Department of Electrical and Computer Engineering NYU Tandon School of Engineering Brooklyn, New York

July 15, 2020



Regularization

## Outline

- 1 Review of Day 2
- 2 Polynomial Fitting
- 3 Regularization
- 4 Non-linear Optimization



- For the Boston housing dataset we have the following information in the data:
- 'CRIM', 'ZN', 'INDUS', 'CHAS', 'NOX', 'RM', 'AGE', 'DIS', 'RAD', 'TAX', 'PTRATIO', 'B', 'LSTAT', 'PRICE'
- What is the feature and label if we want to estimate price?
- What is the feature and label if we want to estimate RM? (RM: average number of rooms per dwelling)



- You have a bunch of photos of 6 people but without information about who is on which one and you want to divide this dataset into 6 piles, each with the photos of one individual.
- You have a bunch of molecules and information about which are drugs and you train a model to answer whether a new molecule is also a drug.
- (Credit to lejlot)



- You have a large inventory of identical items, you want to predict how many you can sell in the next 3 months.
- You want a software to examine individual costumer's account and for each account decide if it has been hacked.
- (Credit to Andrew Ng)



$$y = ax + b$$

bias

intercept

Loss: 
$$\frac{1}{N} \sum_{i=1}^{N} || y_i - \hat{y}_i ||^2 = || Y - x_i ||$$

$$= \frac{W_0 + W_1 \times i}{W_1 - X_i}$$

$$= \frac{U_0 \cdot 1}{V_1 - X_i} + \frac{W_1 - X_i}{V_1}$$

$$= \frac{U_1 \times 2}{V_1 \times 2}$$

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$$\frac{1}{N} = \frac{1}{|Y_1 - \hat{Y}_1||^2} \qquad \text{for } i \text{ in } (I - N)$$

$$= \frac{1}{N} \left( \frac{|Y_1 - \hat{Y}_1||^2}{|Y_1 - \hat{Y}_1||^2} \right) \qquad \text{for } i \text{ in } (I - N)$$

$$= \frac{1}{N} \left( \frac{|Y_1 - \hat{Y}_1|| + |I_1 \hat{Y}_2 - \hat{Y}_2|| + \dots}{|Y_N - \hat{Y}_N||^2} \right) \qquad \text{for } i \text{ in } (I - N)$$

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$$= \frac{1}{N} \left( \frac{|Y_1 - \hat{Y}_1|| + \dots}{|Y_N - \hat{Y}_N|| + \dots} \right) \qquad \text{for } i$$

$$= \frac{1}{N} \left[ \left( \begin{array}{c} y_1 - \hat{y}_1 \\ y_2 - \hat{y}_2 \end{array} \right) \right] \left[ \begin{array}{c} y_1 \\ y_2 - \hat{y}_2 \end{array} \right] \left[ \begin{array}{c} y_1 \\ y_2 \end{array} \right]$$

$$= \frac{1}{N} \left( \left( y_1 - \hat{y}_1 \right) + \left( y_2 - \hat{y}_2^2 \right) + \dots + \left( y_n - \hat{y}_n \right)^2 \right)$$

$$(x^{T}x)^{T}x^{T}) = w$$

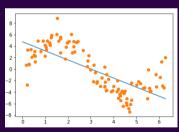
$$= x^{T}y = x^{T}y = w$$

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- We have been using straight lines to fit our data. But it doesn't work well every time
- Some data have more complex relation that cannot be fitted well using a straight line



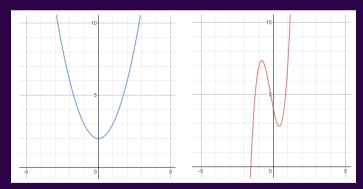
■ Can we use some other model to fit this data?





- Can we use a polynomial to fit our data?
- Polynomial: A sum of different powers of a variable

■ Examples: 
$$y = x^2 + 2$$
,  $y = 5x^3 - 3x^2 + 4$ 



- Polynomials of x:  $\hat{y} = w_0 + w_1 x + w_2 x^2 + w_3 x^3 + \cdots + w_M x^M$
- lacktriangleq M is called the order of the polynomial.
- The process of fitting a polynomial is similar to linearly fitting multivariate data.

