

PARCIALES ECUACIONES DIFERENCIALES

$$\textcircled{1} \quad y''' + 4y' = 3 \sin(2x) + x \cos(2x)$$

Ora y_p sin hallar
Constantes

$$M^3 + 4M = 0$$

$$M(M^2 + 4) = 0$$

$$M^2 = -4$$

$$M = \pm 2i$$

$$y_c(x) = C_1 + C_2 \cos(2x) + C_3 \sin(2x)$$

$$\boxed{y_p(x) = x(Ax+B) \cos(2x) + x(Cx+D) \sin(2x)}$$

$$\textcircled{2} \quad y(x) = e^{-2x} (C_1 \cos(\ln(3x)) + C_2 \sin(\ln(3x)))$$

$$M = -2 \pm 3i$$

Ejercicio mal
desendido

Propuesta real

$$Y(x) = x^{-2} (C_1 \cos(3\ln(x)) + C_2 \sin(3\ln(x)))$$

$$(M+2-3i) \quad (M+2+3i)$$

$$(M+2)^2 - 9i^2 \quad (M+2)^2 + 9$$

$$m^2 + 2m + 4 + 9$$

$$m^2 + 2n + 13$$

$$m^2 - m + 2m + m + 3$$

$$m(m-1) + 3m + 13$$

$$a=1 \quad b=3 \quad = c=17$$

$$\boxed{x^2 y'' + 3x y' + 13y = 0}$$

③ El valor de B

$$9y'' - y = 0 \quad y(0) = 2$$

$$y(0) = B$$

$$9m^2 - 1 = 0$$

$t \rightarrow \infty ?$

$$m^2 = \frac{1}{9}$$

$$m = \pm \frac{1}{3}$$

$$y(x) = C_1 e^{x/3} + C_2 e^{-x/3}$$

$$2 = C_1 + C_2$$

$$\beta = C_1 \frac{1}{3} e^{\frac{x}{3}} - \frac{1}{3} C_2 e^{-\frac{x}{3}}$$

$$C_1 = 0$$

$$\beta = \frac{1}{3} C_1 - \frac{1}{3} C_2$$

$$C_2 = ② 2$$

~~$$\beta = \frac{1}{3} (C_1 - C_2)$$~~

~~$$\beta = \frac{1}{3} (C_1 - 2C_1)$$~~

~~$$\beta = \frac{1}{3} (-C_1)$$~~

$$\left| \begin{array}{c} \frac{1}{3} (-2) \\ \hline -\frac{2}{3} \end{array} \right| = \beta$$

④

$$w = t^2 e^t$$

$$f(t) = t$$

$$w(x, y) = c e^{-\int p(x) dx}$$

$$x^2 e^x = c e^{-\int p(x) dx}$$

$$\begin{pmatrix} t & g(x) \\ 1 & g'(x) \end{pmatrix}$$

$$\begin{cases} \frac{1}{t} \\ \frac{1}{t} \end{cases} \begin{array}{l} e^{-\int \frac{1}{t} dt} \\ e^{-h(t)} \end{array}$$

$$t g'(x) - g(x) = t^2 e^t$$

$$g' - \frac{g}{t} = t e^t$$

$$\frac{g}{t} = \int \frac{t e^t}{t} dt$$

$$\frac{g}{t} = e^t + C \quad t = ct$$

$$g = e^t t + K$$

(5)

$$\frac{3}{2}U'' + Ku = 0$$

$$U(0) = 2$$

$$U'(0) = V$$

$$K = ?$$

$$V = ?$$

$$T = \pi$$

$$A = 3$$

$$\omega = 2$$

$$\frac{2\pi}{\omega} =$$

$$U'' + \frac{2}{3}U = 0$$

$$m^2 + \frac{2}{3}K = 0$$

$$m = \pm \sqrt{\frac{2K}{3}} i$$

~~$$\sqrt{2K} = 2$$~~

~~$$\sqrt{\frac{2K}{3}} = 2$$~~

$$\frac{2K}{3} = 4$$

$$K = 6$$

~~$$2 = C_1 \cos\left(\frac{\sqrt{2K}}{3}t\right) + C_2 \sin\left(\frac{\sqrt{2K}}{3}t\right)$$~~

~~$$2 = C_1 \cos(2t) + C_2 \sin(2t)$$~~

~~$$2 = C_1$$~~

$$\pi = \frac{2\pi}{\mu}$$

$$C_1 = 2$$

~~A2~~

$$z = \sqrt{2^2 + C_2^2}$$

$$q = \sqrt{4 + C_2^2}$$

$$S = C_2^2$$

$$C_2 = \sqrt{5}$$

$$-\sin(2t) C_1(z) + 2C_2 \cos(2t)$$

$$V = 2C_2$$

~~C2~~ $V = 2\sqrt{5}$

⑥ $(x^2 - 6x + 9) y'' - (x-3) y' + y = x-3 \quad x \geq 3$

$$(x-3)^2 y'' - (x-3) y' + y = x-3$$

$$m(m-1) - m + 1 = 0 \quad y = (x-3)^m$$

$$m^2 - m - m + 1 = 0 \quad y = m(x-3)^{m-1}$$

$$m^2 - 2m + 1 = 0 \quad y'' = m(m-1)(x-3)^{(m-2)}$$

~~(m-1)~~
 $(m-1)^2$

$$m_1 = 1$$

$$m_2 = 1$$

~~$y_{\text{eff}}(x) = C_1 x + C_2 \ln(x)$~~

$$y_c(x) = C_1(x-3) + C_2(x-3)\ln(x-3)$$

$$g(x) = \frac{1}{x-3}$$

$$y_p(x) = U_1(x-3) + U_2(x-3)\ln(x-3)$$

$$\begin{matrix} \omega = & | & x-3 & & (x-3)\ln(x-3) \\ \text{D} = & | & 1 & & \ln(x-3) + \frac{(x-3)}{(x-3)} \end{matrix}$$

$$\ln((x-3)(x-3)) - \ln(x-3)$$

$$\ln(x-3)[x-3] + [x-3] - [x-3]\ln(x-3)$$

$$\begin{matrix} U_1 = & | & 0 & & (x-3)\ln(x-3) \\ & | & \frac{1}{x-3} & & \ln(x-3) + 1 \end{matrix}$$

