E: 21

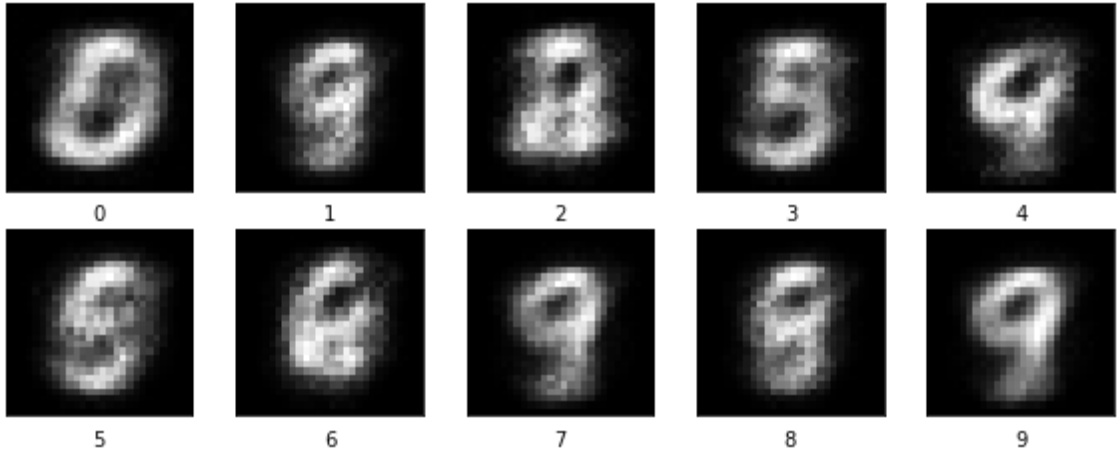
[illegible]

E: 22

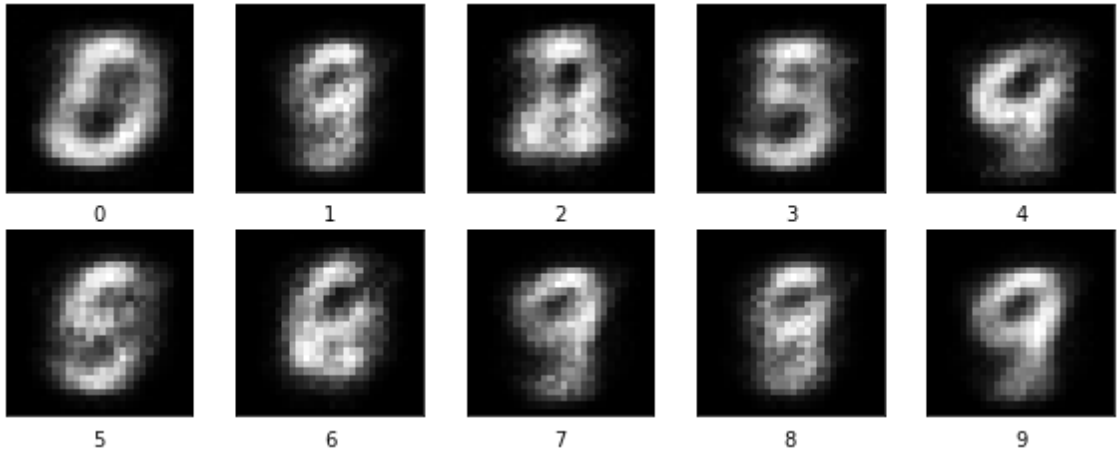
[illegible]

E: 23

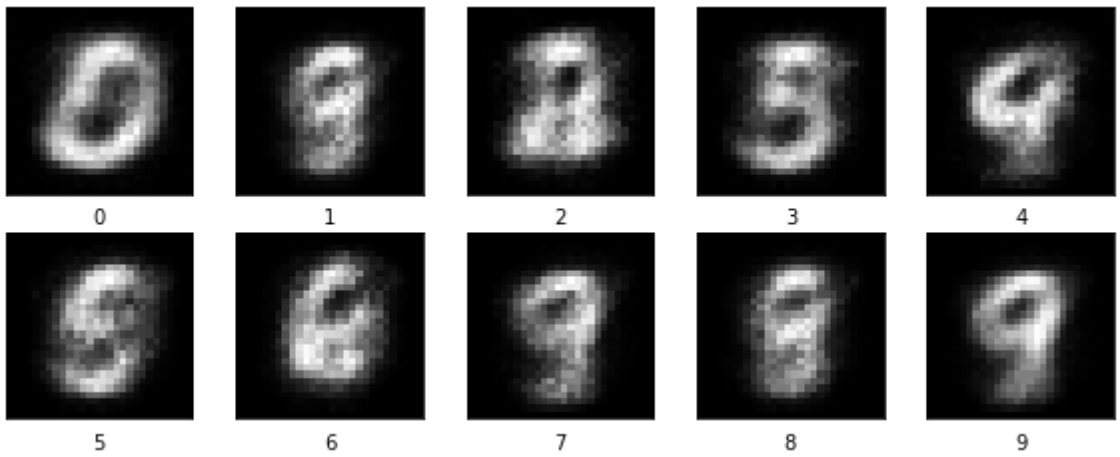
100%|



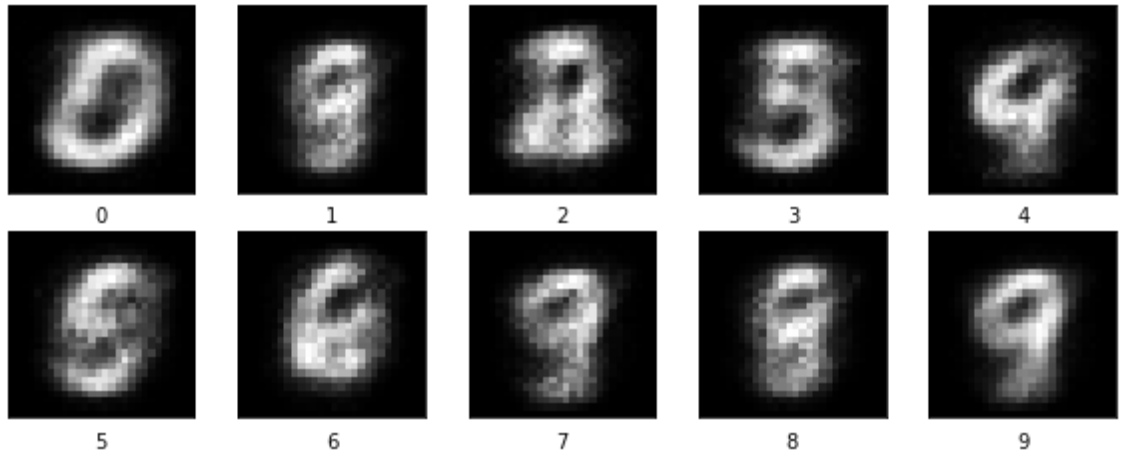
E: 24



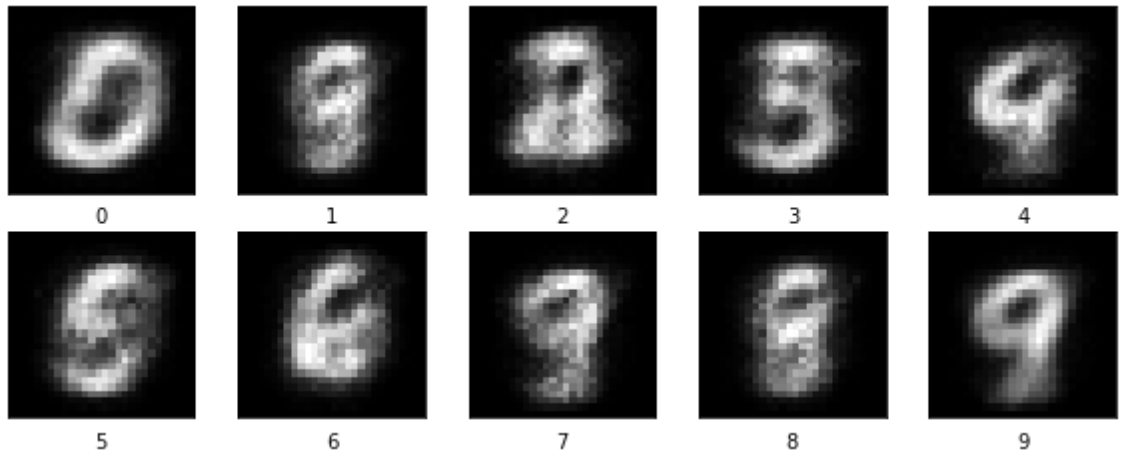
E: 25



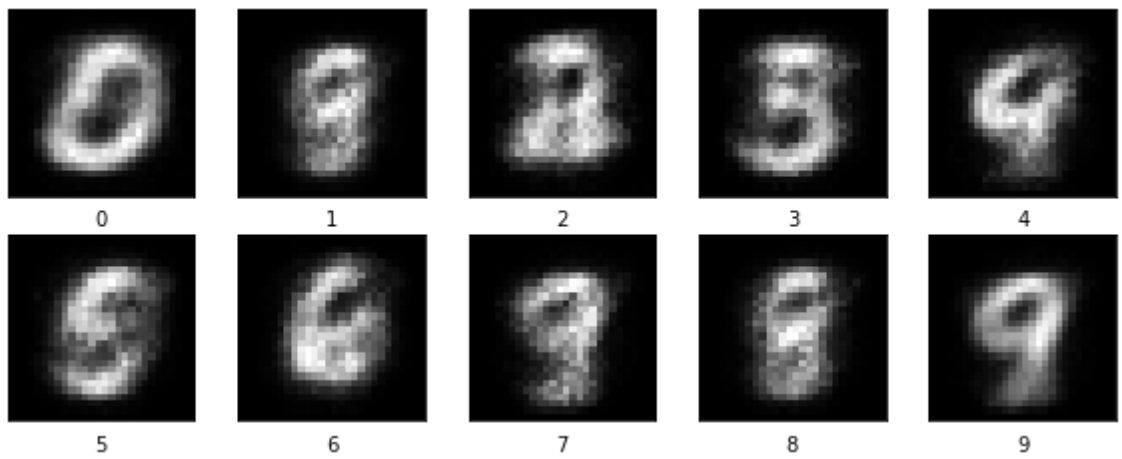
E: 26



E: 27

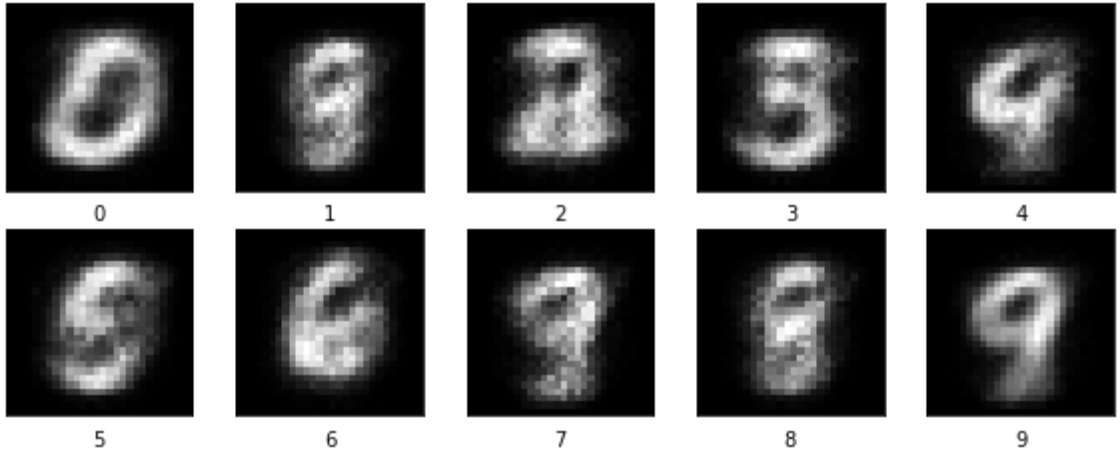


E: 28

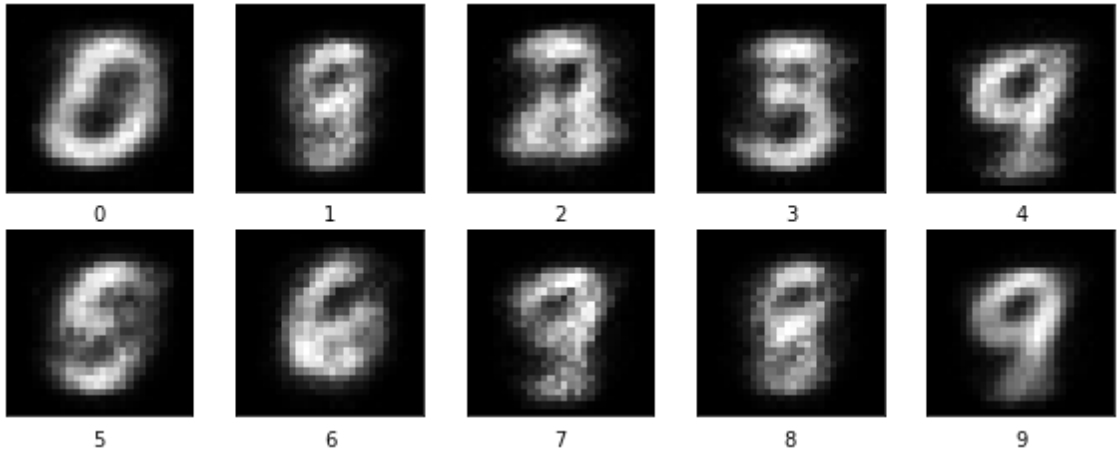


E: 29

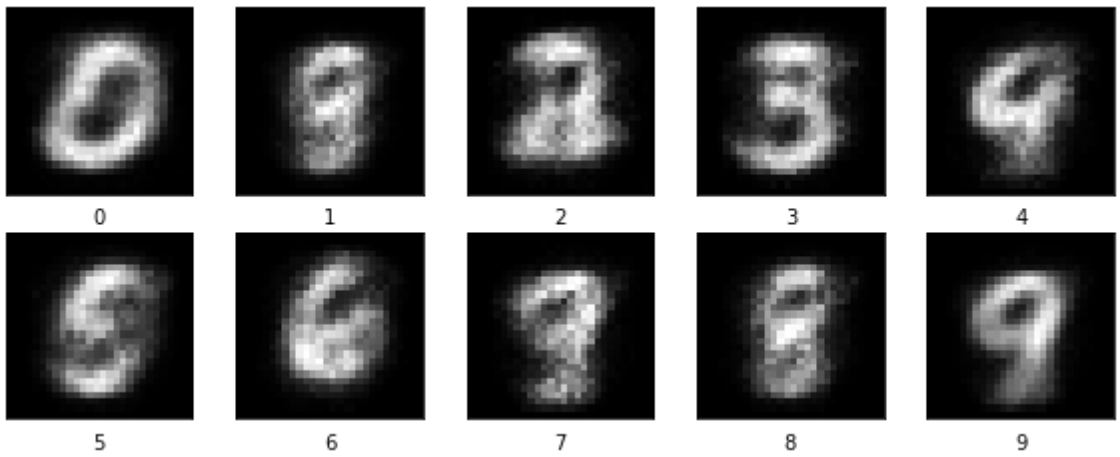
100%|

[illegible]

E: 30

[illegible]

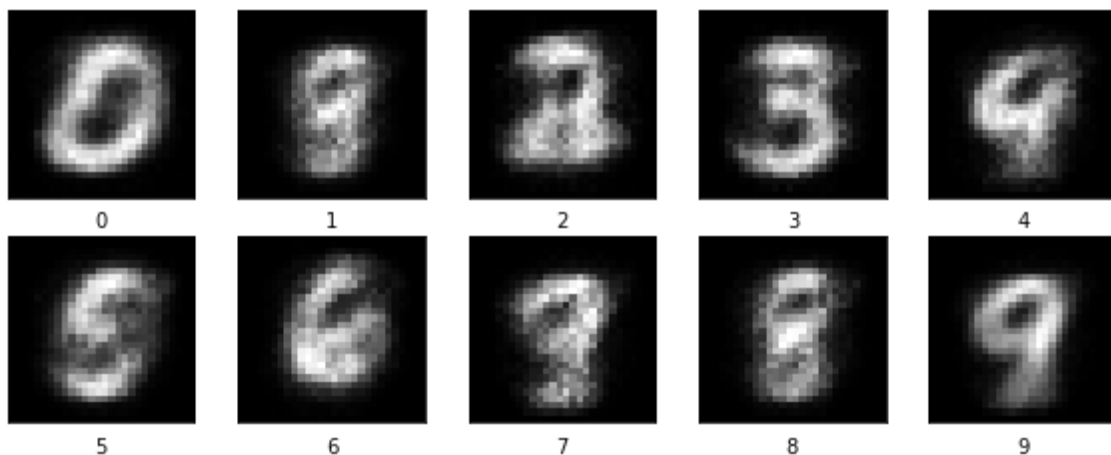
E: 31

[illegible]

