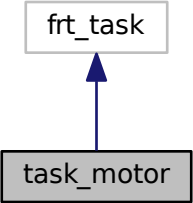


frt_task



```
graph BT; task_motor[task_motor] --> frt_task[frt_task]
```

A diagram showing a relationship between two tasks. At the bottom is a gray rectangular box labeled 'task_motor'. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box labeled 'frt_task' positioned above it.

task_motor