

# Design Assignment 5

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Primary Github address: [https://github.com/DylanCaz/Submission\\_DA](https://github.com/DylanCaz/Submission_DA)

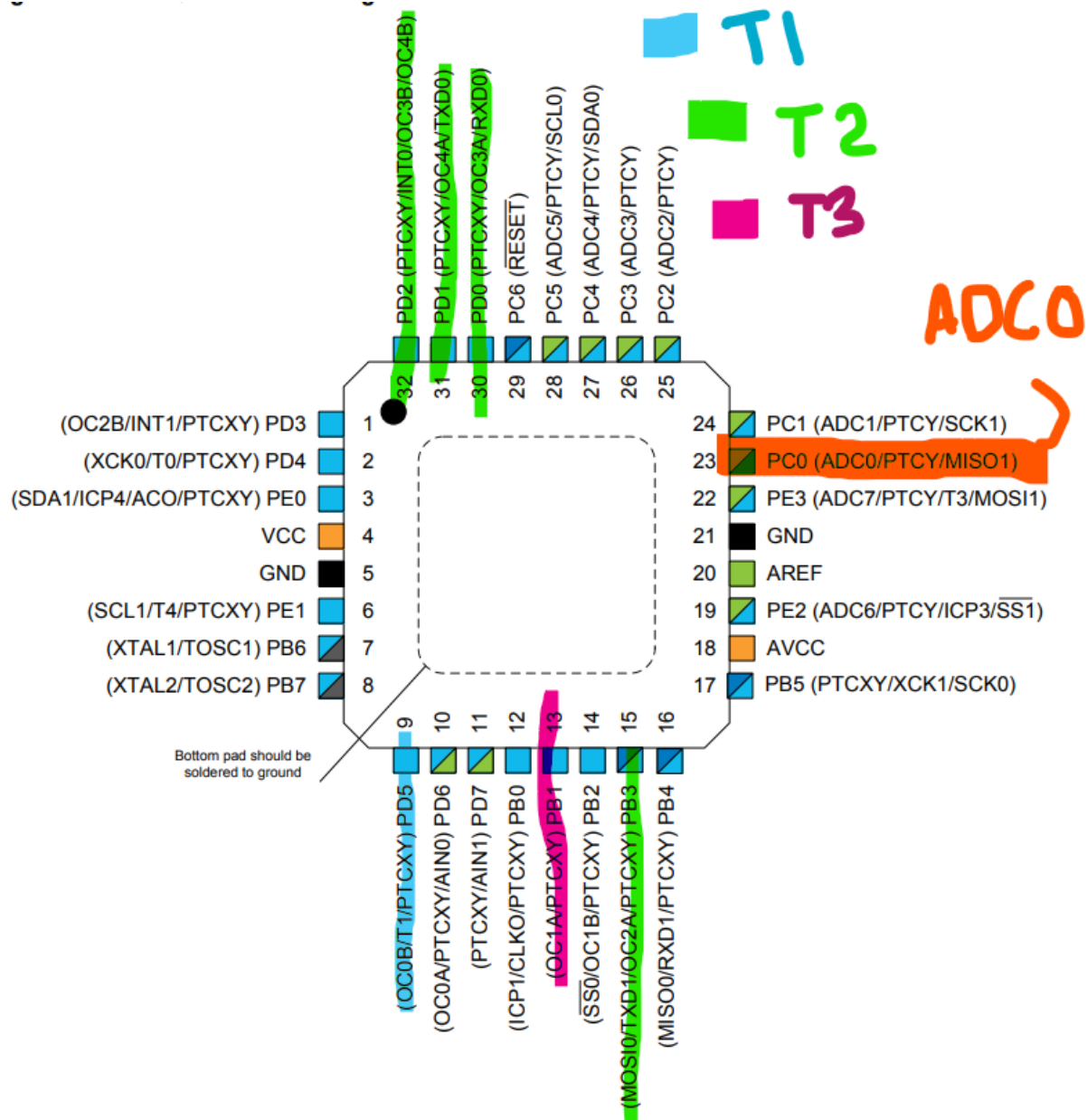
Directory:

[https://github.com/DylanCaz/Submission\\_DA/tree/main/Design\\_Assignments\\_sub/DA\\_5\\_sub](https://github.com/DylanCaz/Submission_DA/tree/main/Design_Assignments_sub/DA_5_sub)

Submit the following for all Labs:

1. In the document, for each task submit the modified or included code (only) with highlights and justifications of the modifications. Also, include the comments.
2. Use the previously create a Github repository with a random name (no CPE/301, Lastname, Firstname). Place all labs under the root folder ESD301/DA, sub-folder named LABXX, with one document and one video link file for each lab, place modified asm/c files named as LabXX-TYY.asm/c.
3. If multiple asm/c files or other libraries are used, create a folder LabXX-TYY and place these files inside the folder.
4. The folder should have a) Word document (see template), b) source code file(s) and other include files, c) text file with youtube video links (see template).