ω

$$\int \frac{\ln(x-3)}{x-3} dx$$

$$U = \ln(x-3)$$

$$dU = \frac{1}{x-3} dx$$

$$\int U du$$

$$\frac{U^2}{2}$$

$$\frac{\ln^2(x-3)}{2} = U$$

$$U_2 = \begin{vmatrix} x-3 & 0 \\ 1 & \frac{1}{x-3} \end{vmatrix}$$

$$U_2' = \frac{1}{x-3}$$

$$\int \frac{1}{x-3} dx$$

$$U_2 \ln(x-3)$$

$$\frac{1}{2} + \frac{1}{2}$$

$$Y_p(x) = \frac{\ln 2(x-3)[x-3]}{2} + \ln^2(x-3)(x-3)$$

$$Y_p(x) = 2\cancel{x^2}(x-3)\cancel{(x-3)}$$

$$C_1(x-3) + C_2(x-3) + \frac{3(x-3)}{2} [\ln^2(x-3)]$$

$$Y(x) = [x-3] \left[C_1 + C_2 + \frac{3[\ln^2(x-3)]}{2} \right]$$

⑦ Halle la otra solución utilizando el parámetro

$$x^2 y'' + xy' + \left(x^2 - \frac{1}{4}\right)y = 0 \quad x > 0$$

$$y_1 = x^{-1/2} \sin(x)$$

$$y_2 = x^{-1/2} \cdot \sin(x) \int \frac{Be^{-\int p(x)dx}}{x^{-1} \sin^2(x)}$$

$$x^{-1/2} \sin(x) \int \frac{1}{\sin^2(x)} dx$$

$$\int \csc^2(x) dx$$

$$-\cot x$$

$$-x^{-1/2} \sin(x) \cdot \frac{\cos(x)}{\sin(x)}$$

$$\boxed{-x^{-1/2} \cos(x)}$$

Resorte

(8)

$$\frac{64}{32} = 2$$

$$64 = K8$$

$$K=8$$

$$\begin{aligned} M &= 2 \\ K &= 8 \\ B &= B \end{aligned}$$

$$\begin{aligned} x(0)' &= -1 \\ x'(0) &= 5 \end{aligned}$$

$$2x'' + Bx' + 8x = 0$$

$$\text{PVI} \quad \begin{cases} x(0) = -1 \\ x'(0) = 5 \end{cases}$$

Criterio amortiguado?

$$-\frac{B}{4} \pm \frac{\sqrt{B^2 - 4(2)(8)}}{4}$$

$$-\frac{B}{4} \pm \frac{\sqrt{B^2 - 64}}{4}$$

~~• Diferencia~~

$$2r^2 + 18 + 8 = 0$$

$$B^2 - 64 = 0$$

$$r^2 + 8r + 9 = 0$$

$$B^2 = 64$$

$$B = 8$$

$$-\frac{4}{2} \pm \sqrt{16 - 16}$$

$$r = -2$$

$$x(t) = \cancel{e^{rt}}$$

$$x(t) = C_1 e^{-2t} + * e^{-2t} C_2$$

$$-1 = C_1$$

$$x'(t) = -2C_1 e^{-2t} + C_2 e^{-2t}$$

~~$$-2C_1 e^{-2t}$$~~

$$5 = 2 + C_2$$

$$C_2 = 3$$

$$X(t) = -e^{-2t} + 3te^{-2t}$$

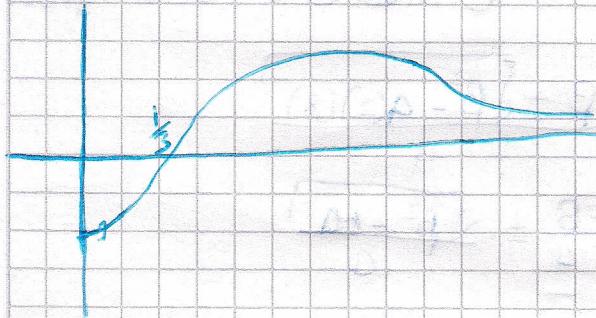
$$0 = -e^{-2t} + 3te^{-2t}$$

$$0 = e^{-2t} (3t - 1)$$

$$3t - 1 = 0$$

$$3t = 1$$

$$\boxed{t = \frac{1}{3}}$$



⑨ Soluzione

$$\textcircled{1} \quad y'' - 2y' + 2y = \underline{e^x \sin x} \quad \frac{3}{3}$$

Intervallo $(0, \frac{\pi}{8})$

$$m^2 - 2m + 2 = 0$$

~~Ortogonalità~~

$$\frac{t_2 + \sqrt{4-8}}{2}$$

$$m = 1 \pm i$$

$$y_c(x) = e^x [C_1 \cos(\alpha x) + C_2 \sin(\alpha x)]$$

$$W = \begin{vmatrix} e^x \cos(\alpha x) & e^x \sin(\alpha x) \\ -\alpha \sin(\alpha x) e^x + e^x \cos(\alpha x) & \alpha e^x \cos(\alpha x) + e^x \sin(\alpha x) \end{vmatrix}$$

$$\frac{\cancel{\alpha e^{2x} \cos^2(\alpha x)} + \cancel{e^{2x} \cos(\alpha x) \sin(\alpha x)}}{\cancel{+\alpha^2 e^{2x} \sin^2(\alpha x)} - \cancel{e^{2x} \sin(\alpha x) \cos(\alpha x)}}$$

$$W = \boxed{\alpha e^{2x}}$$

$$W = e^{2x}$$

$$W = \begin{vmatrix} 0 & e^x \sin(x) \\ \cancel{e^x \sec(x)} & e^x \cos(x) + e^x \sin(x) \end{vmatrix}$$

$$\frac{-e^{2x} \frac{\sin(x)}{\cos(x)}}{e^{2x}} =$$

3

$$\begin{aligned} & -\frac{\sin(x)}{\cos(x)} \\ & -\tan(x) \end{aligned}$$

$$\int -\frac{\tan(x)}{3} dx = -\frac{1}{3} \int \frac{\sin(x)}{\cos(x)} dx$$

$$u = \cos(x)$$

$$du = -\sin(x) dx$$

$$\int \frac{1}{u} du = \ln(\cos(x))$$

$$U_1 = -\frac{\ln(\cos(x))}{3}$$

$$U_2 = \begin{pmatrix} e^x \cos(x) & 0 \\ -\sin(x)e^x + e^x \cos(x) & e^x \sec(x) \end{pmatrix}$$

