Spherical Barotropic Primitive Equations Model

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$$\begin{cases} \frac{\partial U}{\partial t} + \frac{1}{2a\cos\theta} \left(u\frac{\partial U}{\partial \lambda} + \frac{\partial uU}{\partial \lambda} + v\cos\theta\frac{\partial U}{\partial \theta} + \frac{\partial vU\cos\theta}{\partial \theta} \right) + \frac{h}{a\cos\theta}\frac{\partial \phi}{\partial \lambda} - f^*V = 0 \\ \frac{\partial V}{\partial t} + \frac{1}{2a\cos\theta} \left(u\frac{\partial V}{\partial \lambda} + \frac{\partial uV}{\partial \lambda} + v\cos\theta\frac{\partial V}{\partial \theta} + \frac{\partial vV\cos\theta}{\partial \theta} \right) + \frac{h}{a}\frac{\partial \phi}{\partial \theta} + f^*U = 0 \\ \frac{\partial \phi}{\partial t} + \frac{1}{a\cos\theta} \left(\frac{\partial hU}{\partial \lambda} + \frac{\partial hV\cos\theta}{\partial \theta} \right) = 0 \end{cases}$$

Where $f^* = 2\Omega \sin \theta + \frac{u}{a} \tan \theta$

For discretization on C-grid, the equations have to be written as

$$\begin{cases} \frac{\partial U}{\partial t} + \frac{1}{2a\cos\theta} \left(u \frac{\partial U}{\partial \lambda} + \frac{\partial uU}{\partial \lambda} + 2 \frac{\partial vU\cos\theta}{\partial \theta} - U \frac{\partial v\cos\theta}{\partial \theta} \right) + \frac{h}{a\cos\theta} \frac{\partial \phi}{\partial \lambda} - f^*V = 0 \\ \frac{\partial V}{\partial t} + \frac{1}{2a\cos\theta} \left(2 \frac{\partial uV}{\partial \lambda} - V \frac{\partial u}{\partial \lambda} + v\cos\theta \frac{\partial V}{\partial \theta} + \frac{\partial vV\cos\theta}{\partial \theta} \right) + \frac{h}{a} \frac{\partial \phi}{\partial \theta} + f^*U = 0 \\ \frac{\partial \phi}{\partial t} + \frac{1}{a\cos\theta} \left(\frac{\partial hU}{\partial \lambda} + \frac{\partial hV\cos\theta}{\partial \theta} \right) = 0 \end{cases}$$

Discretization On C-grid

$$\begin{cases} \frac{\partial U}{\partial t} + \frac{1}{2a\cos\theta} \left[u\overline{U}_x^x + \overline{(uU)}_x^x + 2\left(\overline{v\cos\theta}^x\overline{U}^y\right)_y - U\left(\overline{v\cos\theta}^x\right)_y \right] + \frac{\overline{h}^x}{a\cos\theta} \phi_x - 2\Omega\sin\theta\,\overline{V}_u^{xy} - \frac{u}{a}\tan\theta\,\overline{V}_u^{xy} = 0 \\ \frac{\partial V}{\partial t} + \frac{1}{2a\cos\theta} \left[2\left(\overline{u}^y\overline{V}^x\right)_x - V\overline{u}_x^y + v\cos\theta\,\overline{V}_y^y + \overline{(v\cos\theta\,V)}_y^y \right] + \frac{\overline{h}^y}{a}\phi_y + 2\Omega\,\overline{\sin\theta\,U}^{xy} + \frac{1}{a}\overline{uU\tan\theta}^{xy} = 0 \\ \frac{\partial \phi}{\partial t} + \frac{1}{a\cos\theta} \left[\left(\overline{h}^xU\right)_x + \left(\overline{h}^yV\cos\theta\right)_y \right] = 0 \end{cases}$$

$$h_{u} = \overline{h}^{x} = \frac{h_{i+1,j} + h_{i,j}}{2}$$

$$h_{v} = \overline{h}^{y} = \frac{h_{i,j+1} + h_{i,j}}{2}$$

$$U = h_{u}u = \frac{h_{i+1,j} + h_{i,j}}{2}u$$

$$V = h_{v}v = \frac{h_{i,j+1} + h_{i,j}}{2}v$$

$$\overline{V_{u}}^{xy} = \frac{1}{4} \left[C_{1} \left(V_{i+1,j} + V_{i,j} \right) + C_{2} \left(V_{i+1,j-1} + V_{i,j-1} \right) \right]$$

where

$$C_1 = \frac{\cos \theta_{vj}}{\cos \theta_{z_j}}$$
$$C_2 = \frac{\cos \theta_{vj-1}}{\cos \theta_{z_j}}$$