## 1. COMPONENTS LIST AND CONNECTION BLOCK DIAGRAM w/ PINS



## 2. DEVELOPED CODE OF TASK 1

```

/*****
Dylan Cazares
CPE301 - Design Assignment 5
Task 1
*****/
#define F_CPU 16000000UL
#include <avr/io.h>
#include <util/delay.h>
void adc_init(void);

```

```

void read_adc(void);
void timer_init(void);
float duty;

int main(void)
{
    DDRD |= (1 << 5) ; // setting PD5 PD6 as an output
    timer_init();
    adc_init();
    while (1)
    {
        read_adc(); // read Potentiometer Value
        duty = (ADC/1023.0) * 155.0; // scale for percentage
        OCR0B = duty;
        // ClockWise
        PORTD |= (1 << 5);
    }
}

void adc_init(void)
{
    ADMUX |= (0 << REFS1) | // Reference Selection Bits
    (1 << REFS0) | // AVCC with external capacitor at AREF pin
    (0 << ADLAR) | // Left adjusts
    (0 << MUX3) | (0 << MUX2) | (0 << MUX1) | (0 << MUX0); // Channel 0 (PC0)

    ADCSRA = (1 << ADEN) | // ADC Enable
    (0 << ADSC) | // ADC Start Conversion
    (0 << ADIF) | // ADC Auto Trigger Enable
    (0 << ADIF) | // ADC Interrupt Flag
    (0 << ADIE) | // ADC Interrupt Enable
    (1 << ADPS2) | (0 << ADPS1) | (1 << ADPS0); // prescaler 64
}

void read_adc(void)
{
    ADCSRA |= (1 << ADSC);
    while(ADCSRA & (1 << ADSC));
}

void timer_init(void)
{
    //FAST PWM
    TCCR0A =
    (0 << COM0A1) | // Normal Port Operation
    (0 << COM0A0) | // Normal Port Operation
    (1 << COM0B1) | // Clear OC0A on Compare Match
    (0 << COM0B0) | // Set OC0A at Bottom (non-inverting mode)
    (1 << WGM01) | (1 << WGM00); // Fast PWM Mode
    TCCR0B =
    (0 << FOC0A) | // Input Capture Noise Canceler
    (0 << FOC0B) | // Input Capture Edge Select
    (1 << WGM02) | // Top = OCRA,
    (1 << CS02) | (0 << CS01) | (1 << CS00); // Prescaler 1024
    OCR0A = 155; // FOCnx = 100Hz
}

```

### 3. DEVELOPED CODE OF TASK 2

```

/*****
Dylan Cazares
CPE301 - Design Assignment 5
Task 2
*****/

#define F_CPU 16000000UL
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>
void adc_init(void);
void read_adc();
void timer_init();
int main(void)
{
    DDRD |= 0x0F; // Set PD0, PD1, PD2, PD3 as an Output
    timer_init();
    adc_init();
    while (1)
    {
        read_adc();
        // 100ms period at lowest ADC val
        OCR1A = (((ADC) * (3124.0)) / (1023.0));
        if((PIND & 0x10) == 0x10){
            PORTD = 0x09;
            while((TIFR1 & 0x2) != 0x2); // OCF1A (Wait for flag to match)
            TIFR1 |= (1 << OCF1A); // Clear flag
            PORTD = 0x03;
            while((TIFR1 & 0x2) != 0x2);
            TIFR1 |= (1 << OCF1A);
            PORTD = 0x06;
            while((TIFR1 & 0x2) != 0x2);
            TIFR1 |= (1 << OCF1A);
            PORTD = 0x0C;
            while((TIFR1 & 0x2) != 0x2);
            TIFR1 |= (1 << OCF1A);
        }
        else
        {
            PORTD = 0x0C;
            while((TIFR1 & 0x2) != 0x2);
            TIFR1 |= (1 << OCF1A);
            PORTD = 0x06;
            while((TIFR1 & 0x2) != 0x2);
            TIFR1 |= (1 << OCF1A);
            PORTD = 0x03;
            while((TIFR1 & 0x2) != 0x2);
            TIFR1 |= (1 << OCF1A);
            PORTD = 0x09;
            while((TIFR1 & 0x2) != 0x2);
            TIFR1 |= (1 << OCF1A);
        }
    }
}

void adc_init(void)
{
    ADMUX =