E: 32

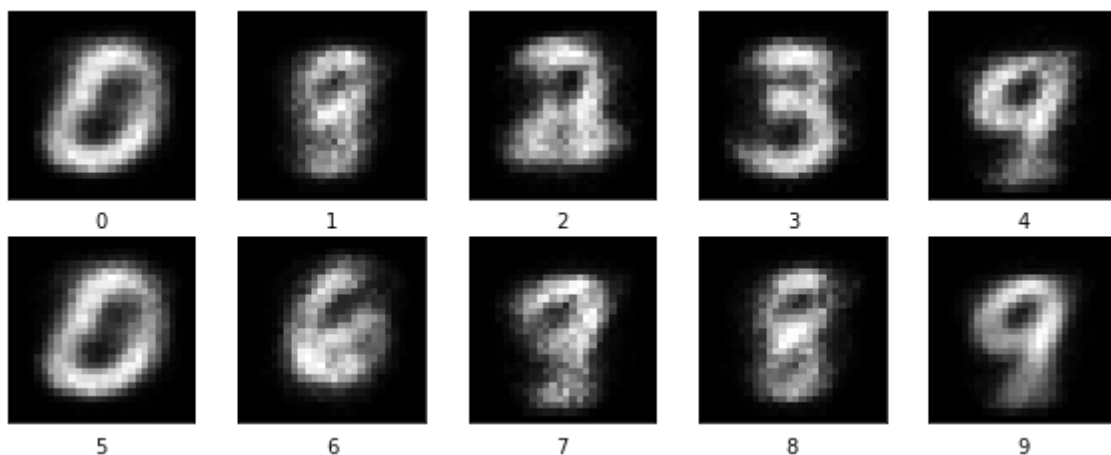
100%|

9it/s] | 858/858 [00:11<00:00, 77.5



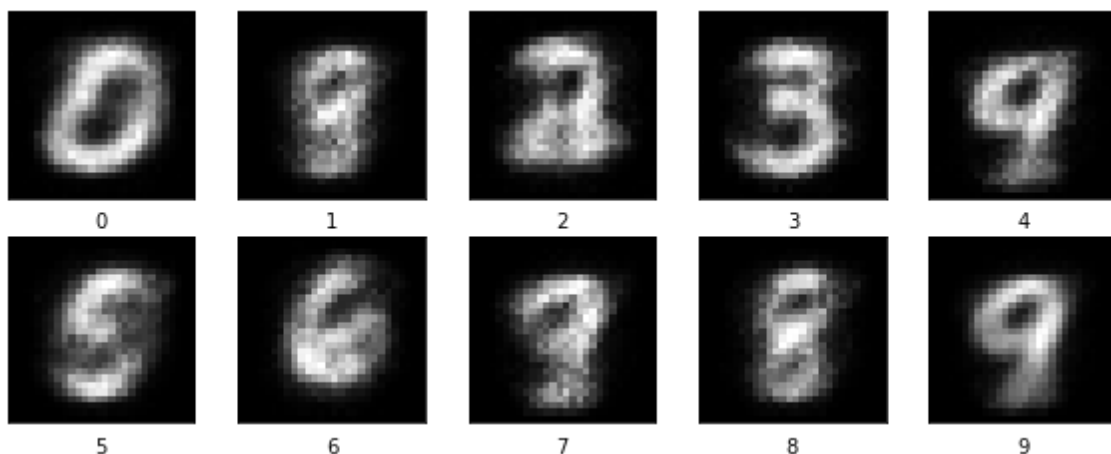
E: 33

100%| | 858/858 [00:11<00:00, 74.3
7it/s]



E: 34

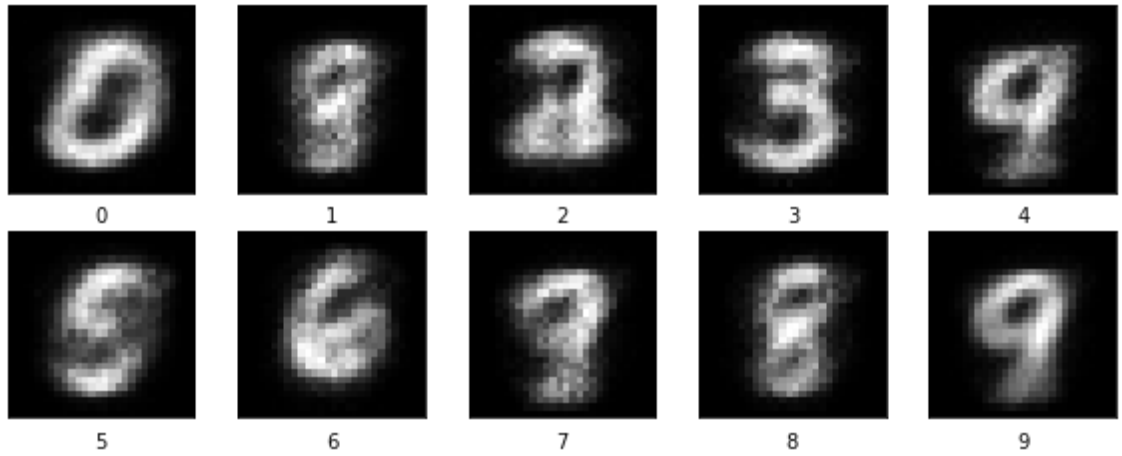
100%| | 858/858 [00:10<00:00, 78.9
4it/s]



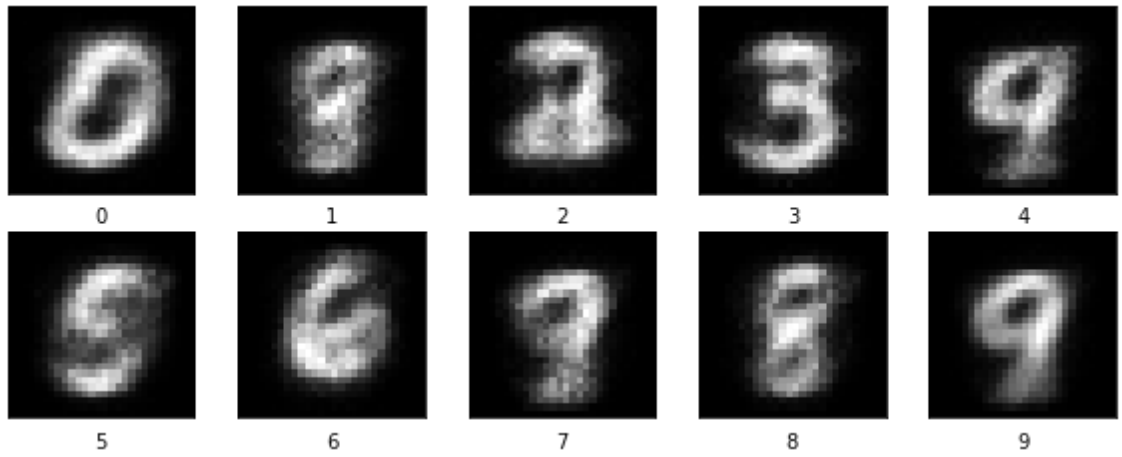
E: 35

100%|

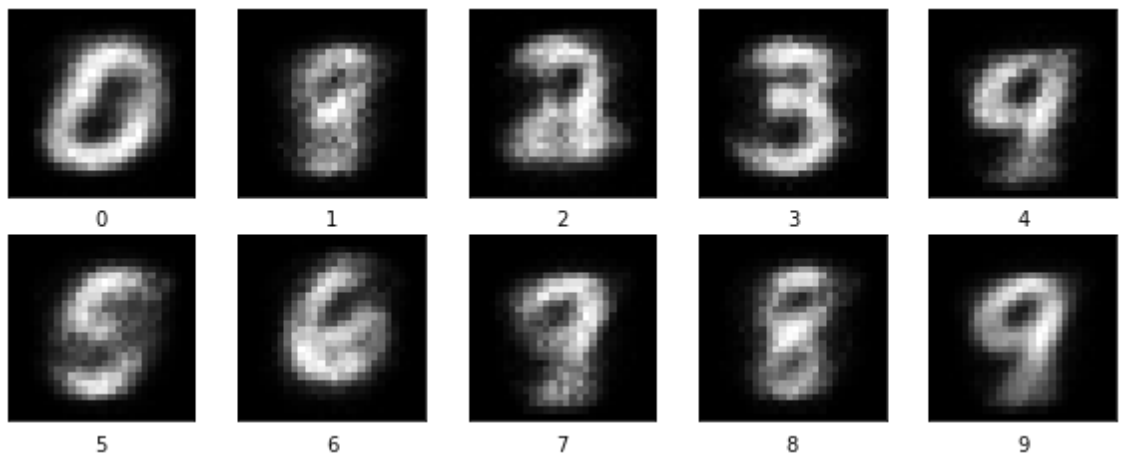
```
|██████████| 858/858 [00:10<00:00, 80.0  
lit/s]
```



E: 36

[illegible]

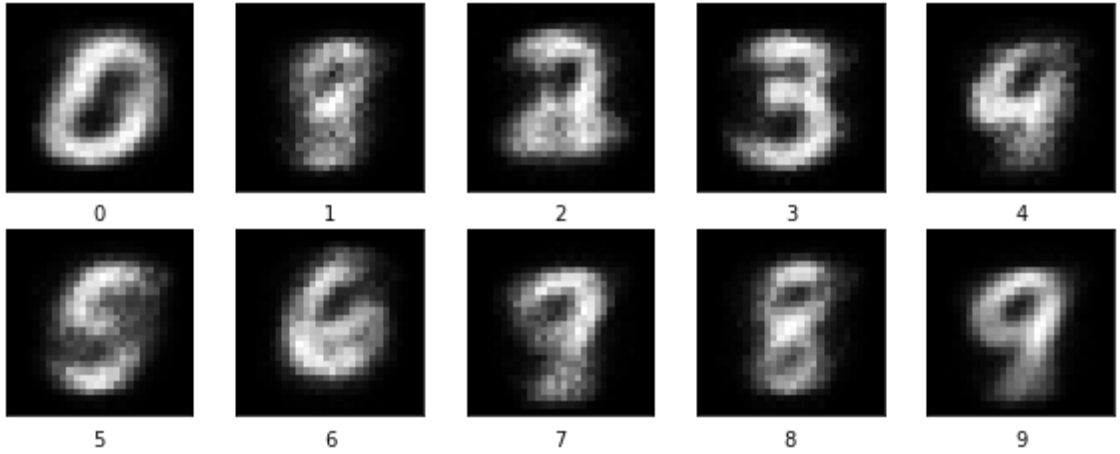
E: 37

[illegible]

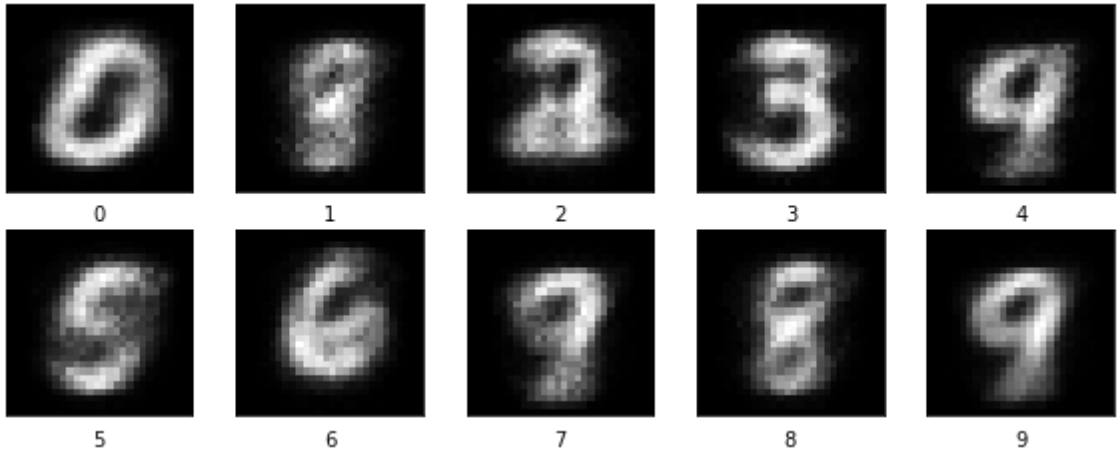
E: 38

[illegible]

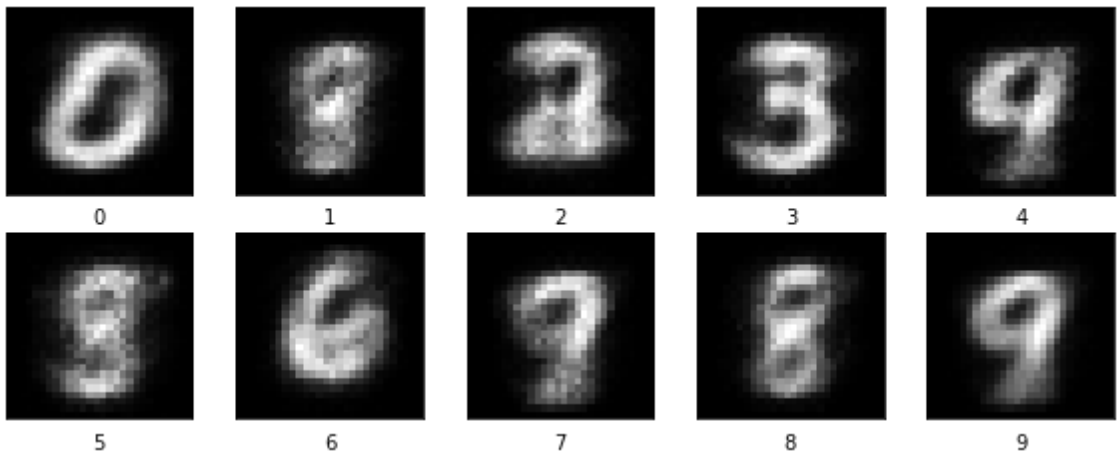
```
|██████████| 858/858 [00:11<00:00, 77.9  
4it/s]
```



E: 39

[illegible]

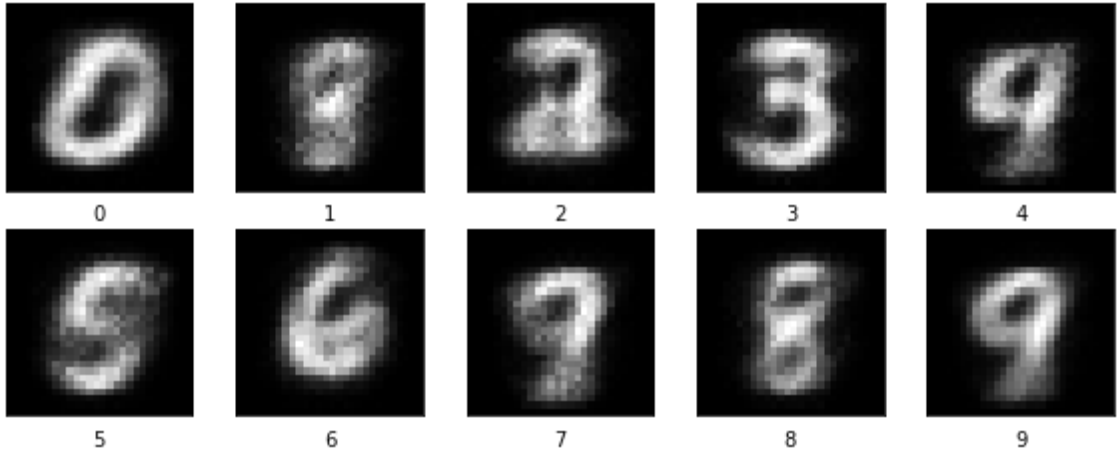
E: 40

[illegible]

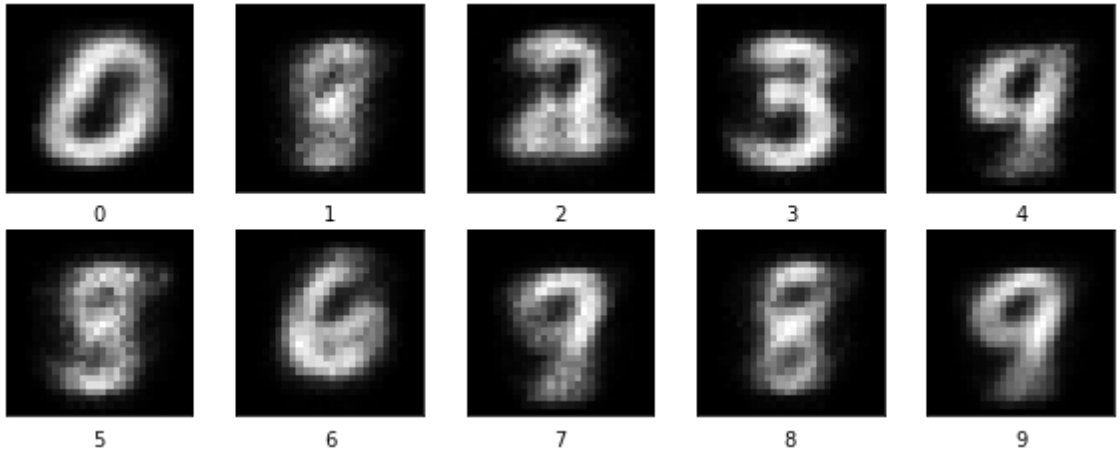
E: 41

[illegible]

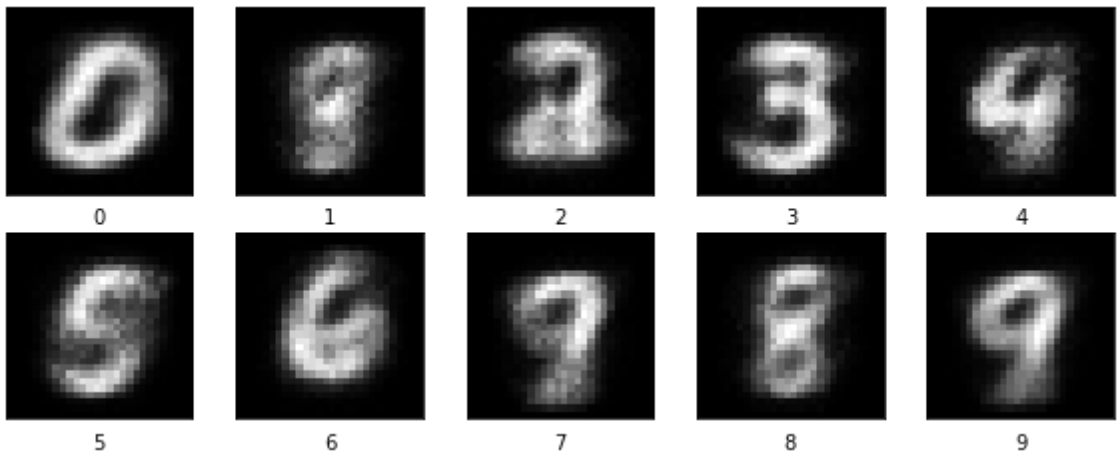
```
[REDACTED] | 858/858 [00:10<00:00, 81.1  
0it/s]
```



