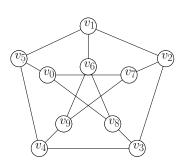


Word-Representable Temporal Graphs Duncan Adamson 20 March 2025

- Word-representable graphs are a class of graphs that can be represented by a word.
- These generalise several fundamental classes of graphs, including circle graphs, three-colourable graphs, and comparability graphs.
- Every word can be used to represent a graph, but not every graph can be represented by a word.
- A graph may have multiple word representations.

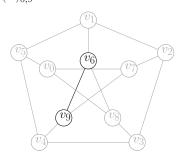
- Given a word
   w = w<sub>1</sub>w<sub>2</sub>...w<sub>n</sub>, we make
   the graph G(w) = (V, E)
   based on the alphabet and
   subsequences of w.
- We create the vertex set V
  as V = {v<sub>x</sub> | x ∈ alph(w)}
- Let π<sub>x,y</sub>(w) denote the subsequence of w containing every instance of the symbols x and y.
- $(v_x, v_y) \in E$  iff  $\pi_{x,y}(w) \in \{(xy)^k, (yx)^k, y(xy)^k, x(yx)^k\}$ .

w = 138729607493541283076850194562

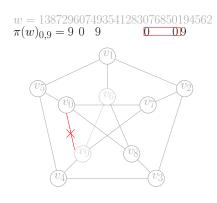


- Given a word  $w = w_1 w_2 \dots w_n$ , we make the graph G(w) = (V, E)based on the alphabet and **subsequences** of w.
- We create the vertex set V as  $V = \{v_x \mid x \in alph(w)\}$
- Let  $\pi_{x,y}(w)$  denote the subsequence of w containing every instance of the symbols x and y.
- $(v_x, v_y) \in E$  iff  $\pi_{x,y}(w) \in$  $\{(xy)^k, (yx)^k, y(xy)^k, x(yx)^k\}.$

 $\pi(w)_{6.9} = 96$ 



- Given a word  $w = w_1 w_2 \dots w_n$ , we make the graph G(w) = (V, E)based on the alphabet and **subsequences** of w.
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### Temporal Graphs

- A temporal graph is a generalisation of (static) graphs when, rather than one single set of edges, there is an ordered sequence of edge sets.
- By convention:

$$\mathcal{G} = (V, E_1, E_2, \dots, E_T)$$

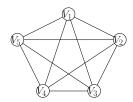
where:

- V is the set of vertices.
- $E_i \subseteq V \times V$  is a set of edges.
- We call each set of edges a time step, and the number of sets as the lifetime of the graph.
- An edge e is **active** in timestep i iff  $e \in E_i$ .
- The underlying graph is the static graph

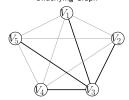
$$U(\mathcal{G}) = \left(V, \bigcup_{\substack{i \in [1,T] \\ \text{Duncan Adamson}}} E_i\right).$$

## Temporal Graph Example

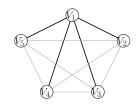
### $G = (\{v_1, v_2, v_3, v_4, v_5\}, E_1, E_2, E_3, E_4, E_5)$



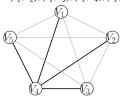
Underlying Graph



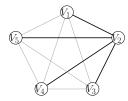
 $E_3 = (v_1, v_3), (v_2, v_3), (v_3, v_4), (v_3, v_5)$ 



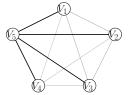
 $E_1 = (v_1, v_2), (v_1, v_3), (v_1, v_4), (v_1, v_5)$ 



 $E_4 = (v_1, v_4), (v_2, v_4), (v_3, v_4), (v_4, v_5)$ 



 $E_2 = (v_1, v_2), (v_2, v_3), (v_2, v_4), (v_2, v_5)$ 



 $E_5 = (v_1, v_5), (v_2, v_5), (v_3, v_5), (v_4, v_5)$ 

Word-Representable Temporal Graphs

Duncan Adamson

### Word-Representable Temporal Graphs

- In order to generalise word-representable graphs to temporal graphs, we need to represent different timesteps in a "reasonable" way.
- This means, being able represent a wide class of graphs in each timestep, while still being a compact representation of the temporal graph.

