Chapter 5

Pipelined Computations

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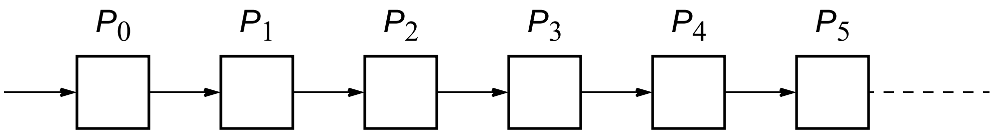
Pipelined Computations

Problem divided into a series of tasks that have to be completed one after the other (the basis of sequential programming).

Each task executed by a separate process or processor.



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Example

Add all the elements of array **a** to an accumulating sum:

```
for (i = 0; i < n; i++)
  sum = sum + a[i];
```

The loop could be “unfolded” to yield

```
sum = sum + a[0];
sum = sum + a[1];
sum = sum + a[2];
sum = sum + a[3];
sum = sum + a[4];
    .
```

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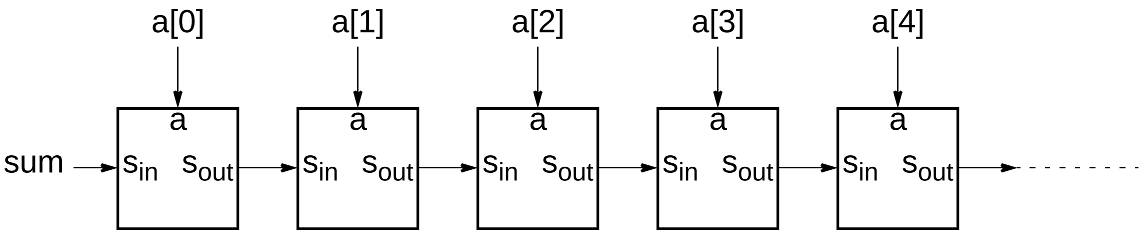
Pipeline for an unfolded loop



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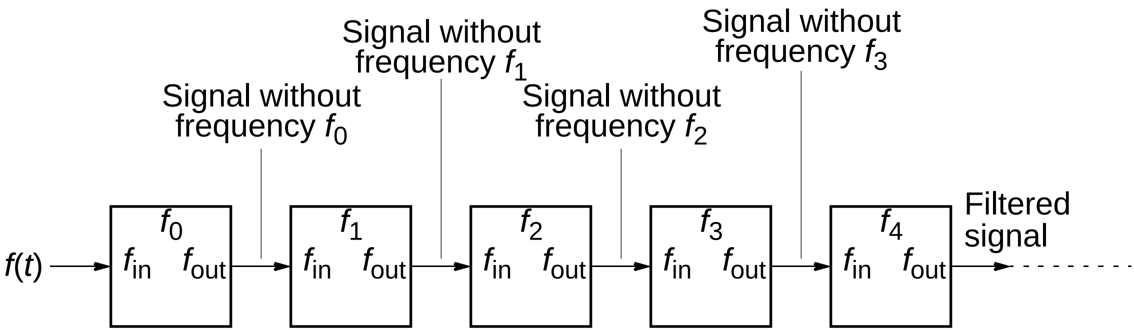
Another Example

Frequency filter - Objective to remove specific frequencies (f_0, f_1, f_2, f_3, etc.) from a digitized signal, $f(t)$. Signal enters pipeline from left:



Where pipelining can be used to good effect

Assuming problem can be divided into a series of sequential tasks, pipelined approach can provide increased execution speed under the following three types of computations:

1. If more than one instance of the complete problem is to be executed

2. If a series of data items must be processed, each requiring multiple operations

3. If information to start the next process can be passed forward before the process has completed all its internal operations

