

March 18, 2017

Stochastic Processes: Data Analysis and Computer Simulation

Brownian motion 2: computer simulation
 -Random force in the Langevin equation-

1 Langevin equation

1.1 Model for a Brownian particle in 3-D

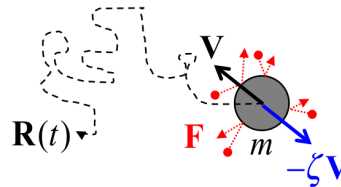
$$m \frac{d\mathbf{V}(t)}{dt} = -\zeta \mathbf{V}(t) + \mathbf{F}(t) \quad (21)$$

1.2 Time evolution equations

$$\frac{d\mathbf{R}(t)}{dt} = \mathbf{V}(t) \quad (F1)$$

$$m \frac{d\mathbf{V}(t)}{dt} = -\zeta \mathbf{V}(t) + \mathbf{F}(t) \quad (F2)$$

Particle radius:	a
Particle mass:	m
Solvent viscosity:	η
Friction constant:	$\zeta = 6\pi\eta a$
Particle position:	$\mathbf{R}(t)$
Particle velocity:	$\mathbf{V}(t) = d\mathbf{R}/dt$
Friction force:	$-\zeta \mathbf{V}(t)$
Random force:	$\mathbf{F}(t)$



1.3 Random force

$$\langle \mathbf{F}(t) \rangle = \mathbf{0} \quad (\text{F3})$$

$$\langle \mathbf{F}(t) \mathbf{F}(0) \rangle = 2k_B T \zeta \mathbf{I} \delta(t) \quad (\text{F4})$$

1.4 Cf. Euler method for a damped harmonic oscillator

$$\frac{d\mathbf{R}(t)}{dt} = \mathbf{V}(t) \quad (\text{B1})$$

$$m \frac{d\mathbf{V}(t)}{dt} = -\zeta \mathbf{V}(t) - k\mathbf{R}(t) \quad (\text{B2})$$

$$\mathbf{R}_{i+1} = \mathbf{R}_i + \int_{t_i}^{t_{i+1}} dt \mathbf{V}(t) \simeq \mathbf{R}_i + \mathbf{V}_i \Delta t \quad (\text{B3})$$

$$\begin{aligned} \mathbf{V}_{i+1} &= \mathbf{V}_i - \frac{\zeta}{m} \int_{t_i}^{t_{i+1}} dt \mathbf{V}(t) - \frac{k}{m} \int_{t_i}^{t_{i+1}} dt \mathbf{R}(t) \\ &\simeq \left(1 - \frac{\zeta}{m} \Delta t\right) \mathbf{V}_i - \frac{k}{m} \mathbf{R}_i \Delta t \end{aligned} \quad (\text{B4})$$

1.5 Application of Euler method to Eqs.(F1) and (F2)

$$\mathbf{R}_{i+1} = \mathbf{R}_i + \int_{t_i}^{t_{i+1}} dt \mathbf{V}(t) \simeq \mathbf{R}_i + \mathbf{V}_i \Delta t \quad (\text{F5})$$

$$\begin{aligned} \mathbf{V}_{i+1} &= \mathbf{V}_i - \frac{\zeta}{m} \int_{t_i}^{t_{i+1}} dt \mathbf{V}(t) + \frac{1}{m} \int_{t_i}^{t_{i+1}} dt \mathbf{F}(t) \\ &\neq \left(1 - \frac{\zeta}{m} \Delta t\right) \mathbf{V}_i + \frac{1}{m} \mathbf{F}_i \Delta t \end{aligned} \quad (\text{F6})$$

$$\because \int_{t_i}^{t_{i+1}} dt \mathbf{F}(t) \neq \mathbf{F}_i \Delta t \quad (\text{F7})$$

1.6 Cumulative impulse $\Delta \mathbf{W}_i$: the Wiener process

$$\int_{t_i}^{t_{i+1}} dt \mathbf{F}(t) \equiv \Delta \mathbf{W}_i \quad (\text{F8})$$

- $F_\alpha(t) \rightarrow$ A series of random numbers drawn from some distribution with an average and variance equal to zero and $2k_B T \zeta$, respectively.
- $\Delta W_{\alpha,i} \rightarrow$ A series of random numbers drawn from a “Gaussian distribution”, with an average and variance equal to zero and $2k_B T \zeta \Delta t$, respectively. This is a consequence of the central limit theorem (see the supplemental note for details).

1.7 Modified velocity update equation (Eq.(F6)→(F9))

$$\begin{aligned}\mathbf{V}_{i+1} &= \mathbf{V}_i - \frac{\zeta}{m} \int_{t_i}^{t_{i+1}} dt \mathbf{V}(t) + \frac{1}{m} \int_{t_i}^{t_{i+1}} dt \mathbf{F}(t) \\ &\simeq \left(1 - \frac{\zeta}{m} \Delta t\right) \mathbf{V}_i + \frac{1}{m} \Delta \mathbf{W}_i\end{aligned}\tag{F9}$$

$$\langle \Delta \mathbf{W}_i \rangle = \mathbf{0}\tag{F10}$$

$$\langle \Delta \mathbf{W}_i \Delta \mathbf{W}_j \rangle = 2k_B T \zeta \Delta t \mathbf{I} \delta_{ij}\tag{F11}$$