E: 42

[illegible]

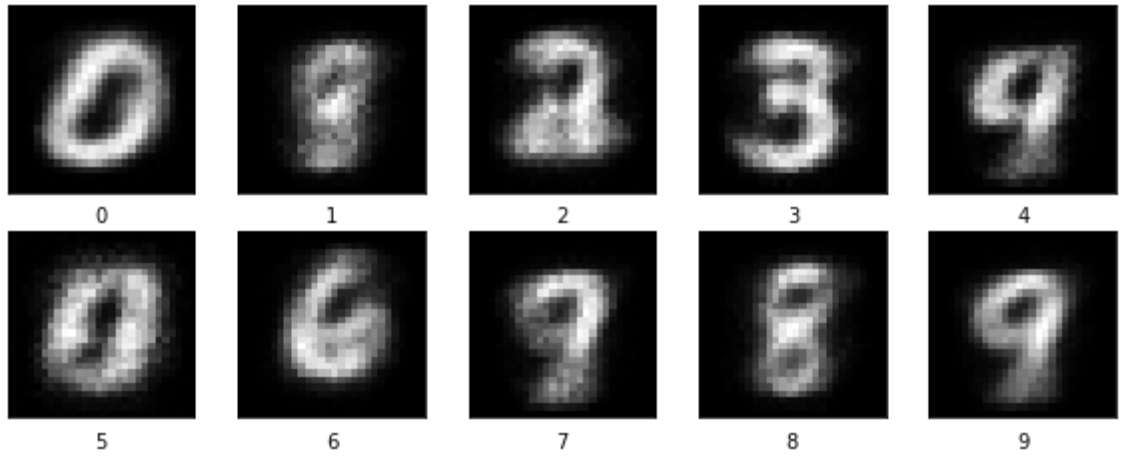
E: 43

[illegible]

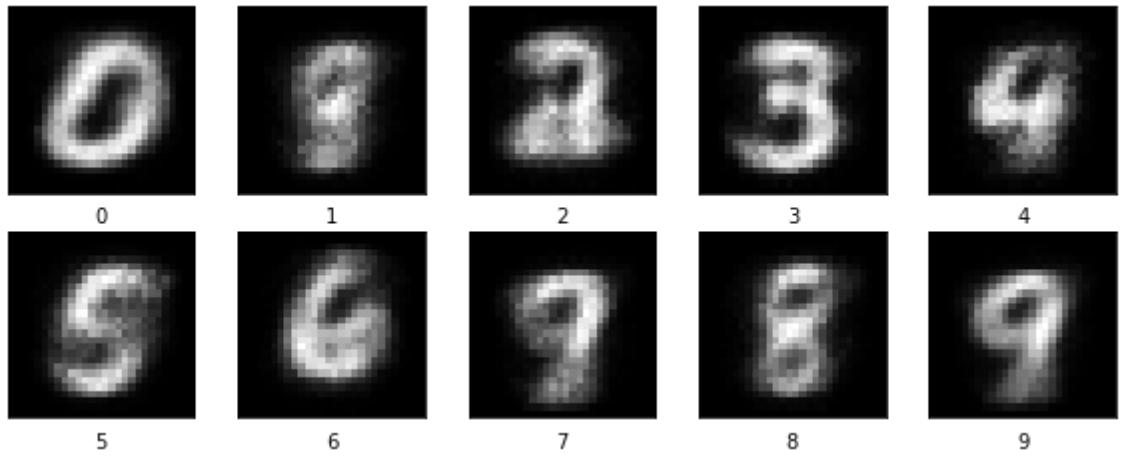
E: 44

100%|

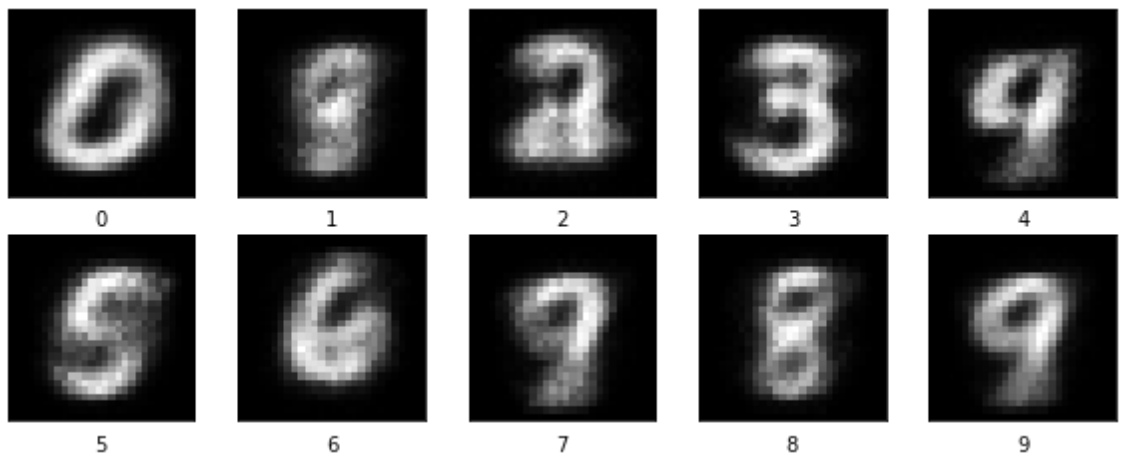
```
|██████████| 858/858 [00:10<00:00, 78.9  
4it/s]
```



E: 45

[illegible]

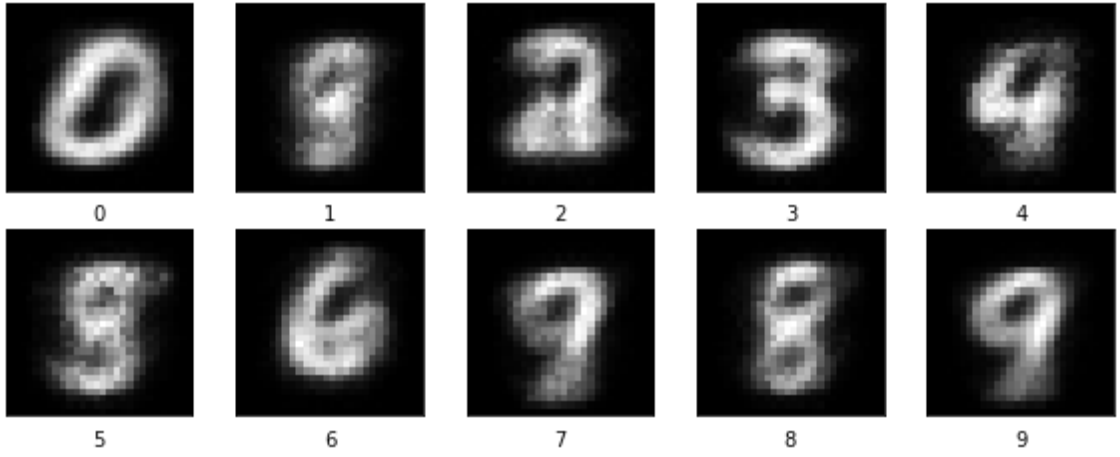
E: 46

[illegible]

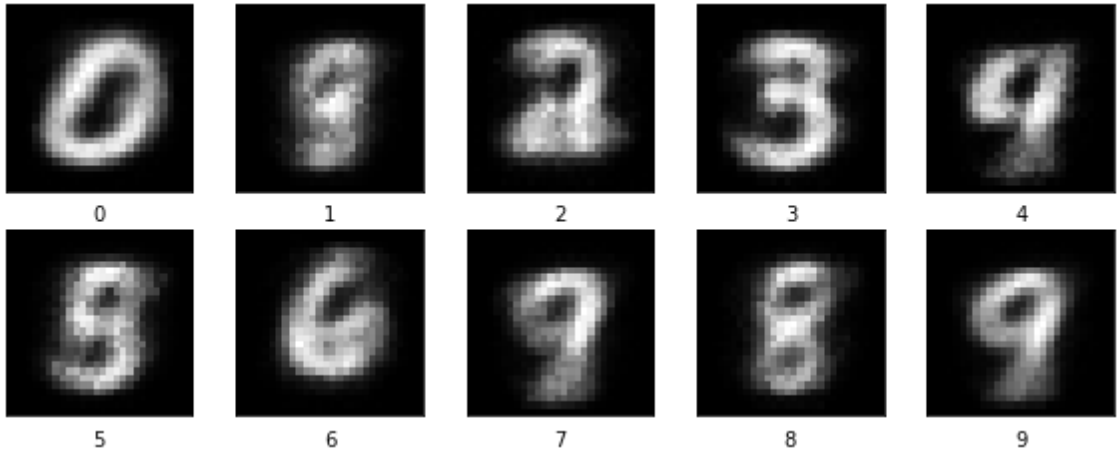
E: 47

100%

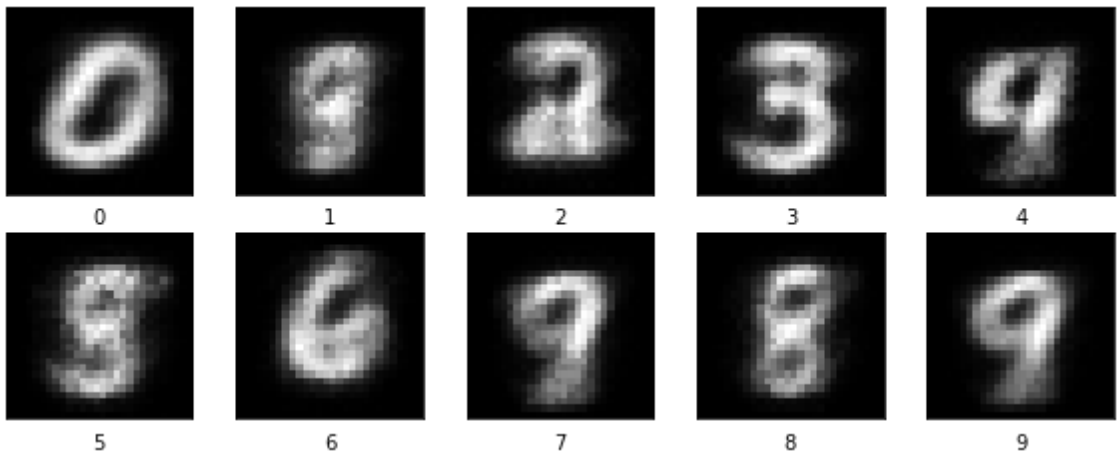
```
|██████████| 858/858 [00:11<00:00, 75.3  
lit/s]
```



E: 48

[illegible]

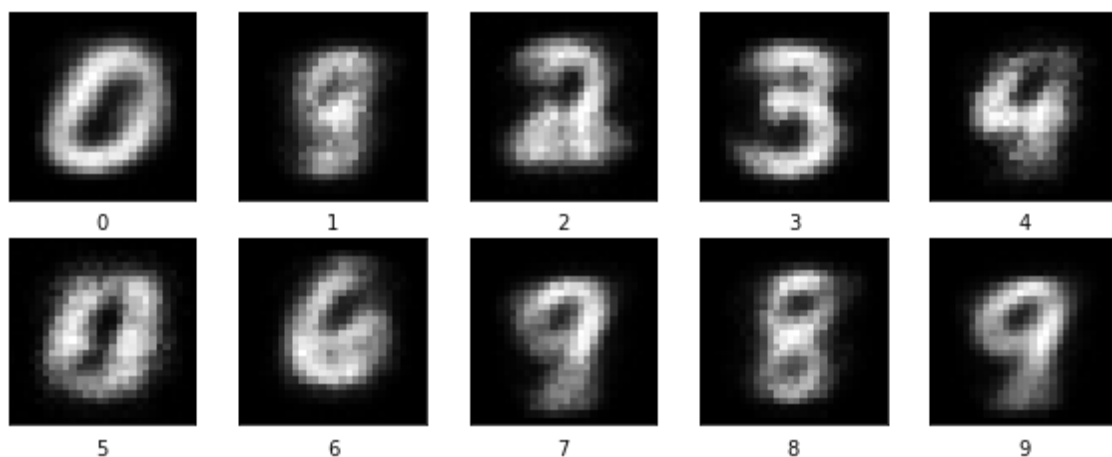
E: 49

[illegible]

E: 50

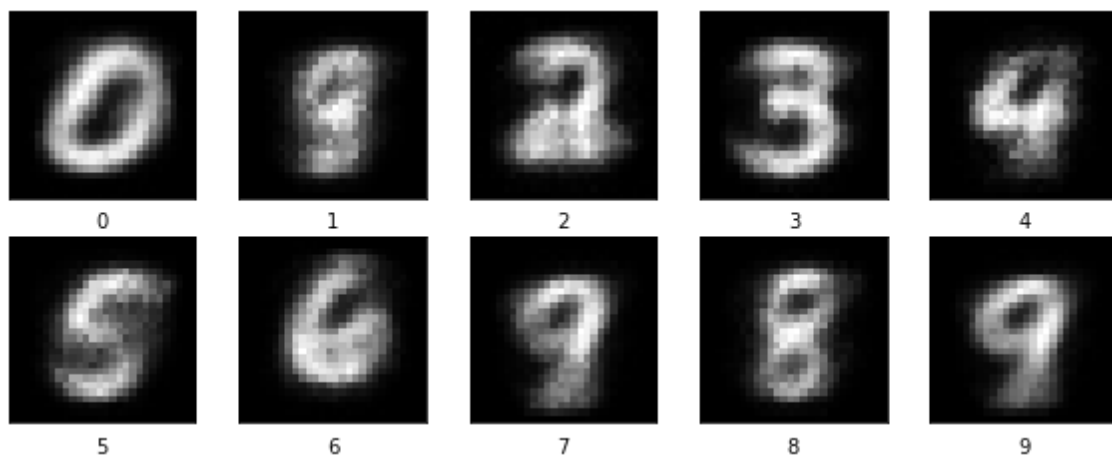
100%

858/858 [00:12<00:00, 71.2
5it/s]



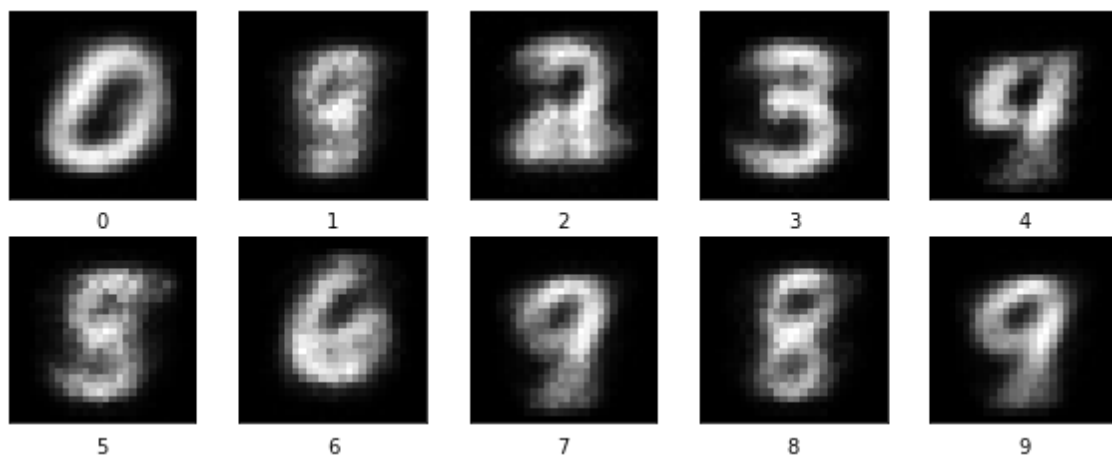
E: 51

100%| 858/858 [00:14<00:00, 59.5
4it/s]



E: 52

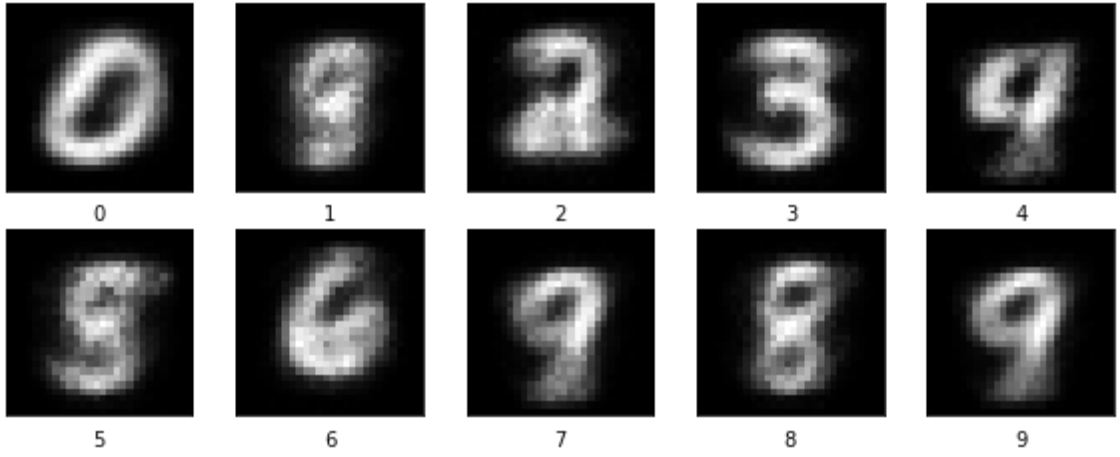
100%| 858/858 [00:11<00:00, 71.9
7it/s]



