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205 import numpy as np
    import pandas as pd
    from sklearn.cluster import KMeans
    from sklearn.cluster import Birch
    from sklearn.cluster import AgglomerativeClustering
    from sklearn.cluster import DBSCAN
    from matplotlib import pyplot as plt

    np.random.seed(1)

206 def equalProb():
    if np.random.random() < 0.5:
        return 0
    else:
        return 1

    def boundedNormal(bound, stddev):
        rNum = np.random.normal(0, stddev)
        while rNum < -bound or rNum > bound:
            rNum = np.random.normal(0, stddev)
        return rNum

207 def gen_data_one():
    """This Function Generates Data Set 1"""
    center1 = 10
    center2 = 20
    center3 = 30
    bound = 4
    stddev = 2

    tuples = []
    numTuples = 1000

    for i in range(numTuples):
        rNum = np.random.randint(3)
        if rNum == 0:
            # candidate = 0
            rNum = boundedNormal(bound, stddev)
            a1 = center1 + rNum
            rNum = boundedNormal(bound, stddev)
            a2 = center1 + rNum

        elif rNum == 1:
            candidate = 1
            rNum = boundedNormal(bound+10, stddev+10)
            a1 = center2 + rNum
            rNum = boundedNormal(bound+5, stddev+5)
            a2 = center2 + rNum + 5

        else:
            candidate = 2
            rNum = boundedNormal(bound+4, stddev)
            a1 = center3 + rNum
            rNum = boundedNormal(bound+2, stddev)
            a2 = center3 + rNum

        atuple = (a1, a2)
        tuples.append(atuple)

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df = pd.DataFrame(tuples, columns=["a1", "a2"])
return df
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208 def gen_data_two():
    """This Function Generates Data Set 2"""
    center1 = 15
    center2 = 15
    center3 = 15
    bound = 25
    stddev = 2

    tuples = []
    numTuples = 1000

    for i in range(numTuples):
        rNum = np.random.randint(3)
        if rNum == 0:
            # candidate = 0
            rNum = boundedNormal(bound, stddev)
            a1 = center1 + rNum
            rNum = boundedNormal(bound, stddev)
            a2 = center1 + rNum

        elif rNum == 1:
            # candidate = 1
            rNum = boundedNormal(bound, stddev)
            a1 = center2 + rNum
            rNum = boundedNormal(bound, stddev)
            a2 = center2 + rNum

        else:
            # candidate = 2
            rNum = boundedNormal(bound, stddev)
            a1 = center3 + rNum
            rNum = boundedNormal(bound, stddev)
            a2 = center3 + rNum

        atuple = (a1, a2)
        tuples.append(atuple)

    df = pd.DataFrame(tuples, columns=["a1", "a2"])
    return df

209 def plot_clustering(theData, kmeansLabels, brclLabels, agglLabels, dbLabels, graph_title):
    fig, ax = plt.subplots(2,2)

    # Plotting Kmeans
    for i in range(len(theData)):
        theColor = None
        if kmeansLabels[i] == 0: theColor= "red"
        if kmeansLabels[i] == 1: theColor= "green"
        if kmeansLabels[i] == 2: theColor= "blue"
        ax[0,0].scatter(theData[i][0], theData[i][1], s=9.5, alpha=1.0, color=theColor)
        ax[0,0].set_title("kmeans")

    # Plotting Birch
    for i in range(len(theData)):
        if brclLabels[i] == 0: theColor = "blue"
        if brclLabels[i] == 1: theColor = "red"
        if brclLabels[i] == 2: theColor = "green"
        ax[0,1].scatter(theData[i][0], theData[i][1], s=9.5, alpha=1.0, color=theColor)
        ax[0,1].set_title("birch")
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# Plotting Agglomerative
for i in range(len(theData)):
    if aggLabels[i] == 0: theColor = "red"
    if aggLabels[i] == 1: theColor = "green"
    if aggLabels[i] == 2: theColor = "blue"
    ax[1, 0].scatter(theData[i][0], theData[i][1], s=9.5, color=theColor)
    ax[1, 0].set_title("Agglomerative")

