

REGION-BASED SEGMENTATION ¹

- Includes 3 methods:

Region Growing

Region Merging

Region Split and Merge

REGION GROWING

- It is a procedure that groups pixels or sub regions into larger regions based on predefined criteria for growth.
- Basic approach is to start with a set of seed point and

from this grow regions by appending to each seed those neighboring pixels that have predefined properties similar to the seed.

- Suppose v is the current point in the region and u is the pixel point in its neighbourhood to be compared; then criteria for the given image function f is defined as follows:-

$$S = \begin{cases} 1, & \text{if } |f(u) - f(v)| < T \\ 0, & \text{if } |f(u) - f(v)| \geq T \end{cases}$$

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where $T \rightarrow$ pre assigned threshold

- When $S = 1$, u and v are similar and are put in the

same region; otherwise, u and v belong to different regions.

- Advantages

Very simple concept

Can separate the regions that have the same properties we define.

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- Disadvantages

Descriptors can yield misleading results if connectivity properties are not used in region growing process.

Region growing is the formulation of a stopping rule. Region growth should stop when no more

pixels satisfy the criteria for inclusion in that region.

Seed point must be specified correctly as different seed point will give different results.

Algorithm 4.6: The region-growing method

For the given image $f(i, j): 0 \leq i \leq m-1, 0 \leq j \leq n-1$

Preassign a seed pixel v_0 and a threshold τ ;

Initialize the current region $R := \{v_0\}$; The set of candidate seeds $C := \{v_0\}$;

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While ( $C \neq \emptyset$ ) do
{
    select a seed pixel  $v$  from  $C$ ;
     $C := C \setminus \{v\}$ ; // delete the seed pixel  $v$  from the candidate seed set;
     $N(v) :=$  the set containing 4-neighbouring pixels of  $v$ ;
    For each  $u \in N(v)$ : if ( $u \notin R$ ) and ( $s = 1$ ) // From Equation 4.13
    {
         $R := R \cup \{u\}$ ;
         $C := C \cup \{u\}$  //  $u$  is added to the region and is a candidate seed
    }
}
End-Algorithm

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REGION MERGING

- It partitions the image into small regions followed by combination of similar adjacent regions into bigger region according to a given principle.
- This process is repeated until no more neighboring

regions satisfy the homogeneity principle.

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        (i, j) belongs to the region which u belongs to;
    case (f(u) = f(i, j)) and (u is unmarked):
        (i, j) and u belong to the same region  $R_k$ ;
         $k := k + 1$ ; mark u;
    case (f(u)  $\neq$  f(i, j)):
        (i, j) belongs to the region  $R_k$ ;  $k := k + 1$ ;
    end-for;
}}
n_merge = 0; // tag of merges;
Repeat
{ For all region  $R_s$ , compute  $r_s$  = the mean grey level of  $R_s$ ;
  For each region  $R_t$ , compare  $R_s$  with its neighbour region  $R_t$ :
      if  $|r_s - r_t| < T$  then
          combine  $R_s, R_t$  to form a new region;
           $n\_merge = n\_merge + 1$ ;
      endif
} until (n_merge = 0)
End-Algorithm

```

Algorithm 4.7: Region merging

Given the image $f(i, j)$, $0 \leq i \leq m-1$, $0 \leq j \leq n-1$.

REGION SPLIT AND MERGE

- Let R represent the entire image region and select a predicate Q .
- To segment R , we subdivide it successively into smaller and smaller quadrant regions so that for any

region R_i , $Q(R_i)=\text{TRUE}$.

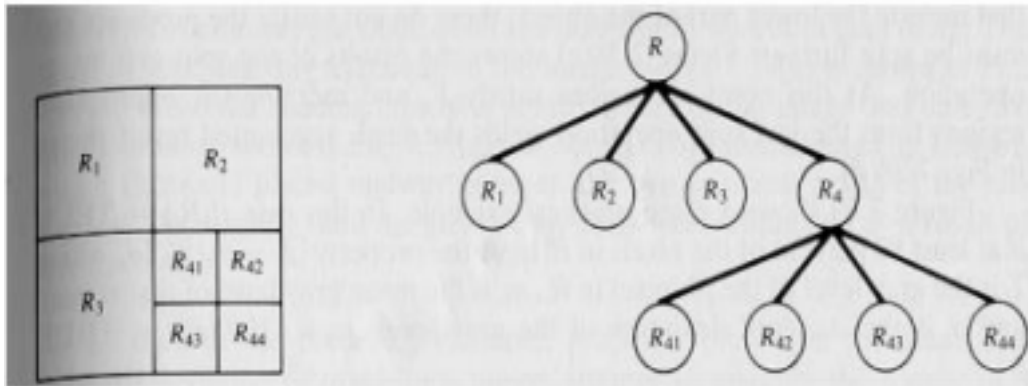
- We start with the entire region. If $Q(R) = \text{FALSE}$, we divide the image into quadrants.
- If Q is false for any quadrant, we subdivide that quadrant into sub quadrants and so on.
- This can be represented by a quad trees, that is, trees in which each node has exactly four descents as shown in figure below.

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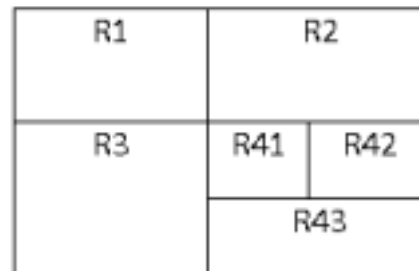
- Root of the tree corresponds to the entire image and each node corresponds to the subdivision of a node into four descendent nodes.
- In the figure R_4 is subdivided further.

- Procedure

- 1) Split into four disjoint quadrants any region R_i for which $Q(R_i)=\text{FALSE}$.
- 2) When no further splitting is possible merge any adjacent regions R_j and R_k for which $Q(R_j \cup R_k)=\text{TRUE}$.
- 3) Stop when no further merging is possible.



Partitioned Image and quadtree R represents the entire image region.



Merged Regions