

Learning Systems (DT8008)

- Overfitting and Generalization
- Ensemble Methods

Dr. Mohamed-Rafik Bouguelia mohamed-rafik.bouguelia@hh.se

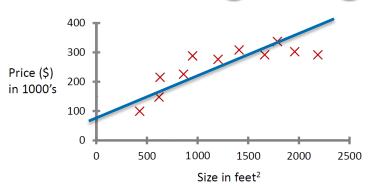
Halmstad University

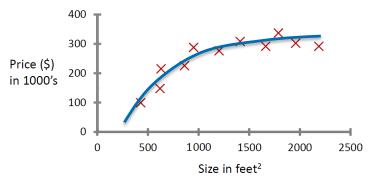
# The Problem of Overfitting

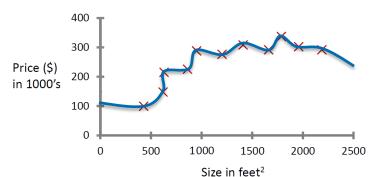
# The problem of overfitting - regression

Example: Linear regression (housing prices)

Which of these models do you think is a good model for this data?







$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

$$h_{\theta}(x) = \theta_0 + \theta_1 x + \theta_2 x^2$$

$$\begin{aligned} h_{\theta}(x) &= \theta_0 + \\ \theta_1 x + \theta_2 x^2 \\ &+ \theta_3 x^3 + \theta_4 x^4 \\ &+ \theta_5 x^5 + \theta_6 x^6 \\ &+ \theta_7 x^7 + \theta_8 x^8 \\ &+ \theta_9 x^9 + \theta_{10} x^{10} \end{aligned}$$



## The problem of overfitting - regression

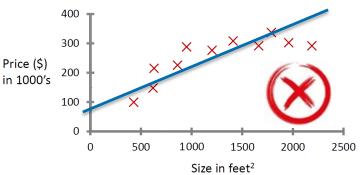
#### **Underfitting**

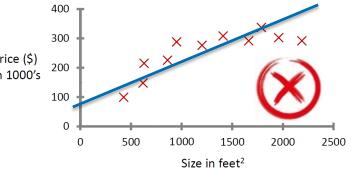
- The model has a high bias
- The model makes a strong assumption that the housing prices will vary linearly with their size, but ends up not fitting the training data well (poor fit).

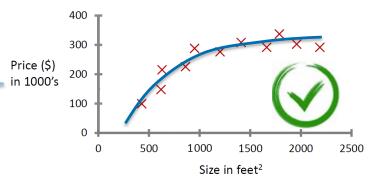
- Just right
- It fits the data pretty well

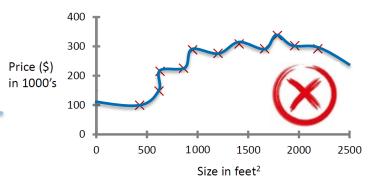
#### **Overfitting**

- The model has a high variance
  - The space of possible hypothesis functions of this order is too large (too variable), and we do not have enough data to construct a good hypothesis of this type.
- Seems to fit the training data perfectly, but will have very poor performance on new data. It has 0 error on the training data, but it does not generalize well.









#### Simple model

$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

#### More complex model

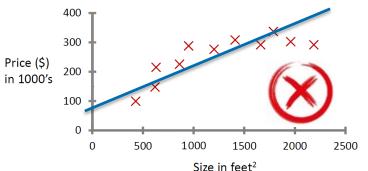
$$h_{\theta}(x) = \theta_0 + \theta_1 x + \theta_2 x^2$$

#### Much more complex model

$$h_{\theta}(x) = \theta_{0} + \theta_{1}x + \theta_{2}x^{2} + \theta_{3}x^{3} + \theta_{4}x^{4} + \theta_{5}x^{5} + \theta_{6}x^{6} + \theta_{7}x^{7} + \theta_{8}x^{8} + \theta_{9}x^{9} + \theta_{10}x^{10}$$

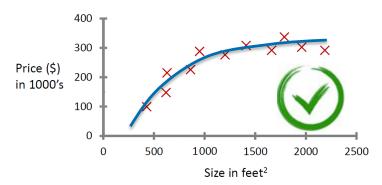
# The problem of overfitting - regression