$$= \frac{e^{2x}}{3} = \int \frac{1}{3} dx \quad U_2 = \boxed{\frac{x}{3}}$$

$$y_1(x) = \left[-\frac{\ln(\cos(x))}{3} \right] \cdot e^x \cos(x) + \frac{x}{3} e^x \sin(x)$$

$$+ C_1 e^x \cos(x) + C_2 e^x \sec(x)$$

10

~~$y'' + 9y = ?$~~

~~$VP = ?$~~

$$y'' + 9y = \sin 2t + te^t + 15$$

$$m^4 + 4m^2 = 0$$

$$m^2(m^2 + 4) = 0$$

$$m^2 = -4$$

$$m = \pm 2i$$

$$\begin{array}{c} | \\ m^2 = -4 \\ | \\ m = \pm 2i \end{array}$$

~~$\rightarrow C_1 + C_2x$~~

$$Y_c(x) = C_1 + C_2x + C_3 \cos(2x)$$

$$+ C_4 \sin(2x)$$

~~$Ax + Bx^2e^{2x} + Cx^2 \cos(2x)$~~

$$t [A \sin(2t) + B \cos(2t)] + Cx^2 \sin(2x)$$

$$+ (Kt + D)e^t + t^2 E$$

11

$$4y'' - Ky' + 9y = 0$$

$$m = \frac{K \pm \sqrt{K^2 - 4(9)(4)}}{24}$$

Volar de K para

que

$$CF.54 e^{\frac{3}{2}x}, \times e^{\frac{3}{2}x} y$$

$$\frac{3}{2}$$

$$\boxed{12 = K \pm}$$

(12)

$$r = -2 \pm 5i$$

$$(r+2)^2 = 25$$

$$(r+2)^2 + 25$$

$$x^2y'' + 5xy' + 29y = 0$$

$$r^2 + 4r + 4 + 25$$

$$r^2 + 4r + 29$$

$$r^2 - r + 4r + r + 29$$

$$r(r-1) + 5r + 29$$

$$a=1 \quad b=5 \quad c=29$$

(13) Major intervals PVI on the solution set

$$\ln(x)y'' + \sqrt{10-x}y' + \left(\frac{1}{x-5}\right)y = 0$$

$$y(3) = 1$$

$$y'(3) = 1$$

~~x > 0~~

$$x > 1$$

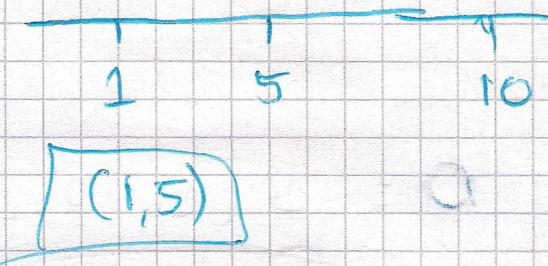
$$10 - x \geq 0$$

$$10 \geq x$$

$$x \leq 10$$

$$x-5 \neq 0$$

$$x \neq 5$$



(14)

$$\frac{R}{32} \quad \frac{1}{16}$$

$$1=5$$

$$m = 1/16$$

$$K=2$$

$$K=2$$

$$\frac{320}{32}$$

$$\frac{1}{10} = m$$

$$b = \frac{4}{10}$$

$$x(0) = -1/2$$

$$x'(0) = -1$$

~~$$10x'' + \frac{4}{10}x' + 2x = 0$$~~

$$x'' + 4x' + 20x = 0$$

~~$$x'' + \frac{4}{100}x' + \frac{2}{10}x = 0$$~~

$$m^2 + 4m + 20 = 0$$

PVI

$$x'' + \frac{1}{25}x' + \frac{1}{5}x = 0$$

$$m = \frac{-4 \pm \sqrt{16 - 80}}{2}$$

$$x(0) = -1/2$$

$$-2 \pm 4i$$

Sobramos trigonado

$$x(t) = e^{-2t} [C_1 \cos(\omega t) + C_2 \sin(\omega t)]$$

$$0 = 1 (C_1 + 0)$$

$$\boxed{-\frac{1}{2} = C_1}$$

$$x'(t) = -4e^{-2t} \sin(\omega t) C_1 + -2e^{-2t} \cos(\omega t) C_1$$

$$tqe^{-2t} \cancel{\sin(\omega t)} \cdot C_2 - 2e^{-2t} \cdot \cancel{\sin(\omega t)}$$

$$x'(t) = e^{-2t} (\cos(\omega t)) + 4e^{-2t} \cos(\omega t) C_2$$

$$-1 = 1 + 4 C_2$$

$$\Delta C_2 = \Delta C_2 = -2$$
$$\boxed{C_2 = -\frac{1}{2}}$$

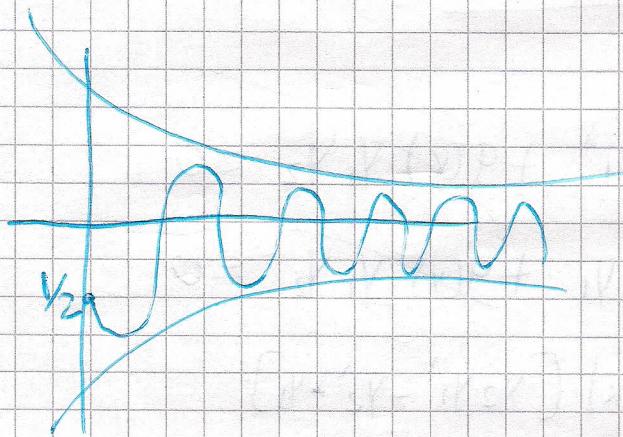
$$\sin(\omega t + \phi)$$

$$\cos(\omega t) \sin \phi + \sin \omega t \cos \phi$$

$$\tan = 1$$

$$\boxed{\frac{\pi}{4}}$$

$$-\frac{e^{-2x}}{2} \left(\operatorname{Sen} 4t + \frac{\pi}{4} \right)$$



(15) $y'' + p(x)y' + q(x)y = 0$

Pruebe que

$$w(y, y_2) = c e^{-\int p(x) dx}$$

$$\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} \quad y_1 y_2' - y_2 y_1' = w$$

