

# User Manual

for S32K1XX PORT Driver

Rev. 1 — 11 January 2022

UM2PORTASR4.2 Rev0002R1.0.5

User manual



## Revision History

Revision	Date	Author	Description
1.0	11/01/2022	NXP MCAL Team	Updated version for ASR 4.2.2 S32K1XX R1.0.5

## 1 Introduction

This User Manual describes NXP Semiconductors AUTOSAR Port ( Port ) for S32K1XX .

AUTOSAR Port driver configuration parameters and deviations from the specification are described in Port Driver chapter of this document. AUTOSAR Port driver requirements and APIs are described in the AUTOSAR Port driver software specification document.

### 1.1 Supported Derivatives

The software described in this document is intended to be used with the following microcontroller devices of NXP Semiconductors .

**Table 1. S32K1XX Derivatives**

NXP Semiconductors	s32k142_lqfp100, s32k142_lqfp64, s32k142_lqfp48, s32k144_lqfp100, s32k144_mapbga100, s32k144_lqfp64, s32k144_lqfp48, s32k146_lqfp144, s32k146_lqfp100, s32k146_mapbga100, s32k146_lqfp64, s32k148_lqfp176, s32k148_lqfp144, s32k148_lqfp100, s32k148_mapbga100, s32k118_lqfp48, s32k118_lqfp64, s32k116_lqfp48, s32k116_qfn32, s32k144w_lqfp48, s32k144w_lqfp64, s32k142w_lqfp64, s32k142w_lqfp48
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All of the above microcontroller devices are collectively named as S32K1XX .

### 1.2 Overview

**AUTOSAR (AUTomotive Open System ARchitecture)** is an industry partnership working to establish standards for software interfaces and software modules for automobile electronic control systems.

AUTOSAR

- paves the way for innovative electronic systems that further improve performance, safety and environmental friendliness.
- is a strong global partnership that creates one common standard: "Cooperate on standards, compete on implementation".
- is a key enabling technology to manage the growing electrics/electronics complexity. It aims to be prepared for the upcoming technologies and to improve cost-efficiency without making any compromise with respect to quality.
- facilitates the exchange and update of software and hardware over the service life of the vehicle.

### 1.3 About this Manual

This Technical Reference employs the following typographical conventions:

**Boldface** type: Bold is used for important terms, notes and warnings.

*Italic font:* Italic typeface is used for code snippets in the text. Note that C language modifiers such "const" or "volatile" are sometimes omitted to improve readability of the presented code.

Notes and warnings are shown as below:

**Note:** *This is a note.*

## 1.4 Acronyms and Definitions

Table 2. Acronyms and Definitions

Term	Definition
API	Application Programming Interface
AUTOSAR	Automotive Open System Architecture
ASM	Assembler
BSMI	Basic Software Make file Interface
CAN	Controller Area Network
DEM	Diagnostic Event Manager
DET	Development Error Tracer
C/CPP	C and C++ Source Code
VLE	Variable Length Encoding
N/A	Not Applicable
MCU	Micro Controller Unit
DIO	Digital Input Output

## 1.5 Reference List

Table 3. Reference List

#	Title	Version
1	Specification of Port Driver	AUTOSAR Release 4.2.2
2	S32K1xx Series Reference Manual	Rev. 13, 04/2020
3	S32K1xx Data Sheet	Rev. 13, 04/2020
4	S32K142 Mask Set Errata for Mask 0N33V (0N33V)	Rev. 20/APR/2020
5	S32K144 Mask Set Errata for Mask 0N57U (0N57U)	Rev. 20/APR/2020
6	S32K146 Mask Set Errata for Mask 0N73V (0N73V)	Rev. 20/APR/2020
7	S32K148 Mask Set Errata for Mask 0N20V (0N20V)	Rev. 20/APR/2020
8	S32K118 Mask Set Errata for Mask 0N97V (0N97V)	Rev. 20/APR/2020
9	S32K116 Mask Set Errata for Mask 0N96V (0N96V)	Rev. 20/APR/2020
10	S32K144W Mask Set Errata for Mask 0P64A (0P64A)	Rev. 14 FEB 2020

## 2 Driver

### 2.1 Requirements

Requirements for this driver are detailed in the AUTOSAR 4.2 Rev0002 Port Driver Software Specification document (See Table [Section 1.5](#) ).

## 2.2 Driver Design Summary

This module provides the service for initializing the whole PORT structure of the microcontroller. Many ports and port pins can be assigned to various functionalities, e.g.

- General purpose I/O
- ADC
- SPI
- SCI
- PWM
- CAN
- LIN
- etc

For this reason, there is an overall configuration and initialization of this port structure. The configuration and mode of these port pins is microcontroller and ECU dependent.

Port initialisation data are written to each port as efficiently as possible. This PORT driver module completes the overall configuration and initialisation of the port structure which is used in the DIO driver module. Therefore, the DIO driver works on pins and ports which are configured by the PORT driver.

The PORT driver is initialised prior to use of the DIO functions. Otherwise DIO functions will exhibit undefined behaviour.

## 2.3 Hardware Resources

The hardware configured by the Port driver is PORT (Port Control and Interrupts).

Every PortPin configured in a PortContainer of the Port plugin can be mapped to one and only one microcontroller pin. The following steps must be followed in order to correctly map a Port plugin pin over a specific microcontroller pin:

- 1. Open the S32K1xx\_IO\_Signal\_Description\_Input\_Multiplexing.xlsx Excel file attached to the Reference Manual
- 2. Go to 'IO Signal Table' sheet
- 3. Identify the microcontroller pin you want to use (eg. PTC7]), searching after the values in columns 'Module' and 'Function'.

- 3. Compute the number of the PCR (Pin Control Register) associated to the identified pin, using the following information: S32K1XX platforms have 5 consecutive ports, listed as A to E and numbered from 0 to 4, like below:
  - 0 - PORTA
  - 1 - PORTB
  - 2 - PORTC
  - 3 - PORTD
  - 4 - PORTEEach of the 5 ports have a number of 32 pins, such that the pins are allocated to ports like below:
  - 0-31 -> PORTA
  - 32-63 -> PORTB
  - 64-95 -> PORTC
  - 96-127 -> PORTD
  - 128-159 -> PORTEThe PCR number for a given pin (eg. PTC7) is computed like this:
  - Take the port information from the pin name (eg. C for PTC7) and multiply it's corresponding numeric identifier with 32
  - Take the pin information from the pin name (eg. 7 for PTC7)
  - Add the 2 values obtained above and note down the result (eg. 71 for PTC7)
- 4. Go to port container inside the Port plugin where you want to add the pin
- 5. Add a new PortPin in the port container list then double click the newly added PortPin to open it's properties
- 6. Go to the 'PortPinPcr' attribute and type the number noted down at above
- 7. Go to the 'PortPin Mode' attribute and choose the functionality you want to use for the selected pin

## 2.4 Deviation from Requirements

The driver deviates from the AUTOSAR Port Driver software specification in some places. Table identifies the AUTOSAR requirements that are not fully implemented, implemented differently, or out of scope for the Port driver. Table [Table 4](#) provides Status column description.

Table 4. Deviations Status Column Description

Term	Definition
N/S	Out of scope
N/I	Not implemented
N/F	Not fully implemented

Below table identifies the AUTOSAR requirements that are not fully implemented, implemented differently, or out of scope for the driver.

Table 5. Driver Deviations Table

Requirement	Status	Description	Notes
SWS_Port_00205	N/S	Port_Lcfg.c shall include Port_MemMap.h and Port.h.	Currently no support for link-time configuration is provided.
SWS_Port_00220	N/S	The type Port_PinDirectionType shall be of enumeration type having range as PORT_PIN_IN and PORT_PIN_OUT.	Replaced by SMCAL_SW066.port

Table 5. Driver Deviations Table...continued

Requirement	Status	Description	Notes
ECUC_Port_00128	N/S	Name : PortPinInitialMode {PORT_PIN_INITIAL_MODE} Description : Port pin mode from mode list for use with Port_Init() function. Range: PORT_PIN_MODE_ADC PORT_PIN_MODE_CAN PORT_PIN_MODE_DIO PORT_PIN_MODE_DIO_GPT PORT_PIN_MODE_DIO_WDG PORT_PIN_MODE_FLEXRAY PORT_PIN_MODE_ICUPort PORT_PIN_MODE_LINPort PORT_PIN_MODE_MEMPort PORT_PIN_MODE_PWMPort PORT_PIN_MODE_SPIPort	Currently implemented in a different mode in MCAL 4.0. This requirement was replaced by requirement ECUC_Port_00130.
ECUC_Port_00130	N/S	SWS Item ECUC_Port_00130 : Name PortPinMode Description Port pin mode from mode list. Note that more than one mode is allowed by default. That way it is e.g. possible to combine DIO with another mode such as ICU. Multiplicity 1..* Type EcucEnumerationParamDef Range PORT_PIN_MODE_ADC Port Pin used by ADC PORT_PIN_MODE_CAN Port Pin used for CAN PORT_PIN_MODE_DIO Port Pin configured for DIO. It shall be used under control of the DIO driver. PORT_PIN_MODE_DIO_GPT Port Pin configured for DIO. It shall be used under control of the general purpose timer driver. PORT_PIN_MODE_DIO_WDG Port Pin configured for DIO. It shall be used under control of the watchdog driver. PORT_PIN_MODE_FLEXRAY Port Pin used for FlexRay PORT_PIN_MODE_ICU Port Pin used by ICU PORT_PIN_MODE_LIN Port Pin used for LIN PORT_PIN_MODE_MEM Port Pin used for external memory under control of a memory driver. PORT_PIN_MODE_PWM Port Pin used by PWM PORT_PIN_MODE_SPI Port Pin used by SPI Post-Build Variant Multiplicity true Post-Build Variant Value true Multiplicity Configuration Class Pre-compile time X VARIANT-PRE-COMPILE Link time -- Post-build time X VARIANT-POST-BUILD Value Configuration Class Pre-compile time X VARIANT-PRE-COMPILE Link time -- Post-build time X VARIANT-POST-BUILD Scope / Dependency scope: local	Replaced by requirement CPR-MCAL-846.port