Overfitting: If we have too many features, the learned model may fit the training set very well  $(E(\theta) = \frac{1}{n}\sum_{i=1}^{n} \left[h_{\theta}(x^{(i)}) - y^{(i)}\right]^{2} \approx 0)$ , but fails to generalize to new examples (predict prices on new examples).





$$h_{\theta}(x) = \theta_0 + \theta_1 x$$

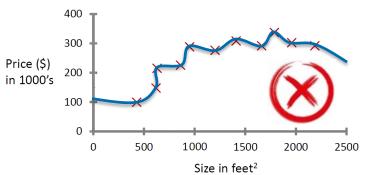


#### More complex model

$$h_{\theta}(x) = \theta_0 + \theta_1 x + \theta_2 x^2$$

#### Much more complex model

$$h_{\theta}(x) = \theta_{0} + \theta_{1}x + \theta_{2}x^{2} + \theta_{3}x^{3} + \theta_{4}x^{4} + \theta_{5}x^{5} + \theta_{6}x^{6} + \theta_{7}x^{7} + \theta_{8}x^{8} + \theta_{9}x^{9} + \theta_{10}x^{10}$$



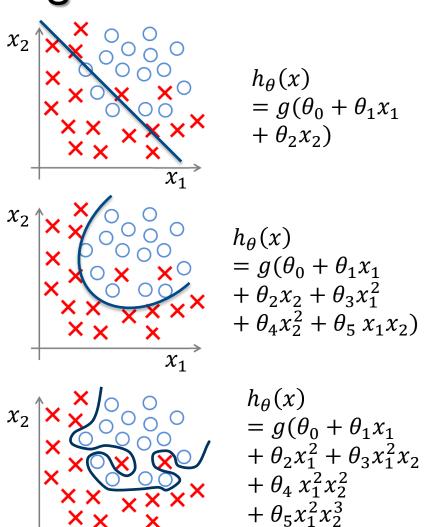


### The problem of overfitting - classification

Example: Classification (with Logistic Regression)

NOTE: *g* here is the sigmoid function.

Which of these models do you think is a good model for this data?



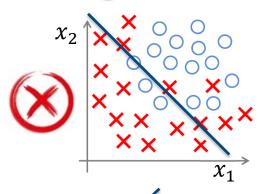
 $+ \theta_6 x_1^3 x_2 + \cdots)$ 

### The problem of overfitting - classification

Example: Classification (with Logistic Regression)

NOTE: *g* here is the sigmoid function.

Underfitting (high bias)

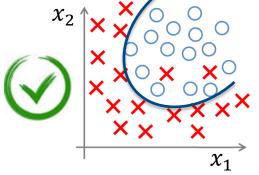


#### Simple model

$$h_{\theta}(x)$$

$$= g(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$$

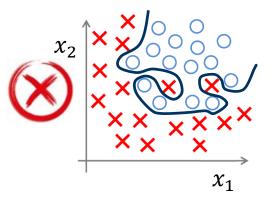
Ok



#### More complex model

$$h_{\theta}(x) = g(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1^2 + \theta_4 x_2^2 + \theta_5 x_1 x_2)$$

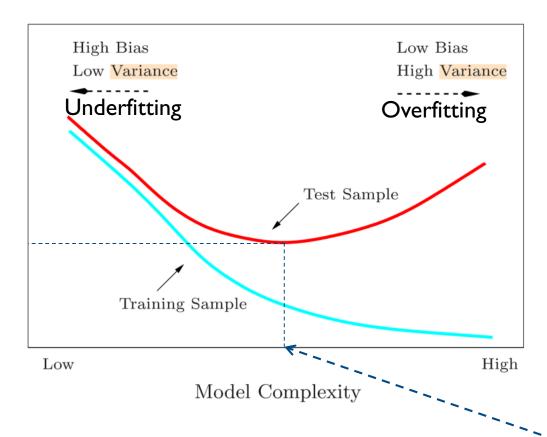
Overfitting (high variance)



#### Much more complex model

$$h_{\theta}(x)$$
=  $g(\theta_0 + \theta_1 x_1 + \theta_2 x_1^2 + \theta_3 x_1^2 x_2 + \theta_4 x_1^2 x_2^2 + \theta_5 x_1^2 x_2^3 + \theta_6 x_1^3 x_2 + \cdots)$ 

# The problem of overfitting



- What makes it more likely to overfit?
  - Not enough training examples (small training dataset)
  - Too many features
  - Using a non-convenient type of models / hypothesis functions (e.g. too much complex for our problem / data).