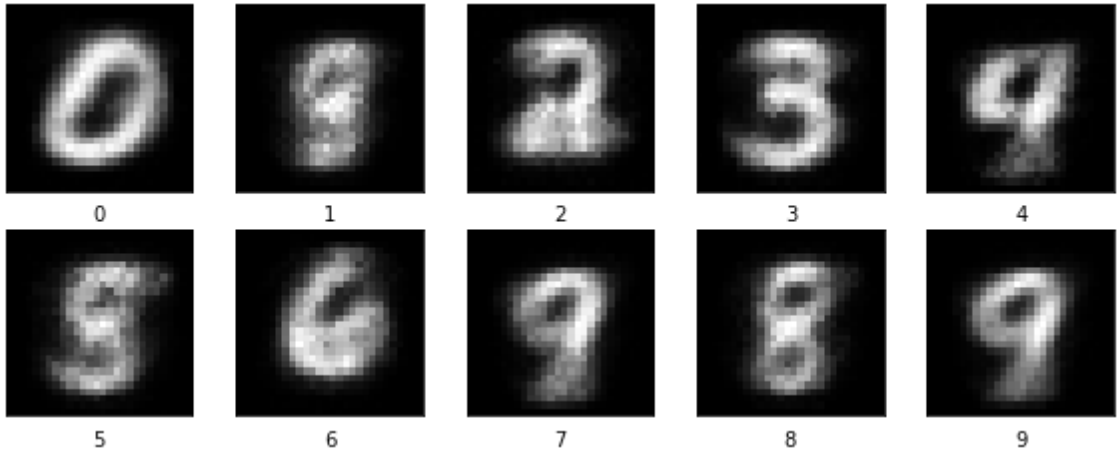
E: 53

100%|

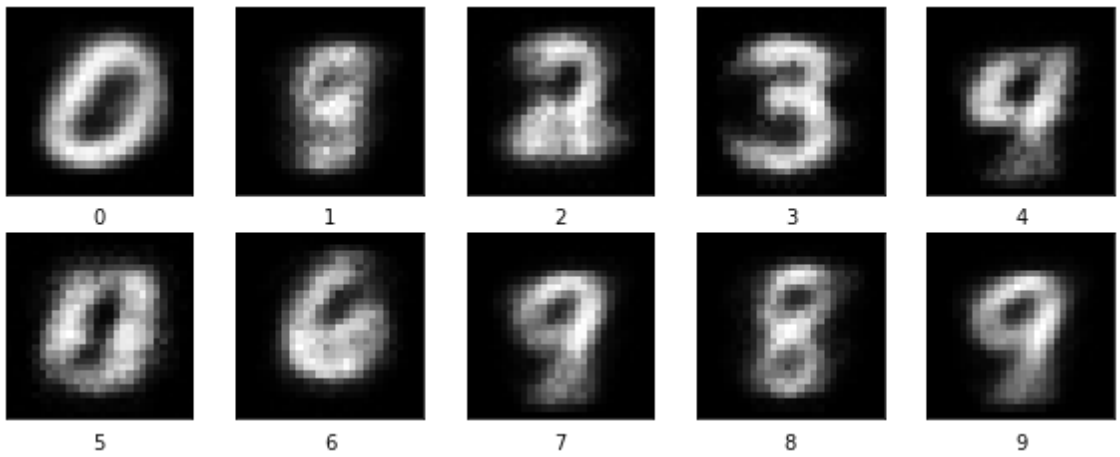

```
██████████| 858/858 [00:10<00:00, 79.0  
2it/s]
```



E: 54

[illegible]

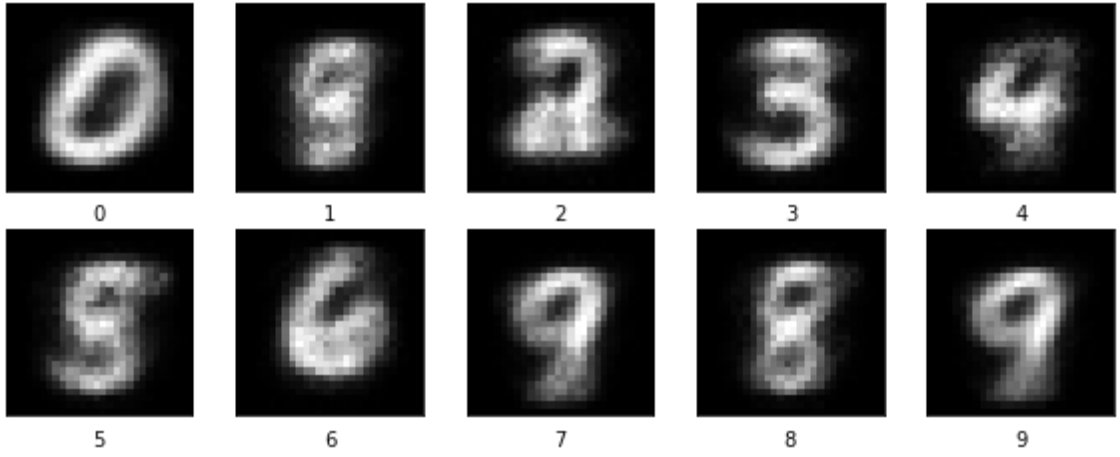
E: 55

[illegible]

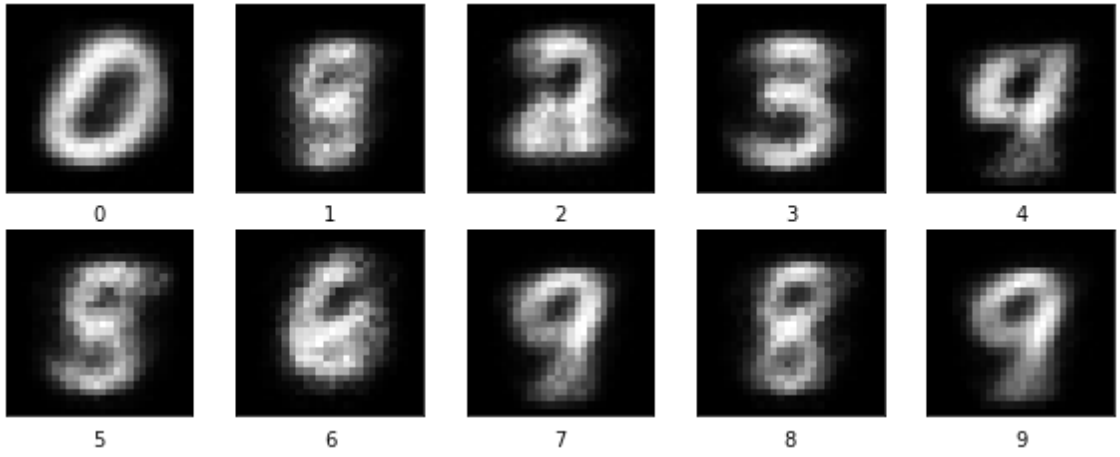
E: 56

100% |

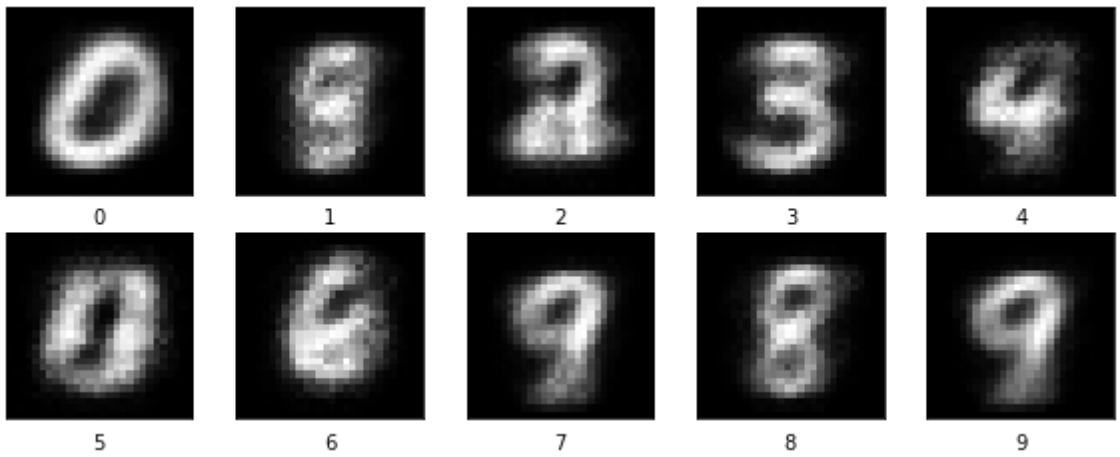
```
|██████████| 858/858 [00:10<00:00, 83.0  
5it/s]
```



E: 57

[illegible]

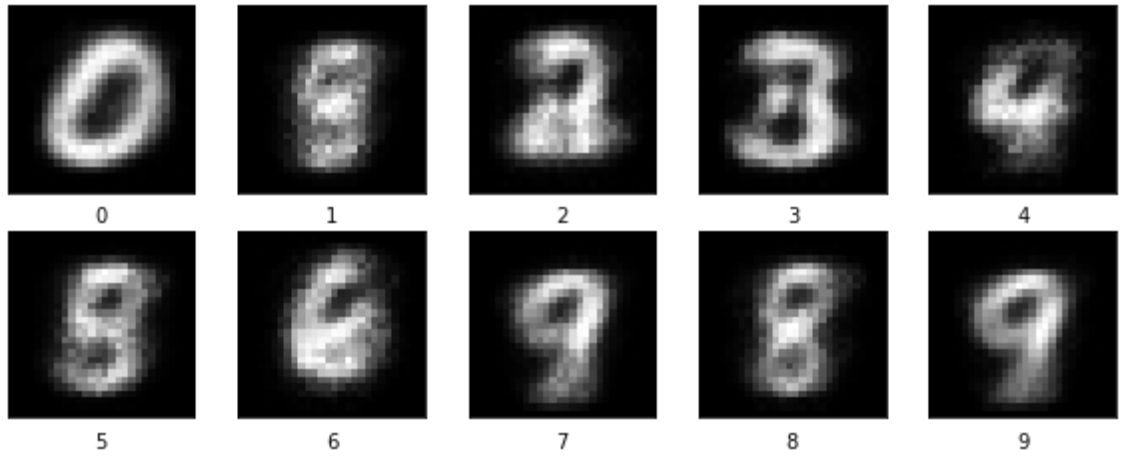
E: 58

[illegible]

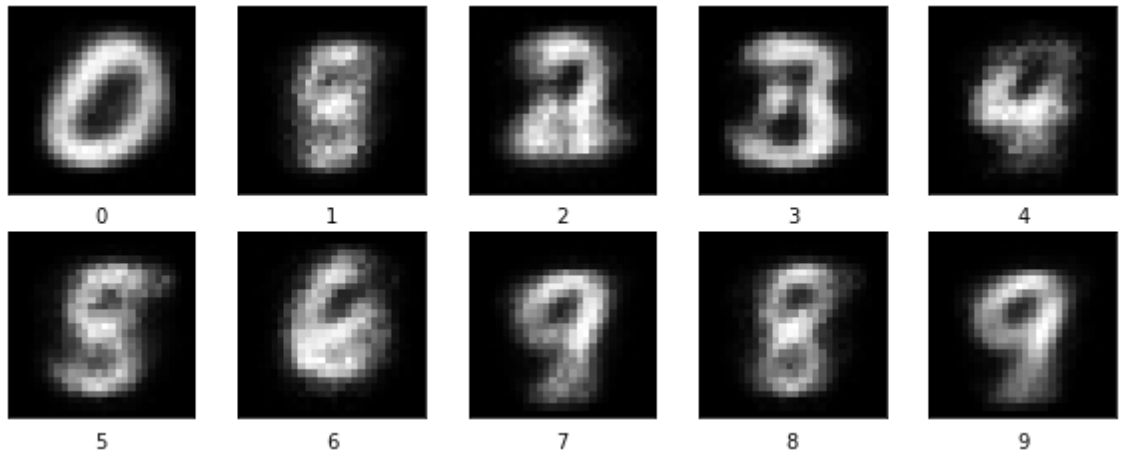
E: 59

[illegible]

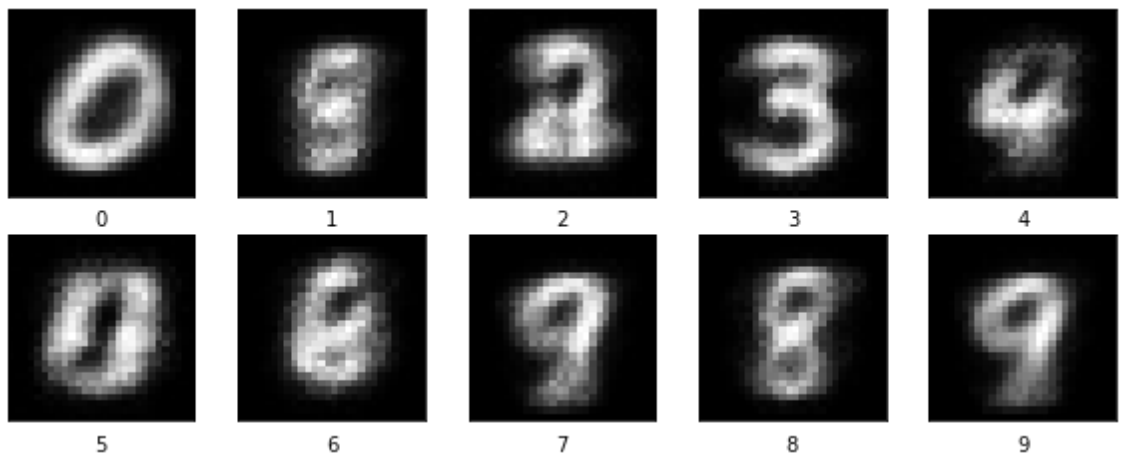
```
[██████████] | 858/858 [00:10<00:00, 83.4  
3it/s]
```



E: 60

[illegible]

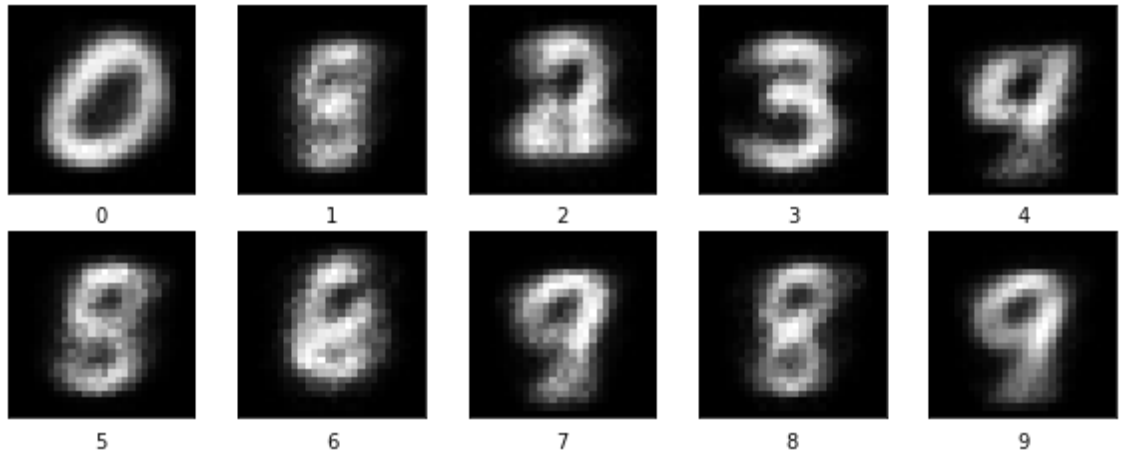
E: 61

[illegible]