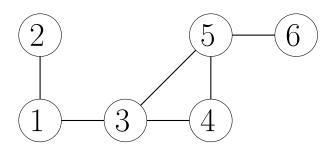
### Word-Representable Temporal Graphs

- Given a word  $w = w_1 w_2 \dots w_n$ , we construct the temporal graph  $\mathcal{G}(w) = (V, E_1, E_2, \dots, E_T)$  with the underlying graph  $\mathcal{G}(w)$  (i.e., the static graph represented by w).
- To determine the timesteps, we split w into a set of factors (timestep words)  $u_1, u_2, \dots u_T$  such that  $w = u_1 u_2 \dots u_T$ .
- $u_1$  is defined as  $w[1, i_1]$ , where  $i_1$  satisfies  $|\operatorname{alph}(w[1, i_1])| = i_1$  and  $w[i_1 + 1] \in \operatorname{alph}(w[1, i_1])$ .
  - Informally,  $i_1 + 1$  is the index of the first repeated symbol in w.
- Now, let  $i_{t-1} = |u_1 u_2 \dots u_{t-1}|$ . The index  $i_t$  is the value such that  $|\operatorname{alph}(w[i_{t-1}+1,i_t])| = i_t i_{t-1}$  and  $w[i_t+1] \in \operatorname{alph}(w[i_{t-1}+1,i_t])$ .
  - Informally,  $i_t + 1$  is the index of the first repeated symbol in the suffix of w,  $w[i_{t-1} + 1, n]$ .
- $u_t$  is then set to  $w[i_{t-1}+1, i_t]$ .

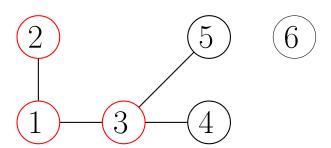
### Word-Representable Temporal Graphs

- Let  $w = u_1 u_2 \dots u_T$  as in the previous slide.
- Let G(w) = (V, E) be the static graph represented by w, and  $G(w) = (V, E_1, E_2, \dots, E_T)$  the temporal graph represented by w.
- We set the edge set  $E_t$  to  $\{(v_i, v_j) \in E \mid i \in alph(u_t) \text{ or } j \in alph(u_t)\}.$ 
  - Informally, E<sub>t</sub> contains every edge incident to some vertex in the factor u<sub>t</sub>.

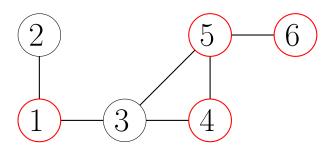
# 123145653465



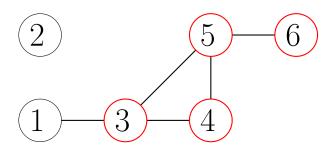
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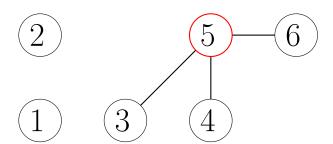
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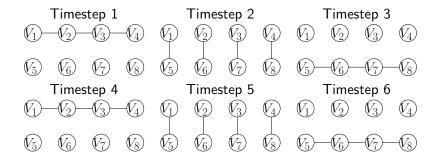


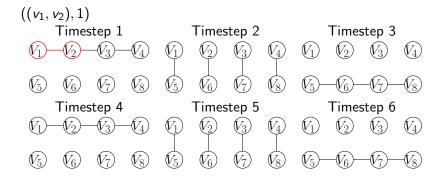
### Why are we interested in these graphs?

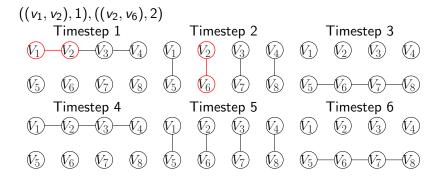
- In many networks, a node is either active or inactive (a phone is on or off, a server is connected or disconnected).
- When active, we can assume, in a simple model, that all connections are available.
- Word-representable temporal graphs provide a subclass of such graphs that can be represented in a **compact manner**.