# Plotting DBScan
for i in range(len(theData)):
    if dbLabels[i] == 0: theColor = "red"
    elif dbLabels[i] == 1: theColor = "green"
    elif dbLabels[i] == 2: theColor = "blue"
    else: theColor = "pink"
    ax[1, 1].scatter(theData[i][0], theData[i][1], s= 9.5, alpha=1.0, color=theColor)
    ax[1, 1].set_title("DBScan")

fig.tight_layout()
fig.suptitle(graph_title)
fig.subplots_adjust(top=0.88)
plt.figure(figsize=(7, 5))
plt.show()

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210 def create_graph(df_in, title):
    """This Function Goes through and creates the clustering graphs out of the data shown"""
    df = df_in.copy()
    numClusters= 3
    theData = df.to_numpy()

    # kMeans
    kmeans = KMeans(n_clusters=numClusters, random_state=0).fit(df)

    # Birch
    brc = Birch(n_clusters=numClusters).fit(df)

    # Agglomerative
    agg = AgglomerativeClustering(n_clusters=numClusters, linkage="ward").fit(df)

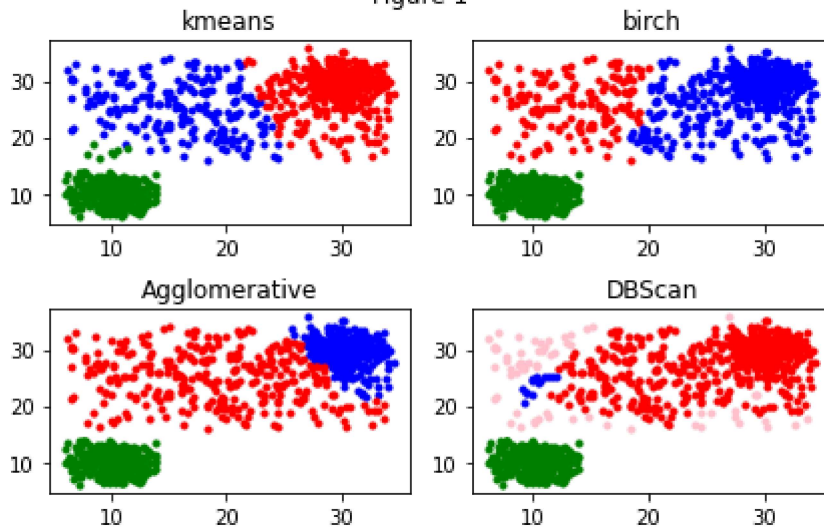
    # DBSCAN
    db = DBSCAN(eps=1.5, min_samples=4).fit(df)

    plot_clustering(theData, kmeans.labels_, brc.labels_, agg.labels_, db.labels_, title)

211 df1 = gen_data_one()
    create_graph(df1, "Figure 1")

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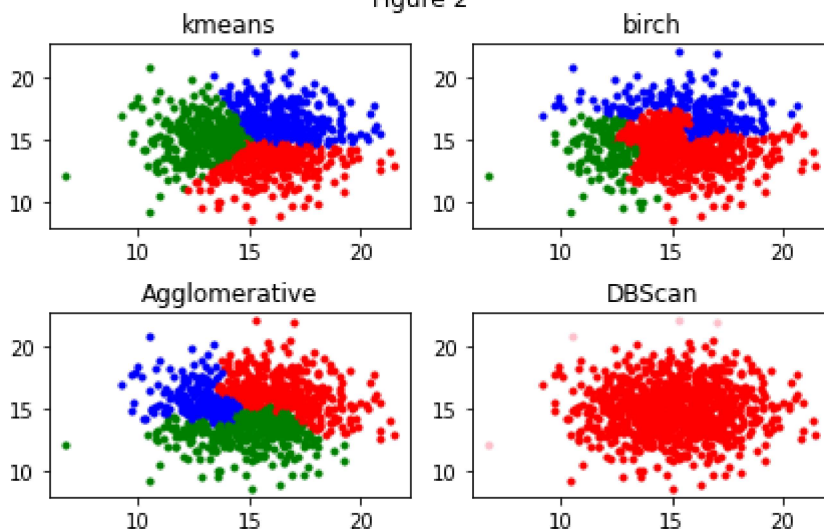
Figure 1