$$w = y_1 y_2'' - y_2 y_1''$$

52

$$y_1'' + p(x)y_1' + q(x)y_1 = 0 \quad \bullet \quad y_2$$

$$y_2'' + p(x)y_2' + q(x)y_2 = 0 \quad \bullet \quad y_2$$

~~$y_1'' + p(x)y_1' + q(x)y_1 = 0$~~

~~$y_2'' + p(x)y_2' + q(x)y_2 = 0$~~

$$y_2 y_1'' + p(x) y_2 y_1' + q(x) y_1 y_2 = 0$$

$$- y_2'' y_1 + p(x) y_2' y_1 + q(x) y_1 y_2 = 0$$

$$y_2 y_1'' - y_2'' y_1 + p(x) [y_2 y_1' - y_2' y_1]$$

$$- w' - p(x)w = 0$$

$$w' + p(x)w = 0$$

$$\frac{dw}{dx} + p(x)w = 0$$

$$\frac{dw}{dx} = -p(x)w$$

$$\frac{\int dw}{w} = - \int P(x) dx$$

$$\Leftrightarrow \ln(w) = \int -P(x) dx$$

~~$$e^{\int -P(x) dx} = e$$~~

$$e^c e^{\ln(w)} = e^{-\int P(x) dx}$$

$$w = D e^{-\int P(x) dx}$$

(16)

$$\Delta lb$$

$$\frac{\Delta}{\frac{A}{b}} = \frac{1}{8}$$

$$m = \frac{1}{8} \quad k = 8$$

$$\beta = B$$

$$\frac{x''}{8} + Bx' + 8x = 0$$

$$S = \frac{1}{2}$$

Hooke

$$\Delta = KS$$

$$8 = K$$

$$x(0) = -\frac{1}{4} \quad m^2 + 8Bm + 64$$

$$x'(0) = 3 \quad -\frac{8B}{2} \pm \sqrt{(8B)^2}$$

$$x'' + 8Bx' + 64x = 0$$

$$x'' + 8Bx' + 64x = 0$$

$$x(0) = -1/4$$

$$x'(0) = 3$$

$$m^2 + 8Bm + 64$$

$$\frac{-8B \pm \sqrt{(8B)^2 - 4(64)}}{2}$$

$$(8B)^2 - 4(64) = 0$$

~~$m^2 + 8Bm + 64$~~

$$64B = 460$$

$$\boxed{B^2 = 4}$$

$$B = 2$$

$$m^2 + 16m + 64$$

$$\frac{-16}{2}$$

$$m = -8$$

$$x(t) = C_1 e^{-8t} + C_2 t e^{-8t}$$

$$\boxed{\frac{-1}{4} = C_1}$$

$$x'(t) = -8e^{-8t}c_1 + c_2 e^{-8t} - 8te^{-8t}$$

$$3 = \cancel{c_1} 2 + c_2$$

$$\boxed{c_2 = 1}$$

$$x(t) = \frac{-e^{-8t}}{4} + te^{-8t}$$

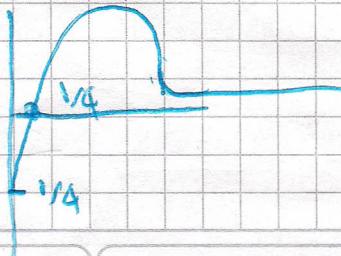
$$x(t) = -e^{-8t} \left(t - \frac{1}{4} \right)$$

$$\boxed{t = \frac{1}{4}}$$

Falso por
cero

$$\begin{cases} x = \frac{11}{4}e^{-24} \\ \text{en} \\ t = 3 \end{cases}$$

$$\frac{3 - \cancel{\frac{1}{4}}}{\cancel{\frac{1}{4}}} = \frac{12 - 1}{1}$$



TERCER CORTÉ ECUACIONES DIFERENCIALES

①

① Calcula la transformada de laplace de

$$f(t) = t \int_0^t \cosh(j) dt$$

Convolución

$$\mathcal{L} \{ t * \cosh(t) \}$$

$$-\frac{d}{ds} \mathcal{L} \{ \cosh(t) \}$$

$$-\frac{d}{ds} \left[\frac{1}{s} - \frac{s}{s^2-1} \right]$$

$$-\frac{d}{ds} \left(\frac{1}{s^2-1} \right)$$

$\frac{2s}{(s^2-1)^2}$

② Calcula la transformada inversa de laplace de

$$F(s) = \frac{2(s+5)e^{-3s}}{s^2 + 10s + 29}$$

$$\mathcal{L}^{-1} \left\{ \frac{2(s+5)e^{-3s}}{(s+5)^2 + 4} \right\}$$

$2U_3(t) e^{-st} \cos(2t-6)$

$$e^{-st} \mathcal{L}^{-1} \left\{ \frac{2s e^{-3s}}{s^2 + 4} \right\}$$

$$2U_3(t) e^{-s(t-3)} \cos(2t-6)$$

$$U_3(t) e^{-st} 2 \cos(2(t-3))$$

$$2U_3(t) e^{-st} e^{+15} \cos(2t-6)$$

(2)

a) Suponga que $\mathcal{L}^{-1} f(t) = F(s)$ existe para $s > a \geq 0$. Verifique que si K es una constante positiva, entonces

$$\mathcal{L}^{-1} \left[f(Kt) \right] = \frac{1}{K} f\left(\frac{t}{K}\right)$$

$$\mathcal{L}^{-1} \left[\mathcal{L}^{-1} f(Kt) \right] = \mathcal{L}^{-1} \left[\frac{1}{K} f\left(\frac{t}{K}\right) \right]$$

$$F(Kt) = \mathcal{L}^{-1} \left[\frac{1}{K} f\left(\frac{t}{K}\right) \right]$$

$$\frac{1}{K} \int_0^\infty e^{-st} F\left(\frac{t}{K}\right) dt = \int_0^\infty e^{-sKt} F(Kt) dt$$