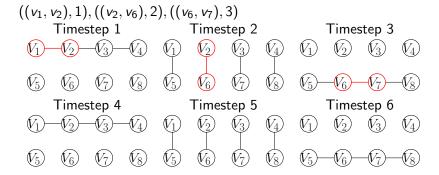
### Temporal Walks

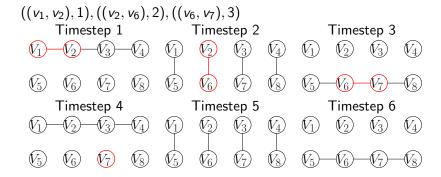
- A temporal walk is the temporal analogue of a walk in a static graph.
- A temporal walk on the temporal graph  $\mathcal{G}$  is an ordered sequence of edges,  $e_1, e_2, \ldots, e_k$ , and timesteps  $t_1, t_2, \ldots, t_k$  such that:
  - $e_1, e_2, \ldots, e_k$  form a walk in  $U(\mathcal{G})$ , and,
  - *e*; is active in timestep *t*;.
  - $1 < t_1 < t_2 < \cdots < t_k < T$
- Given an agent following a temporal walk, if there is some timestep t that does not appear in the sequence of timesteps, we say the agent is waiting.

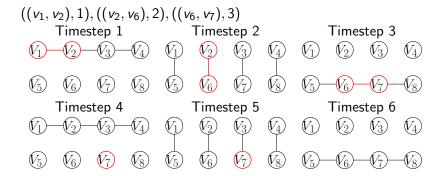


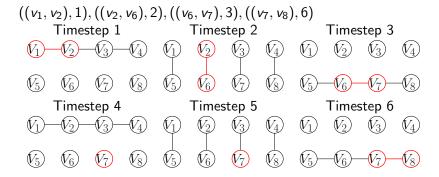












### Problems on Temporal Graphs

- Most algorithmic work on temporal graphs focuses on questions of reachability and exploration.
- **Reachability:** Given a temporal graph G and pair of vertices  $v_i, v_i$ , does there exist a temporal walk from  $v_i$  to  $v_i$ ?
  - Optimisation Variant: What is the earliest an agent starting at v<sub>i</sub> can reach v<sub>i</sub>?
- **Exploration:** Given a temporal graph  $\mathcal{G}$ , does there exist a temporal walk visiting every vertex at least once?
  - Optimisation Variant: What is the earliest an agent starting at v<sub>i</sub> can visit every vertex in the graph?

### Always Connected Graphs

- A temporal graph is *Always Connected* if every timestep contains only a single connected-component.
- A word-representable temporal graph is always connected if the corresponding temporal graph is always connected.
- It is known that any always connected temporal graph with n vertices and a lifespan of at least  $n^2$  can be explored, and that this bound is tight.

### Exploring Always Connected Temporal Graphs

#### **Theorem**

Let  $w \in \Sigma^*$  be a word representing an always connected temporal graph  $\mathcal{G}(w) = (V, E_1, E_2, \dots, E_T)$  with a minimum degree of  $\delta$  and  $T > 2\delta\sigma$ . Then, there exists a temporal walk exploring  $\mathcal{G}$ .

### Outline

### High Level Idea:

- We find a walk exploring the underlying graph.
- A Eulerian tour of a spanning tree gives such a walk of length at most 2n - 1.

#### Problem:

 Transforming this into a temporal walk requires these edges to be active in order.

### Lemma (Informal)

Given any 
$$t \in [1, T - \delta]$$
,  $E = \bigcup_{d \in [\delta]} E_{t+d}$ .