A good model complexity



### **Generalization Error**

### Generalization Error

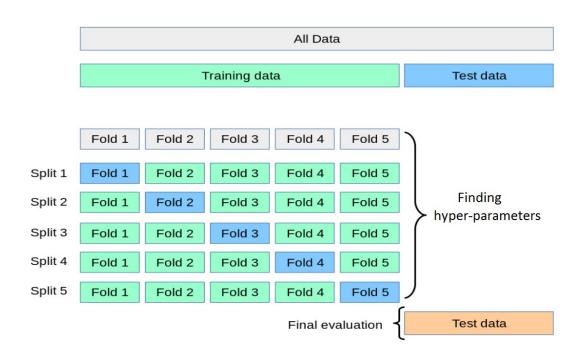
- The training error is the error of the model  $h_{ heta}$  on the training examples.
  - It is **not** an estimation for the error that the model  $h_{\theta}$  will have when deployed and applied on new data.
- The **generalization error** is the error of the model  $h_{\theta}$  on new (unseen) data.
  - The generalization error is typically higher than the training error.
- How do we estimate the generalization error of some model?
  - Using k-fold Cross Validation (k-CV)
  - Using Leave-One-Out estimate (LOO)
    - Same as k-CV with k = the number of examples.
    - LOO is better when the number of data-points in our dataset is small.



#### Generalization Error

#### Example of **k=5-fold cross validation**:

- Split the training dataset into 5 parts (folds).
- Each time, train a model on the training parts (green) and apply it on the remaining part (blue) to estimate the error.
- So, you will finally get 5 estimates of the error. The **generalization error** is the average of these 5 errors. In the case of classification, you can also compute the generalization accuracy the same way (accuracy% = 100 error%)



#### Leave-one-out cross validation:

- It is similar to the k-fold cross validation, but the training dataset is split into n parts, where n is the number of training samples. i.e., we leave one sample each time.
- It is useful when you have a small training dataset (i.e. when n is small).

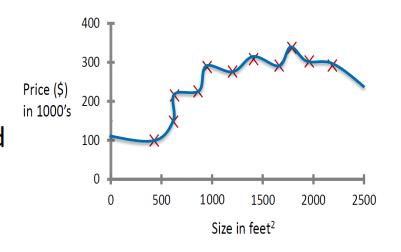


# Addressing overfitting

# Addressing overfitting

- It becomes hard to visualize the data and the model when we have more than 2 or 3 features.
  - So how can we avoid overfitting?

```
x_1 =  size of house x_2 =  no. of bedrooms x_3 =  no. of floors x_4 =  age of house x_5 =  average income in neighborhood x_6 =  kitchen size \vdots
```





 $x_{100}$ 

# Addressing overfitting

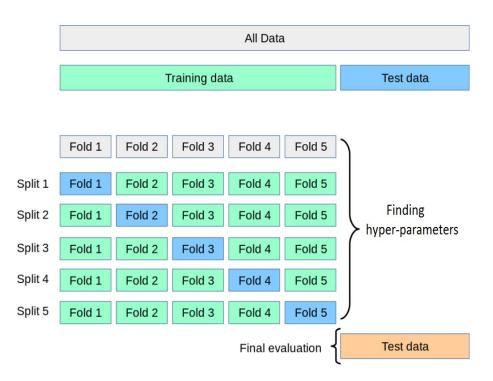
- I. Model selection / hyperparameters tuning (this lecture)
  - You can try various models of different complexity (e.g. with various hyperparameters values), compute the generalization error for each of them (as explained previously), and keep the best hyperparameters.
- 2. Reducing the number of features (this lecture)
  - We are more likely to overfit when the number of features is high (relatively to the size of the dataset).
    - Manually select which features to keep / remove
    - · Or using feature selection algorithms
- 3. Using an ensemble methods (this lecture)
- 4. Using regularization (next lecture)
  - Keep all features, but reduce the magnitude / values of parameters  $heta_j$
  - Works well when we have a lot of features, and each feature contributes a bit to predicting y