Δ

~~$\frac{d}{dt} e^{-st} = -se^{-st}$~~

~~$\frac{d}{dt} e^{-sKt} = -sK e^{-sKt}$~~

~~$\frac{d}{dt} F(Kt) = f(Kt) K$~~

$\Delta u = dt$

$$C = \frac{1}{K}$$

$$C \int_0^\infty e^{-st} f(ct) dt$$

$$w = ct \quad t = w/c$$

$$dw = C dt$$

$$\frac{dw}{C} = dt$$

$$\int_0^\infty e^{-sw} f(w) dw$$

Δ

$F\left(\frac{sw}{C}\right)$

$F(ws)$

$F\left(\frac{s}{C}\right) = \boxed{F(Ks)}$

(b) Resuelva el siguiente PVI

$$y'(t) = \frac{1}{2} \int_0^t (t-\tau)^2 y(\tau) d\tau \quad y(0) = -1$$

$$s y(s) - y(0) - \frac{1}{2} \Re \left\{ \int e^{2s} \cdot y(t) dt \right\} = 2y + y$$

$$s y(s) + 1 - \frac{1}{2} \left(\frac{2}{s^3} \cdot y(s) \right) = -\frac{d}{ds} \left(\frac{1}{s} \right)$$

$$s y(s) + 1 - \frac{y(s)}{s^3} = -\frac{1}{s^2}$$

$$y(s) \left[s - \frac{1}{s^3} \right] = \frac{1}{s^2} - 1$$

$$y(s) \left[\frac{s^4 - 1}{s^3} \right] = \frac{1}{s^2} - \frac{1}{1} \quad \frac{1 - s^2}{s^2}$$

$$y(s) = \cancel{\frac{s^3}{s(s^3-1)}} \quad \cancel{\frac{s^3}{s^2-1}}$$

$$y(s) = \frac{(1-s^2) s^3}{s^2 (s^3-1)} \quad \left| \quad y(s) = -\frac{s}{(s^2+1)} \right.$$

$$y(s) = \frac{s(1-s^2)}{(s^2-1)(s^2+1)} \quad \left| \quad \begin{aligned} & \Re^{-1} y(s) = y(t) \\ & \Rightarrow y(t) = -\cos(t) \end{aligned} \right.$$

$$y(s) = \frac{-s(s^2-1)}{(s^2-1)(s^2+1)} \quad \left| \quad \right.$$

(3)

$$x''(t) + 4x(t) = -\delta'(t - \frac{\pi}{2}) \quad x(0) = 0$$

$$x'(0) = -1$$

a) Halle la posición de la morsa en cualquier instante (t).

$$\mathcal{L}^{-1}[x(t)] = x(s)$$

$$s^2 X(s) - sX(0) - x'(0) + 4X(s) = -e^{-\frac{\pi s}{2}}$$

$$s^2 X(s) + 1 + 4X(s) = -e^{-\frac{\pi s}{2}}$$

$$X(s)[s^2 + 4] = -e^{-\frac{\pi s}{2}} - 1$$

$$X(s) = \frac{-e^{-\frac{\pi s}{2}}}{s^2 + 4} - \frac{1}{s^2 + 4}$$

$$\mathcal{L}^{-1}[X(s)] = x(t)$$

$$x(t) = -\frac{v_{\pi/2}}{2} \sin(2(t - \pi/2)) - \frac{\sin(2t)}{2}$$

$$x(t) = -\frac{v_{\pi/2}}{2} \sin(2t - \pi) - \frac{\sin(2t)}{2}$$

Antes
del golpe

$$x(t) = +\frac{v_{\pi/2}}{2} \overset{+1}{\sin(2t)} - \frac{\sin(2t)}{2}$$

Despues del
golpe

despues de $\pi/2$

equilibrio

la posición es el

④ Sean $\lambda = -\frac{1}{2} + i$ un valor propio de una matriz

$A \mathbf{y} \mathbf{v} = \begin{pmatrix} 1 \\ i \end{pmatrix}$ un vector propio de A correspondiente

al valor propio λ

a) Hallar la solución general (de valores reales) del sistema $\dot{\mathbf{x}}(t) = A \mathbf{x}(t)$

$$\begin{pmatrix} 1 \\ i \end{pmatrix} e^{(\frac{-1}{2}+i)t} = e^{-t/2} \begin{pmatrix} 1 \\ i \end{pmatrix} e^{it} =$$

$$e^{-t/2} \left[\begin{pmatrix} 1 \\ i \end{pmatrix} \cos(t) + i \sin(t) \right]$$

$$e^{-t/2} \left[\begin{pmatrix} \cos(t) + i \sin(t) \\ i \cos(t) - \sin(t) \end{pmatrix} \right]$$

$$e^{-t/2} \left(\begin{pmatrix} \cos(t) \\ -\sin(t) \end{pmatrix} + i \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix} \right)$$

$$\mathbf{x}(t) = e^{-t/2} \left[C_1 \begin{pmatrix} \cos(t) \\ -\sin(t) \end{pmatrix} + C_2 \begin{pmatrix} \sin(t) \\ \cos(t) \end{pmatrix} \right]$$

b) Hallar la solución general (de valores reales) del sistema $\dot{\mathbf{x}}(t) = A \mathbf{x} + \mathbf{g}(t)$ donde

$$\mathbf{g}(t) = e^{-t/2} \begin{pmatrix} 0 \\ \csc(t) \end{pmatrix}$$

$$\Psi = \begin{pmatrix} e^{-t/2} \cos(\epsilon) & e^{-t/2} \sin(\epsilon) \\ -e^{-t/2} \sin(\epsilon) & e^{-t/2} \cos(\epsilon) \end{pmatrix}$$

Wth: $\det \Psi = e^{-\frac{t}{2}} \cos^2(\epsilon) + e^{-\frac{t}{2}} \sin^2(\epsilon)$
 $= e^{-\frac{t}{2}}$

$$\Psi^{-1} = \cancel{e^t} \begin{pmatrix} e^{-t/2} \cos(\epsilon) & -e^{-t/2} \sin(\epsilon) \\ e^{t/2} \sin(\epsilon) & e^{-t/2} \cos(\epsilon) \end{pmatrix}$$

$$g(t) \cdot \Psi^{-1} = \begin{pmatrix} e^{t/2} \cos(\epsilon) & -e^{t/2} \sin(\epsilon) \\ e^{t/2} \cos(\epsilon) & e^{t/2} \cos(\epsilon) \end{pmatrix} \begin{pmatrix} 0 \\ e^{-t/2} \\ \hline \sin(\epsilon) \end{pmatrix}$$

$$\Psi^{-1} g(t) = \begin{pmatrix} 0 & -1 \\ 0 & +\cot(\epsilon) \end{pmatrix} \cdot \begin{pmatrix} -1 \\ \cot(\epsilon) \end{pmatrix}$$

$$x_p(t) = \Psi \int \begin{pmatrix} -1 \\ \cot(\epsilon) \end{pmatrix} dt$$

$$x_p(t) = \Psi \left[\begin{pmatrix} -t \\ \ln(\sin(\epsilon)) \end{pmatrix} \right]$$

$$X_p(t) = \begin{pmatrix} e^{-t/2} \cos(t) & e^{-t/2} \sin(t) \\ -e^{-t/2} \sin(t) & e^{-t/2} \cos(t) \end{pmatrix} \begin{pmatrix} -t \\ \ln |\sin(t)| \end{pmatrix}$$