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"Type 1" Pipeline Space-Time Diagram

p - 1 | m

P_5						Instance 1	Instance 2	Instance 3	Instance 4	Instance 5	
P_4					Instance 1	Instance 2	Instance 3	Instance 4	Instance 5	Instance 6	
P_3				Instance 1	Instance 2	Instance 3	Instance 4	Instance 5	Instance 6	Instance 7	
P_2			Instance 1	Instance 2	Instance 3	Instance 4	Instance 5	Instance 6	Instance 7		
P_1		Instance 1	Instance 2	Instance 3	Instance 4	Instance 5	Instance 6	Instance 7			
P_0	Instance 1	Instance 2	Instance 3	Instance 4	Instance 5	Instance 6	Instance 7				

Time →

Execution time = m + p - 1 cycles for a p-stage pipeline and m instances.

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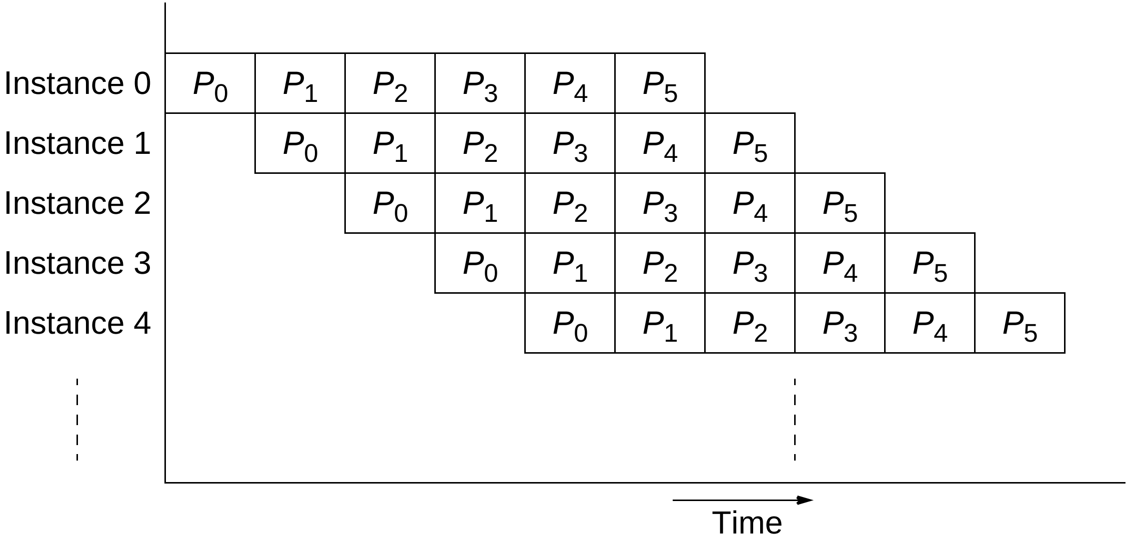
Alternative space-time diagram



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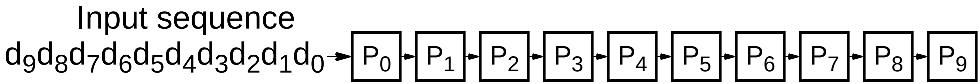
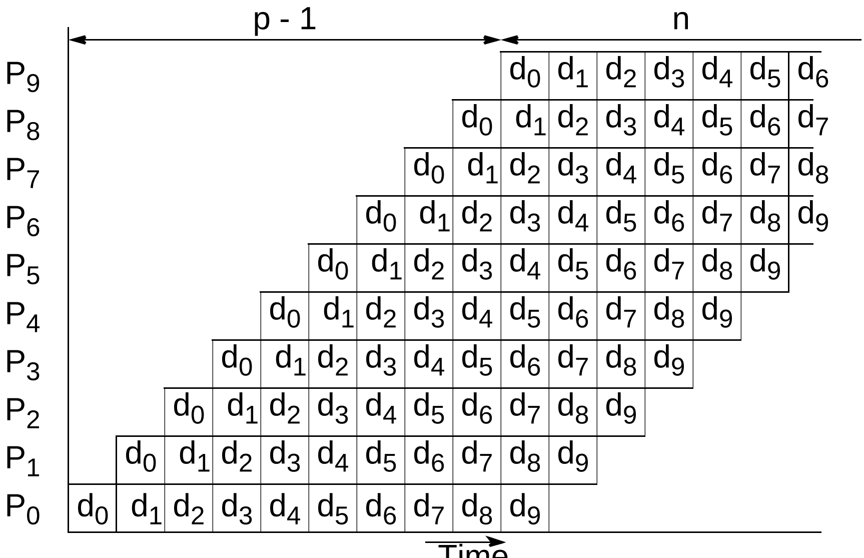
"Type 2" Pipeline Space-Time Diagram