■ Rewrite in matrix-vector form

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} \approx \begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^M \\ 1 & x_2 & x_2^2 & \cdots & x_2^M \\ \vdots & \ddots & & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^M \end{bmatrix} \begin{bmatrix} w_0 \\ w_1 \\ \vdots \\ w_M \end{bmatrix}$$

■ This can still be written as

$$Y \approx X \mathbf{w}$$

- Loss  $J(\mathbf{w}) = \frac{1}{N} \|Y X\mathbf{w}\|^2$
- The i-th row of the design matrix X is simply a transformed feature  $\phi(x_i) = (1, x_i, x_i^2, \dots, x_i^M)$



■ Original design matrix: 
$$\begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix}$$
■ Design matrix after feature transform

■ Design matrix after feature transformation:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \cdots & x_1^M \\ 1 & x_2 & x_2^2 & \cdots & x_2^M \\ \vdots & \ddots & & \vdots \\ 1 & x_N & x_N^2 & \cdots & x_N^M \end{bmatrix}$$

■ For the polynomial fitting, we just added columns of features that are powers of the original feature



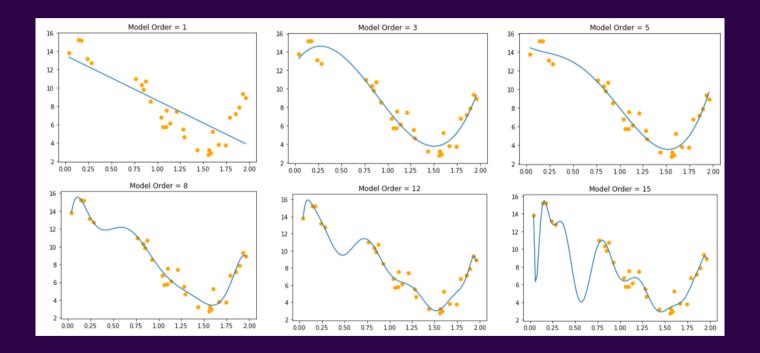
- lacksquare Model  $\hat{y} = \mathbf{w}^T \phi(\mathbf{x})$
- Loss  $J(\mathbf{w}) = \frac{1}{N} \|Y X\mathbf{w}\|^2$
- Find w that minimizes  $J(\mathbf{w})$

# Overfitting

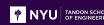
- We learned how to fit our data using polynomials of different order
- With a higher model order, we can fit the data with increasing accuracy
- As you increase the model order, at certain point it is possible find a model that fits your data perfectly (ie. zero error)
- What could be the problem?



## Overfitting



■ Which of these model do you think is the best? Why?





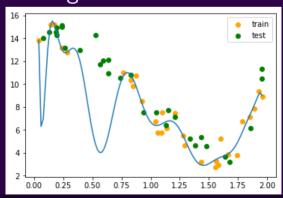
## Demo

 $Open\ demo\_fit\_polynomial.ipynb$ 



## Overfitting

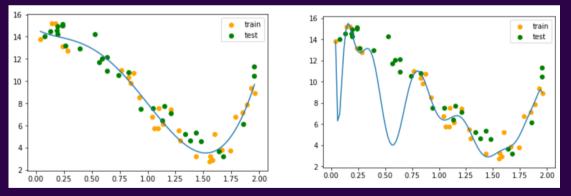
- The problem is that we are only fitting our model using data that is given
- Data usually contains noise
- When a model becomes too complex, it will start to fit the noise in the data
- What happens if we apply our model to predict some data that the model has never seen before? It will not work well.
- This is called over-fitting





## Overfitting

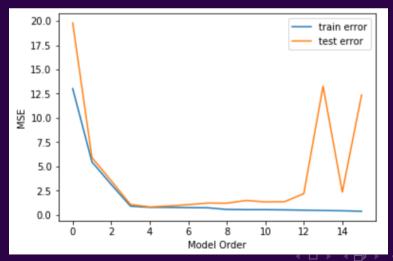
- Split the data set into a train set and a test set
- Train set will be used to train the model
- The test set will not be seen by the model during the training process
- Use test set to evaluate the model when a model is trained



■ With the training and test sets shown, which one do you think is the better model now?

#### Train and Test Error

- Plot of train error and test error for different model order
- Initially both train and test error go down as model order increase
- But at a certain point, test error start to increase because of overfitting





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How can we prevent overfitting without knowing the model order before-hand?

■ **Regularization**: methods to prevent overfitting



Regularization

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- **Regularization**: methods to prevent overfitting
  - We just covered regularization by model order selection



Review

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- **Regularization**: methods to prevent overfitting
  - We just covered regularization by model order selection
- Is there another way? Talk among your classmates.



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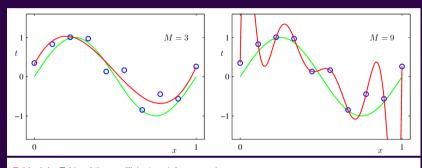
# How can we prevent overfitting without knowing the model order before-hand?