~~$$X_p(t) = \begin{pmatrix} -t \cos(t) \\ t \sin(t) \end{pmatrix}$$~~

$$X_p(t) = e^{-t/2} \begin{pmatrix} -t \cos(t) + \sin(t) \ln |\sin(t)| \\ t \sin(t) + \cos(t) \ln |\sin(t)| \end{pmatrix}$$

$$X(t) = X_c(t) + X_p(t)$$

$$X(t) = e^{-t/2} \left[c_1 \begin{pmatrix} \cos t \\ -\sin t \end{pmatrix} + c_2 \begin{pmatrix} \sin t \\ \cos t \end{pmatrix} + t \begin{pmatrix} \cos t \\ \sin t \end{pmatrix} \right]$$

+ ↗

$$+ \ln |\sin(t)| \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

⑤ Resuelve la siguiente ecuación integral

$$⑥ f(t) = 3e^{4t} + 16 \int_0^t t e^{4t} f(t-\tau) d\tau$$

$$\text{Q: } h P(t) = F(s)$$

$$F(s) = 32 \cdot h e^{4t} + 16 \cdot \int_0^t t e^{4t} f(t-\tau) d\tau$$

$$F(s) = \frac{3}{s-4} + 16 \cdot \int_0^t t e^{4t} * f(t) d\tau$$

$$F(s) = \frac{3}{s-4} + 16 \cdot \int_0^t t e^{4t} \cdot h f(t) d\tau$$

$$F(s) = \frac{3}{s-4} + 16 (-) \frac{d}{ds} \left[\frac{1}{s-4} \right] \cdot F(s)$$

$$F(s) = \frac{3}{s-4} + 16 \frac{F(s)}{(s-4)^2} \quad \begin{array}{|c|} \hline F(s) \cdot \left[1 - \frac{16}{(s-4)^2} \right] = \frac{3}{(s-4)^3} \\ \hline \end{array}$$

$$F(s) - \frac{16 F(s)}{(s-4)^2} = \frac{3}{(s-4)^2} \quad \begin{array}{|c|} \hline F(s) \quad \frac{(s-4)^2 - 16}{(s-4)^2} = \frac{3}{(s-4)^3} \\ \hline \end{array}$$

$$F(s) = \frac{3(s-4)}{(s-4)^2 - 16} \quad \begin{array}{|c|} \hline f(t) = 3 \cdot t e^{4t} \cos h(t) \\ \hline \end{array}$$

$$F(s) = \frac{3(s-4)}{(s-4)^2 - 16} \quad \begin{array}{|c|} \hline F(s) = \frac{3(s-4)}{(s-4)^2 - 16} \\ \hline \end{array}$$

$$g^{-1} h F(s) = F(t) \quad \begin{array}{|c|} \hline \rightarrow P(t) = 3 e^{4t} \cos h(t) \\ \hline \end{array}$$

- (b) Si f, f' son continuas en $o [0, \infty)$ y son de orden exponencial entonces demuestre que

$$\mathcal{L} \{ f'(t) \} = s \mathcal{L} \{ f(t) \} - f(0)$$

$$\int_0^{\infty} e^{-st} f'(t) dt$$

$$\begin{aligned} u &= e^{-st} & du &= -se^{-st} \\ dv &= f'(t) & v &= f(t) \end{aligned}$$

$$e^{-st} f(t) \Big|_0^{\infty} + \int_0^{\infty} f(t) se^{-st} dt$$

$$\mathcal{L} \{ f(t) \} = -f(0) + s \left[\int_0^{\infty} f(t) e^{st} dt \right]$$

$$\mathcal{L} \{ f'(t) \} = -f(0) + s \mathcal{L} \{ f(t) \}$$

- (2) En los siguientes literales complete

- a) Se sabe que 2 es un valor propio repetido de la matriz $A = \begin{pmatrix} 3 & 1 \\ -1 & 1 \end{pmatrix}$ y que todos los vectores propios asociados a este valor propio son multiplicaciones escalares en función de ξ solución general del sistema

$$\xi \begin{pmatrix} -2 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 3 & -1 \\ -1 & 1-2 \end{pmatrix} \begin{pmatrix} P_1 \\ P_2 \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \end{pmatrix}$$

$$3P_1 + P_2 = -2 \quad \cdot \quad \begin{pmatrix} 0 \\ -1 \end{pmatrix} \quad \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$P_2 = -3P_1 - 2$$

$$X(t) = e^{2t} \left[c_1 \begin{pmatrix} -2 \\ 2 \end{pmatrix} + c_2 \left[\begin{pmatrix} 1^2 \\ 2 \end{pmatrix} t + \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right] \right]$$

b) Sea f una función continua y de orden exponencial en $(0, \infty)$ si $\mathcal{L}[f] = 1 - t \cos(t)$ entonces $f(t) =$

$$\mathcal{L}^{-1}[1 - t \cos(t)] = \mathcal{L}^{-1}[1] - \mathcal{L}^{-1}[\cos(t)]$$

~~1/(s-1) + 1/s^2~~

$$\frac{1}{s} \cdot F(s) = \frac{1}{s} - \frac{s}{s^2+1}$$

$$F(s) = f = \frac{s^2}{s^2+1}$$

$$F(s) = \frac{s^2+1 - s^2}{s^2+1}$$

$$F(s) = \frac{1}{s^2+1}$$

$$\mathcal{L}^{-1}[f(s)] = f(t)$$

$$f(t) = \underline{\sin(t)}$$

$$\mathcal{L} \{ U_{2\pi} f(t) \} = e^{-2\pi s} \operatorname{sen}(t - 2\pi)$$

$$= e^{-2\pi s} \mathcal{L} \{ \operatorname{sen}(t - 2\pi) \}$$

$$\operatorname{sen}(t) (\cos(2\pi) - \cancel{\operatorname{sen}(2\pi) \cos(t)})$$

$$= e^{-2\pi s} \mathcal{L} \{ \operatorname{sen}(t) \}$$

$$= \boxed{e^{-2\pi s} \frac{s}{s^2 + 1}}$$

C) Si $F(s) = \frac{e^{-2\pi s}}{s^2 + 25}$ entonces su transformada inversa es

$$\mathcal{L}^{-1} \{ F(s) \} = F(t)$$

$$F(t) = U_{2\pi}(t) \frac{1}{5} \operatorname{sen}(st - 2\pi)$$

$$\boxed{F(t) = U_{2\pi}(t) \frac{1}{5} \operatorname{sen}(st - 10\pi)}$$

(7)

a) Halle la solucion general del sistema.