(a) Pipeline structure



(b) Timing diagram

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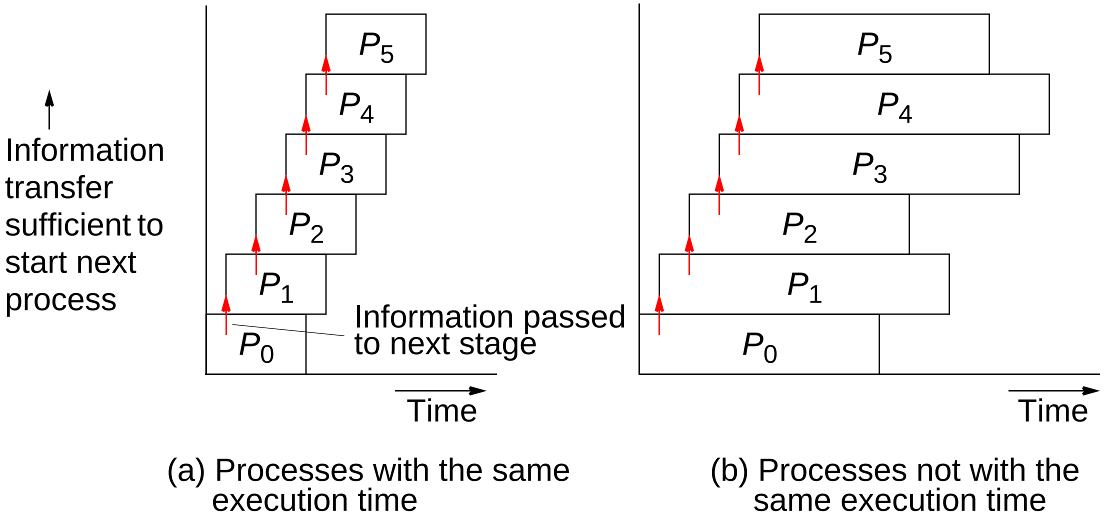
"Type 3" Pipeline Space-Time Diagram



Pipeline processing where information passes to next stage before end of process.

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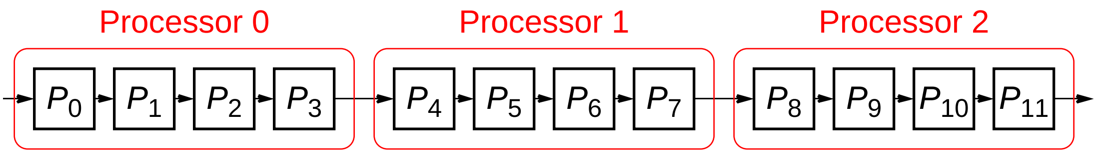
If the number of stages is larger than the number of processors in any pipeline, a group of stages can be assigned to each processor:



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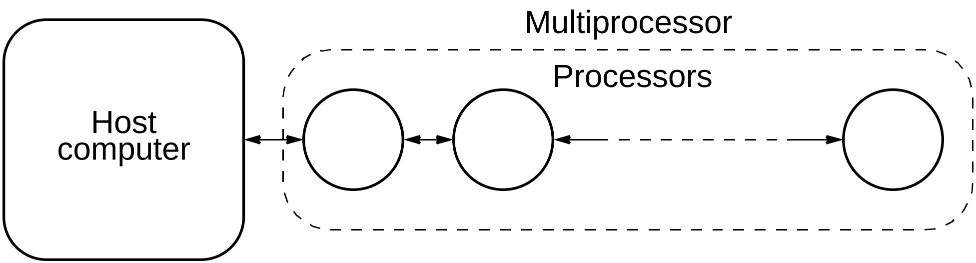
Computing Platform for Pipelined Applications

Multiprocessor system with a line configuration.



