```
1. < P > ::= < P > < E >
         2. < P > ::=
         3. < E > := < m > " = " < T > ";"
           \{E.v = meta\_map(m), meta\_body\_set\_uni(E.v, T.v)\}
         4. < T > := < T > "|" < C > \{ metabody_set_push(T_1.v, C.v), T.v = T_1.v \}
         5. < T > := < C > \{T.v = meta_body_set_new(), meta_body_set_push(T.v, C.v)\}
         6. < C > := < C > ", " < X > \{ meta\_body\_cat(C_1.v, X.v), C.v = C_1.v \}
         7. < C > := < X > \{C.v = X.v\}
         8. < X > ::= < X > "-" < F > \{ meta\_body\_sub(X_1.v, F.v), X.v = X_1.v \}
         9. < X > := < F > \{X.v = F.v\}
        10. \langle F \rangle := \langle m \rangle \{F.v = \text{meta\_body\_new}(), \text{meta\_body\_push\_n}(F.v, m)\}
       11. \langle F \rangle ::= \langle s \rangle \{F.v = \text{meta\_body\_new}(), \text{meta\_body\_push\_t}(F.v, s.v)\}
       12. < F > ::= \{F.v = meta\_body\_new()\}
\mathbf{First}(S) = \{ m \}
\mathbf{First}(P) = \{ m \}
\mathbf{First}(E) = \{ m \}
\mathbf{First}(T) = \{ m, f \}
\mathbf{First}(C) = \{ m, f \}
\mathbf{First}(X) = \{ m, f \}
\mathbf{First}(F) = \{ m, s \}
```

0. < S > := < P >

	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
	m	s	=		,	_	;	e	S	P	E	T	C	X	F
0	r2							r2		1					
1	s2							ac			15				
2			s3												
3	s9	s10		r12	r12	r12	r12					4	6	7	8
4				s16			s5								
5	r3							r3							
6				r5	s11		r5								
7				r7	r7	s12	r7								
8				r9	r9	r9	r9								
9				r10	r10	r10	r10								
10				r11	r11	r11	r11								
11	s9	s10		r12	r12	r12	r12							14	8
12	s9	s10		r12	r12	r12	r12								17
13				r4	s11		r4								
14				r6	r6	s12	r6								
15	r1							r1							
16	s9	s10		r12	r12	r12	r12						13	7	8
17				r8	r8	r8	r8								