Table 5. Driver Deviations Table...continued

Requirement	Status	Description	Notes
SWS_Port_00227	N/S	These requirements are not applicable to this specification. (SRS_BSW_00005, SRS_BSW_00006, SRS_BSW_00007, SRS_BSW_00010, SRS_BSW_00160, SRS_BSW_00161, SRS_BSW_00162, SRS_BSW_00164, SRS_BSW_00167, SRS_BSW_00168, SRS_BSW_00170, SRS_BSW_00172, SRS_BSW_00307, SRS_BSW_00308, SRS_BSW_00309, SRS_BSW_00321, SRS_BSW_00325, SRS_BSW_00326, SRS_BSW_00328, SRS_BSW_00329, SRS_BSW_00330, SRS_BSW_00331, SRS_BSW_00333, SRS_BSW_00334, SRS_BSW_00335, SRS_BSW_00336, SRS_BSW_00341, SRS_BSW_00342, SRS_BSW_00343, SRS_BSW_00344, SRS_BSW_00347, SRS_BSW_00355, SRS_BSW_00357, SRS_BSW_00359, SRS_BSW_00360, SRS_SPAL_12463, SRS_SPAL_12462, SRS_SPAL_12265, SRS_SPAL_12092, SRS_SPAL_12078, SRS_SPAL_12077, SRS_SPAL_12067, SRS_SPAL_12064, SRS_SPAL_12129, SRS_SPAL_12075, SRS_SPAL_12063, SRS_SPAL_12169, SRS_SPAL_00157, SRS_SPAL_12069, SRS_SPAL_12068, SRS_SPAL_12267, SRS_SPAL_12056, SRS_BSW_00440, SRS_BSW_00439, SRS_BSW_00437, BSW00434, SRS_BSW_00433, SRS_BSW_00432, BSW00431, SRS_BSW_00429, SRS_BSW_00428, SRS_BSW_00427, SRS_BSW_00426, SRS_BSW_00425, SRS_BSW_00424, SRS_BSW_00423, BSW00421, BSW00420, SRS_BSW_00419, SRS_BSW_00417, SRS_BSW_00416, SRS_BSW_00413, SRS_BSW_00398, SRS_BSW_00395, SRS_BSW_00387, SRS_BSW_00378, SRS_BSW_00377, SRS_BSW_00376, SRS_BSW_00375, SRS_BSW_00373, SRS_BSW_00371, SRS_BSW_00370)	This is not a requirement

## 2.5 PORT Driver limitations

S32K supports to set input pin to high-Z. However, it is not available in S32K11X (follow newest RM chapter 13). When in GPIO mode (PORT\_PCRn[MUX] programmed to 0x1), the register PIDR cannot be written to 0x1. This programming helps to disable the input mode and this is not possible to achieve in S32K11x. The implication of this is that when the GPIO is configured in output mode (PDDR[n] programmed to 1), the data written on PDOR register would be reflected on PDIR after some delay if the output does not toggle to often. If the pad needs to be tristated, the PORT\_PCRn[MUX] needs to be 00.



## 2.6 Driver usage and configuration tips

The Port driver is responsible with configuring the functionality that should be active on a platform hardware pin. The information about the functionalities available on each of the hardware pins of the platform can be found in the S32K1xx\_IO\_Signal\_Description\_Input\_Multiplexing.xlsx Excel file attached to the Reference Manual.

The Port plugin allows the user to configure each pin's functionality using 2 distinct mechanisms:

- A. Define the functionality of a specific pin. This can be done by adding a new entry in the PortContainer/PortPin list and setting the attributes of the pin. The following steps should be followed:
  - 1. Open the S32K1xx\_IO\_Signal\_Description\_Input\_Multiplexing.xlsx Excel file attached to the Reference Manual
  - 2. Go to 'IO Signal Table' sheet
  - 3. Identify the microcontroller pin you want to use (eg. PTC7]), searching after the values in columns 'Module' and 'Function'.
  - 4. Compute the number of the PCR (Pin Control Register) associated to the identified pin, using the following information: S32K1XX platforms have 5 consecutive ports, listed as A to E and numbered from 0 to 4, like below:
    - 0 - PORTA
    - 1 - PORTB
    - 2 - PORTC
    - 3 - PORTD
    - 4 - PORTE

Each of the 5 ports have a number of 32 pins, such that the pins are allocated to ports like below:

  - 0-31 -> PORTA
  - 32-63 -> PORTB
  - 64-95 -> PORTC
  - 96-127 -> PORTD
  - 128-159 -> PORTE

The PCR number for a given pin (eg. PTC7) is computed like this:

  - Take the port information from the pin name (eg. C for PTC7) and multiply it's corresponding numeric identifier with 32
  - Take the pin information from the pin name (eg. 7 for PTC7)
  - Add the 2 values obtained above and note down the result (eg. 71 for PTC7)
  - 5. Go to port container inside the Port plugin where you want to add the pin
  - 6. Add a new PortPin in the port container list then double click the newly added PortPin to open it's properties
  - 7. Go to the 'PortPinPcr' attribute and type the number noted down at step A.4
  - 8. Go to the 'PortPin Mode' attribute and choose the functionality you want to use for the selected pin
  - 9. Look at the other attributes of the PortPin and set them to the desired values
- B. Define pins that should not be touched by any Port driver functionality, including Port\_Init() function. This option allows the user to configure a list of pins for which the driver will not touch their PCRs, leaving them containing the reset values. This list is

named `UnTouchedPortPin` and is available in the `PortConfigSet` container and adding new entries in this list should follow the next steps:

- 1. Open the `S32K1xx_IO_Signal_Description_Input_Multiplexing.xlsx` Excel file attached to the Reference Manual.
- 2. Go to 'IO Signal Table' sheet.
- 3. Identify the microcontroller pin you want the Port driver to not touch (eg. `PTC7`), searching after the values in columns 'Module' and 'Function'
- 4. Go to `UnTouchedPortPin` list inside the `PortConfigSet` container
- 5. Add a new entry in the list and double click it to open it's properties
- 6. Go to the 'PortPin PCR' attribute and type the number noted down at step A.4
- C. Define the settings for all platform hardware pins that were not configured using mechanism described at point A or point B. This option allows the user to configure all platform pins that are not explicitly configured by the user as GPIOs, with some specific settings. These settings are available in the container `NotUsedPortPin` where the user can define the pin direction (in or out), pin level (high or low), pull up/down.

Every single platform hardware pin is configured by the Port driver, either by mechanism A, B or C. There are no hardware pins that are left untouched by the Port driver `Port_Init()` API.

For this reason, if the platform contains hardware pins that need to have certain non GPIO functionalities, these pins must be explicitly added in the Port configuration using mechanism A. Otherwise, they will be configured by `Port_Init()` API as GPIOs.

### Important note

In order to be able to use the debug capabilities, the JTAG pins need to be configured in the Port driver using mechanism A. This means that the following pins/functionalities need to be added in the `PortContainer/PortPin` list:

- `PortPin_JTAG_TDI` having `PortPinPcr` set to 69 and `PortPinMode` set to `JTAG_TDI`
- `PortPin_JTAG_TDO` having `PortPinPcr` set to 10 and `PortPinMode` set to `JTAG_TDO`
- `PortPin_JTAG_TCK` having `PortPinPcr` set to 68 and `PortPinMode` set to `JTAG_TCLK_SWD_CLK`
- `PortPin_JTAG_TMS` having `PortPinPcr` set to 4 and `PortPinMode` set to `JTAG_TMS_SWD_DIO`
- `PortPin_Reset_b` having `PortPinPcr` set to 5 and `PortPinMode` set to `RESET_b`

In order to be easier to add the above pins into the configuration, no need to manually add each pin in the plugin, the Port configuration must be selected along with Default recommended configuration as: `PortRecConfiguration_JtagPins`.

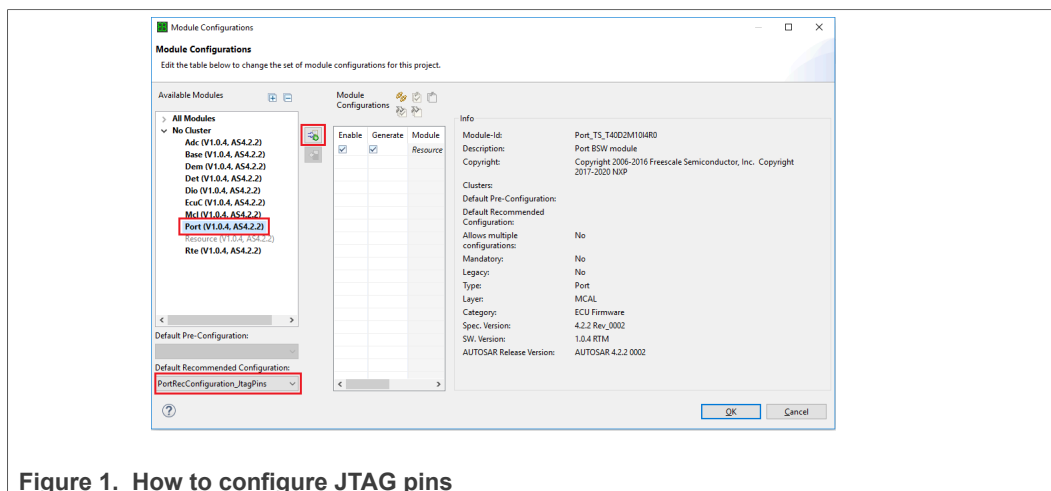


Figure 1. How to configure JTAG pins

### Autosar extension functionality

**1. Support to run driver's code from User Mode.** This option is configurable on/off per entire driver, using the checkbox 'Enable Port User Mode Support' in PortGeneral container. When this parameter is enabled, the Port module will adapt to run from user mode so that the registers under protection can be accessed from user mode. For more information, please see the IM chapter 'User Mode Support'.