$$\mathbf{X}'(t) = \begin{pmatrix} -2 & 4 \\ -2 & 2 \end{pmatrix} \mathbf{X}$$

$$\begin{pmatrix} -2-\lambda & 4 \\ -2 & 2-\lambda \end{pmatrix} = 0$$

$$(-2-\lambda)(2-\lambda) + 8 = 0$$

$$-4 + 2\lambda - 2\lambda + \lambda^2 + 8 = 0$$

$$\lambda^2 + 4 = 0$$

$$\lambda^2 = \pm 2i$$

$$\begin{pmatrix} 2 \\ 1+i \end{pmatrix}$$

$$\begin{pmatrix} -2+2i & 4 \\ -2 & 2-2i \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$(-2-2i)v_1 + 4v_2 = 0$$

$$v_2 = \frac{(-2-2i)v_1}{4}$$

$$v_2 = \frac{(2+2i)v_1}{4}$$

$$v_2 = \frac{(1+i)v_1}{2}$$

$$\begin{pmatrix} 1 \\ 1+i \end{pmatrix}$$

$$\begin{pmatrix} 2 \\ 1+i \end{pmatrix} e^{2it} = \begin{pmatrix} 2 \\ 1+i \end{pmatrix} \cos(2t) + i \sin(2t)$$

$$2\cos(2t) + 2i\sin(2t)$$

$$\cos(2t) + i\sin(2t) + i\cos(2t) - \sin(2t)$$

$$\left(2\cos(2t) - \sin(2t) \right) + i \left(2\sin(2t) + \cos(2t) \right)$$

$$\mathbf{X}(t) = C_1 \begin{pmatrix} 2\cos(2t) \\ \cos(2t) - \sin(2t) \end{pmatrix} + C_2 \begin{pmatrix} 2\sin(2t) \\ \sin(2t) + \cos(2t) \end{pmatrix}$$

b) Considerar el sistema no homogéneo

$$\dot{\mathbf{x}}'(t) = A \mathbf{x}'(t) + \begin{pmatrix} 3 \\ 1 \end{pmatrix} e^{2t}$$

Donde A es una matriz 2×2 con entradas constantes. Si se sabe que

$\Psi = \begin{pmatrix} 2e^t & e^{2t} \\ e^t & e^{2t} \end{pmatrix}$ es una matriz fundamental del sistema homogéneo asociado entonces

$\mathbf{x}_c(t) = C_1 e^t \begin{pmatrix} 2 \\ 1 \end{pmatrix} + C_2 e^{2t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ encuentre la solución general de sistema homogéneo dado en $(-\infty, \infty)$

$$\det \Psi = 2e^{3t} - e^{3t} = e^{3t}$$

$$\Psi^{-1} = \frac{1}{e^{3t}} \begin{pmatrix} e^{-t} & -e^{-t} \\ -e^{-2t} & 2e^{-2t} \end{pmatrix} = \underline{\Psi^{-1}}$$

$$\Psi^{-1} = -e^{-3t} \begin{pmatrix} e^{2t} & -e^{2t} \\ -e^t & 2e^t \end{pmatrix}$$

$$\text{g.d. } \Psi^{-1} = \begin{pmatrix} e^{-t} & -e^{-t} \\ -e^{-2t} & 2e^{-2t} \end{pmatrix} \begin{pmatrix} 3e^{2t} \\ e^{2t} \end{pmatrix} \parallel \begin{pmatrix} 2e^t & e^{2t} \\ e^t & e^{2t} \end{pmatrix} \begin{pmatrix} 2e^t \\ -t \end{pmatrix}$$

$$= \begin{pmatrix} 3e^t - e^t \\ -3 + 2e^t \end{pmatrix} = \begin{pmatrix} 2e^t \\ -1 \end{pmatrix} = \begin{pmatrix} 4e^{2t} - te^{2t} \\ 2e^{2t} - te^{2t} \end{pmatrix} = \underline{\Psi^{-1} \mathbf{x}_p(t)}$$

$$\text{D.P. } \mathbf{x}_p = \Psi \cdot \int \begin{pmatrix} 2e^t \\ -1 \end{pmatrix} dt$$

$$\mathbf{x}_p = \Psi \begin{pmatrix} 2e^t \\ -t \end{pmatrix} \quad \text{?}$$

$$X(t) = C_1 e^{2t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + C_2 e^{2t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + e^{2t} \begin{pmatrix} 4 \\ 2 \end{pmatrix} - t e^{2t} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$X(t) = C_1 e^{2t} \begin{pmatrix} 2 \\ 1 \end{pmatrix} + C_2 e^{2t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + e^{2t} \left[-\begin{pmatrix} 1 \\ 1 \end{pmatrix} t + \begin{pmatrix} 4 \\ 2 \end{pmatrix} \right]$$

⑧

a) Resolver el siguiente PVI

$$t y'' - 3t y' - 3y = 0 \quad Y(0) = 0 \quad Y'(0) = 2$$

$$\mathcal{L}[y(t)] = Y(s)$$

$$s^2 Y + sY' - 3s^2 Y - 3sY' - 3Y = 0$$

$$(-1) \frac{d}{ds} [s^2 Y(s) - sY(s) - Y(s)] - 3 (-1) \frac{d}{ds} [sY(s) - Y(s)]$$

$$-3 Y(s)$$

$$(-1) \frac{d}{ds} [s^2 Y(s) - 2] - 3 (-1) \frac{d}{ds} [sY(s)] - 3(Y(s)) = 0$$

$$(-1) [2sY(s) + s^2 Y'(s)] - 3(-1) [Y(s) + sY'(s)] - 3Y(s) = 0$$

~~$$-2sY(s) - s^2 Y'(s) + 3Y(s) + 3sY'(s) - 3Y(s) = 0$$~~

$$-s^2 Y'(s) + 3sY'(s) - 2sY(s) = 0$$

$$Y'(s) [-s^2 + 3s] - Y(s) (2s) = 0$$

$$y'(s) - y(s) \frac{2s}{s^2 + 3s} = 0$$

$$y'(s) + y(s) \frac{s^2}{s(s-3)} = 0$$

$$y'(s) + y(s) \frac{2}{s-3} = 0 \quad \left| \begin{array}{l} y' = \frac{-2y}{s-3} \\ \frac{dy}{ds} = \frac{-2y}{s-3} \\ \int \frac{dy}{y} = -2 \int \frac{ds}{s-3} \end{array} \right.$$

$$\ln(y) = -2 \ln(s-3) + C$$

(R) $\ln(y) = \ln(s-3)^{-2} + C \quad (P) \quad \left| \begin{array}{l} K e^{st} \otimes y \frac{1}{s^2} y \\ \frac{dy}{dt} = K t e^{st} \end{array} \right.$