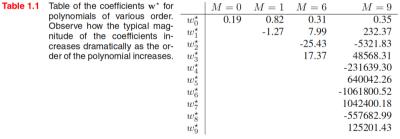
- **Regularization**: methods to prevent overfitting
  - We just covered regularization by model order selection
- Is there another way? Talk among your classmates.
  - Solution: We can change our cost function.



### Weight Based Regularization

- Looking back at the polynomial overfitting
- Notice that weight-size increases with overfitting









#### **New Cost Function**

$$J(\mathbf{w}) = \frac{1}{N} \|Y - X\mathbf{w}\|^2 + \lambda \|\mathbf{w}\|^2$$

- Penalize complexity by simultaneously minimizing weight values.
- We call  $\lambda$  a hyper-parameter
  - lacktriangle  $\lambda$  determines relative importance

Table 1.2	Table of the coefficients $\mathbf{w}^{\star}$ for $M=9$ polynomials with various values for the regularization parameter $\lambda$ . Note that $\ln \lambda = -\infty$ corresponds to a model with no regularization, i.e., to the graph at the bottom right in Figure 1.4. We see that, as the value of

	$\ln \lambda = -\infty$	$\ln \lambda = -18$	$\ln \lambda = 0$
$w_0^{\star}$	0.35	0.35	0.13
$w_1^{\star}$	232.37	4.74	-0.05
$w_2^{\star}$	-5321.83	-0.77	-0.06
$w_3^{\star}$	48568.31	-31.97	-0.05
$w_4^{\star}$	-231639.30	-3.89	-0.03
$w_5^{\star}$	640042.26	55.28	-0.02
$w_6^{\star}$	-1061800.52	41.32	-0.01
$w_7^{\star}$	1042400.18	-45.95	-0.00
$w_8^\star$	-557682.99	-91.53	0.00
$w_9^\star$	125201.43	72.68	0.01
	'		





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- Motivation: never determine a hyper-parameter based on training data
- **Hyper-Parameter**: a parameter of the algorithm that is not a model-parameter solved for in optimization.
  - $\blacksquare$  Ex:  $\lambda$  weight regularization value vs. model weights (**w**)
- Solution: split dataset into three
  - Training set: to compute the model-parameters (w)
  - Validation set: to tune hyper-parameters  $(\lambda)$
  - **Test set**: to compute the performance of the algorithm (MSE)



Open demo\_overfitting\_regularization.ipynb



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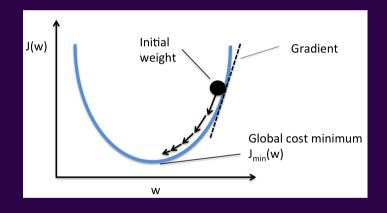


#### Motivation

- Cannot rely on closed form solutions
  - Computation efficiency: operations like inverting a matrix is not efficient
  - For more complex problems such as neural networks, a closed-form solution is not always available
- Need an optimization technique to find an optimal solution
  - Machine learning practitioners use **gradient**-based methods

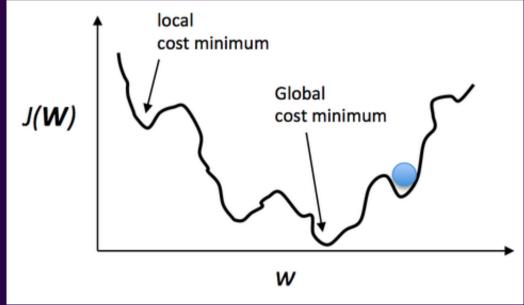


■ Update Rule Repeat {  $\mathbf{w}_{new} = \mathbf{w} - \alpha \nabla J(\mathbf{w})$  $\alpha$  is the learning rate



#### General Loss Function Contours

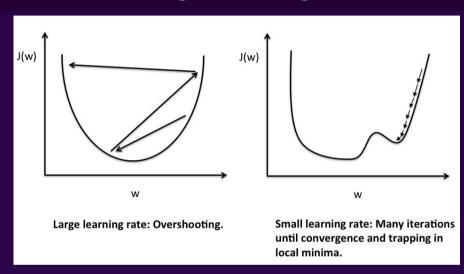
- Most loss function contours are not perfectly parabolic
- Our goal is to find a solution that is very close to global minimum by the right choice of hyper-parameters

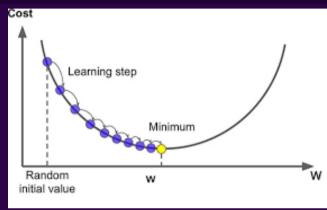






## Understanding Learning Rate





**Correct learning rate** 





## Some Animations

■ Demonstrate gradient descent animation



# Importance of Feature Normalization (Optional)

■ Helps improve the performance of gradient based optimization