**2. Port SetPinMode Does Not Touch GPIO Levels.** This option is configurable on/off and it affects the functionality of the Port\_SetPinMode() API. When not checked, the function Port\_SetPinMode() will set the output level of the pin to the value configured in the PortPinLevelValue combo when called at run time to change mode of a pin from alternate function to GPIO. When checked, the function Port\_SetPinMode() will not touch the output level of the pin when called at run time to change mode of a pin from alternate function to GPIO.

**3. Port Set As Unused Pin API.** This option is configurable on/off and it will be enabled/disabled the Port\_SetAsUnusedPin() API and Port\_SetAsUsedPin() API. When checked, Port\_SetAsUnusedPin and Port\_SetAsUsedPin can be enabled. When Port\_SetAsUnusedPin is called, it shall configure the referenced pin with all the properties specified in the NotUsedPortPin container. When Port\_SetAsUsedPin is called, it shall configure the referenced pin with all the properties that were set during the Port\_Init operation.

**NOTE:** Port\_SetAsUnusedPin() API and Port\_SetAsUsedPin() API are able to use after calling Port\_Init().

**4. Port Reset Pin Mode API.** This option is configurable on/off and it will be enabled/disabled the PortResetPinModeApi() API. When checked, Port\_ResetPinMode can be enabled. When Port\_ResetPinMode is called, it shall revert the port pin mode of the referenced pin to the value that was set by Port\_Init operation.

**NOTE:** Port\_ResetPinMode is able to use after calling Port\_Init().

## 2.7 Runtime Errors

This driver doesn't generate any runtime error.

## 2.8 Software specification

The following sections contains driver software specifications.

### 2.8.1 Define Reference

Constants supported by the driver are as per AUTOSAR Port Driver software specification Version 4.2 Rev0002 .

#### 2.8.1.1 Define PORT\_E\_DIRECTION\_UNCHANGEABLE

Port Pin Direction not configured as changeable.

**Details :**

Det Error value, returned by Port\_SetPinDirection if the passed PortPin have unchangeable direction.

Table 6. Define PORT\_E\_DIRECTION\_UNCHANGEABLE Description

<b>Name</b>	PORT_E_DIRECTION_UNCHANGEABLE
<b>Initializer</b>	(uint8)0x0B

#### 2.8.1.2 Define PORT\_INSTANCE\_ID

Instance IDs

**Details :**

Instance ID of port driver.

Table 7. Define PORT\_INSTANCE\_ID Description

<b>Name</b>	PORT_INSTANCE_ID
<b>Initializer</b>	(uint8)0x0

#### 2.8.1.3 Define PORT\_E\_MODE\_UNCHANGEABLE

API Port\_SetPinMode() service called when mode is unchangeable.

**Details :**

Det Error value, returned by Port\_SetPinMode function if the passed PortPin have a unchangeable Mode.

Table 8. Define PORT\_E\_MODE\_UNCHANGEABLE Description

<b>Name</b>	PORT_E_MODE_UNCHANGEABLE
<b>Initializer</b>	(uint8)0x0E

#### 2.8.1.4 Define PORT\_E\_INIT\_FAILED

API Port\_Init() service called with wrong parameter.

**Details :**

Det Error value, returned by Port\_Init function if Port\_Init is called with wrong parameter.

Table 9. Define PORT\_E\_INIT\_FAILED Description

<b>Name</b>	PORT_E_INIT_FAILED
<b>Initializer</b>	(uint8)0x0C

**2.8.1.5 Define PORT\_E\_PARAM\_INVALID\_MODE**

API `Port_SetPinMode()` service called when mode is invalid.

**Details :**

Det Error value, returned by `Port_SetPinMode` function if the passed `PortPinMode` is invalid.

Table 10. Define PORT\_E\_PARAM\_INVALID\_MODE Description

<b>Name</b>	PORT_E_PARAM_INVALID_MODE
<b>Initializer</b>	(uint8)0x0D

**2.8.1.6 Define PORT\_E\_PARAM\_PIN**

Invalid Port Pin ID requested.

**Details :**

Det Error value, returned by `Port_SetPinDirection` and `Port_SetPinMode` if a wrong `PortPin` ID is passed.

Table 11. Define PORT\_E\_PARAM\_PIN Description

<b>Name</b>	PORT_E_PARAM_PIN
<b>Initializer</b>	(uint8)0x0A

**2.8.1.7 Define PORT\_E\_PARAM\_POINTER**

API service called with NULL Pointer Parameter.

**Details :**

Det Error value, returned by `Port_GetVersionInfo` function if API is called with NULL Pointer Parameter.

Table 12. Define PORT\_E\_PARAM\_POINTER Description

<b>Name</b>	PORT_E_PARAM_POINTER
<b>Initializer</b>	(uint8)0x10

**2.8.1.8 Define PORT\_E\_UNINIT**

API service called without module initialization.

**Details :**

Det Error value, returned by a function if API service called prior to module initialization.

Table 13. Define PORT\_E\_UNINIT Description

<b>Name</b>	PORT_E_UNINIT
<b>Initializer</b>	(uint8)0x0F

**2.8.1.9 Define PORT\_GETVERSIONINFO\_ID**

API service ID for PORT get version info function.

**Details :**

Parameters used when raising an error/exception.

Table 14. Define PORT\_GETVERSIONINFO\_ID Description

<b>Name</b>	PORT_GETVERSIONINFO_ID
<b>Initializer</b>	(uint8)0x03

**2.8.1.10 Define PORT\_INIT\_ID**

API service ID for PORT Init function.

**Details :**

Parameters used when raising an error/exception.

Table 15. Define PORT\_INIT\_ID Description

<b>Name</b>	PORT_INIT_ID
<b>Initializer</b>	(uint8)0x00

**2.8.1.11 Define PORT\_SETPINDIRECTION\_ID**

API service ID for PORT set pin direction function.

**Details :**

Parameters used when raising an error/exception.

Table 16. Define PORT\_SETPINDIRECTION\_ID Description

<b>Name</b>	PORT_SETPINDIRECTION_ID
<b>Initializer</b>	(uint8)0x01

**2.8.1.12 Define PORT\_SETPINMODE\_ID**

API service ID for PORT set pin mode.

**Details :**

Parameters used when raising an error/exception.

Table 17. Define PORT\_SETPINMODE\_ID Description

<b>Name</b>	PORT_SETPINMODE_ID
<b>Initializer</b>	(uint8)0x04

**2.8.1.13 Define PORT\_REFRESHPINDIRECTION\_ID**

API service ID for PORT refresh pin direction function.

**Details :**

Parameters used when raising an error/exception.

Table 18. Define PORT\_REFRESHPINDIRECTION\_ID Description

<b>Name</b>	PORT_REFRESHPINDIRECTION_ID
<b>Initializer</b>	(uint8)0x02

**2.8.1.14 Define PORT\_ALT0\_FUNC\_MODE**

Port Alternate 0 Mode.

Table 19. Define PORT\_ALT0\_FUNC\_MODE Description

<b>Name</b>	PORT_ALT0_FUNC_MODE
<b>Initializer</b>	((Port_PinModeType)0)

**2.8.1.15 Define PORT\_GPIO\_MODE**

Port GPIO Mode.

Table 20. Define PORT\_GPIO\_MODE Description

<b>Name</b>	PORT_GPIO_MODE
<b>Initializer</b>	((Port_PinModeType)1)

**2.8.1.16 Define PORT\_ALT2\_FUNC\_MODE**

Port Alternate 2 Mode.

Table 21. Define PORT\_ALT2\_FUNC\_MODE Description

<b>Name</b>	PORT_ALT2_FUNC_MODE
<b>Initializer</b>	((Port_PinModeType)2)

**2.8.1.17 Define PORT\_ALT3\_FUNC\_MODE**

Port Alternate 3 Mode.

Table 22. Define PORT\_ALT3\_FUNC\_MODE Description

<b>Name</b>	PORT_ALT3_FUNC_MODE
<b>Initializer</b>	((Port_PinModeType)3)

**2.8.1.18 Define PORT\_ALT4\_FUNC\_MODE**

Port Alternate 4 Mode.

Table 23. Define PORT\_ALT4\_FUNC\_MODE Description

<b>Name</b>	PORT_ALT4_FUNC_MODE
<b>Initializer</b>	((Port_PinModeType)4)

**2.8.1.19 Define PORT\_ALT5\_FUNC\_MODE**

Port Alternate 5 Mode.

Table 24. Define PORT\_ALT5\_FUNC\_MODE Description

<b>Name</b>	PORT_ALT5_FUNC_MODE
<b>Initializer</b>	((Port_PinModeType)5)

**2.8.1.20 Define PORT\_ALT6\_FUNC\_MODE**

Port Alternate 6 Mode.

Table 25. Define PORT\_ALT6\_FUNC\_MODE Description

<b>Name</b>	PORT_ALT6_FUNC_MODE
<b>Initializer</b>	((Port_PinModeType)6)

**2.8.1.21 Define PORT\_ALT7\_FUNC\_MODE**

Port Alternate 7 Mode.