# I. Hyper-parameters Tuning

# Hyperparameters Tuning

- Most ML algorithm has hyperparameters that lead to a more or less complex model.
  - e.g. the K in the KNN algorithm, is a hyperparameter.
- To find the values of hyperparameters that lead to a good model (not too simple, not too complex), we need to:
  - 1. Pick some values for our hyperparameters.
  - 2. Compute the generalization error using a 10-fold-cross-validation.
  - 3. Repeat steps I and 2 (with various values for the hyperparameters).
  - 4. Keep the hyperparameters that gave you to the smallest generalization error; and train a model on the whole training set using those hyperparameters.
  - 5. You can now test your trained model on the test data (see figure) to see how it will perform when deployed in real-world.



# Comparing two models

- Suppose that you want to compare two regression algorithms A and B.
- Suppose that, when you performed a 10-fold-cross-validation on A and B, you got the following MSE error estimates:
  - For A: [0.6, 0.1, 1.1, 1.3, 0.3, 3.2, 3.2, 0.9, 1.3, 1.1]. The average is  $\mu_A = 1.31$ . The stdev is  $\sigma_A = 1.01$
  - For B: [3.3, 0.6, 5, 12.4, 1.2, 5.8, 8.6, 0.4, 0.5, 4.35]. The average is  $\mu_B = 4.21$ . The stdev is  $\sigma_B = 3.75$
- Which model is the best?
  - Model A is better than model B as it achieves a smaller generalization error than B ( $\mu_A < \mu_B$ ).
- Is A significantly better than B?
  - To answer this question we need to do some statistical tests. One such test (Wilcoxon test) uses the standard deviations  $\sigma_A$ ,  $\sigma_B$  and compares the means  $\mu_A$ ,  $\mu_B$  to check if:

$$|\mu_A - \mu_B| > 1.96 \frac{\sigma_{AB}}{\sqrt{K}}$$
 where  $\sigma_{AB} = \sqrt{\sigma_A^2 + \sigma_B^2}$  and K=10 folds in this example.

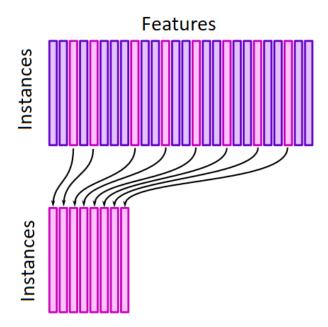
→ If true, then the results achieved by A and B are significantly different (i.e. A significantly better), otherwise not (i.e. A not significantly better).



### 2. Features Selection

#### Motivation behind features selection

- Why? To reduce overfitting which arises
  - when we have a regular data set (with enough data-points), but too flexible model
  - or when we have a high-dimensional dataset with not enough data.
- Datasets with thousands or millions of features are quite usual these days. We want to choose only those, which are needed to construct simpler, faster, and more accurate models.





# Simple (naïve) feature selection

- Removing features with low variance:
  - One very simple (and unsupervised) way to do feature selection is to remove features with low variance.
- Motivating example:
  - Suppose that we have a feature that have the same value in all samples (i.e. a column of X which has a constant value)
  - Such feature would be useless because it doesn't help differencing between samples.
  - It will have a variance of 0, and will therefore be removed.

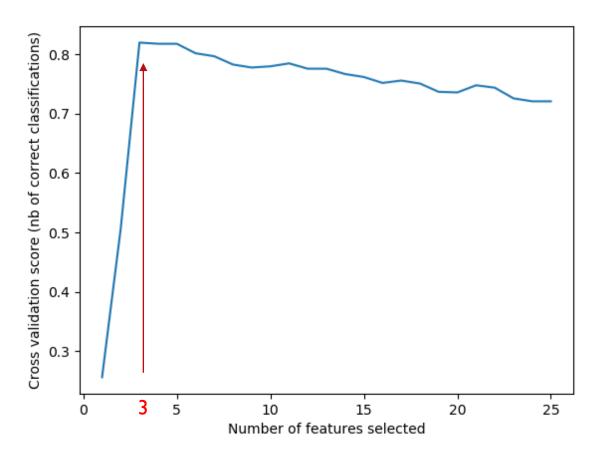
### Recursive feature elimination

- Suppose that we have a model that assigns weights to features (e.g., the coefficients  $\theta$  of a linear model)
  - $h_{\theta}(x) = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_3 + \dots + \theta_d x_d$  (it's a weighted sum of the features).
  - Features  $x_i$  that have small coefficients  $\theta_i$  are considered less important.
- In the *recursive feature elimination* we select features by recursively considering smaller and smaller sets of features, as follows:
  - We train a model using the initial set of features.
  - We obtain the importance of each feature (e.g. through the coefficients  $\theta$  if it's a linear model).
  - We remove the least important features from current set of features.
  - We repeat this procedure recursively until the desired number of features to select is reached.
- The selection of the best number of features to keep (i.e. the stopping criteria) can be done using cross-validation.



