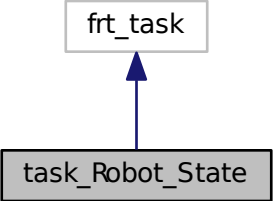


frt_task



```
graph BT; task_Robot_State[task_Robot_State] --> frt_task[frt_task]
```

A diagram showing a relationship between two tasks. A light gray box labeled 'frt_task' is at the top, and a darker gray box labeled 'task_Robot_State' is at the bottom. A blue arrow points from the top of the 'task_Robot_State' box to the bottom of the 'frt_task' box.

task_Robot_State