U equation

$$v \to u : i + \frac{1}{2}, j - \frac{1}{2}$$

$$h \to u : i + \frac{1}{2}$$

$$h \to v : j + \frac{1}{2}$$

$$u\overline{U}_{x}^{x} = u_{i,j} \frac{U_{i+1,j} - U_{i-1,j}}{2dx}$$

$$\overline{(uU)}_{x}^{x} = \frac{(uU)_{i+1,j} - (uU)_{i-1,j}}{2dx}$$

$$2\left(\overline{v\cos\theta_{v}}^{x}\overline{U}^{y}\right)_{y} = \frac{\left[(v\cos\theta_{v})_{i+1,j} + (v\cos\theta_{v})_{i,j}\right]\left(U_{i,j+1} + U_{i,j}\right) - \left[(v\cos\theta_{v})_{i+1,j-1} + (v\cos\theta_{v})_{i,j-1}\right]\left(U_{i,j} + U_{i,j-1}\right)}{2dy}$$

$$U\left(\overline{v\cos\theta_{v}}^{x}\right)_{y} = \frac{U_{i,j}\left[(v\cos\theta_{v})_{i+1,j} + (v\cos\theta_{v})_{i,j} - (v\cos\theta_{v})_{i+1,j-1} - (v\cos\theta_{v})_{i,j-1}\right]}{2dy}$$

$$2\left(\overline{v\cos\theta_{v}}^{x}\overline{U}^{y}\right)_{y} - U\left(\overline{v\cos\theta_{v}}^{x}\right)_{y} = \frac{\left[(v\cos\theta_{v})_{i+1,j} + (v\cos\theta_{v})_{i,j}\right]U_{i,j+1} - \left[(v\cos\theta_{v})_{i+1,j-1} + (v\cos\theta_{v})_{i,j-1}\right]U_{i,j-1}}{2dy}$$

$$\phi_{x} = \frac{\phi_{i+1,j} - \phi_{i,j}}{dx}$$

$$2\Omega\sin\theta\overline{V}_{u}^{xy} = \frac{1}{2}\sin\theta\left[C_{1}(V_{i+1,j} + V_{i,j}) + C_{2}(V_{i+1,j-1} + V_{i,j-1})\right]$$

$$\frac{u}{a}\tan\theta\overline{V}_{u}^{xy} = \frac{u}{a}\tan\theta\frac{C_{1}(V_{i+1,j} + V_{i,j}) + C_{2}(V_{i+1,j-1} + V_{i,j-1})}{4}$$

V equation

$$h \to v : j + \frac{1}{2}$$

$$u \to v : i - \frac{1}{2}, j + \frac{1}{2}$$

$$2\left(\overline{u}^{y}\overline{v}^{x}\right)_{x} = \frac{\left(u_{i,j+1} + u_{i,j}\right)\left(V_{i+1,j} + V_{i,j}\right) - \left(u_{i-1,j+1} + u_{i-1,j}\right)\left(V_{i,j} + V_{i-1,j}\right)}{2dx}$$

$$V\overline{u}_{x}^{y} = \frac{V_{i,j}\left(u_{i,j+1} + u_{i,j} - u_{i-1,j+1} - u_{i-1,j}\right)}{2dx}$$

$$2\left(\overline{u}^{y}\overline{v}^{x}\right)_{x} - V\overline{u}_{x}^{y} = \frac{\left(u_{i,j+1} + u_{i,j}\right)V_{i+1,j} - \left(u_{i-1,j+1} + u_{i-1,j}\right)V_{i-1,j}}{2dx}$$

$$v \cos\theta \overline{V}_{y}^{y} = \frac{v \cos\theta \left(V_{i,j+1} - V_{i,j-1}\right)}{2dy}$$