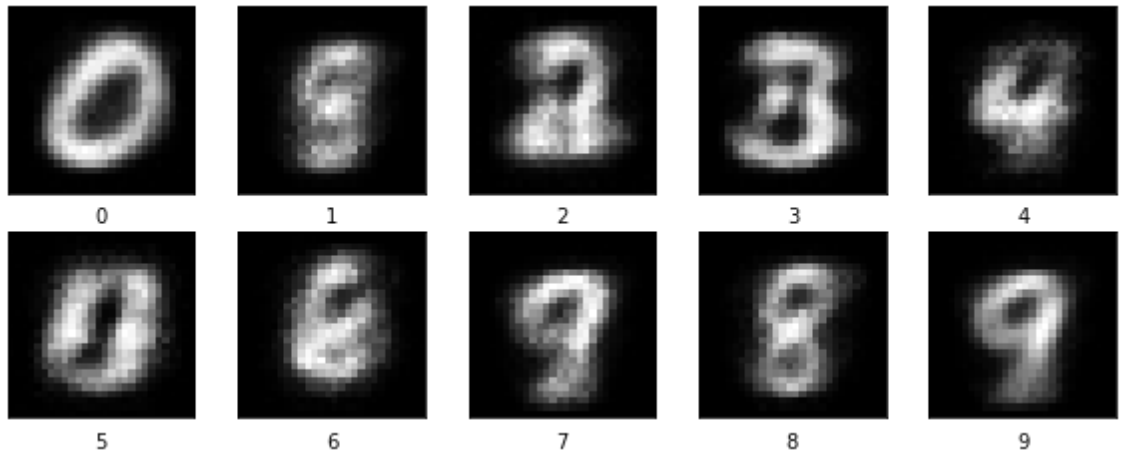
E: 62

100%|

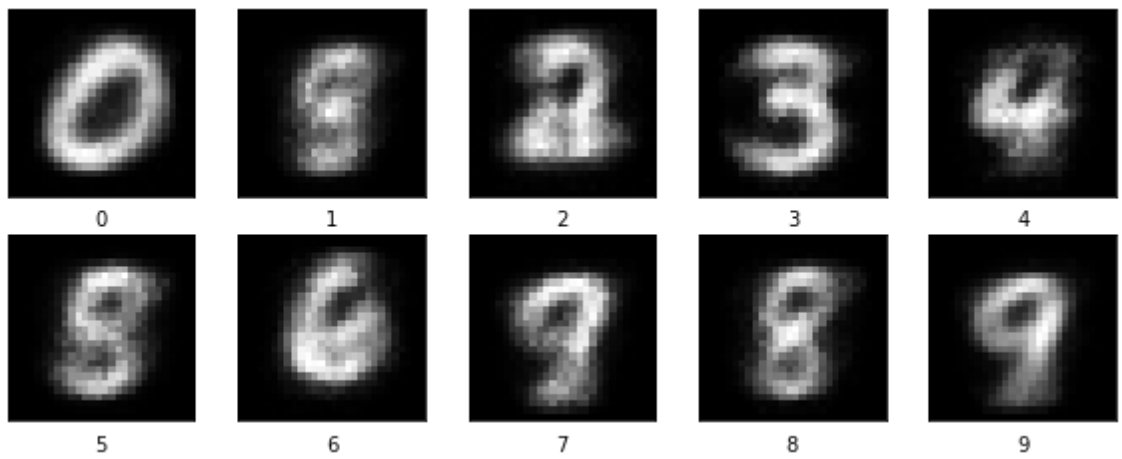
```
|██████████| 858/858 [00:10<00:00, 81.2  
0it/s]
```



E: 63

[illegible]

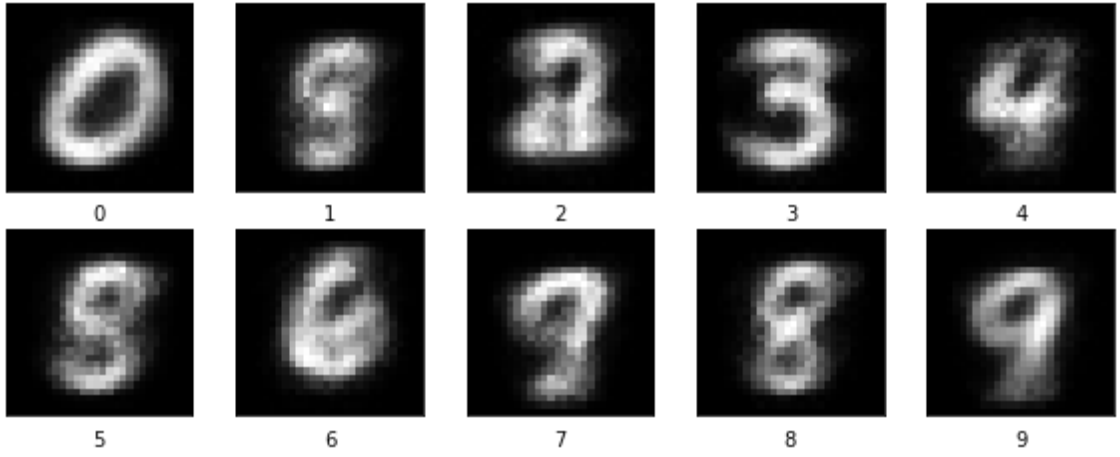
E: 64

[illegible]

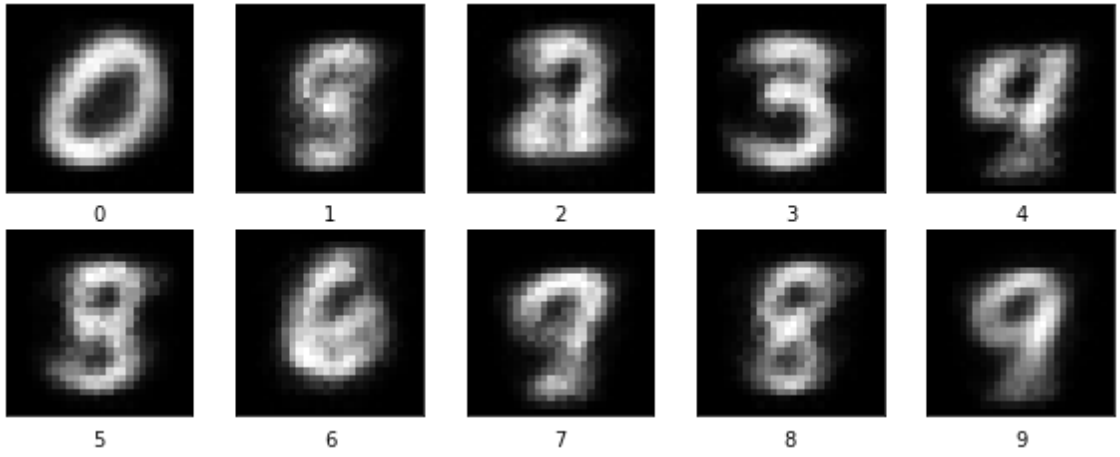
E: 65

100%|

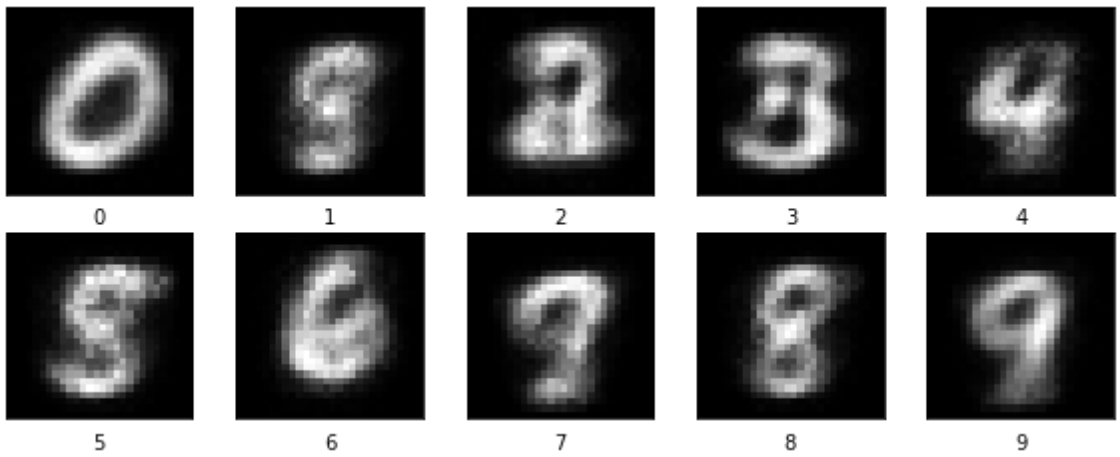
```
|██████████| 858/858 [00:10<00:00, 84.1  
lit/s]
```



E: 66

[illegible]

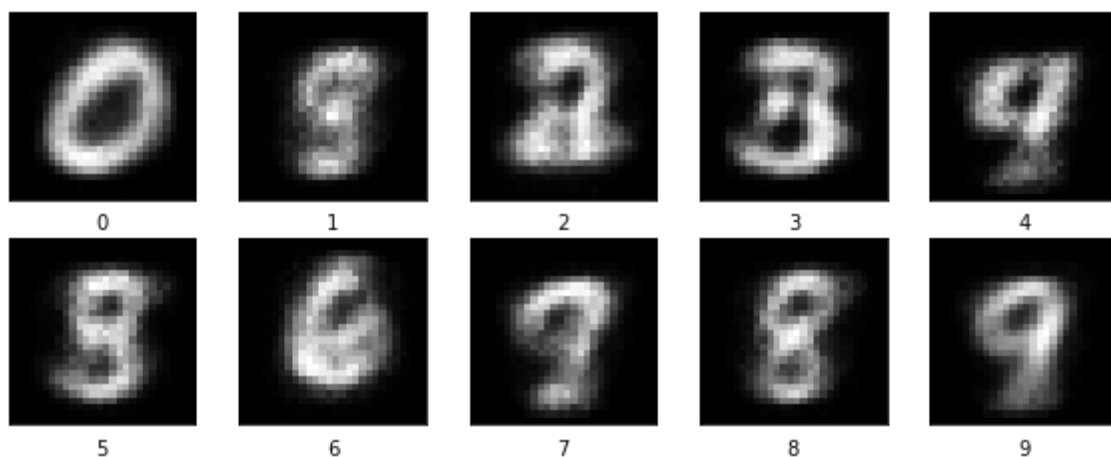
E: 67

[illegible]

E: 68

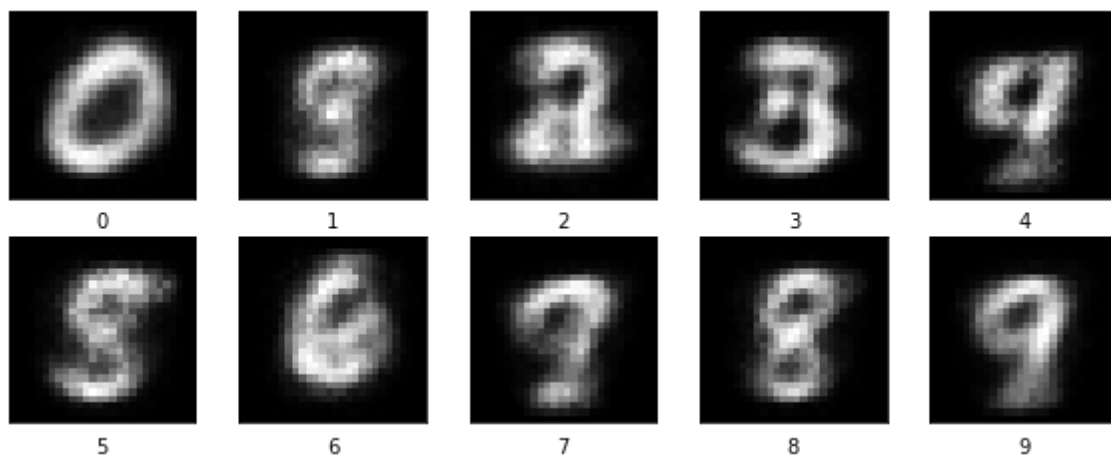
100%

858/858 [00:10<00:00, 82.3
8it/s]



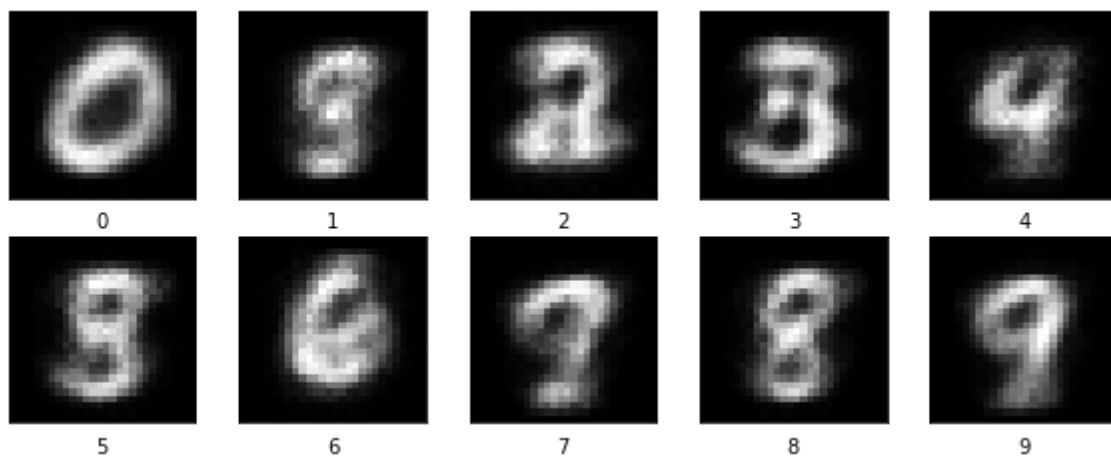
E: 69

100%| 858/858 [00:10<00:00, 83.4
6it/s]



E: 70

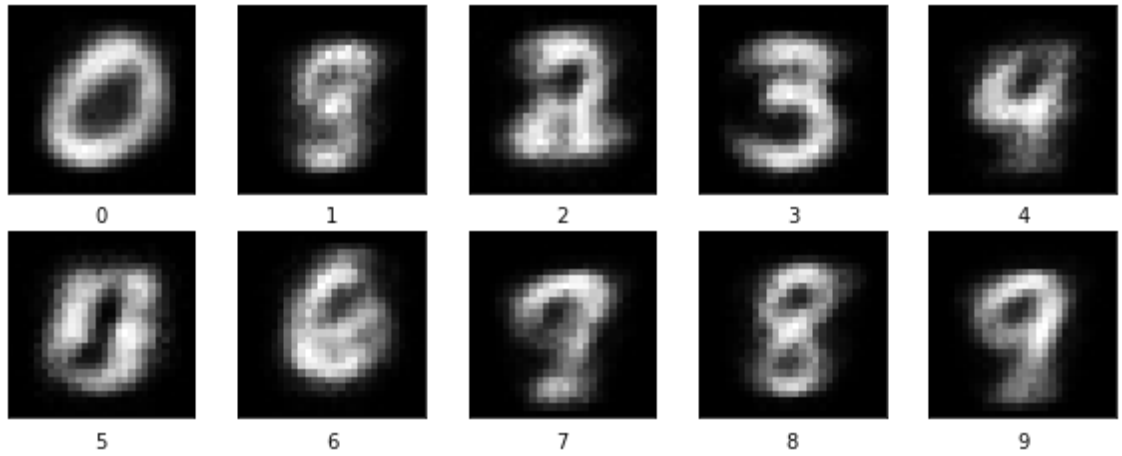
100%| 858/858 [00:10<00:00, 80.7
9it/s]



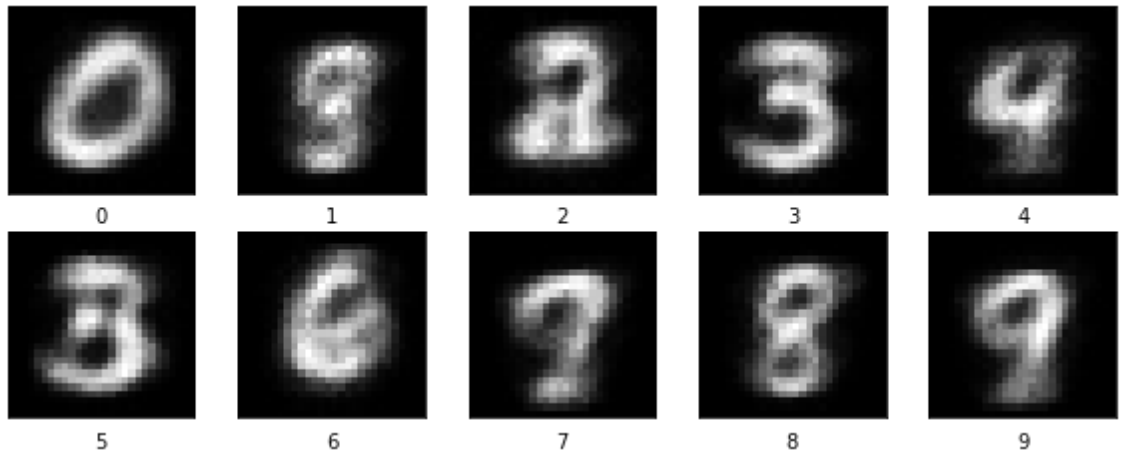
E: 71

100%|

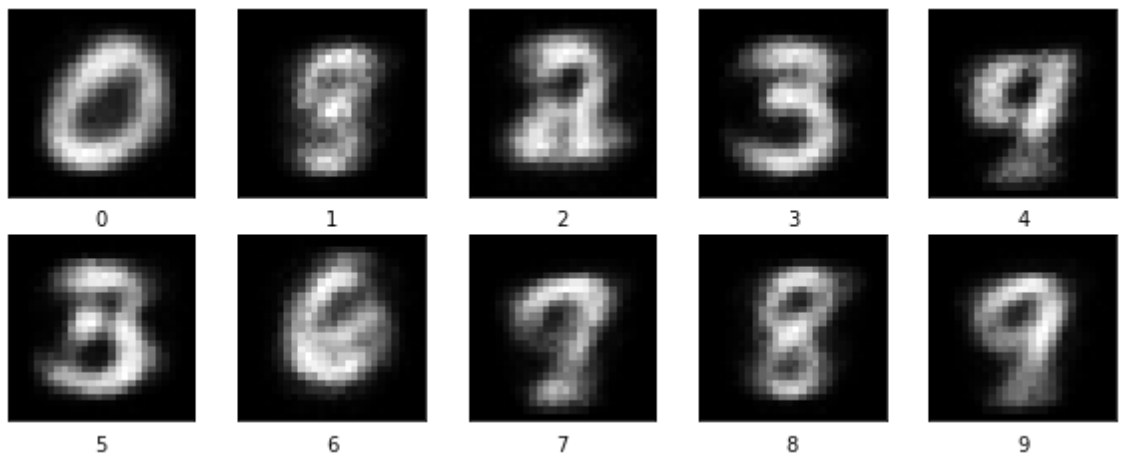
```
[REDACTED] | 858/858 [00:11<00:00, 75.2  
4it/s]
```



E: 72

[illegible]