Table 26. Define PORT\_ALT7\_FUNC\_MODE Description

<b>Name</b>	PORT_ALT7_FUNC_MODE
<b>Initializer</b>	(Port_PinModeType)7

## 2.8.2 Enum Reference

Enumeration of all constants supported by the driver are as per AUTOSAR Port Driver software specification Version 4.2 Rev0002 .

### 2.8.2.1 Structure Port\_PinDirectionType

Structure needed by `Port_SetPinDirection()`.

#### **Details:**

The structure `Port_PinDirectionType` Possible directions of a port pin.

#### **Declaration:**

```
typedef enum
{
    PORT_PIN_DISABLED = 0,
    PORT_PIN_IN,
    PORT_PIN_OUT,
    PORT_PIN_HIGH_Z
}
```

Table 27. Enumeration `Port_PinDirectionType` member description

Member	Description
PORT_PIN_DISABLED	No settings: the pin is not available.
PORT_PIN_IN	Sets port pin as input.
PORT_PIN_OUT	Sets port pin as output.
PORT_PIN_HIGH_Z	Sets port pin as high-Z.

## 2.8.3 Function Reference

Functions of all functions supported by the driver are as per AUTOSAR Port Driver software specification Version 4.2 Rev0002 .

### 2.8.3.1 Function Port\_Init

Initializes the Port Driver module.

#### **Details :**

The function `Port_Init()` will initialize ALL ports and port pins with the configuration set pointed to by the parameter `ConfigPtr`. It always requires an input as a valid pointer.

#### **Pre :**

Function `Port_Init()` should not have been called before.

**Post :** `Port_Init()` must be called before all other Port Driver module's functions otherwise no operation can occur on the MCU ports and port pins.

**Prototype :** `void Port_Init(const Port_ConfigType *ConfigPtr);`



Table 28. Port\_Init Arguments

Type	Name	Direction	Description
const Port_ConfigType*	ConfigPtr	input	A pointer to the structure which contains initialization parameters.

### 2.8.3.2 Function Port\_SetPinDirection

Sets the port pin direction.

#### Details :

The function `Port_SetPinDirection()` will set the port pin direction during runtime.

**Pre :** `Port_Init()` must have been called first. In order to change the pin direction the `PortPinDirectionChangeable` flag must have been set to `TRUE`.

**Prototype :** `void Port_SetPinDirection(Port_PinType Pin, Port_PinDirectionType Direction);`

Table 29. Port\_SetPinDirection Arguments

Type	Name	Direction	Description
Port_PinType	Pin	input	Pin ID number.
Port_PinDirectionType	Direction	input	Port Pin direction.

### 2.8.3.3 Function Port\_SetPinMode

Sets the port pin mode.

#### Details :

The function `Port_SetPinMode()` will set the port pin mode of the referenced pin during runtime.

**Pre :** `Port_Init()` must have been called first.

**Prototype :** `void Port_SetPinMode(Port_PinType Pin, Port_PinModeType Mode);`

Table 30. Port\_SetPinMode Arguments

Type	Name	Direction	Description
Port_PinType	Pin	input	Pin ID number.
Port_PinModeType	Mode	input	New Port Pin mode to be set on port pin.

### 2.8.3.4 Function Port\_RefreshPortDirection

Refreshes port direction.

#### Details :

This function will refresh the direction of all configured ports to the configured direction. The PORT driver will exclude from refreshing those port pins that are configured as "pin direction changeable during runtime".

**Pre :** `Port_Init()` must have been called first.

**Prototype :** `void Port_RefreshPortDirection(void);`

2.8.3.5 Function Port\_GetVersionInfo

Returns the version information of this module.

Details :

The function `Port_GetVersionInfo()` will return the version information of this module. The version information includes:

- Module Id,
- Vendor Id,
- Vendor specific version numbers.

Pre : None

Prototype : `void Port_GetVersionInfo(Std_VersionInfoType *versioninfo);`

Table 31. Port\_GetVersionInfo Arguments

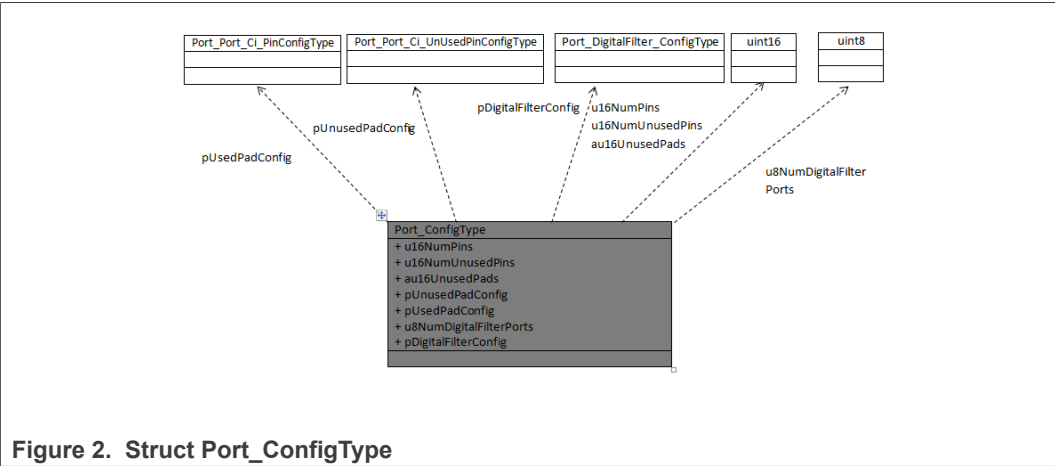
Type	Name	Direction	Description
Std_VersionInfoType *	versioninfo	input, output	Pointer to where to store the version information of this module.

2.8.4 Structs Reference

Data structures supported by the driver are as per AUTOSAR Port Driver software specification Version 4.2 Rev0002 .

2.8.4.1 Structure Port\_ConfigType

Structure needed byPort\_Init().



Details:

The structure `Port_ConfigType` is a type for the external data structure containing the initialization data for the PORT Driver.

**Note:** The user must use the symbolic names defined in the configuration tool.

Declaration:

```
typedef struct
```

```

{
    VAR(uint16, AUTOMATIC) u16NumPins;
    VAR(uint16, AUTOMATIC) u16NumUnusedPins;
    P2CONST(uint16, AUTOMATIC, PORT_APPL_CONST) paul6UnusedPads;
    P2CONST(Port_Port_Ci_UnusedPinConfigType, AUTOMATIC, PORT_APPL_CONST) pUnusedPadConfig;
    P2CONST(Port_Port_Ci_PinConfigType, AUTOMATIC, PORT_APPL_CONST) pUsedPadConfig;
    VAR(uint8, AUTOMATIC) u8NumDigitalFilterPorts;
    P2CONST(Port_DigitalFilter_ConfigType, AUTOMATIC, PORT_APPL_CONST) pDigitalFilterConfig;
} Port_ConfigType;

```

Table 32. Structure Port\_ConfigType member description

Member	Description
u16NumPins	Number of used pads (to be configured).
u16NumUnusedPins	Number of unused pads.
pau16UnusedPads	Unused pad id's array.
pUnusedPadConfig	Unused pad configuration.
pUsedPadConfig	Used pads data configuration
u8NumDigitalFilterPorts	Number of configured digital filter ports
pDigitalFilterConfig	Digital filter ports configuration

#### 2.8.4.2 Structure Port\_Port\_Ci\_PinConfigType

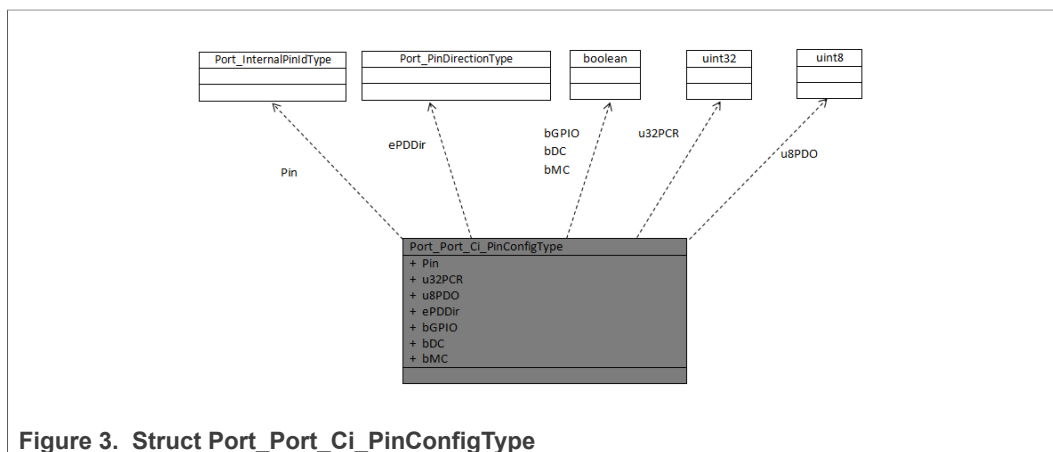


Figure 3. Struct Port\_Port\_Ci\_PinConfigType

##### Details:

The structure `Port_Port_Ci_PinConfigType` contains all configuration parameters of a single pin identified by `@p PORT Pin..`

**Note:** The user must use the symbolic names defined in the configuration tool.

##### Declaration:

```

typedef struct
{
    VAR(Port_InternalPinIdType, AUTOMATIC) Pin;
    VAR(uint32, AUTOMATIC) u32PCR;
    VAR(uint8, AUTOMATIC) u8PDO;
    VAR(Port_PinDirectionType, AUTOMATIC) ePDDir;
    VAR(boolean, AUTOMATIC) bGPIO;
    VAR(boolean, AUTOMATIC) bDC;
    VAR(boolean, AUTOMATIC) bMC;
} Port_Port_Ci_PinConfigType;

```

Table 33. Structure Port\_Port\_Ci\_PinConfigType member description

Member	Description
Pin	Pin Defined on PORT.
u32PCR	Pad Control Register.
u8PDO	Pad Data Output.
ePDDir	Pad Data Direction.
bGPIO	GPIO initial mode.
bDC	Direction changeability.
bMC	Mode changeability.