### Sketch

- Let  $w = u_1 u_2 \dots u_T$ ,  $\mathcal{G}(w) = (V, E_1, E_2, \dots, E_T)$ , and  $\mathcal{G}(w) = (V, E)$ .
- To be always connected, there needs to be, for every vertex  $v_i \in V$  and  $t \in [1, T]$ , some  $v_j \in V$  s.t.  $(v_i, v_j) \in E_t$ .
  - By extension,  $\{j \in [1, \sigma] \mid i = j \text{ or } (v_i, v_i) \in E\} \cap \text{alph}(u_t) \neq \emptyset$ ,
- As  $(v_i, v_j) \in E$  iff i and j alternate, then, for every  $t \in [1, T deg(v_i) 1]$ ,  $i \in alph(u_t u_{t+1} \dots u_{t+deg(v_i)+1})$ .
  - Informally, the letter i has to appear at least once every deg(v<sub>i</sub>) timesteps.

## Sketch (part 2)

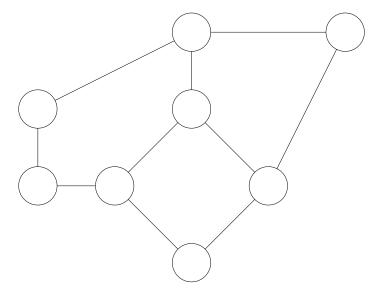
- Now, if (v<sub>i</sub>, v<sub>j</sub>) ∈ E, then, if i appears at least once every deg(v<sub>i</sub>) timesteps, then j must also appear at least once every deg(v<sub>i</sub>) consecutive timesteps words.
- Similarly, if j appears at least once every deg(v<sub>i</sub>) timesteps, then i must also appear at least once every deg(v<sub>j</sub>) consecutive timestep words.
- So, *i* appears at least once every  $min(deg(v_i), deg(v_j))$  timestep words.
- In general, i appears at least once every

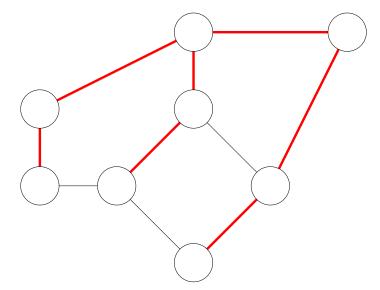
$$\min \left( deg(v_i), \min_{v_j \in N(v_i)} (deg(v_j)) \right)$$

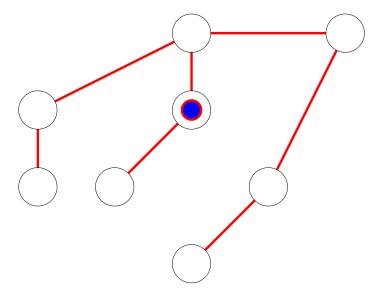
consecutive timestep words.

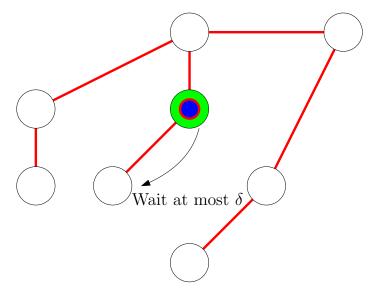
## Sketch (part 3)

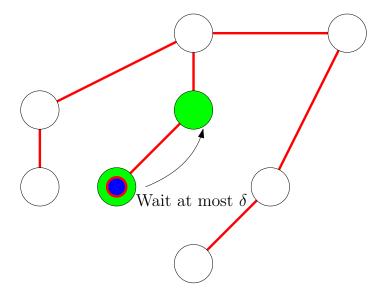
- Extrapolating out, if  $(v_i, v_j) \in E$ , and j appears in every d consecutive timestep words, then i appears (at least once) in every d consecutive timestep words.
- So, if there exists a path between  $v_i$  and  $v_k$ , and k appears in every d' consecutive timestep words, i appears (at least once) in every d' consecutive timestep words.
- Hence, every symbol is active at least once every  $\delta+1$  timesteps.
- By extension, each edge is active at least once every  $\delta$  timesteps.