Strictly speaking pipeline may not be the best structure for a cluster - however a cluster with switched direct connections, as most have, can support simultaneous message passing.

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Example Pipelined Solutions

(Examples of each type of computation)

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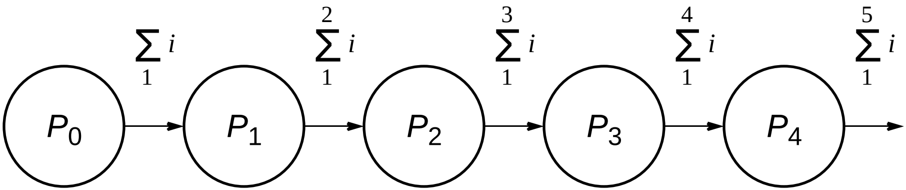
Pipeline Program Examples

Adding Numbers



Type 1 pipeline computation

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Basic code for process P_i :

```
recv(&accumulation, P_i-1);
accumulation = accumulation + number;
send(&accumulation, P_i+1);
```

except for the first process, P_0, which is

```
send(&number, P_1);
```

and the last process, P_{n-1}, which is

```
recv(&number, P_n-2);

accumulation = accumulation + number;
```

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SPMD program

```
if (process > 0) {
  recv(&accumulation, P_{i-1});
  accumulation = accumulation + number;
}
if (process < n-1) send(&accumulation, P_{i+1});
```

The final result is in the last process.

Instead of addition, other arithmetic operations could be done.

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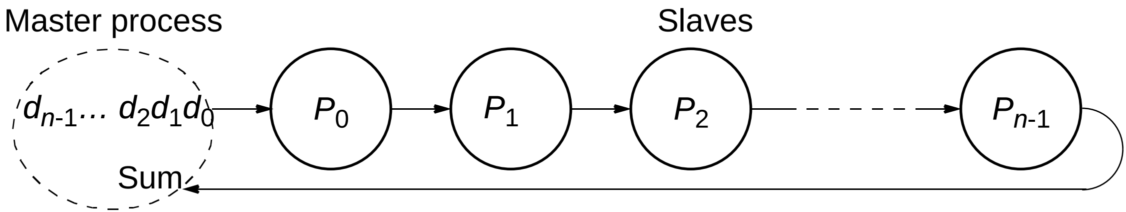
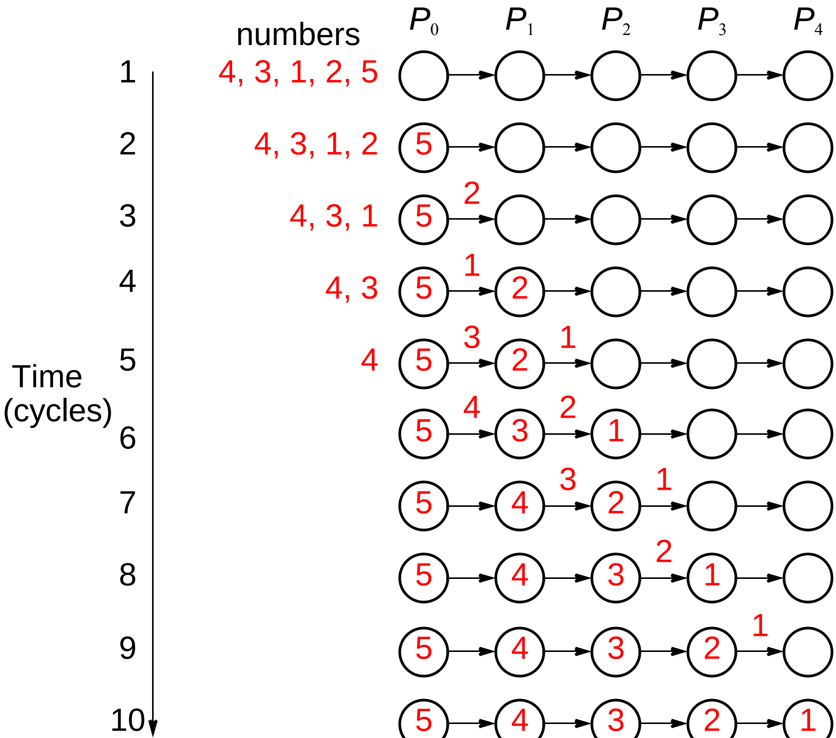
Pipelined addition numbers with a master process and ring configuration