$y(s) = (s-3)^{-2} \cdot e^C \quad \left| \begin{array}{l} K \\ \Rightarrow K t e^{st} = y(t) \end{array} \right.$

$\therefore y(s) = K \frac{1}{(s-3)^2}$ $\left| \begin{array}{l} y(t) = K t e^{st} \end{array} \right.$

$$y'(t) = K \left[e^{st} + t \frac{e^{st}}{3} \right]$$

$$2 = K [1]$$

$$\boxed{K=2}$$

$$\boxed{y(t) = 2t e^{st}}$$

b) Si f es continua por tramos en $(0, \infty)$, de orden exponencial y periódica con período T entonces prueba que

$$F(s) = \Im \{ f(t) \} = \frac{1}{1-e^{-sT}} \int_0^T e^{-st} f(t) dt$$

$$\Im \{ f(t) \} = \int_0^T e^{-st} f(t) dt + \int_T^\infty e^{-st} f(t) dt$$

$$(w = t - T)$$

$$dw =$$

$$= \int_0^T e^{-st} f(t) dt + \int_0^\infty e^{-s(w+T)} f(w+T) dw$$

$$+ \int_0^\infty e^{-sw} e^{-sT} f(w+T) dw$$

$$+ e^{-sT} \left(\int_0^\infty e^{-sw} f(w) dw \right) F(s)$$

$$F(s) - e^{-sT} F(s) = \int_0^T e^{-st} f(t) dt$$

$$F(s) [1 - e^{-sT}] = \int_0^T e^{-st} f(t) dt$$

$$\boxed{F(s) = \frac{1}{1-e^{-sT}} \int_0^T e^{-st} f(t) dt}$$

(9) Rellene

a) $v = i$ es un vector propio de una matriz A
 $\in \mathbb{R}^{2 \times 2}$ si $K = \begin{pmatrix} 1 \\ 1+i \end{pmatrix}$ es un vector propio

de A correspondiente al valor propio v entonces la

Solución general del sistema $\dot{X}(t) = AX(t)$

$$\begin{pmatrix} 1 \\ 1+i \end{pmatrix} e^{it} \stackrel{?}{=} \begin{pmatrix} 1 \\ 1+i \end{pmatrix} (\cos(t) + i \sin(t))$$

$$\cos(t) + i \sin(t)$$

$$\cos(t) + i \sin(t) + i \cos(t) - \sin(t)$$

$$X(t) = C_1 \begin{pmatrix} \cos(t) \\ \cos(t) - \sin(t) \end{pmatrix} + C_2 \begin{pmatrix} \sin(t) \\ \sin(t) + \cos(t) \end{pmatrix}$$

b) $\mathcal{L}^{-1} \left[3t \cos(5\pi t) \right]$

$$(-1)^3 \frac{d}{ds} \left[e^{5\pi s} \frac{s}{s^2 + 25} \right]$$

-3

$$\textcircled{C} \quad F(s) = \frac{5e^{-7\pi s}}{5s - 2}$$

$$g^{-1} g F(s) h = F(t)$$

$$F(t) = \frac{5}{5} U_{7\pi} e^{\frac{2t\pi}{5}}$$

$$= \boxed{U_{7\pi}(t)} e^{2(t-\pi)}$$

\textcircled{10}

a) Halle la Solución general del sistema

$$X'(t) = \begin{pmatrix} -1 & 3 \\ -3 & 5 \end{pmatrix} X(t)$$

Puede usar que $\lambda=2$ es un valor propio de multiplicidad 2 de la matriz asociada al sistema

$$\begin{pmatrix} -1-2 & 3 \\ -3 & 5-2 \end{pmatrix} \begin{pmatrix} -3 & 3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$-8v_1 + 3v_2 = 0$$

$$-v_1 + v_2 = 0$$

$$v_2 = v_1 \quad (!)$$

$$\begin{pmatrix} -3 & 3 \\ -3 & 3 \end{pmatrix} \begin{pmatrix} P_1 \\ P_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$-3P_1 + 3P_2 = 1$$

$$\begin{pmatrix} 1 \\ 4/3 \end{pmatrix}$$

$$3P_2 = 1 + 3P_1$$

$$P_2 = \frac{1}{3} + P_1$$

$$X(t) = e^{2t} \left[C_1 \begin{pmatrix} 1 \\ 1 \end{pmatrix} + C_2 \left[\begin{pmatrix} 1 \\ 1 \end{pmatrix} t + \begin{pmatrix} 1 \\ 4/3 \end{pmatrix} \right] \right]$$

(b) Considerar el sistema no homogéneo

$$\dot{X}(t) = AX(t) + \begin{pmatrix} e^{-2t} \\ -2e^t \end{pmatrix}$$

Si se sabe que $\Psi \begin{pmatrix} e^{-3t} & e^{2t} \\ -4e^{-3t} & e^{2t} \end{pmatrix}$

$$\det \Psi = e^{-6} + 4e^{-6}$$

$$\Psi^{-1} = \begin{pmatrix} 5e^{3t} & -5e^{3t} \\ 20e^{-2t} & 5e^{-2t} \end{pmatrix}$$

$$\Psi^{-1} = 5e^t \begin{pmatrix} e^{2t} & -e^{2t} \\ 4e^{-3t} & e^{-3t} \end{pmatrix}$$

$$\frac{1}{5} \begin{pmatrix} e^{3t} \\ 4e^{-2t} \end{pmatrix} \begin{pmatrix} -e^{3t} \\ e^{-2t} \end{pmatrix} \begin{pmatrix} e^{-2t} \\ 2e^t \end{pmatrix}$$

~~e^{3t}~~

~~e^{-2t}~~

$$\frac{1}{5} \begin{pmatrix} e^t + 2e^{4t} \\ 4e^{-4t} + 2e^{-4t} \end{pmatrix}$$