$$\overline{\left(v \cos\theta V\right)_{y}^{y}} = \frac{\left(vV \cos\theta\right)_{i,j+1} - \left(vV \cos\theta\right)_{i,j-1}}{2dy}$$

$$\phi_{y} = \frac{\phi_{i,j+1} - \phi_{i,j}}{dy}$$

$$\overline{\sin\theta_{u}} \overline{U}^{xy} = \frac{\left(U_{i,j+1} + U_{i-1,j+1}\right) \sin\theta_{u_{j+1}} + \left(U_{i,j} + U_{i-1,j}\right) \sin\theta_{u_{j}}}{4}$$

$$\overline{uU \tan\theta_{u}}^{xy} = \frac{\left[\left(uU\right)_{i,j+1} + \left(uU\right)_{i-1,j+1}\right] \tan\theta_{u_{j+1}} + \left[\left(uU\right)_{i,j} + \left(uU\right)_{i-1,j}\right] \tan\theta_{u_{j}}}{4}$$

ϕ equation

$$u \to h : i - \frac{1}{2}$$

$$v \to h : j - \frac{1}{2}$$

$$\left(\overline{h}^{x}U\right)_{x} = \frac{\left(h_{i+1,j} + h_{i,j}\right)U_{i,j} - \left(h_{i,j} + h_{i-1,j}\right)U_{i-1,j}}{2dx}$$

$$\left(\overline{h}^{y}V\cos\theta\right)_{y} = \frac{\left(h_{i,j+1} + h_{i,j}\right)(V\cos\theta)_{i,j} - \left(h_{i,j} + h_{i,j-1}\right)(V\cos\theta)_{i,j-1}}{2dy}$$

Final equations

$$LU = \frac{1}{4a \cdot dx \cdot \cos \theta} \left[u(U_{i+1,j} - U_{i-1,j}) + (uU)_{i+1,j} - (uU)_{i-1,j} \right]$$

$$+ \frac{1}{4a \cdot dy \cdot \cos \theta} \left\{ \left[(v \cos \theta_v)_{i+1,j} + (v \cos \theta_v)_{i,j} \right] U_{i,j+1} - \left[(v \cos \theta_v)_{i+1,j-1} + (v \cos \theta_v)_{i,j-1} \right] U_{i,j-1} \right\}$$

$$+ \frac{(h_{i+1,j} + h_{i,j}) (\phi_{i+1,j} - \phi_{i,j})}{2a \cdot dx \cdot \cos \theta} - 2\Omega \sin \theta \overline{V_u}^{xy} - \frac{u}{a} \tan \theta \overline{V_u}^{xy}$$

$$LV = \frac{1}{4a \cdot dx \cdot \cos \theta} \left[(u_{i,j+1} + u_{i,j}) V_{i+1,j} - (u_{i-1,j+1} + u_{i-1,j}) V_{i-1,j} \right]$$

$$+ \frac{1}{4a \cdot dy \cdot \cos \theta} \left[v \cos \theta \left(V_{i,j+1} - V_{i,j-1} \right) + (vV \cos \theta)_{i,j+1} - (vV \cos \theta)_{i,j-1} \right]$$

$$+ \frac{(h_{i,j+1} + h_{i,j}) (\phi_{i,j+1} - \phi_{i,j})}{2a \cdot dy} + \Omega \frac{(U_{i,j+1} + U_{i-1,j+1}) \sin \theta_{u_{j+1}} + (U_{i,j} + U_{i-1,j}) \sin \theta_{u_{j}}}{2}$$

$$+ \frac{[(uU)_{i,j+1} + (uU)_{i-1,j+1}] \tan \theta_{u_{j+1}} + [(uU)_{i,j} + (uU)_{i-1,j}] \tan \theta_{u_{j}}}{4a}$$

$$LZ = \frac{1}{2a \cdot dx \cdot \cos \theta} \left[(h_{i+1,j} + h_{i,j}) U_{i,j} - (h_{i,j} + h_{i-1,j}) U_{i-1,j} \right]$$

$$+ \frac{1}{2a \cdot dy \cdot \cos \theta} \left[(h_{i,j+1} + h_{i,j}) (V \cos \theta)_{i,j} - (h_{i,j} + h_{i,j-1}) (V \cos \theta)_{i,j-1} \right]$$