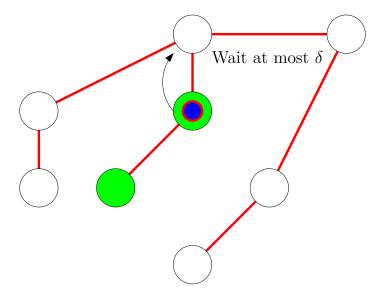


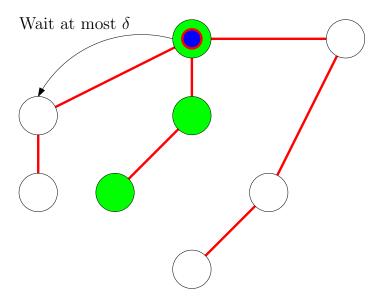


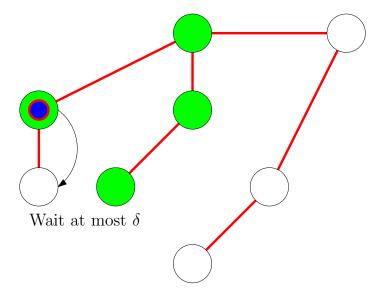


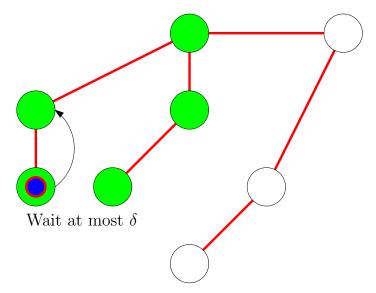


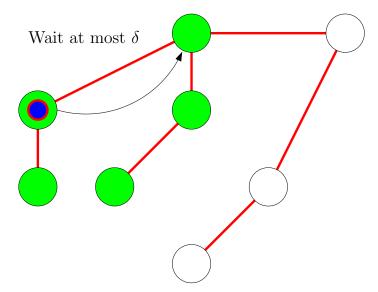


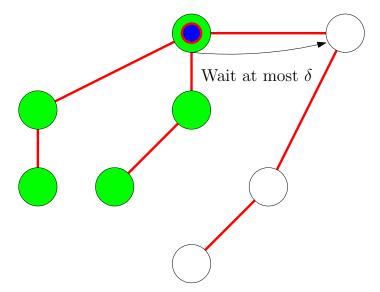


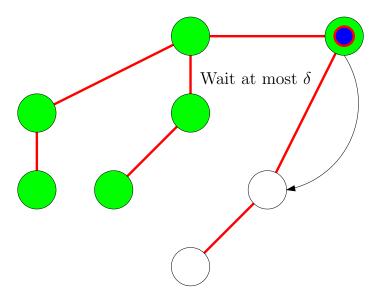


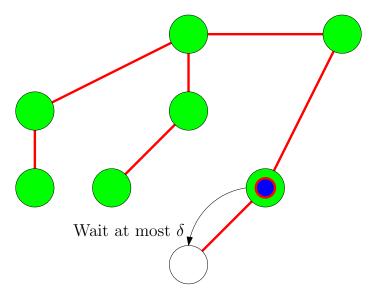


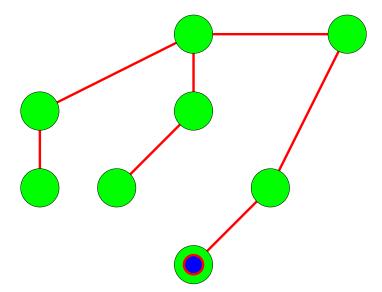












### Connected Graphs

#### Theorem

Let  $w \in \Sigma^*$  be a word representing a connected temporal graph  $\mathcal{G}(w) = (V, E_1, E_2, \dots, E_T)$  with a diameter of d and  $T \ge 2d\sigma$ . Then, there exists a temporal walk exploring  $\mathcal{G}$ .

#### **Theorem**

Given some number of vertices  $\sigma$  and diameter  $d < \sigma$ , there exists a word w representing a connected graph requiring  $d\sigma/2$  timesteps to explore.

### Next Steps

- Is the  $O(\delta \sigma)$  algorithm asymptotically optimal for exploring word-representable always connected temporal graphs?
- Is the  $2d\sigma$  bound for exploring word-representable connected temporal graph tight?
- What kind of graphs can be represented at each timestep?
- Thank you for listening!