2.8.4.3 Structure Port\_Port\_Ci\_UnUsedPinConfigType

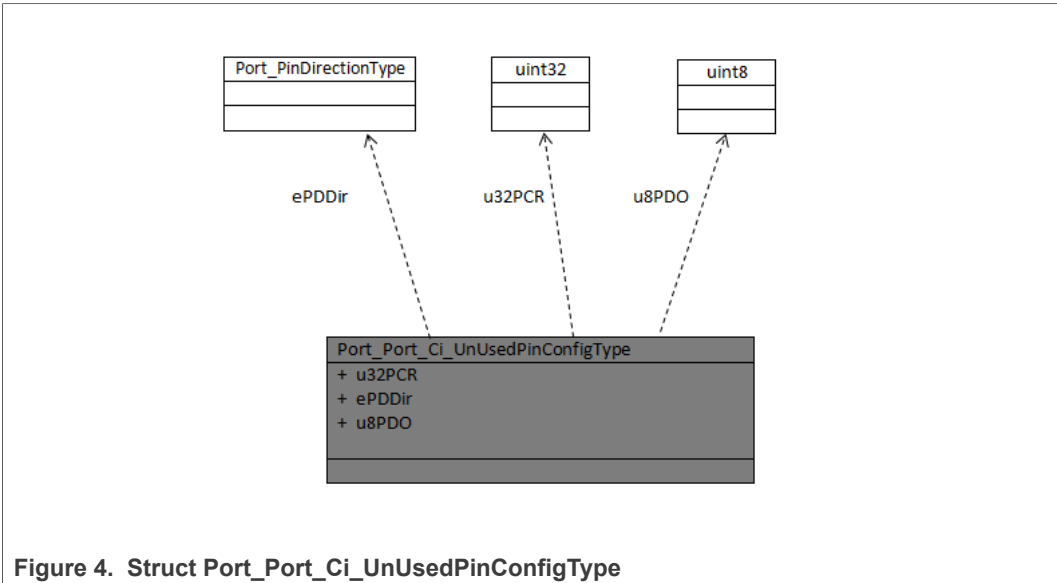


Figure 4. Struct Port\_Port\_Ci\_UnUsedPinConfigType

Details:

The structure `Port_Port_Ci_UnUsedPinConfigType` contains all configuration parameters of a Default pin.

**Note:** The user must use the symbolic names defined in the configuration tool.

Declaration:

```
typedef struct
{
    VAR(uint32,                AUTOMATIC)    u32PCR;
    VAR(Port_PinDirectionType, AUTOMATIC)    ePDDir;
    VAR(uint8,                 AUTOMATIC)    u8PDO;
} Port_Port_Ci_UnUsedPinConfigType;
```

Table 34. Structure Port\_Port\_Ci\_UnUsedPinConfigType member description

Member	Description
u32PCR	Pad Control Register.
ePDDir	Pad Data Direction.
u8PDO	Pad Data Output.

2.8.4.4 Structure Port\_DigitalFilter\_ConfigType

Structure needed by Port\_Init().

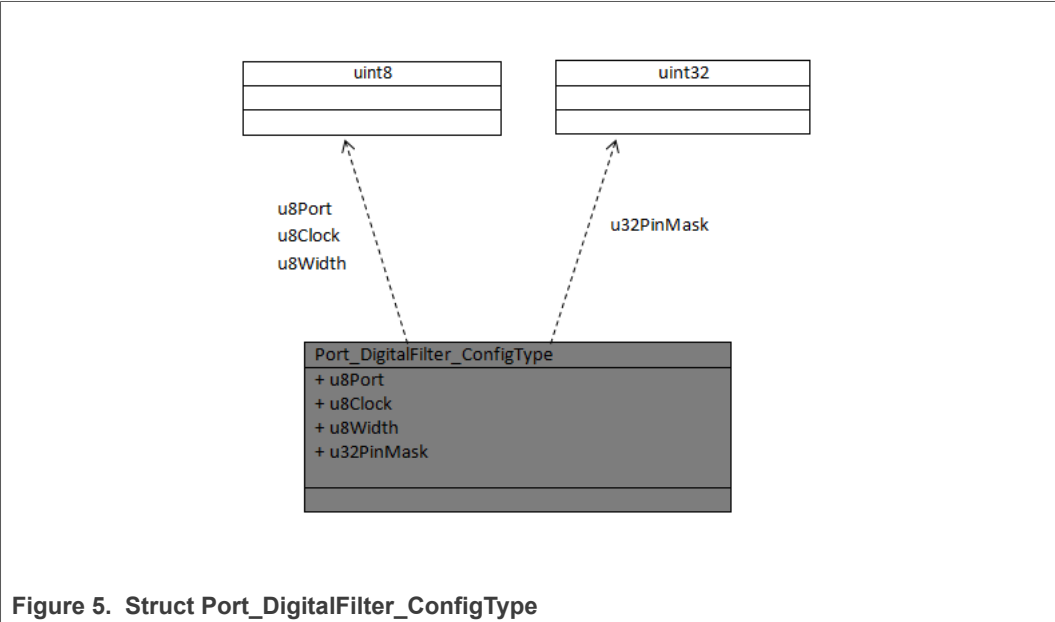


Figure 5. Struct Port\_DigitalFilter\_ConfigType

Details:

The structure `Port_DigitalFilter_ConfigType` contains all configuration parameters of a digital filter port.

**Note:** The user must use the symbolic names defined in the configuration tool.

Declaration:

```
typedef struct
{
    VAR(uint8, AUTOMATIC) u8Port;
    VAR(uint8, AUTOMATIC) u8Clock;
    VAR(uint8, AUTOMATIC) u8Width;
    VAR(uint32, AUTOMATIC) u32PinMask;
} Port_DigitalFilter_ConfigType;
```

Table 35. Structure Port\_DigitalFilter\_ConfigType member description

Member	Description
u8Port	Digital Filter Port.
u8Clock	Digital Filter Clock.
u8Width	Digital Filter Width.
u32PinMask	Mask of pins for which digital filter is enabled.

2.8.5 Types Reference

Types supported by the driver are as per AUTOSAR Port Driver software specification Version 4.2 Rev0002 .

#### 2.8.5.1 Typedef Port\_InternalPinIdType

It is the same with the index of the PCR register.

**Type:** uint16

#### 2.8.5.2 Typedef Port\_PinModeType

A port pin shall be configurable with a number of port pin modes (type Port\_PinModeType). The type Port\_PinModeType shall be used with the function call Port\_SetPinMode

**Type:** uint8

#### 2.8.5.3 Typedef Port\_PinType

Data type for the symbolic name of a port pin.

**Type:** uint32

#### 2.8.5.4 Typedef Port\_Port\_Ci\_PadSelConfigType

Data type used for Pad Selection Multiplexed Configuration.

**Type:** uint8

#### 2.8.5.5 Typedef Port\_RegValueType

A port register shall be written with a 32 bits value (type Port\_RegValueType). The type Port\_RegValueType shall be used with the function call Port\_SetPinMode

**Type:** uint16

### 2.9 Symbolic Names Disclaimer

All containers having the symbolic name tag set as true in the Autosar schema will generate defines like:

```
#define <Container_Short_Name> <Container_ID>
```

For this reason it is forbidden to duplicate the name of such containers across the MCAL configuration, or to use names that may trigger other compile issues (e.g. match existing #ifdefs arguments).

## 3 Tresos Configuration Plug-in

This chapter describes the Tresos configuration plug-in for the Port Driver. The most of the parameters are described below.

### 3.1 Configuration elements of Port

**Included forms :**

- IMPLEMENTATION\_CONFIG\_VARIANT
- PortGeneral
- PortConfigSet
- CommonPublishedInformation

### 3.2 Form IMPLEMENTATION\_CONFIG\_VARIANT

VariantPreCompile: Only precompile time configuration parameters. Only one set of parameters. VariantPostBuild: Mix of precompile and postbuild time configuration parameters. More sets of parameters. If Config Variant = VariantPreCompile, the files Port\_Cfg.h and Port\_Cfg.c should be used. If Config Variant = VariantPostBuild, the files Port\_Cfg.h and Port\_PBcfg.c should be used.

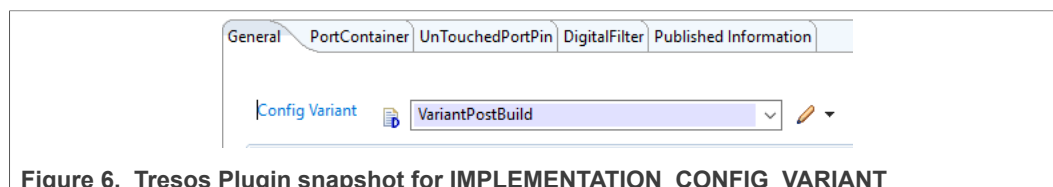


Figure 6. Tresos Plugin snapshot for IMPLEMENTATION\_CONFIG\_VARIANT

Table 36. Attribute IMPLEMENTATION\_CONFIG\_VARIANT detailed description

Property	Value
Label	Config Variant
Default	VariantPostBuild
Range	VariantPostBuild VariantPreCompile

### 3.3 PortGeneral

Module wide configuration parameters of the PORT driver.