Sorting Numbers

A parallel version of *insertion sort*.



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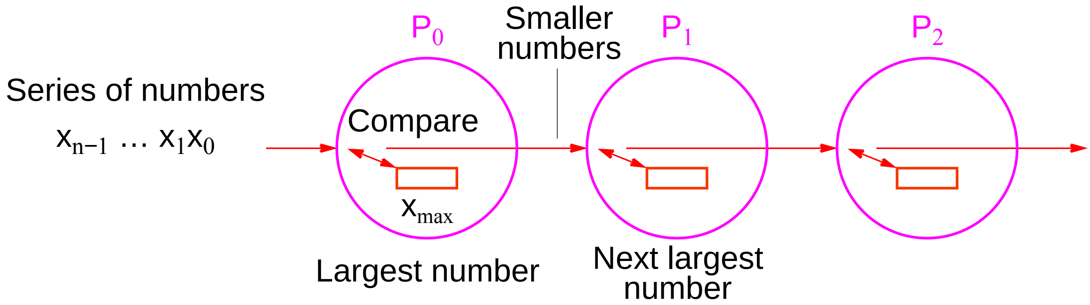
Pipeline for sorting using insertion sort



Type 2 pipeline computation

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The basic algorithm for process P_i is

```
recv(&number, Pi-1);
if (number > x) {
  send(&x, Pi+1);
  x = number;
} else send(&number, Pi+1);
```

With n numbers, how many the ith process is to accept is known; it is given by $n - i$. How many to pass onward is also known; it is given by $n - i - 1$ since one of the numbers received is not passed onward. Hence, a simple loop could be used.

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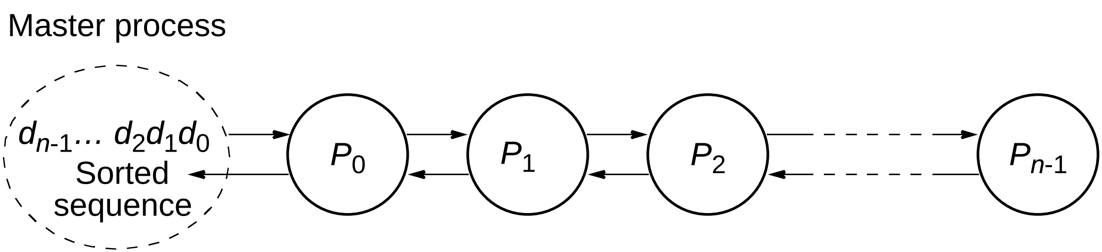
Insertion sort with results returned to the master process using a bidirectional line configuration