```

```

    (0 << REFS1) | (1 << REFS0) | // AVCC w/ external cap at AREF pin
    (0 << ADLAR) | // ADC Left Adjust Result
    (0 << MUX3) | (0 << MUX2) | (0 << MUX1) | (0 << MUX0); // Channel ADC0
    ADCSRA =
    (1 << ADEN) | // ADC Enable
    (0 << ADSC) | // ADC Start Conversion Disable
    (0 << ADATE) | // ADC Auto Trigger Disable
    (0 << ADIF) | // ADC Interrupt Flag Disable
    (0 << ADIE) | // ADC Interrupt Disable
    (1 << ADPS2) | (1 << ADPS1) | (1 << ADPS0); // Prescaler 128
}
void read_adc()
{
    ADCSRA |= (1 << ADSC); // Start ADC conversion
    while(ADCSRA & (1 << ADSC));
}
void timer_init()
{
    TCCR1B |= (1 << WGM12) | (1 << CS12); // Prescaler 256, CTC Mode
}

```

#### 4. DEVELOPED CODE OF TASK 3

/\*\*\*\*\*

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CPE301 - Design Assignment 5

Task 3

\*\*\*\*\*/

```
#define F_CPU 16000000UL
```

```
#include <avr/io.h>
```

```
#include <util/delay.h>
```

```
void adc_init(void);
```

```
void read_adc(void);
```

```
void timer_init(void);
```

```
int main(void)
```

```

{
    DDRB = (1 << 1); // Setting PB1 as an output
    adc_init();
    timer_init();
    while (1)
    {
        read_adc();
        OCR1A = 0.48 * ADC + 150;
    }
}

```

```
void adc_init(void)
```

```

{
    ADMUX =
    (0 << REFS1) | (1 << REFS0) | // AVCC w/ external cap at AREF pin
    (0 << ADLAR) | // ADC Left Adjust Result
    (0 << MUX3) | (0 << MUX2) | (0 << MUX1) | (0 << MUX0); // Channel ADC0
    ADCSRA =
    (1 << ADEN) | // ADC Enable
    (0 << ADSC) | // ADC Start Conversion Disable
    (1 << ADATE) | // ADC Auto Trigger Disable
    (0 << ADIF) | // ADC Interrupt Flag Disable