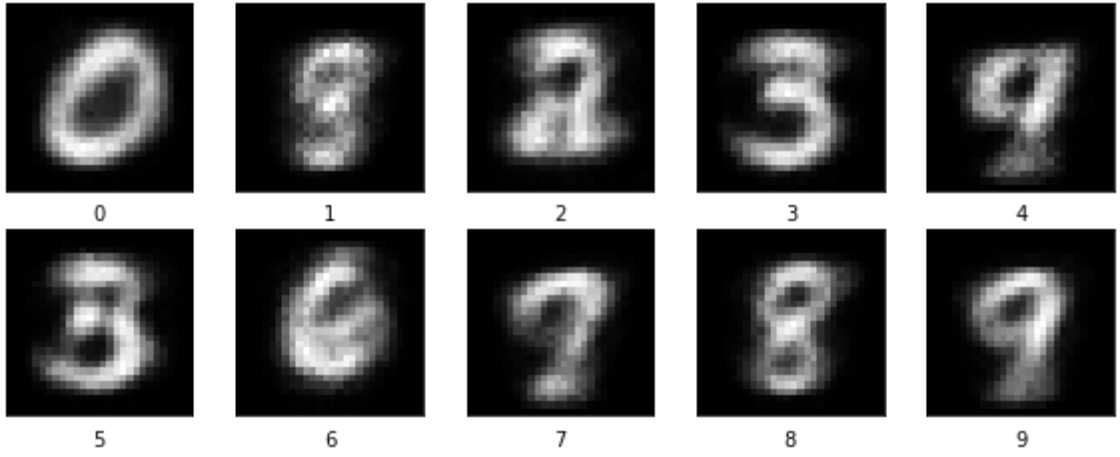
E: 73

[illegible]

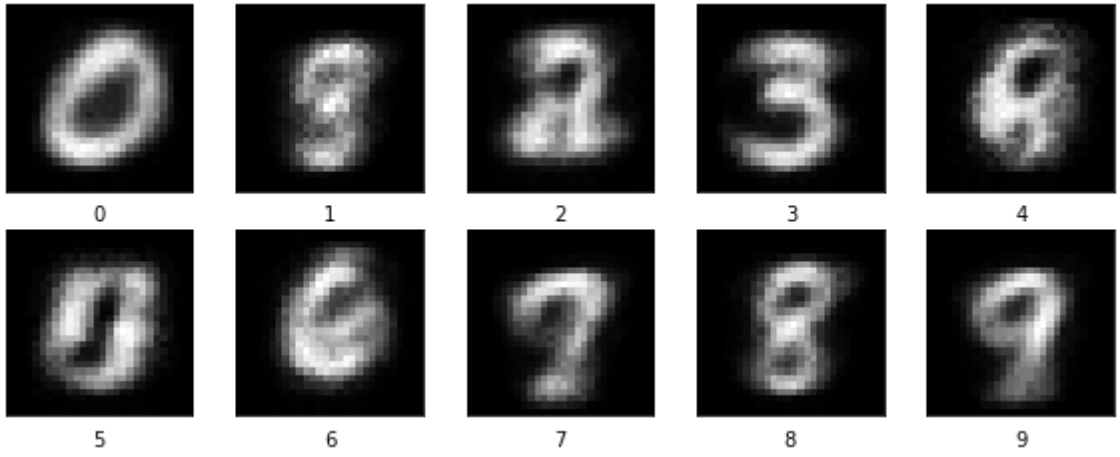
E: 74

100%|

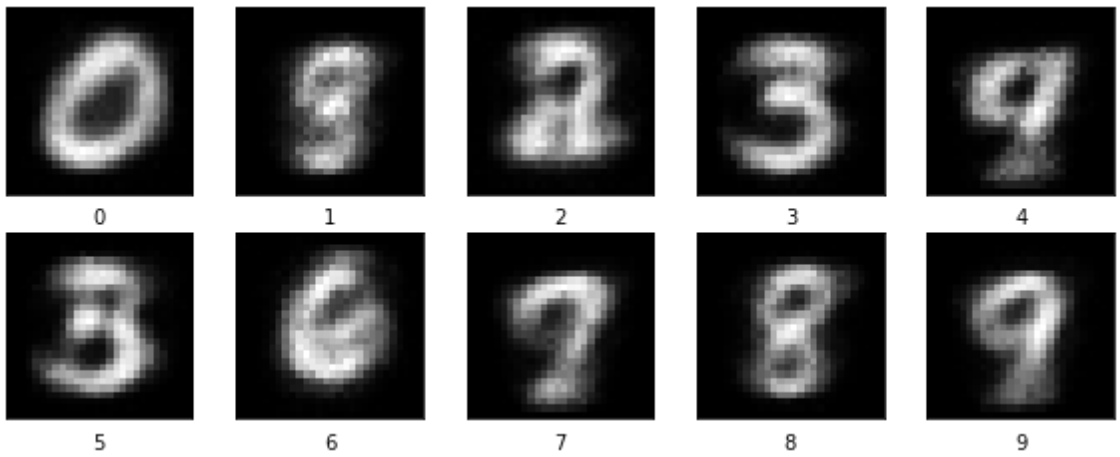
```
███████████| 858/858 [00:10<00:00, 84.3  
3it/s]
```



E: 75

[illegible]

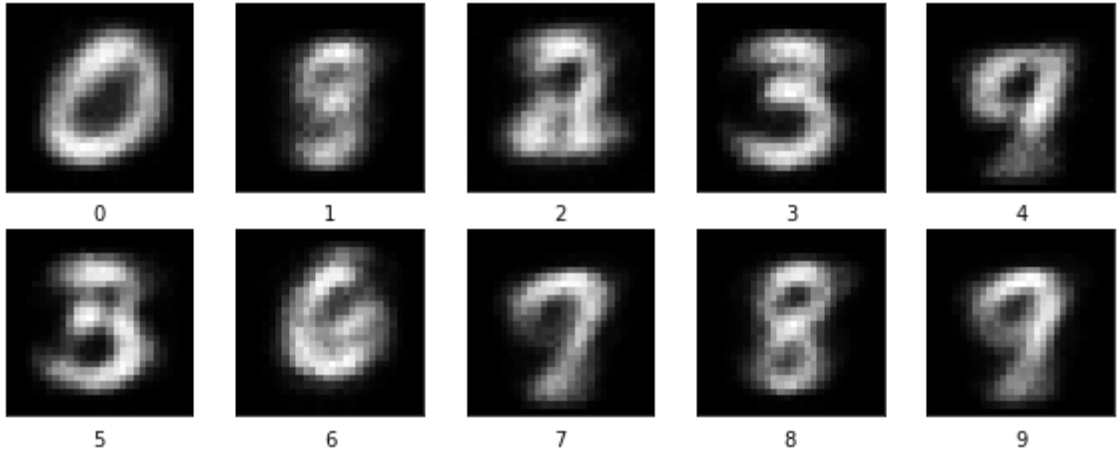
E: 76

[illegible]

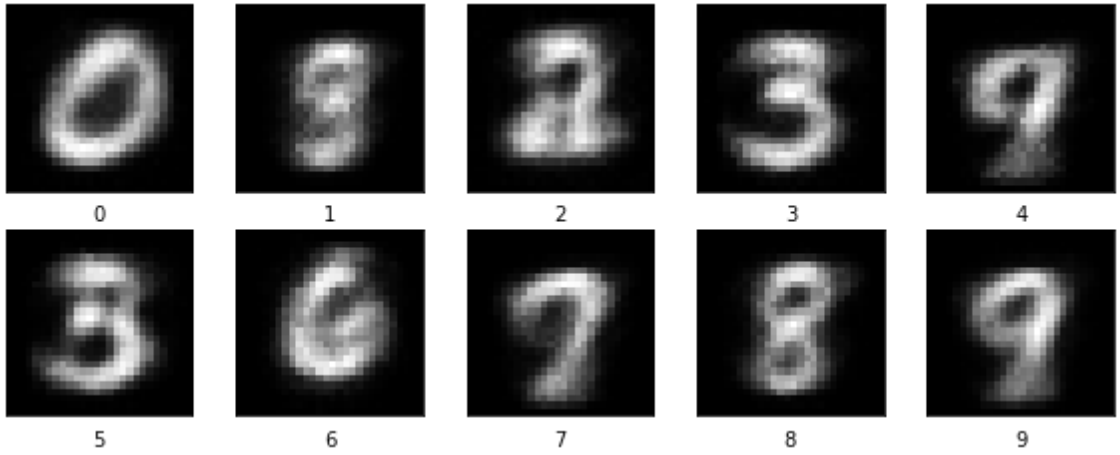
E: 77

100%|██████████

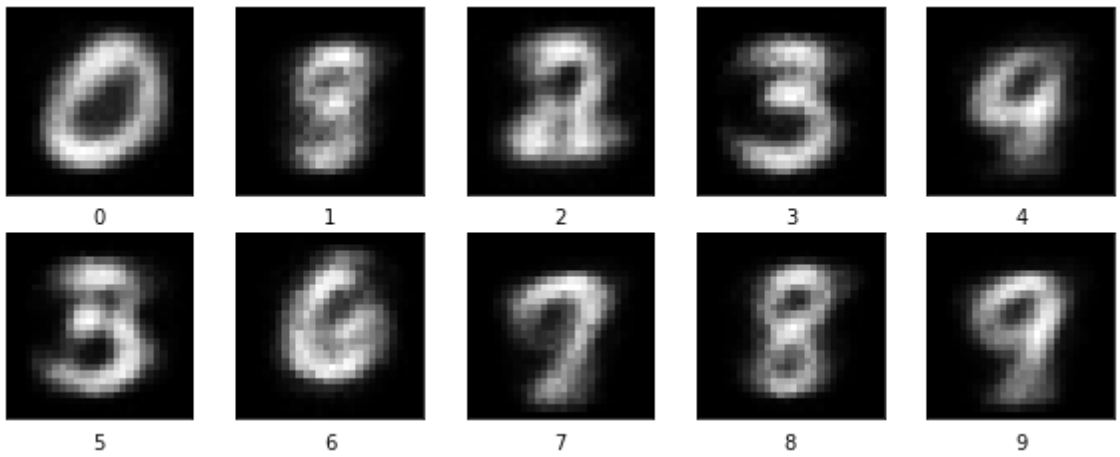

```
|██████████| 858/858 [00:10<00:00, 82.7  
4it/s]
```



E: 78

[illegible]

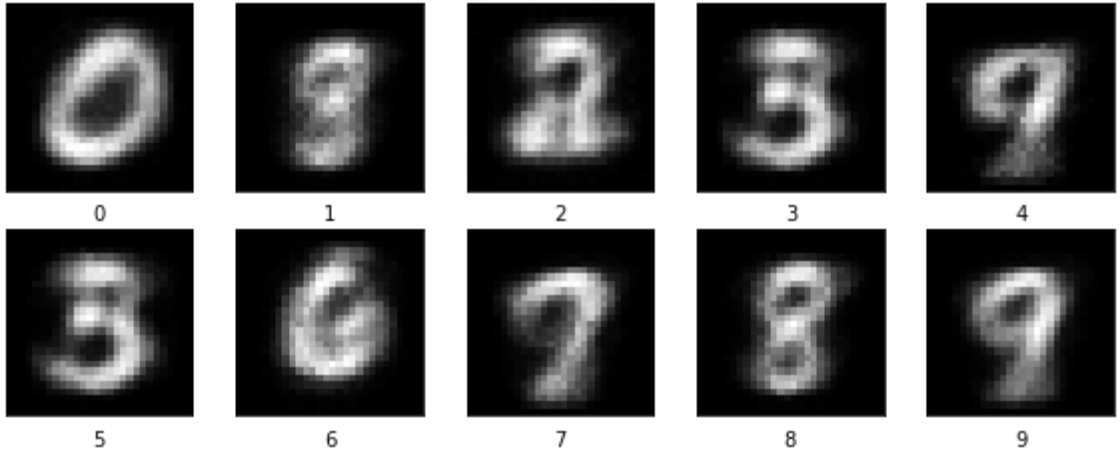
E: 79

[illegible]

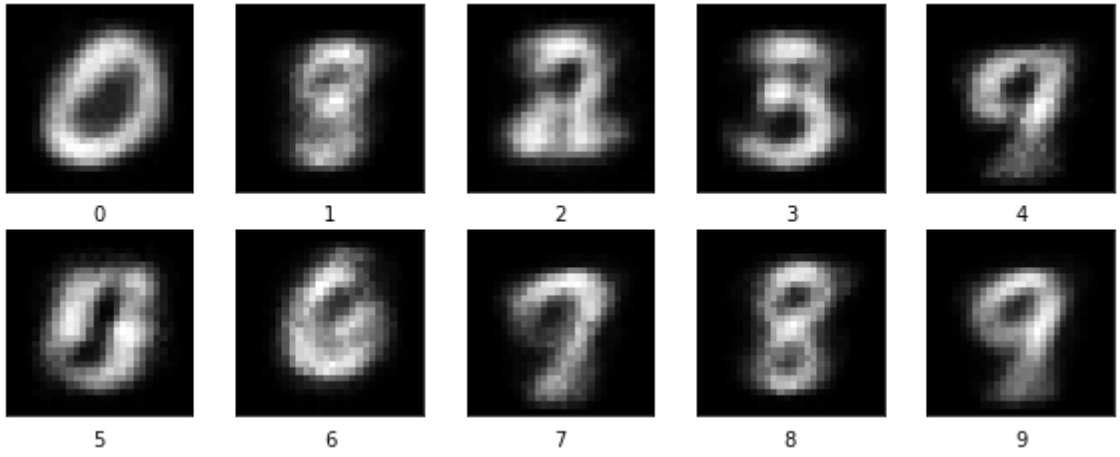
E: 80

100%

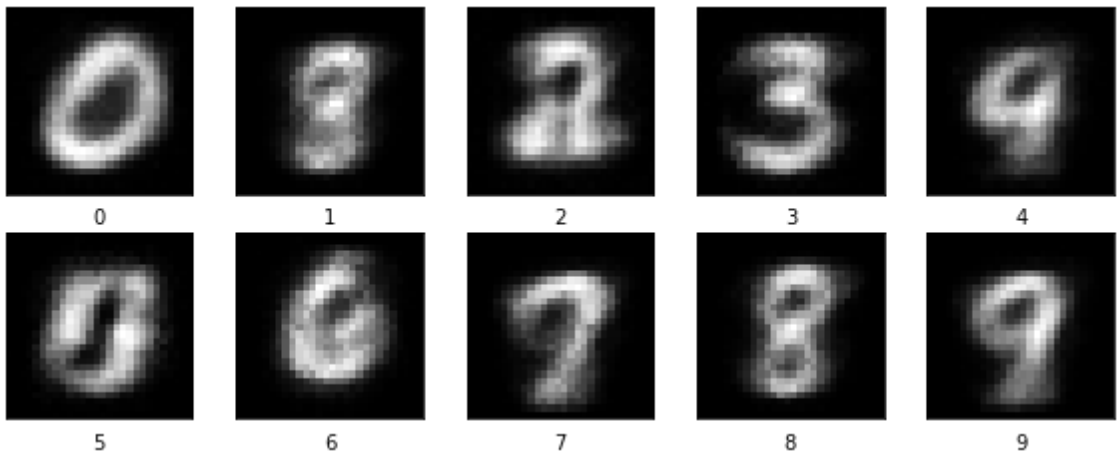
```
[REDACTED] | 858/858 [00:10<00:00, 82.1  
7it/s]
```



E: 81

[illegible]

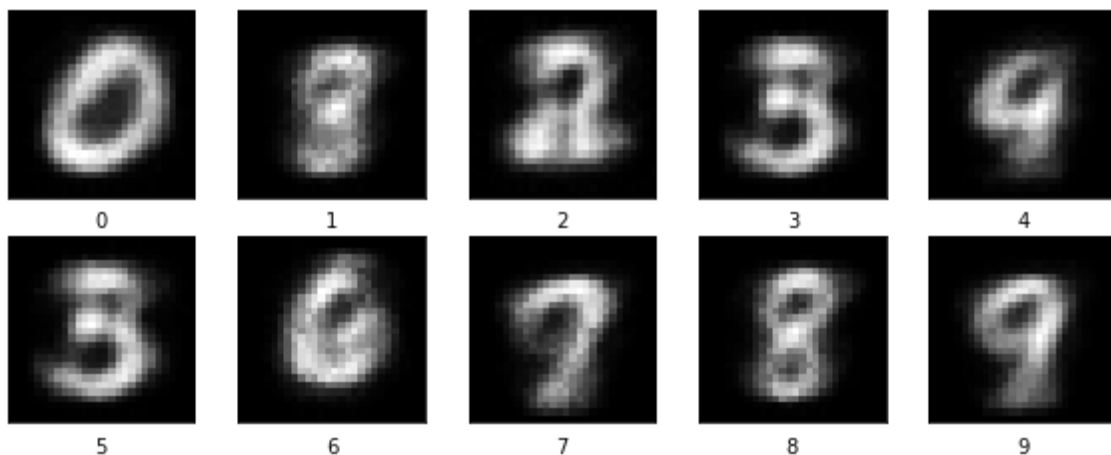
E: 82

[illegible]