<Figure size 504x360 with 0 Axes>

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212 df2 = gen_data_two()
    create_graph(df2, "Figure 2")
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Figure 2



<Figure size 504x360 with 0 Axes>

Objective

Upload a pdf file containing a write up describing one or two data sets, the 4-chart visualization that shows they result in different clusterings, and an explanation of WHY the different Clusters.

For this assignment the amount of N clusters is 3.

K-means

K- Means starts by clustering the data into 3 clusters. A random n centroids are selected and then the data is parsed through and each point is then assigned to the cluster in which the

centroid it is closest to. The mean of the n clusters is then calculated and these are assigned as the new centroids. The algorithm then repeats this process until the centroids stabilize.

In Figure two this creates an even "pie" diagram. Where the clusters all look to be about equal size. In Figure 1 we end up with three clusters, one being the centralized in the lower left corner on in the upper right corner and the middle diagram. As the algorithm works through Figure 1. The center of the points are pulling the data in closer to the center of each color group.

Agglomerative

The Agglomerative algorithm is a bit of the inverse of the K-means. All the points are considered their own clusters And then they are joined to the clusters that are closest to them. The Algorithm uses the bottom up approach using the 'ward' linkage. Each of the new joined clusters gets a centroid and the new clusters are then joined based on clusters that are closest. It is for this reason that we see in Figure one the grouping of blue in the upper right, green in the lower left, and the red all joined. The Blue and Green have close clusters and draw the points in toward those centroids, where red is more dispersed. In Figure two the algorithm is similar in splitting to Kmeans, but it slightly shifts based on the distances between the points from the starting selection leading to three clusters that are not as evenly distributed as Kmeans.

Birch

Birch Stands for Balanced Iterative Reducing and Clustering using Hierarchies. It is an algorithm that can cluster data by first summarizing large data sets into smaller, dense clusters known as Clustering Features where there are N number of data points in the cluster and the linear sum of these data points where the squared sum of the data points is then clustered. It is for this reason that we see a difference between Birch and K mean in Figure 1. Birch has a more evenly spread of the Blue and Red clusters, and a tight cluster on the green. It tries to create more even clusters. A CF tree is a tree where each leaf node contains a sub-cluster. Every entry in a CF tree contains a pointer to a child node and a CF entry made up of the sum of CF entries in the child nodes. There is a maximum number of entries in each leaf node. This maximum number is called the threshold

In figure 2 The Red cluster joins the closest points in the middle and builds outward toward the bottom of the graph. Where the Green and Blue start with clusters to the side of the red center and build outward. The algorithm minimize linear sum and the quadratic sums. It is for this reason the algorithm does not do well with cigar type shapes.

dbscan

DBScan stands for Density-based spatial clustering with noise. The algorithm assumes the data is spherical. The two main features are minpoints and EPS. The minpoints is based off the size of the data set and the eps defines the neighborhood around a data point. If the distance between

two points is lower than ϵ they are considered neighbors. The algorithm starts with large clusters and then adds data to those clusters. In Figure 2 this leads to there being only one main cluster red, with a few outliers in pink. In Figure 1 this leads to three clusters. The main green cluster in the lower left, and a main cluster in the upper right that drifts outwards. There is a small cluster of blue that originates in this data set as well as it the dispersed red points move further away from their center. The red is able to spread toward the left because the DBscan algorithm allows for some more noise in the data set.