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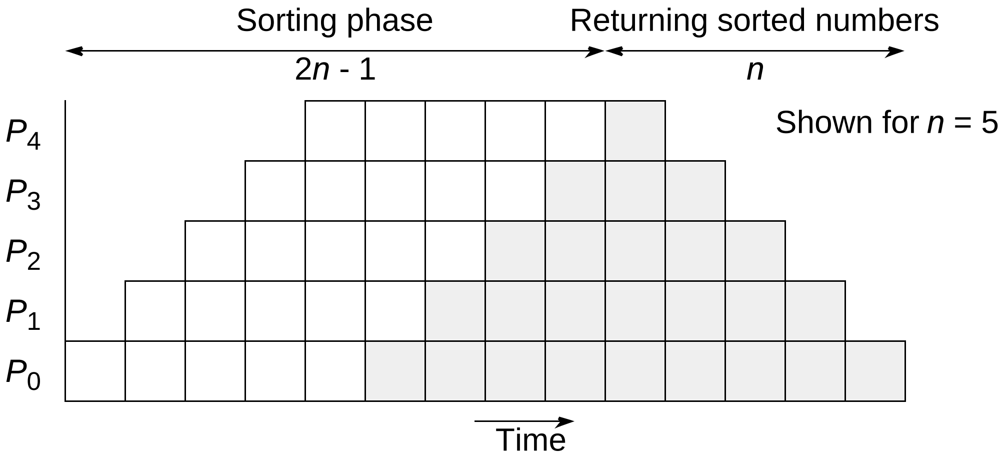
Insertion sort with results returned



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Prime Number Generation

Sieve of Eratosthenes

Series of all integers is generated from 2. First number, 2, is prime and kept. All multiples of this number are deleted as they cannot be prime. Process repeated with each remaining number. The algorithm removes nonprimes, leaving only primes.

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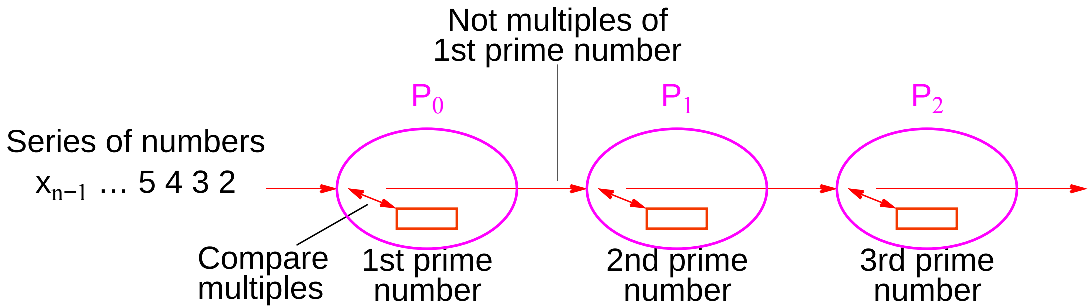
Pipeline for Prime Number Generation



Type 2 pipeline computation

The code for a process, P_i, could be based upon

```
recv(&x, Pi-1);
/* repeat following for each number */
recv(&number, Pi-1);
if ((number % x) != 0) send(&number, Pi+1);
```

Each process will not receive the same amount of numbers and the amount is not known beforehand. Use a "terminator" message, which is sent at the end of the sequence:

```
recv(&x, Pi-1);
for (i = 0; i < n; i++) {
  recv(&number, Pi-1);
  if (number == terminator) break;
  if (number % x) != 0) send(&number, Pi+1);
}
```

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Solving a System of Linear Equations

Upper-triangular form

$$
\begin{array}{llll}
a_{n-1,0}x_0 + a_{n-1,1}x_1 + a_{n-1,2}x_2 & \ldots & + a_{n-1,n-1}x_{n-1} & = b_{n-1} \\
 & & . & \\
 & & . & \\
a_{2,0}x_0 + a_{2,1}x_1 + a_{2,2}x_2 & & & = b_2 \\
a_{1,0}x_0 + a_{1,1}x_1 & & & = b_1 \\
a_{0,0}x_0 & & & = b_0
\end{array}
$$

where the *a's* and *b's* are constants and the *x*'s are unknowns to be found.