E: 83

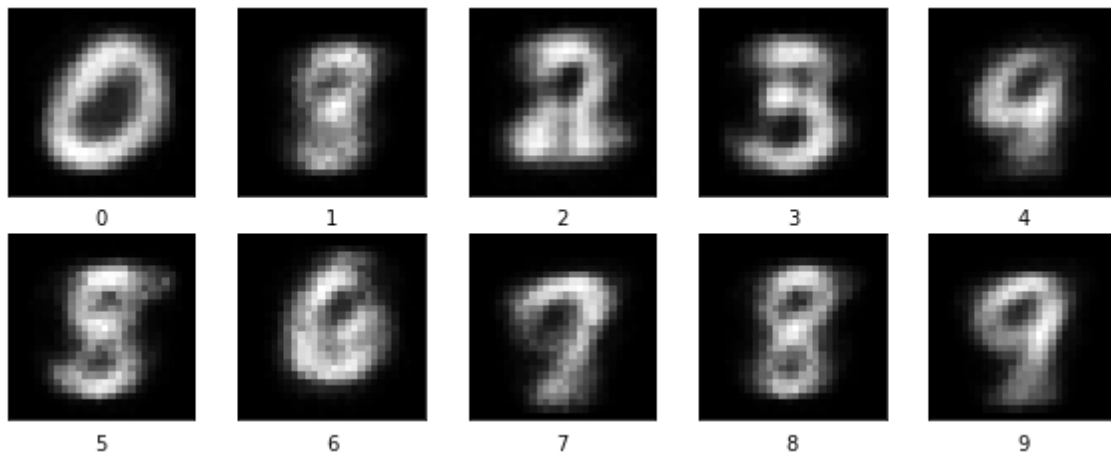
[illegible]

7it/s] | 858/858 [00:10<00:00, 78.8



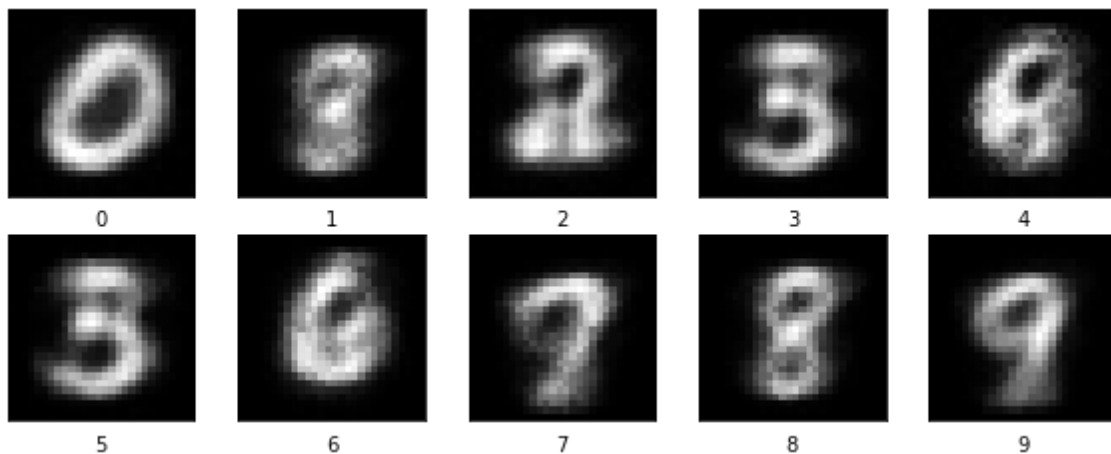
E: 84

100%| | 858/858 [00:11<00:00, 74.3
lit/s]



E: 85

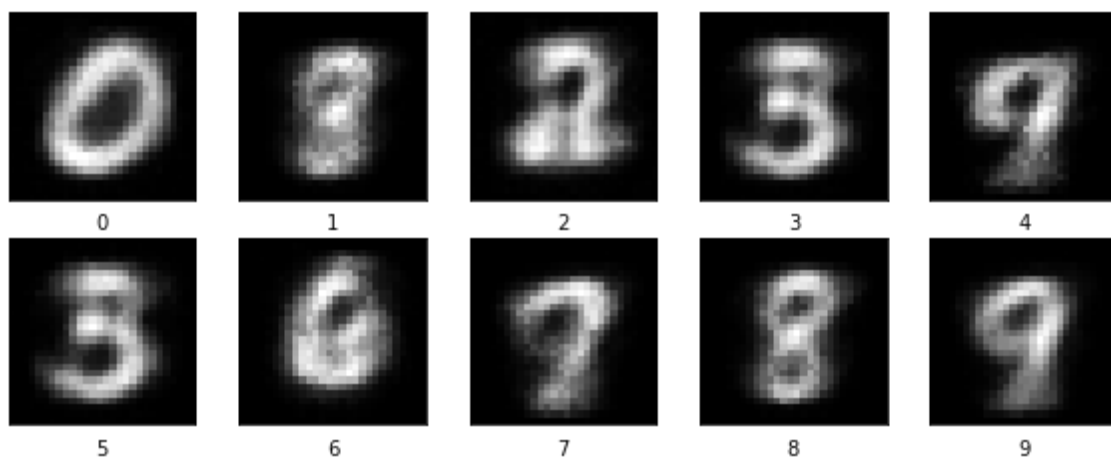
100%| | 858/858 [00:11<00:00, 74.3
lit/s]



E: 86

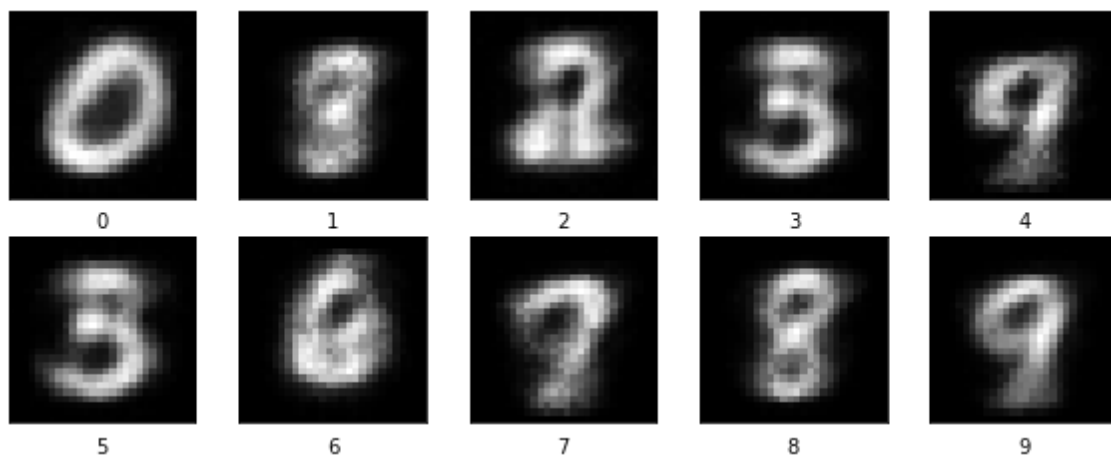
100%| |

858/858 [00:11<00:00, 76.3
8it/s]



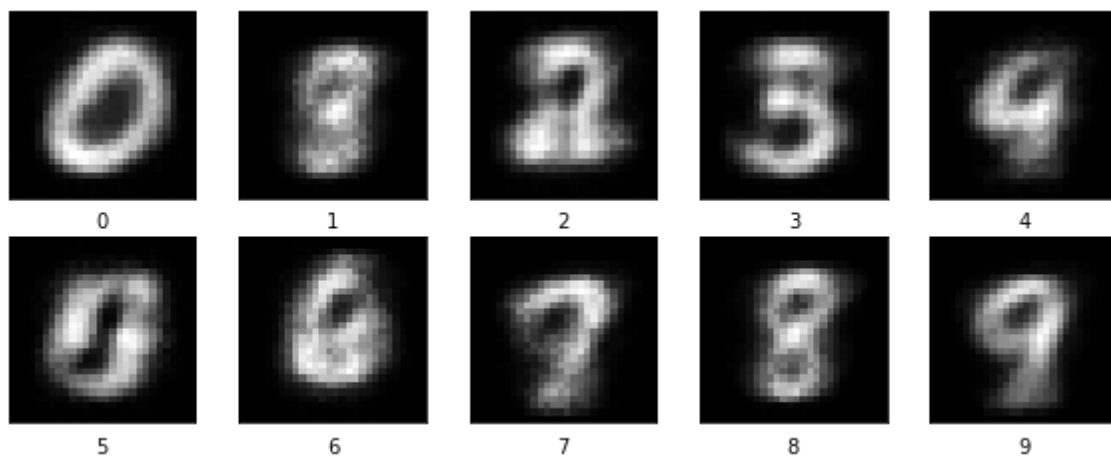
E: 87

100%| 858/858 [00:11<00:00, 75.7
2it/s]



E: 88

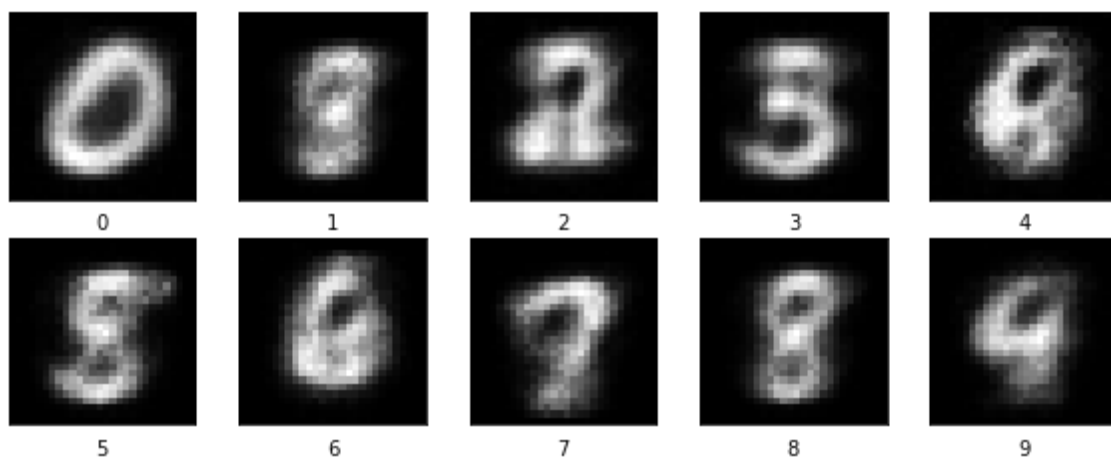
100%| 858/858 [00:11<00:00, 73.0
4it/s]



E: 89

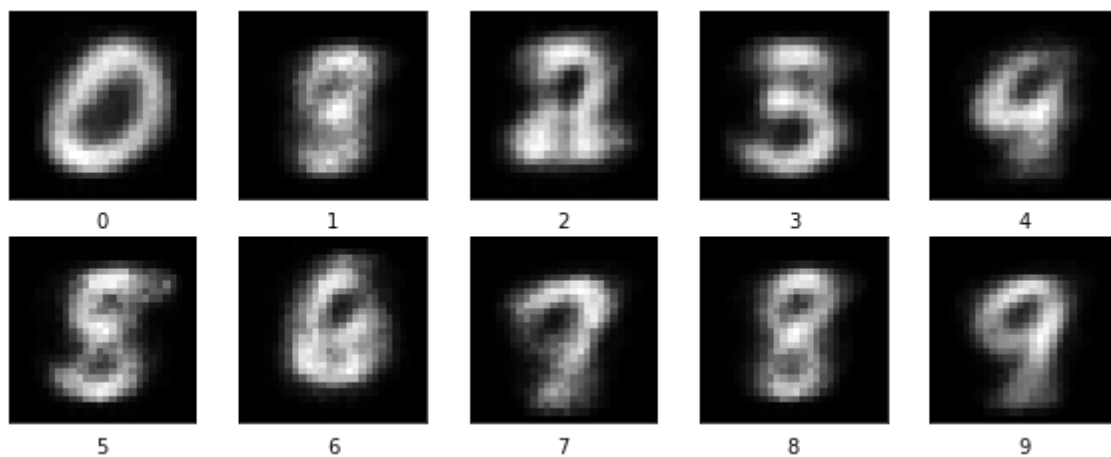
100%|

858/858 [00:10<00:00, 79.4
3it/s]



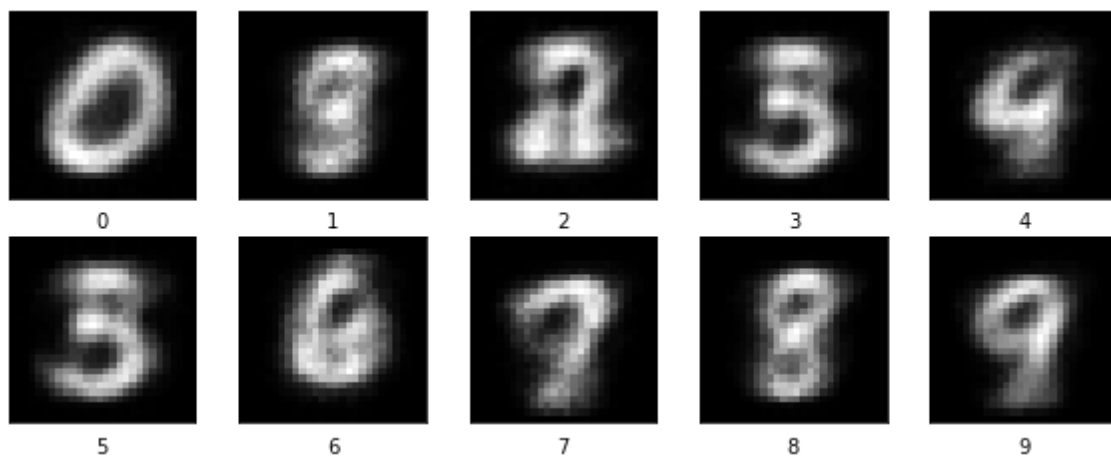
E: 90

100%| 858/858 [00:10<00:00, 83.2
4it/s]



E: 91

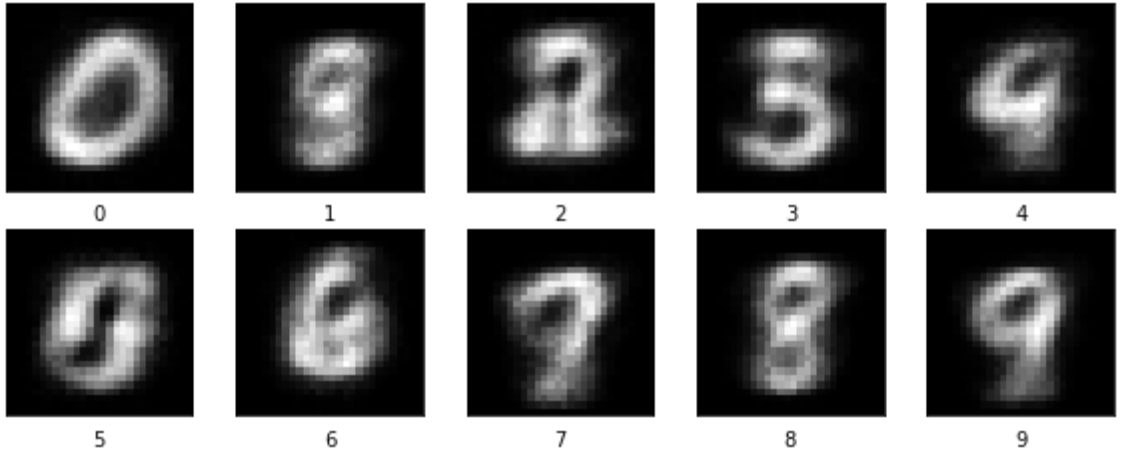
100%| 858/858 [00:11<00:00, 71.9
0it/s]



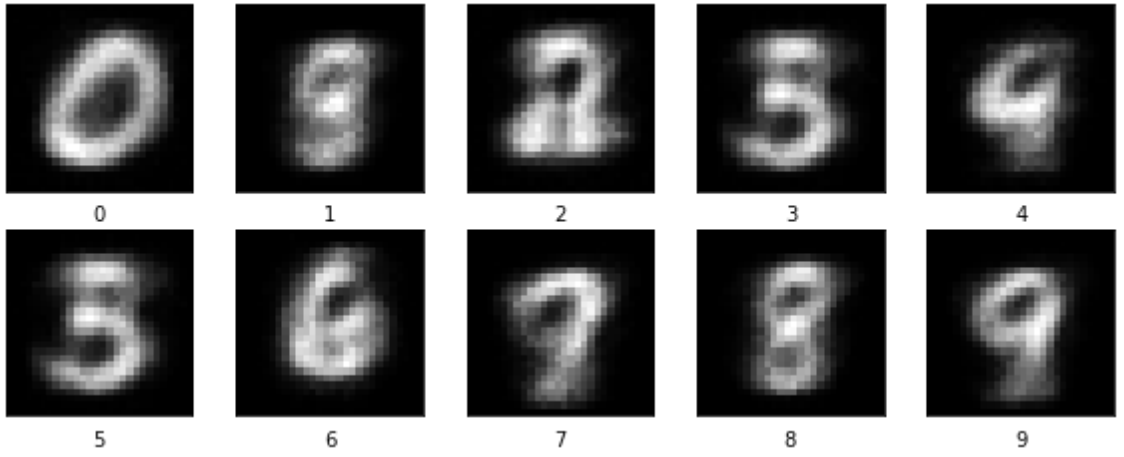
E: 92

100%|

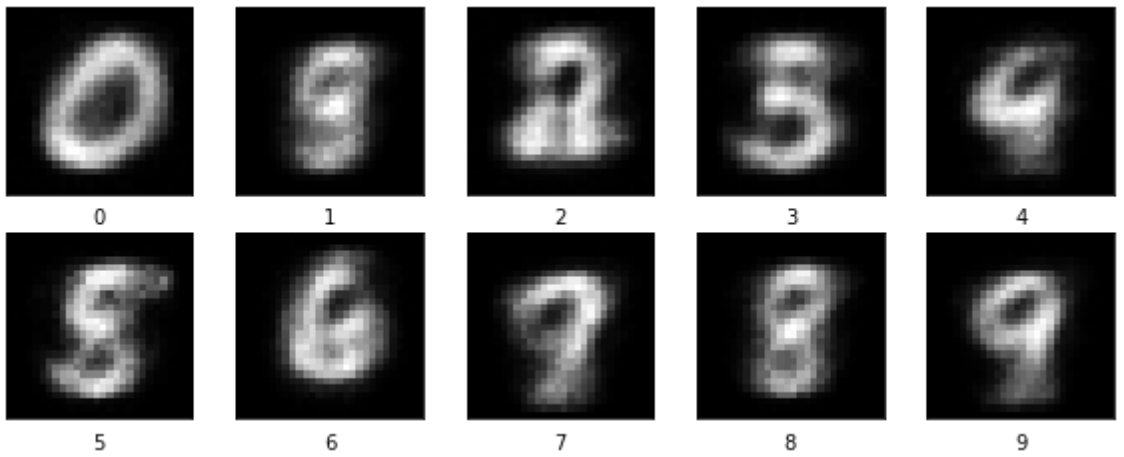
```
██████████| 858/858 [00:10<00:00, 78.0  
4it/s]
```



