## Lecture Notes: Surfaces, Tangent Planes, and Surface Normals

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## 1 Surfaces

We will focus on  $\mathbb{R}^3$  with dimensions x, y, and z. Consider a plane x + 2y + 3z - 4 = 0, or a sphere  $x^2 + y^2 + z^2 = 1$ . What is in common in these two geometric objects is that they seem to have defined a 2d region, perhaps warped (as in the sphere case). In mathematics, we call them *surfaces*.

Formally, there are two standard ways to describe a surface. The first one resorts to a scalar function f(x,y,z), and sets the function to 0, namely, f(x,y,z)=0. In the plane example, f(x,y,z)=x+2y+3z-4, whereas in the sphere example,  $f(x,y,z)=x^2+y^2+z^2-1$ . It would be helpful to understand why f(x,y,z)=0 is a surface in the following way. Take a point (x,y) in the xy plane, and solve the value of z from f(x,y,z)=0. If z exists, think of z as the "elevation" of a mountain at the longitude x and altitude y. If you move (x,y) around, using z you will be tracing out the top of an undulating mountain. Note that sometimes multiple z may satisfy f(x,y,z)=0, as is true for the sphere  $x^2+y^2+z^2=1$ .

Since a surface is intuitively two dimensional, we can also represent it using two real-valued parameters u, v. In this way, we should designate three functions: x(u, v), y(u, v), z(u, v) which give the x, y, and z coordinates of a point on the surface. For example, the plane x + 2y + 3z - 4 = 0 can be alternatively represented with:

$$x(u,v) = u$$
  
 $y(u,v) = v$   
 $z(u,v) = (4-u-2v)/3.$ 

Likewise, the sphere  $x^2 + y^2 + z^2 = 1$  can be represented with:

$$x(u,v) = \cos(u)$$
  

$$y(u,v) = \sin(u)\cos(v)$$
  

$$z(u,v) = \sin(u)\sin(v).$$

## 2 Tangent Planes and Surface Normals

Consider a surface f(x, y, z) = 0. Fix a point  $p(x_0, y_0, z_0)$  on the surface such that  $\frac{\partial f}{\partial x}(x_0, y_0, z_0)$ ,  $\frac{\partial f}{\partial y}(x_0, y_0, z_0)$ ,  $\frac{\partial f}{\partial z}(x_0, y_0, z_0)$  exist, and are not all equal to 0. Take an arbitrary curve C on the surface passing p. We know that C can be described by functions x(t), y(t), and z(t), which take a real-valued parameter t, and give the x-, y-, and z-coordinates of a point on C. Let  $t_0$  be the value of t corresponding to p (hence,  $x_0 = x(t), y_0 = y(t)$ , and  $z_0 = z(t)$ ). We assume that  $x'(t_0), y'(t_0), z'(t_0)$  exist, and are not all equal to 0.

As C is on the surface, we know that

$$f(x(t), y(t), z(t)) = 0.$$

Taking the derivative of both sides with respect to t gives:

$$\frac{d\Big(f(x(t),y(t),z(t))\Big)}{dt} = 0 \Rightarrow$$

$$\frac{\partial f}{\partial x}\frac{dx}{dt} + \frac{\partial f}{\partial y}\frac{dy}{dt} + \frac{\partial f}{\partial z}\frac{dz}{dt} = 0 \text{ (applied the chain rule)} \Rightarrow$$

$$\Big[\frac{\partial f}{\partial x}(x,y,z), \frac{\partial f}{\partial y}(x,y,z), \frac{\partial f}{\partial z}(x,y,z)\Big] \cdot \Big[x'(t),y'(t),z'(t)\Big] = 0 \Rightarrow$$

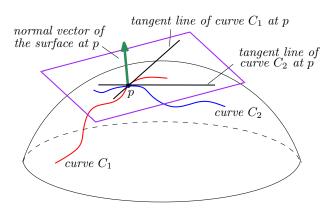
$$\nabla f(x,y,z) \cdot \Big[x'(t),y'(t),z'(t)\Big] = 0.$$

Applying the above equation to point p results in

$$\nabla f(x_0, y_0, z_0) \cdot \left[ x'(t_0), y'(t_0), z'(t_0) \right] = 0$$

The above equation tells us something interesting. Notice that  $[x'(t_0), y'(t_0), z'(t_0)]$  is a tangent vector of C at p. From our assumptions, we have that neither  $\nabla f(x_0, y_0, z_0)$  nor  $[x'(t_0), y'(t_0), z'(t_0)]$  is  $\mathbf{0}$ . It thus follows that the direction of  $\nabla f(x_0, y_0, z_0)$  is perpendicular to that of  $[x'(t_0), y'(t_0), z'(t_0)]$ .

Here is something even more interesting. Recall that we chose C as an arbitrary curve passing p whose tangent vector at p is not  $\mathbf{0}$ . There can be an infinite number of such curves (the figure below shows two examples). All their tangent lines must be perpendicular to the direction of  $\nabla f(x_0, y_0, z_0)$ ! It thus follows that all those tangent lines must form a plane, and that the direction of  $\nabla f(x_0, y_0, z_0)$  is perpendicular to this plane!



The plane aforementioned is therefore called the tangent plane of the surface at p.  $\nabla f(x_0, y_0, z_0)$  is called a normal vector of the surface at p.