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Back Substitution

First, the unknown x_0 is found from the last equation; i.e.,

$$x_0 = \frac{b_0}{a_{0,0}}$$

Value obtained for x_0 substituted into next equation to obtain x_1; i.e.,

$$x_1 = \frac{b_1 - a_{1,0}x_0}{a_{1,1}}$$

Values obtained for x_1 and x_0 substituted into next equation to obtain x_2:

$$x_2 = \frac{b_2 - a_{2,0}x_0 - a_{2,1}x_1}{a_{2,2}}$$

and so on until all the unknowns are found.

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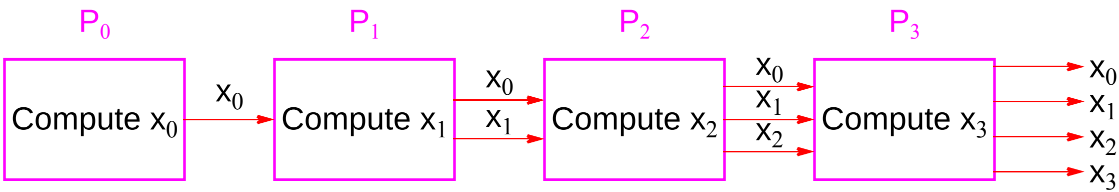
Pipeline Solution

First pipeline stage computes x_0 and passes x_0 onto the second stage, which computes x_1 from x_0 and passes both x_0 and x_1 onto the next stage, which computes x_2 from x_0 and x_1, and so on.



Type 3 pipeline computation

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The ith process ($0 < i < n$) receives the values $x_0, x_1, x_2, \ldots, x_{i-1}$ and computes x_i from the equation:

$$x_i = \frac{b_i - \sum_{j=0}^{i-1} a_{i,j} x_j}{a_{i,i}}$$

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Sequential Code

Given the constants $a_{i,j}$ and b_k stored in arrays **a[][]** and **b[]**, respectively, and the values for unknowns to be stored in an array, **x[]**, the sequential code could be

```
   x[0] = b[0]/a[0][0]; /* computed separately */
   for (i = 1; i < n; i++) {/* for remaining
unknowns */
     sum = 0;
     for (j = 0; j < i; j++
       sum = sum + a[i][j]*x[j];
     x[i] = (b[i] - sum)/a[i][i];
   }
```

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Parallel Code

Pseudocode of process P_i $(1 < i < n)$ of could be

```
for (j = 0; j < i; j++) {
  recv(&x[j], Pi-1);
  send(&x[j], Pi+1);
}
sum = 0;
for (j = 0; j < i; j++)
  sum = sum + a[i][j]*x[j];
x[i] = (b[i] - sum)/a[i][i];
send(&x[i], Pi+1);
```

Now additional computations after receiving and resending values.

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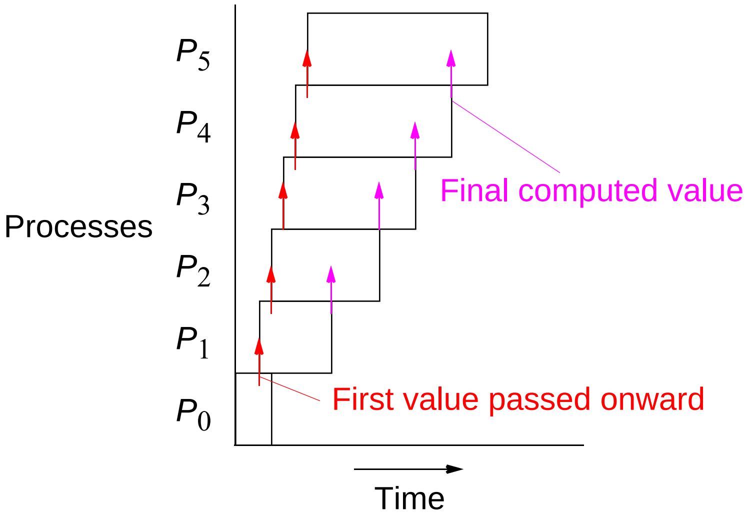
Pipeline processing using back substitution



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