E: 93

[illegible]

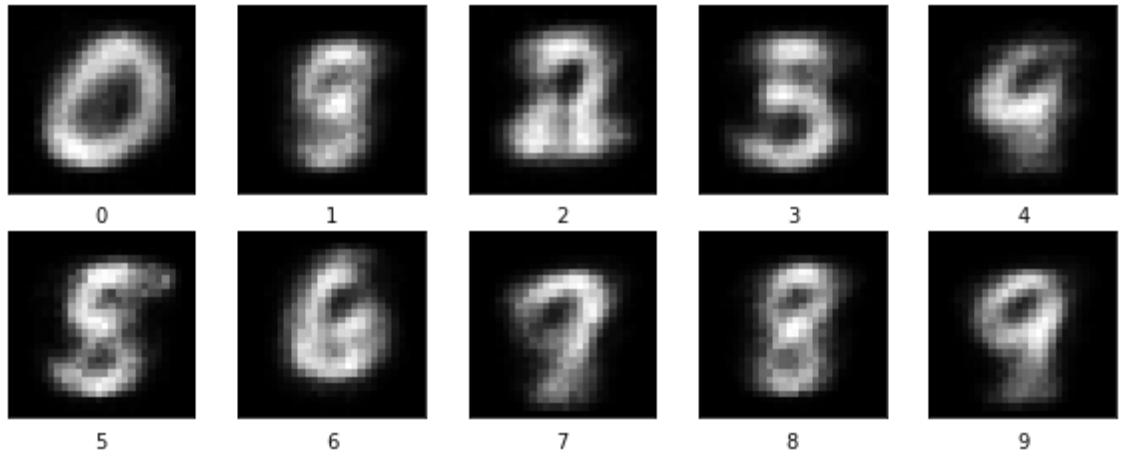
E: 94

[illegible]

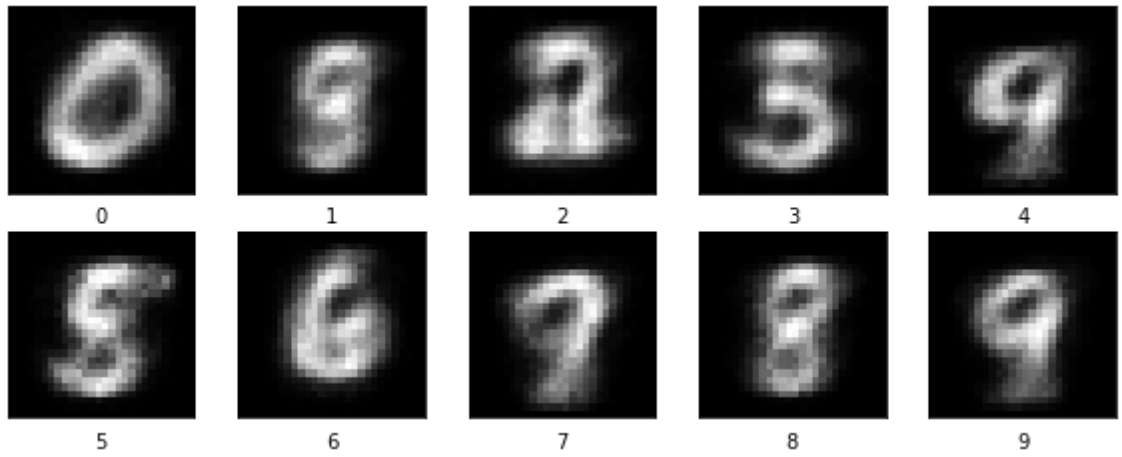
E: 95

100%|

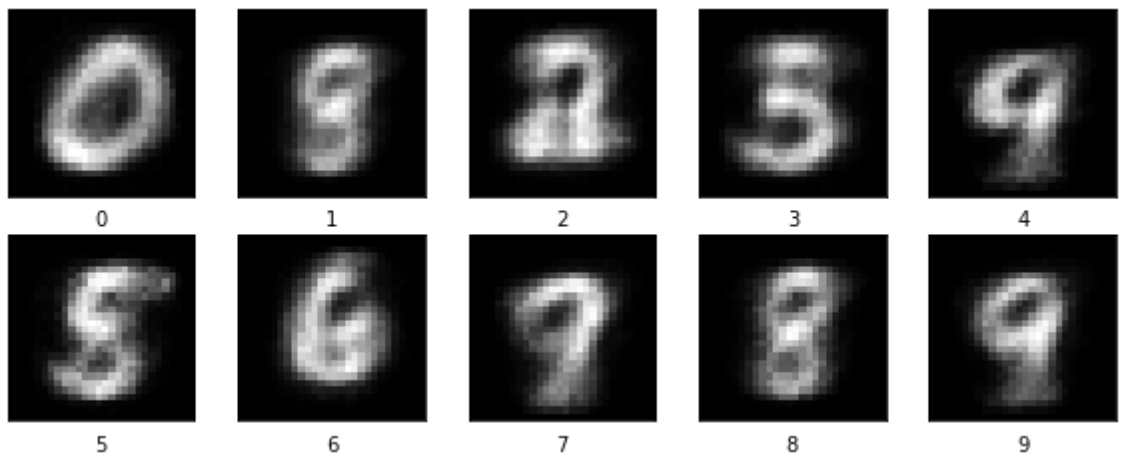
```
|██████████| 858/858 [00:14<00:00, 57.9  
9it/s]
```



E: 96

[illegible]

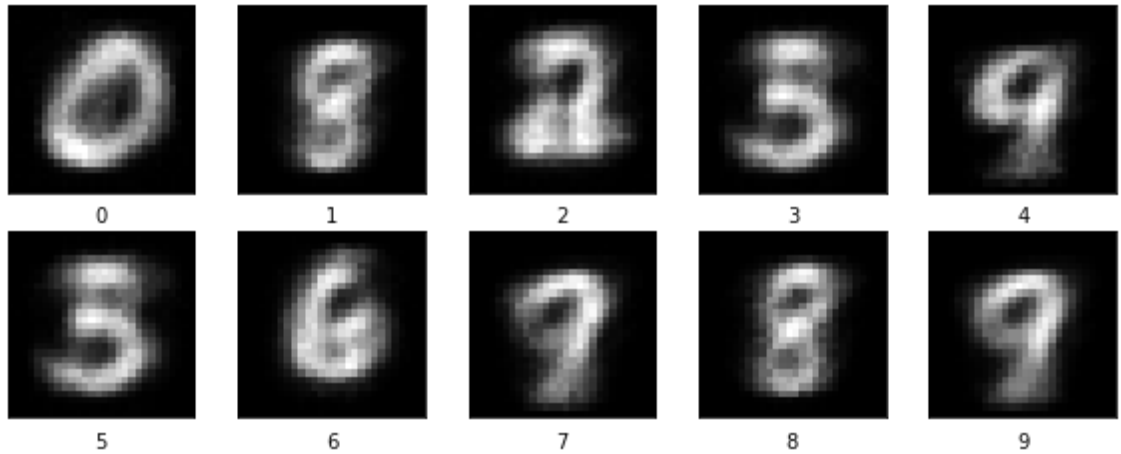
E: 97

[illegible]

E: 98

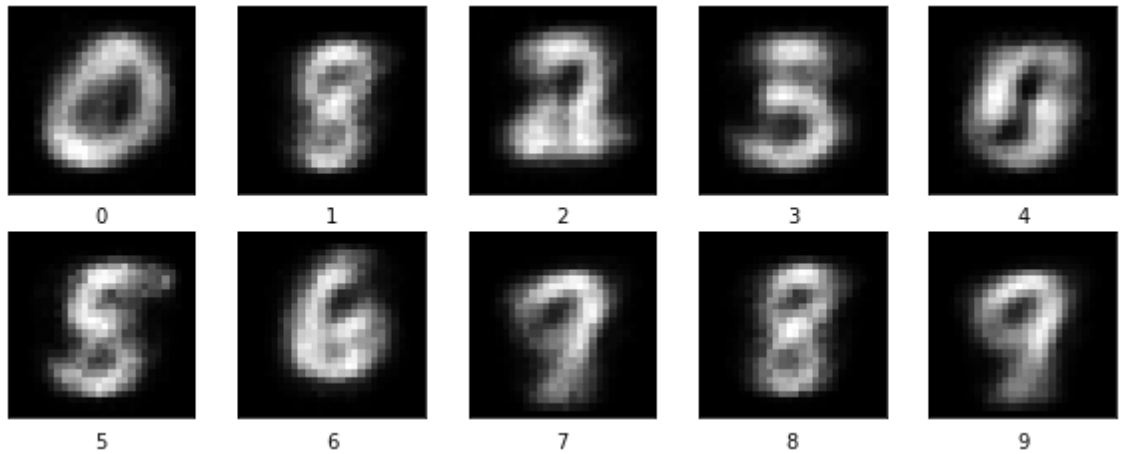
100%|

858/858 [00:11<00:00, 74.2
6it/s]



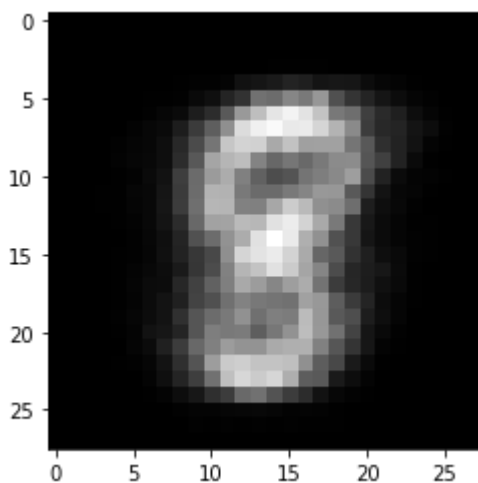
E: 99

100%| 858/858 [00:11<00:00, 75.0
0it/s]



```
In [432]: 1 res = NN.predict([1])  
          2 plt.imshow(res.reshape(28, 28), cmap='gray')
```

Out[432]: <matplotlib.image.AxesImage at 0x7fb71ff178b0>



```
In [ ]: 1
```


In []: 1

In []: 1

In []: 1

In []: 1

In []: 1

In []: 1

In []: 1

In []: 1

In [325]: 1

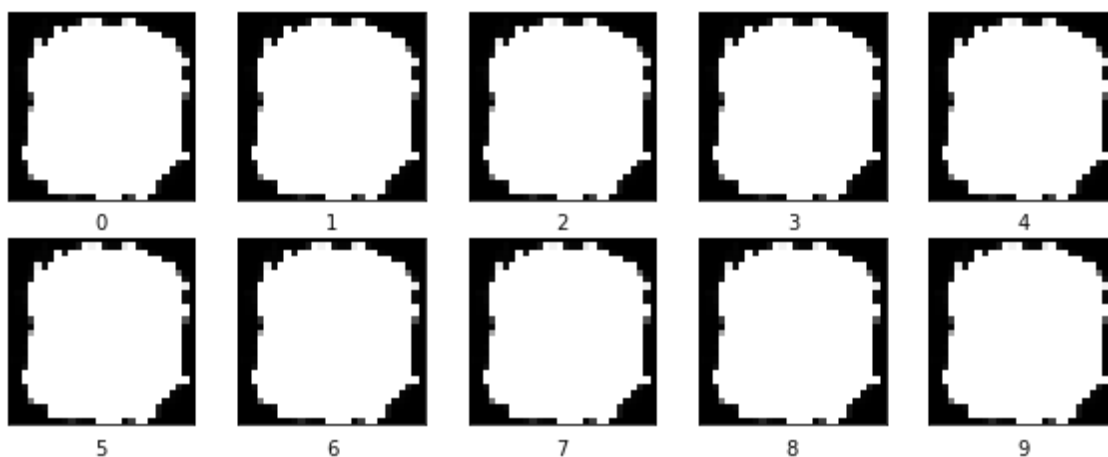
```
/tmp/ipykernel_5437/153577755.py:1: RuntimeWarning: invalid value encountered in log
  np.log(-1)
```

Out[325]: nan

In []: 1

In []: 1

```
In [57]: 1 plt.figure(figsize=(10,10))
        2 for i in range(10):
        3     plt.subplot(5,5,i+1)
        4     plt.xticks([])
        5     plt.yticks([])
        6     plt.grid(False)
        7     res = NN.predict([i])
        8     plt.imshow(res.reshape(28, 28), cmap='gray')
        9     plt.xlabel(i)
       10 plt.show()
       11
```



In []: 1

In []: 1

In []: 1

In []: 1

```

In [ ]: 1 class MyNN:
2         def __init__(self):
3             self.learn_rate = 0.01
4
5             self._weights0 = np.random.rand(784, 49)*0.1 - 0.05
6             self._weights1 = np.random.rand(49, 16)*0.1 - 0.05
7             self._weights2 = np.random.rand(16, 10)*0.1 - 0.05
8
9             self._input = np.zeros([784])
10            self._layer1 = np.zeros([49])
11            self._layer2 = np.zeros([16])
12            self._output = np.zeros([10])
13
14            self._correction_0 = np.zeros([784, 49])
15            self._correction_1 = np.zeros([49, 16])
16            self._correction_2 = np.zeros([16, 10])
17
18            self._activation0 = self.act_relu
19            self._activation1 = self.act_relu
20            self._activation2 = self.act_relu
21
22            self._der_act_0 = self.der_act_relu
23            self._der_act_1 = self.der_act_relu
24            self._der_act_2 = self.der_act_relu
25
26        def zero(self):
27            self._input = np.zeros([784])
28            self._layer1 = np.zeros([49])
29            self._layer2 = np.zeros([16])
30            self._output = np.zeros([10])
31
32        def act_sigmoid(self, layer):
33            return np.array([1/(1+np.exp(-x)) for x in layer])
34
35        def act_relu(self, layer):
36            return np.array([x if x > 0 else 0 for x in layer])
37
38        def act_softplus(self, layer):
39            return np.array([np.ln(1+np.exp(x)) for x in layer])
40
41        def der_act_sigmoid(self, l):
42            _exp = np.exp(-l)
43            return _exp / (1+_exp)**2
44
45        def der_act_relu(self, l):
46            if l > 0:
47                return 1
48            else:
49                return 0
50

```

```

51     def def_act_softplus(self, l):
52         return 1 / (1+np.exp(-l))
53
54     def predict(self, img):
55         self.zero()
56         self._input = img
57
58         self._layer1 = np.dot(self._input, self._weights0)
59         self._layer1 = self._activation0(self._layer1)
60
61         self._layer2 = np.dot(self._layer1, self._weights1)
62         self._layer2 = self._activation1(self._layer2)
63
64         self._output = np.dot(self._layer2, self._weights2)
65         self._output = self._activation2(self._output)
66
67         return self._output
68
69     def learn(self, labels):
70         main_delta = self._output - labels
71         delta_output = main_delta * [self._der_act_2(x) for x in
72         delta_w_2 = np.dot(delta_output.reshape(len(delta_out
73                                     self._layer2.reshape(1, len(self._
74
75         delta_layer2 = np.dot(self._weights2, delta_output) * [s
76         delta_w_1 = np.dot(delta_layer2.reshape(len(delta_lay
77                                     self._layer1.reshape(1, len(self._
78
79         delta_layer1 = np.dot(self._weights1, delta_layer2) * [s
80         delta_w_0 = np.dot(delta_layer1.reshape(len(delta_lay
81                                     self._input.reshape(1, len(self._i
82
83         self._correction_0 += np.transpose(delta_w_0)
84         self._correction_1 += np.transpose(delta_w_1)
85         self._correction_2 += np.transpose(delta_w_2)
86
87     def update(self):
88         self._weights0 = self._weights0 - self.learn_rate * self
89         self._weights1 = self._weights1 - self.learn_rate * self
90         self._weights2 = self._weights2 - self.learn_rate * self
91
92         self._correction_0 = np.zeros([784, 49])
93         self._correction_1 = np.zeros([49, 16])
94         self._correction_2 = np.zeros([16, 10])
95
96     def check_correct(self, test):
97         correct = 0
98         for i in range(len(test)):
99             res = np.argmax(self.predict(test.values[i][1:]))
100             if res == test.values[i][:1]:
101                 correct+=1
102         return correct/len(test)
103
104     def fit(self, test, train, epochs, learn_rate, batch):
105         self.learn_rate = learn_rate
106         for e in range(epochs):
107             for i in range(len(train)):
108                 NN.predict( train.values[i][1:] )
109                 expect = [1 if k == train.values[i][:1] else 0 f
110                 NN.learn(expect)

```

```
111         if not i %batch:
112             NN.update()
113         print("e{}, corr = {}".format(e, NN.check_correct(te
```

In []: 1

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