### Recursive feature elimination

• A recursive feature elimination example with automatic tuning of the number of features selected with cross-validation.



In this example, the optimal number of features was 3.

### Tree-based feature selection

- Some classification or regression models such as tree-based models (decision trees, random forest ...) can be used to compute features importance.
- This is can be used to discard irrelevant features.
- Example with the scikit-learn (sklearn) library in Python:

```
>>> from sklearn.ensemble import DecisionTreeClassifier
...
>>> clf = DecisionTreeClassifier(n_estimators=50)
>>> clf = clf.fit(X, y)
>>> clf.feature_importances_
array([ 0.04...,  0.05...,  0.4...])
```

### **Ensemble Methods**

#### Ensemble methods

#### Wisdom of the crowd

- Instead of using a single model, why not using several models at once.
  - An ensemble (also called committee) is a set of models (classifiers or regressors) whose individual decisions are combined in some way to predict the output of new examples.
- Diversity vs accuracy:
  - The individual classifiers composing an ensemble must be
    - better than random
    - and diverse (i.e. they make different errors on new data points).
  - An ensemble of classifiers must be more accurate than any of its individual members.



### Ensemble methods – Motivating example

- We have 3 individual taggers who tag each word as
  - V (Verb), N (Noun), DT (Determiner), or PN (Pronoun)
- The taggers are diverse (i.e. they make different errors) but each of them is better than random (i.e. weak predictors).

	Bob	gave	Alice	the	key	ACC.
Tagger I	V	V	N	DT	N	0.8
Tagger 2	N	N	V	DT	N	0.6
Tagger 3	N	V	N	PN	N	0.8
Majority	N	V	N	DT	N	1.0

- Average accuracy  $\approx 0.73$ . Majority accuracy = 1.0
- Majority vote is better than individual models



### Ensemble methods

- No Free Lunch Theorem:
  - There is **no** algorithm that is always the most accurate in all situations.

 Generate a group of base-learners which when combined has higher accuracy.

### Ensemble methods

- How do we generate a diverse set of baselearners (models) that complement each other?
  - e.g. using Bagging and Boosting
    - Generate new datasets by sampling from the original dataset uniformly at random (with replacement), and with different subsets of features ...

- How do we combine the outputs of base learner for maximum accuracy?
  - Voting
  - Weighted combination of the outputs ...



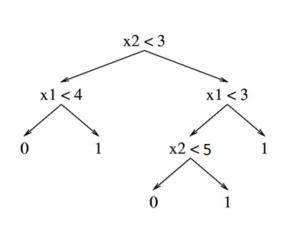
# Ensemble Methods: Random Forest

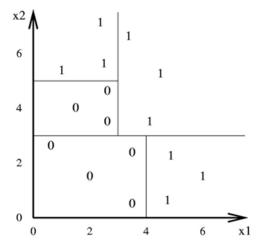
hh.se

#### Reminder about Decision Tree

- Random forest is an ensemble of decision trees.
  - Reminder about decision trees:
    - Here is an example of a possible decision tree:
- Outlook Each internal node: test one feature  $x_i$ Overcast Rain Sunny Each branch from a node: selects one value (or interval) for  $x_i$ Humidity Yes Wind Each leaf node: predict the output. Weak High Normal Strong

#### Reminder about Decision Tree





Entropy = 
$$-\sum_{i=1}^{c} p_i \log_c p_i$$

where c is the number of classes (2 in this example),  $p_i$  is the proportion of samples from the  $i^{th}$  class, and  $log_c$  is the with log base c.