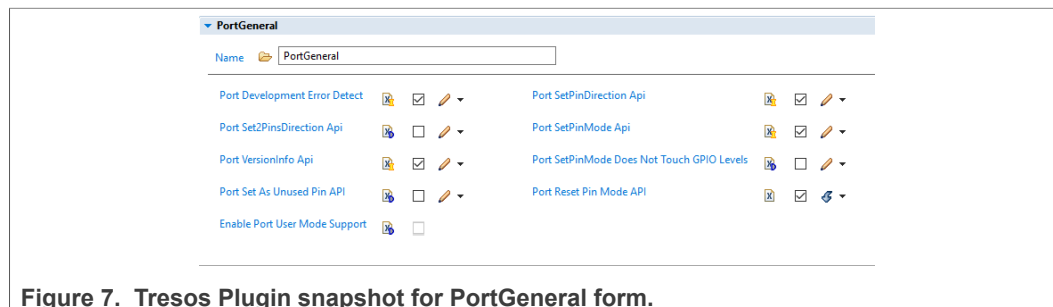


Figure 7. Tresos Plugin snapshot for PortGeneral form.

#### 3.3.1 PortDevErrorDetect (PortGeneral)

Switches the Development Error Detection and Notification ON or OFF.

Table 37. Attribute PortDevErrorDetect (PortGeneral) detailed description

Property	Value
Label	Port Development Error Detect
Type	BOOLEAN
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	true

#### 3.3.2 PortSetPinDirectionApi (PortGeneral)

Pre-processor switch to enable/disable the use of the function Port\_SetPinDirection().

Table 38. Attribute PortSetPinDirectionApi (PortGeneral) detailed description

Property	Value
Label	Port SetPinDirection Api
Type	BOOLEAN
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	true

### 3.3.3 PortSet2PinsDirectionApi (PortGeneral)

Pre-processor switch to enable/disable the use of the function Port\_Set2PinsDirection().

Table 39. Attribute PortSet2PinsDirectionApi (PortGeneral) detailed description

Property	Value
Label	Port Set2PinsDirection Api
Type	BOOLEAN
Origin	NXP
Symbolic Name	false
Default	true

### 3.3.4 PortSetPinModeApi (PortGeneral)

Pre-processor switch to enable/disable the use of the function Port\_SetPinMode().

Table 40. Attribute PortSetPinModeApi (PortGeneral) detailed description

Property	Value
Label	Port SetPinMode Api
Type	BOOLEAN
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	true

### 3.3.5 PortVersionInfoApi (PortGeneral)

Pre-processor switch to enable/disable the API to read out the modules version information.

Table 41. Attribute PortVersionInfoApi (PortGeneral) detailed description

Property	Value
Label	Port VersionInfo Api
Type	BOOLEAN
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	true

### 3.3.6 PortSetPinModeDoesNotTouchGpioLevel (PortGeneral)

Pre-processor switch. When not checked, the function Port\_SetPinMode() will set the output level of the pin to the value configured in the PortPinLevelValue combo when called at run time to change mode of a pin from alternate function to GPIO. When checked, the function Port\_SetPinMode() will not touch the output level of the pin when called at run time to change mode of a pin from alternate function to GPIO.



Table 42. Attribute PortSetPinModeDoesNotTouchGpioLevel (PortGeneral) detailed description

Property	Value
Label	Port SetPinMode Does Not Touch GPIO Levels
Type	BOOLEAN
Origin	NXP
Symbolic Name	false
Default	False

### 3.3.7 PortEnableUserModeSupport (PortGeneral)

This parameter is added in Port configuration in order to keep a consistent design over the entire set of MCAL drivers. It cannot be configured by the user and is always set to 'false'. There are no registers used by the driver which require special measures in order to be accessed from user mode, so Port driver can be run from either user or supervisor mode.

Table 43. Attribute PortEnableUserModeSupport (PortGeneral) detailed description

Property	Value
Label	Port Enable User Mode Support
Type	BOOLEAN
Origin	NXP
Symbolic Name	false
Default	False

### 3.3.8 PortResetPinModeApi (PortGeneral)

Pre-processor switch to enable/disable the use of the function Port\_ResetPinMode(). The function Port\_ResetPinMode shall revert the port pin mode of the referenced pin to the value that was set by Port\_Init operation.

- TRUE: Enabled - Function Port\_ResetPinMode() is available.
- FALSE: Disabled - Function Port\_ResetPinMode() is not available.

Table 44. Attribute PortResetPinModeApi (PortGeneral) detailed description

Property	Value
Label	Port Reset Pin Mode API
Type	BOOLEAN
Origin	NXP
Symbolic Name	false
Default	False

### 3.3.9 PortSetAsUnusedPinApi (PortGeneral)

Pre-processor switch to enable/disable the use of the function Port\_SetAsUnusedPin() and Port\_SetAsUsedPin(). The function Port\_SetAsUnusedPin shall configure the referenced pin with all the properties specified in the NotUsedPortPin container. The function Port\_SetAsUsedPin shall configure the referenced pin with all the properties that were set during the Port\_Init operation.

- TRUE: Enabled - Functions Port\_SetAsUnusedPin() and Port\_SetAsUsedPin() are available.
- FALSE: Disabled - Functions Port\_SetAsUnusedPin() and Port\_SetAsUsedPin() are not available.

Table 45. Attribute PortSetAsUnusedPinApi (PortGeneral) detailed description

Property	Value
Label	Port Set As Unused Pin API
Type	BOOLEAN
Origin	NXP
Symbolic Name	false
Default	False

3.4 PortConfigSet

This container contains a configuration of the PORT driver / PORT module.

Includes:

- [Section 3.4.1](#)
- [Section 3.4.2](#)
- [Section 3.4.3](#)

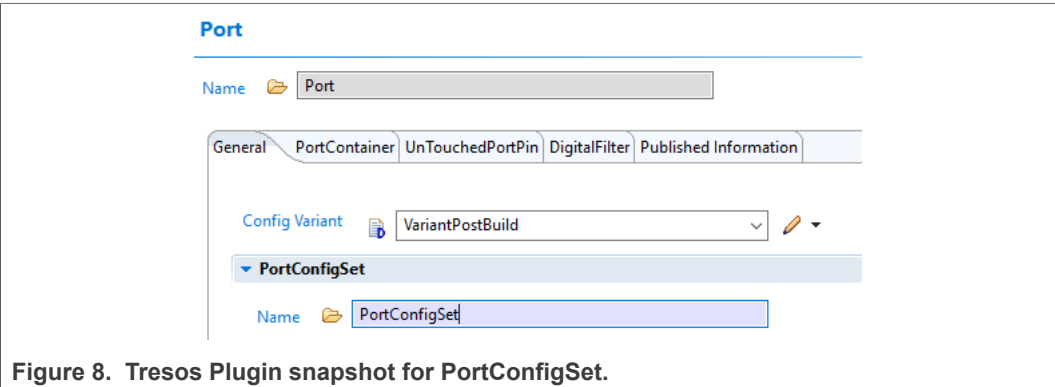


Figure 8. Tresos Plugin snapshot for PortConfigSet.

3.4.1 PortContainer

Container collecting the PortPins.

Is included by : [Section 3.4](#)

Includes :

- [Section 3.4.1.2](#)

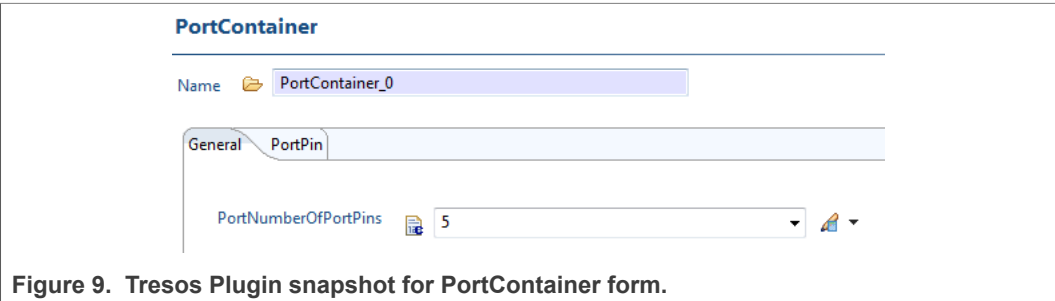


Figure 9. Tresos Plugin snapshot for PortContainer form.

3.4.1.1 PortNumberOfPortPins (PortContainer)

The number of specified PortPins in this PortContainer.

Table 46. Attribute PortNumberOfPortPins (PortContainer) detailed description

Property	Value
Label	PortNumberOfPortPins
Type	INTEGER
Origin	AUTOSAR_ECUC
Symbolic Name	false
Invalid	Range >=1 <=156

3.4.1.2 PortPin

Configuration of the individual port pins.

