FOURIER TRANSFORM

- It is use to decompose an image into its sine and cosine components.
- It finds its application in image analysis, image filtering image reconstruction and image compression. The output of the transformation represents the image in the Fourier or frequency domain, while the input image is the spatial domain equivalent.

One-Dimensional Continuous Fourier Transform Fourier transform F(u) of a continuous function f(t) is given by the equation:-

$$F(u) = \int_{-\infty}^{+\infty} f(t)e^{-i2\pi ut}dt$$
 (1)

 Given F(u), we can obtain f(t) using Inverse Fourier Transform:-

$$f(t) = \int_{-\infty}^{+\infty} F(u)e^{i2\pi ut} du$$
 (2)

where F(u)-> Fourier Transform

f(t)-> Inverse Fourier transform of F(u) 2

• Let $w=2\pi u$, then eq 1 can be rewritten as follows:

$$F(w) = \int_{-\infty}^{+\infty} f(t)e^{-i\omega t}dt$$
(3)

• Inverse Fourier Transform from eq (2) will be rewritten as follows:

Let $w=2\pi u$, therefore $dw=2\pi$.du

Two-Dimensional Continuous Fourier Transform

For two-dimension function f(x,y), Fourier transform and Inverse Fourier Transform is given

$$F(u,v) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} f(x,y) e^{-i2\pi(ux+vy)} dx \, dy$$

$$f(x,y) = \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} F(u,v) e^{i2\pi(ux+vy)} du \, dv$$

DISCRETE FOURIER TRANSFORM

• Let a(m) be finite sequence. Discrete Fourier Transform (DFT) of one –dimensional discrete signal is given by:-

• Inverse Discrete Fourier Transform (IDFT) of one —dimensional discrete signal is given by:-

• For two-dimensional discrete signal, DFT is given by:-

$$A(u,v) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} a(m,n) e^{-i2\pi \left(\frac{um}{M} + \frac{vn}{N}\right)}$$
where $u = 0,1,2,...,M-1$, $v = 0,1,2,...,N-1$.

• For two-dimensional discrete signal, IDFT is given by:-

$$a(m,n) = \frac{1}{MN} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} A(u,v) e^{i2\pi \left(\frac{um}{M} + \frac{vn}{N}\right)}$$

$$m = 0, 1, 2, ..., M - 1; n = 0, 1, 2, ..., N - 1$$
 (4)

PROPERTIES OF DFT

Fourier transform operation, namely,

For the sake of simplicity, the operator Γ is used to denote the $\Gamma(a(m,n)) = A(u,v)$

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Let $a_1(m,n), a_2(m,n)$ be two discrete image functions, and $A_1(u,v), A_2(u,v)$

be the corresponding Fourier transforms of $a_1(m,n), a_2(m,n)$

1. Linearity:

$$\Gamma\{\alpha a_1(m,n) + \beta a_2(m,n)\} = \alpha \Gamma(a_1(m,n)) + \beta \Gamma(a_2(m,n))$$
$$= \alpha A_1(u,v) + \beta A_2(u,v)$$

where α and β are constants.

2. Separability:

$$\Gamma\{a(m,n)\} = \frac{1}{N} \Gamma_m \{\Gamma_n \{a(m,n)\}\}$$

3. Shift in the spatial domain:

$$\Gamma\{a(m-\alpha,n-\beta)\}=A(u,v)e^{-i2\pi(\alpha u+\beta v)}$$

4. Shift in the frequency domain:

$$\Gamma\{a(m,n) e^{i2\pi(u_0m+v_0n)}\} = A(u-u_0,v-v_0)$$



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