- For each node, we find the feature  $x_i$  and a threshold value on that feature, that splits the samples assigned to the node into two subsets so that the label purity (i.e. homogeneity) within these subsets is maximized.
- The homogeneity is measured using (e.g.) entropy:
  - If a subset is completely homogeneous the entropy is zero.
  - If a subset is equally divided (has same proportion of different labels) then it has entropy of one.

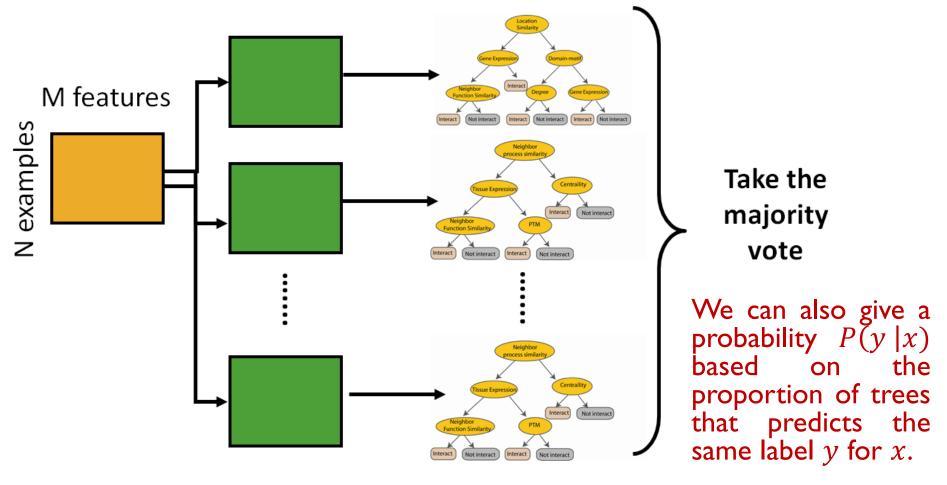
H

#### Simplified Algorithm

- Choose T: the number of trees in the ensemble.
- Choose  $m' < m \pmod{m}$  is the number of total features): m' is the number of features used to calculate the best split at each node (typically 20%).
- For each tree
  - Choose a training set by choosing n times (n is the number of training examples) with replacement from the training set.
  - For each node, randomly choose m' features and calculate the best split (e.g. based on the entropy measure).
- Use majority voting among all the trees to predict.

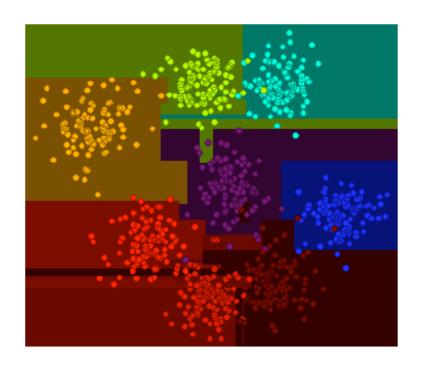


Collection of diverse trees based on various subsets of samples and features ...

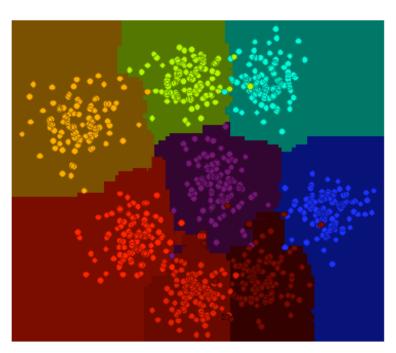


### One Tree vs. Random Forest

#### Decision boundary:



with one Tree



RF with 100 Trees

### Random Forest and Features Importance

- Random Forest can compute the importance of each feature.
   So, it can be used for feature selection.
- This is done using the mean decrease impurity:
  - As we know, Random Forest consists of a number of decision trees:
    - Every node in the decision trees is a condition on a single feature, designed to split the dataset into two sets.
    - The measure based on which the (locally) optimal split (condition) is chosen is called impurity (e.g. based on entropy, or information gain, or Gini impurity).
    - Thus when training a tree, it can be computed how much each feature decreases the weighted impurity in a tree.
  - For the forest, the impurity decrease from each feature can be averaged and the features are ranked according to this measure.



# Summary

 It is often a good idea to combine several learning methods.

 We want diverse classifiers, so their errors cancel out.

 However, remember, ensemble methods do not get free lunch too ...