Is included by : [Section 3.4.1](#)

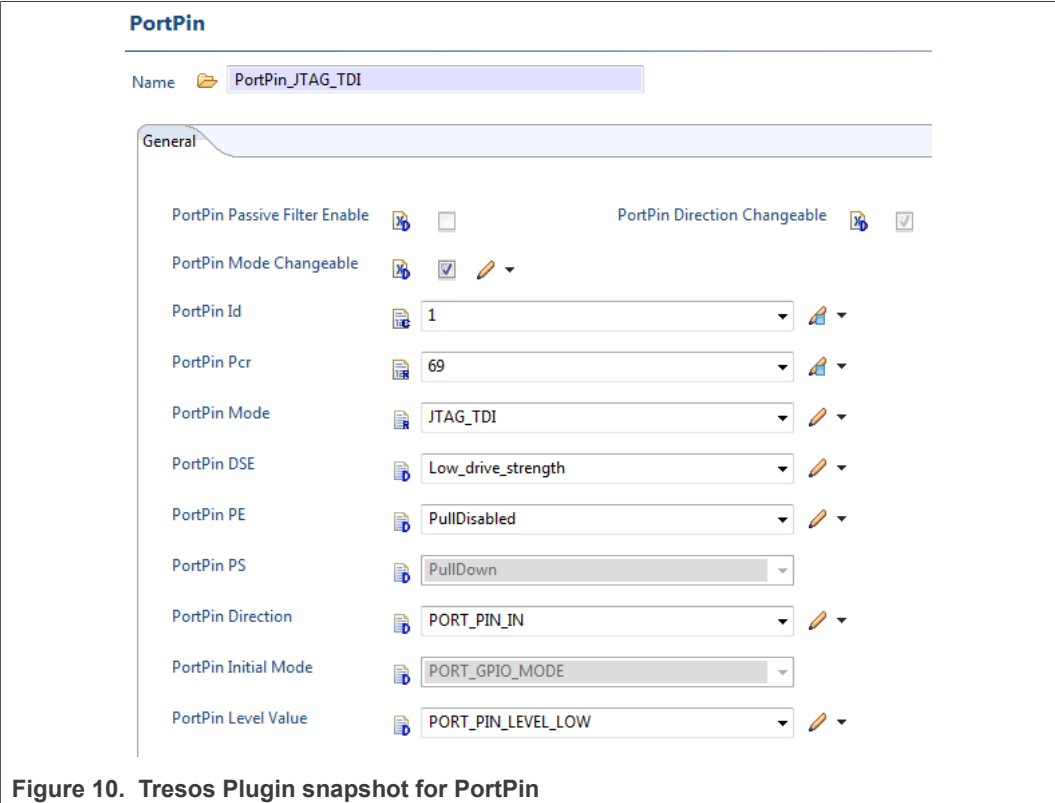


Figure 10. Tresos Plugin snapshot for PortPin

3.4.1.2.1 PortPinDirectionChangeable (PortPin)

Enable/Disable the changeability for the configured Pin. Checked box means the Direction Changeability is enabled. This is an implementation specific parameter.

Table 47. Attribute PortPinDirectionChangeable (PortPin) detailed description

Property	Value
Label	PortPin Direction Changeable
Type	BOOLEAN
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	true

## 3.4.1.2.2 PortPinModeChangeable (PortPin)

Parameter to indicate if the mode of a port pin is changeable during runtime. True: Port Pin mode changeable allowed. False: Port Pin mode changeable not permitted

Table 48. Attribute PortPinModeChangeable (PortPin) detailed description

Property	Value
Label	PortPin Mode Changeable
Type	BOOLEAN
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	true

## 3.4.1.2.3 PortPinPassiveFilterEnable (PortPin)

Passive Filter Enable Passive filter configuration is valid in all digital pin muxing modes

Table 49. Attribute PortPin Passive Filter Enable(PortPin) detailed description

Property	Value
Label	PortPin Passive Filter Enable
Type	BOOLEAN
Origin	NXP
Symbolic Name	false
Default	false

## 3.4.1.2.4 PortPinId (PortPin)

Pin Id of the port pin. This value will be assigned to the symbolic name derived from the port pin container short name.

Table 50. Attribute PortPinId (PortPin) detailed description

Property	Value
Label	PortPin Id
Type	INTEGER
Origin	AUTOSAR_ECUC
Symbolic Name	true
Invalid	Range $\geq 1$ $\leq 156$

## 3.4.1.2.5 PortPinPcr (PortPin)

Used to specify the PCR (Port Configuration Register) for the configured pin.

Table 51. Attribute PortPinPcr (PortPin) detailed description

Property	Value
Label	PortPinPcr
Type	INTEGER
Origin	NXP
Symbolic Name	false
Invalid	Range $\geq 0$ $\leq 155$

## 3.4.1.2.6 PortPinMode (PortPin)

Selects the PORT pin mode from the modes list. By default more than one mode are allowed. That way it is e.g. possible to combine DIO with another mode such as ICU. For the Alternative Function modes (not a GPIO mode) the OUT direction is hw selected for that pin. NOTE: To set the IN direction take care, please, that all the possible module inputs, possible as Alternative Functions for the pad mode, are hw connected together, if IN direction is enabled, to the pad.

Table 52. Attribute PortPinMode (PortPin) detailed description

Property	Value
Label	PortPin Mode
Type	ENUMERATION
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	GPIO

## 3.4.1.2.7 PortPinDSE (PortPin)

Selects the drive strength value for the configured Pin.

Table 53. Attribute PortPinDSE (PortPin) detailed description

Property	Value
Label	PortPin DSE
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	Low_Drive_Strength
Range	Low_Drive_Strength Hight_Drive_Strength

## 3.4.1.2.8 PortPinPE (PortPin)

Selects if the pull-up or pull-down resistors are enabled.

Table 54. Attribute PortPinPE (PortPin) detailed description

Property	Value
Label	PortPin PE
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	PullDisabled
Range	PullDisabled PullEnabled

## 3.4.1.2.9 PortPinPS (PortPin)

Selects between the pull-up and pull-down resistors. Only valid when PortPin PE is set to 'PullEnabled'.

Table 55. Attribute PortPinPS (PortPin) detailed description

Property	Value
Label	PortPin PS

Table 55. Attribute PortPinPS (PortPin) detailed description...continued

Property	Value
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	PullDown
Range	PullDown PullUp

## 3.4.1.2.10 PortPinDirection (PortPin)

Selects the direction of the pin (IN, OUT, HIGH\_Z) that will be configured by Port\_Init() function if the pin is configured as GPIO. If the direction is not changeable, the value configured here is fixed. For the Alternative Function modes (PortPinMode is different than GPIO), the setting in this enumeration control is kept in the port configuration structure and it is used when Port\_SetPinMode() is called at runtime to change the mode of the pin to GPIO. If HIGH\_Z direction is enabled, it is not available in S32K11X (see chapter PORT Driver limitations).

Table 56. Attribute PortPinDirection (PortPin) detailed description

Property	Value
Label	PortPin Direction
Type	ENUMERATION
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	PORT_PIN_IN
Range	PORT_PIN_IN PORT_PIN_OUT PORT_PIN_HIGH_Z

## 3.4.1.2.11 PortPinInitialMode (PortPin)

Port pin mode from mode list for use with Port\_Init() function. NOTE: This parameter is not used in the current implementation and is retained as per std AUTOSAR\_EcucParamDef.xml file.

Table 57. Attribute PortPinInitialMode (PortPin) detailed description

Property	Value
Label	PortPin Initial Mode
Type	ENUMERATION
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	PORT_GPIO_MODE
Enable	false

Table 57. Attribute PortPinInitialMode (PortPin) detailed description...continued

Property	Value
Range	PORT_GPIO_MODE PORT_ALT1_FUNC_MODE PORT_ALT2_FUNC_MODE PORT_ALT3_FUNC_MODE PORT_ALT4_FUNC_MODE PORT_ALT5_FUNC_MODE PORT_ALT6_FUNC_MODE PORT_ALT7_FUNC_MODE

## 3.4.1.2.12 PortPinLevelValue (PortPin)

Port Pin Level value from Port pin list.

Table 58. Attribute PortPinLevelValue (PortPin) detailed description

Property	Value
Label	PortPin Level Value
Type	ENUMERATION
Origin	AUTOSAR_ECUC
Symbolic Name	false
Default	PORT_PIN_LEVEL_LOW
Range	PORT_PIN_LEVEL_HIGH PORT_PIN_LEVEL_LOW PORT_PIN_LEVEL_NOTCHANGED

## 3.4.2 UnTouchedPortPin

List with pins that will not be touched in any way by the Port driver.

Is included by : [Section 3.4](#)

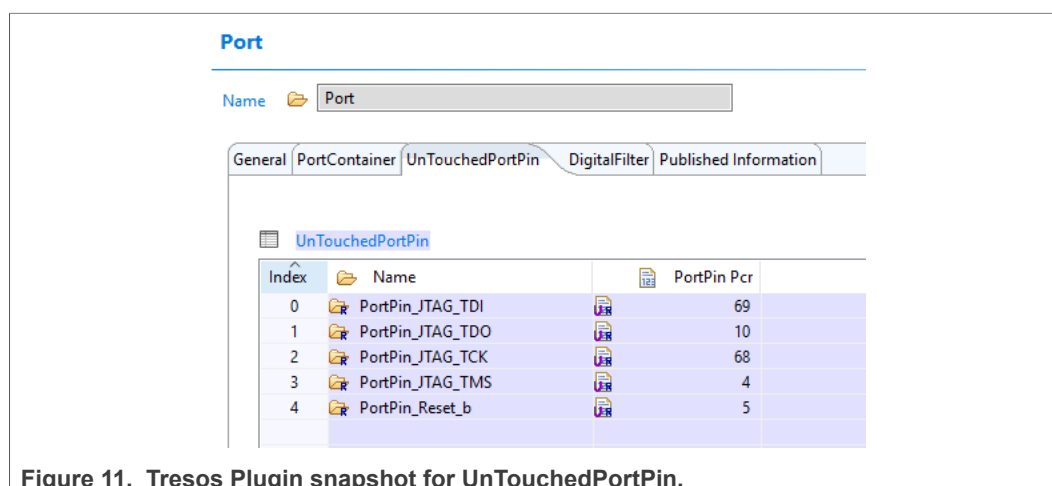


Figure 11. Tresos Plugin snapshot for UnTouchedPortPin.

## 3.4.2.1 PortPin PCR

Selects the PCR of the pin that will not be touched by Port driver.

Table 59. Attribute PortPin PCR detailed description

Property	Value
Label	PortPin PCR
Type	INTEGER
Origin	NXP
Symbolic Name	false
Default	0
Range	0 Max num PCRs on the platform

### 3.4.3 NotUsedPortPin

Module wide configuration parameters of the PORT driver.

Is included by : [Section 3.4](#)

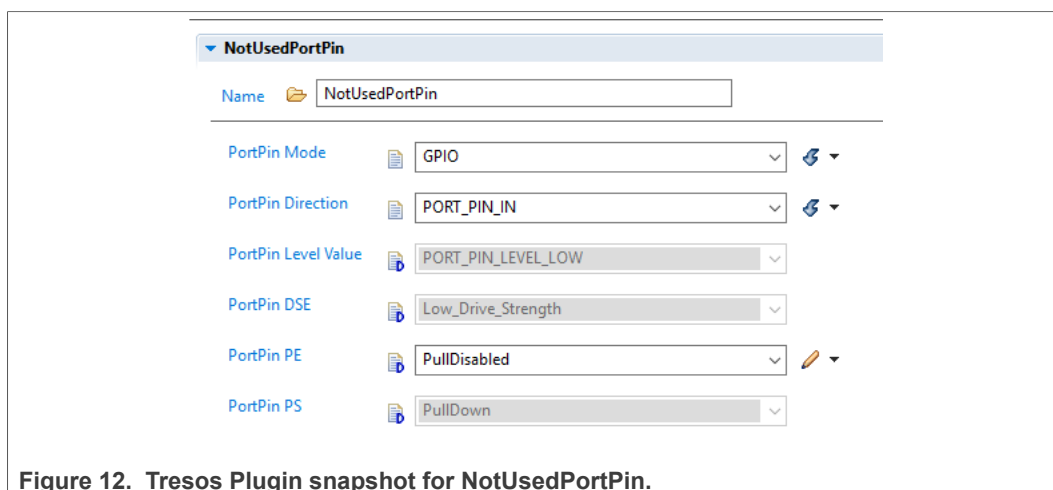


Figure 12. Tresos Plugin snapshot for NotUsedPortPin.

#### 3.4.3.1 PortPinMode(NotUsedPortPin)

Selects the PORT pin mode from the modes list. This is an implementation specific parameter

Table 60. Attribute PortPinMode(NotUsedPortPin) detailed description

Property	Value
Label	PortPin Mode
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	GPIO
Range	GPIO Disabled

#### 3.4.3.2 PortPinDSE (PortPin)

Selects the drive strength value for the configured Pin. This is an implementation specific parameter.



Table 61. Attribute PortPinDSE (NotUsedPortPin) detailed description

Property	Value
Label	PortPin DSE
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	Low_Drive_Strength
Range	Low_Drive_Strength High_Drive_Strength

### 3.4.3.3 PortPinPE (PortPin)

Selects if the pull-up or pull-down resistors are enabled.

Table 62. Attribute PortPinPE (NotUsedPortPin) detailed description

Property	Value
Label	PortPin PE
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	PullDisabled
Range	PullDisabled PullEnabled

### 3.4.3.4 PortPinPS (PortPin)

Selects between the pull-up and pull-down resistors. Only valid when PortPin PE is set to 'PullEnabled'.

Table 63. Attribute PortPinPS (NotUsedPortPin) detailed description

Property	Value
Label	PortPin PKE
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	PullDown
Range	PullDown PullUp

### 3.4.3.5 PortPinDirection (NotUsedPortPin)

Selects the initial direction of the pin (IN, OUT, HIGH\_Z). If the direction is not changeable, the value configured here is fixed. The pin direction can be set only for the GPIO pins. For the Alternative Function modes the OUT pin direction is hw selected. If the IN direction is needed too, it can be set at runtime. NOTE: To set the IN direction take care, please, that all the possible module inputs, possible as Alternative Functions for the pad mode, are hw connected together, if IN direction is enabled, to the pad. If HIGH\_Z direction is enabled, it is not available in S32K11X (see chapter PORT Driver limitations).

Table 64. Attribute PortPinDirection(NotUsedPortPin) detailed description

Property	Value
Label	PortPin Direction

Table 64. Attribute PortPinDirection(NotUsedPortPin) detailed description...continued

Property	Value
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	PORT_PIN_IN
Range	PORT_PIN_IN PORT_PIN_OUT PORT_PIN_HIGH_Z

### 3.4.3.6 PortPinLevelValue(NotUsedPortPin)

Port Pin Level value from Port pin list.

Table 65. Attribute PortPinLevelValue(NotUsedPortPin) detailed description

Property	Value
Label	PortPin Level Value
Type	ENUMERATION
Origin	NXP
Symbolic Name	false
Default	PORT_PIN_LEVEL_LOW
Range	PORT_PIN_LEVEL_HIGH PORT_PIN_LEVEL_LOW

## 3.5 Form CommonPublishedInformation

Common container, aggregated by all modules. It contains published information about vendor and versions.

**CommonPublishedInformation**

Name CommonPublishedInformation

---

AUTOSAR Major Version <AUTOSAR Major Version>

AUTOSAR Minor Version <AUTOSAR Minor Version>

AUTOSAR Release Revision Version <AUTOSAR Release Revision Version>

Module Id <Module ID>

Software Major Version <Software Major Version>

Software Minor Version <Software Minor Version>

Software Patch Version <Software Patch Version>

Vendor Api Infix <Vendor Api Infix>

Vendor Id <Vendor ID>

Figure 13. Tresos Plugin snapshot for CommonPublishedInformation form.

### 3.5.1 ArReleaseMajorVersion (CommonPublishedInformation)

Major version number of AUTOSAR specification on which the appropriate implementation is based on.

Table 66. Attribute ArReleaseMajorVersion (CommonPublishedInformation) detailed description

Property	Value
Label	AUTOSAR Major Version
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	4
Invalid	Range <div>&gt;=4</div> <div>&lt;=4</div>

### 3.5.2 ArReleaseMinorVersion (CommonPublishedInformation)

Minor version number of AUTOSAR specification on which the appropriate implementation is based on.

Table 67. Attribute ArReleaseMinorVersion (CommonPublishedInformation) detailed description

Property	Value
Label	AUTOSAR Minor Version
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	2
Invalid	Range <div>&gt;=2</div> <div>&lt;=2</div>

### 3.5.3 ArReleaseRevisionVersion (CommonPublishedInformation)

Revision version number of AUTOSAR specification on which the appropriate implementation is based on.

Table 68. Attribute ArReleaseRevisionVersion (CommonPublishedInformation) detailed description

Property	Value
Label	AUTOSAR Release Revision Version
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	2
Invalid	Range <div>&gt;=2</div> <div>&lt;=2</div>

### 3.5.4 ModuleId (CommonPublishedInformation)

Module ID of this module from Module List.

Table 69. Attribute ModuleId (CommonPublishedInformation) detailed description

Property	Value
Label	Module Id
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	124
Invalid	Range <div> <div>&gt;=124</div> <div>&lt;=124</div> </div>

### 3.5.5 SwMajorVersion (CommonPublishedInformation)

Major version number of the vendor specific implementation of the module. The numbering is vendor specific.

Table 70. Attribute SwMajorVersion (CommonPublishedInformation) detailed description

Property	Value
Label	Software Major Version
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	1
Invalid	Range <div> <div>&gt;=1</div> <div>&lt;=1</div> </div>

### 3.5.6 SwMinorVersion (CommonPublishedInformation)

Minor version number of the vendor specific implementation of the module. The numbering is vendor specific.

Table 71. Attribute SwMinorVersion (CommonPublishedInformation) detailed description

Property	Value
Label	Software Minor Version
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	0
Invalid	Range <div> <div>&gt;=0</div> <div>&lt;=0</div> </div>

### 3.5.7 SwPatchVersion (CommonPublishedInformation)

Patch level version number of the vendor specific implementation of the module. The numbering is vendor specific.

Table 72. Attribute SwPatchVersion (CommonPublishedInformation) detailed description

Property	Value
Label	Software Patch Version

Table 72. Attribute SwPatchVersion (CommonPublishedInformation) detailed description...continued

Property	Value
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	5
Invalid	Range <div>&gt;=5</div> <div>&lt;=5</div>

### 3.5.8 VendorApiInfix (CommonPublishedInformation)

In driver modules which can be instantiated several times on a single ECU, BSW00347 requires that the name of APIs is extended by the VendorId and a vendor specific name. This parameter is used to specify the vendor specific name. In total, the implementation specific name is generated as follows: <ModuleName>\_<VendorId>\_<VendorApiInfix><Api name from SWS>. E.g. assuming that the VendorId of the implementor is 123 and the implementer chose a VendorApiInfix of "v11r456" a api name Can\_Write defined in the SWS will translate to Can\_123\_v11r456Write. This parameter is mandatory for all modules with upper multiplicity > 1. It shall not be used for modules with upper multiplicity =1.

Table 73. Attribute VendorApiInfix (CommonPublishedInformation) detailed description

Property	Value
Label	Vendor Api Infix
Type	STRING_LABEL
Origin	NXP
Symbolic Name	false
Default	N/A
Enable	false

### 3.5.9 VendorId (CommonPublishedInformation)

Vendor ID of the dedicated implementation of this module according to the AUTOSAR vendor list.

Table 74. Attribute VendorId (CommonPublishedInformation) detailed description

Property	Value
Label	Vendor Id
Type	INTEGER_LABEL
Origin	NXP
Symbolic Name	false
Default	43
Invalid	Range <div>&gt;=43</div> <div>&lt;=43</div>

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