```

```

    (1 << ADIE) | // ADC Interrupt Enable
    (1 << ADPS2) | (1 << ADPS1) | (1 << ADPS0); // Prescaler 128

    ADCSRB = 0x00; //set auto trigger to free running mode
}
void read_adc(void)
{
    ADCSRA |= (1 << ADSC); // Start ADC conversion
}
void timer_init(void)
{
    TCCR1A |=
    (1 << COM1A1) | // Clear OC1A on compare match
    (0 << COM1A0) | // Clear OC1A on compare match
    (1 << COM1B1) | // Clear OC1B on compare match
    (0 << COM1B0) | // Clear OC1B on compare match
    (1 << WGM11) | // Mode Selection bits
    (0 << WGM10); // PWM mode

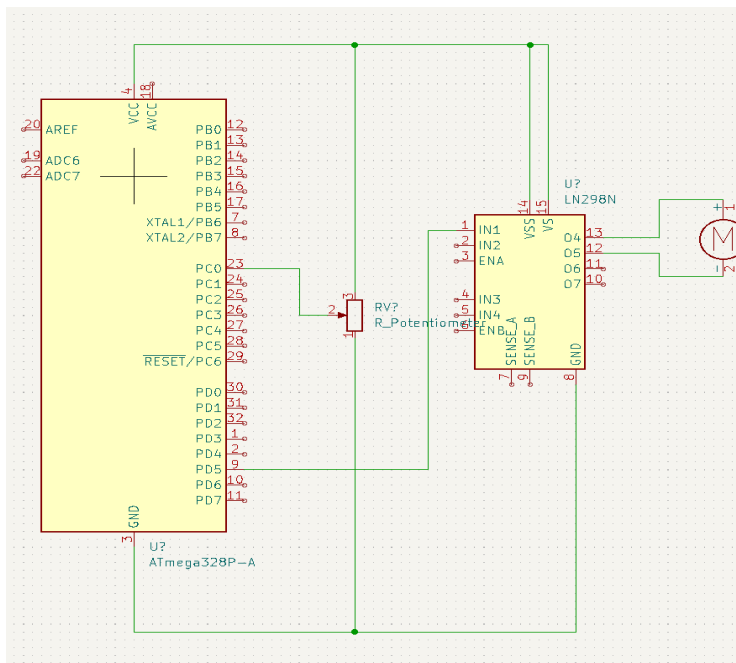
    TCCR1B |=
    (0 << ICNC1) | // Input Capture Noise Canceler
    (0 << ICES1) | // Input Capture Edge Select
    (1 << WGM13) | //Waveform Generation Mode
    (1 << WGM12) | //Fast PWM Mode
    (0 << CS12) | // Clock Select
    (1 << CS11) | // Prescaler = 64
    (1 << CS10);

    ICR1 = 4999; // Period = 20ms (50Hz)
    OCR1A = 150;
}

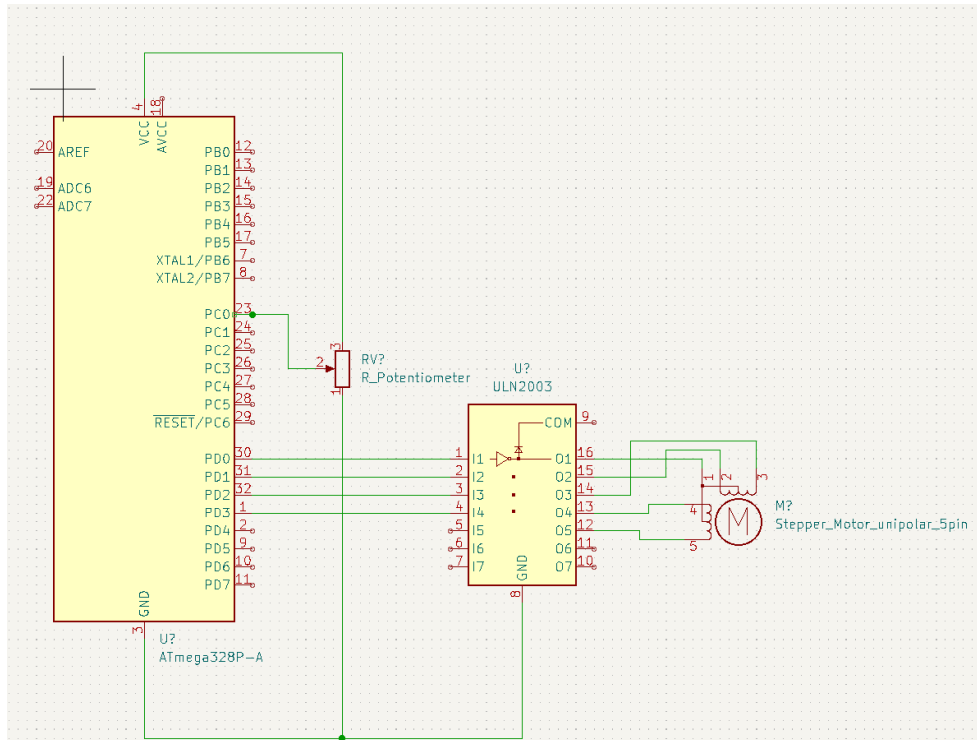
```

## 5. SCHEMATICS

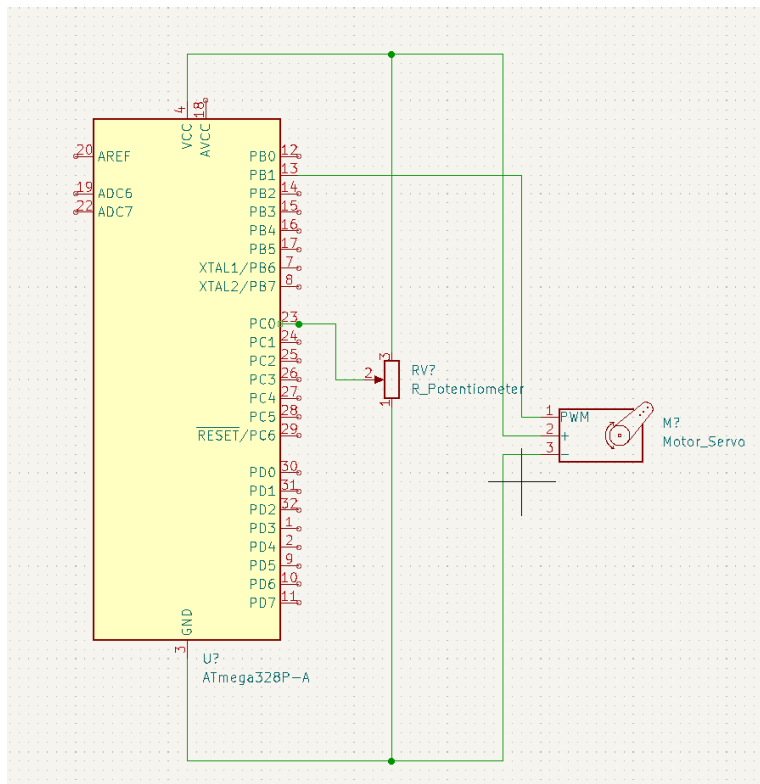
### Task 1



## Task 2



## Task 3



## Task 1

[illegible]

## Task 2

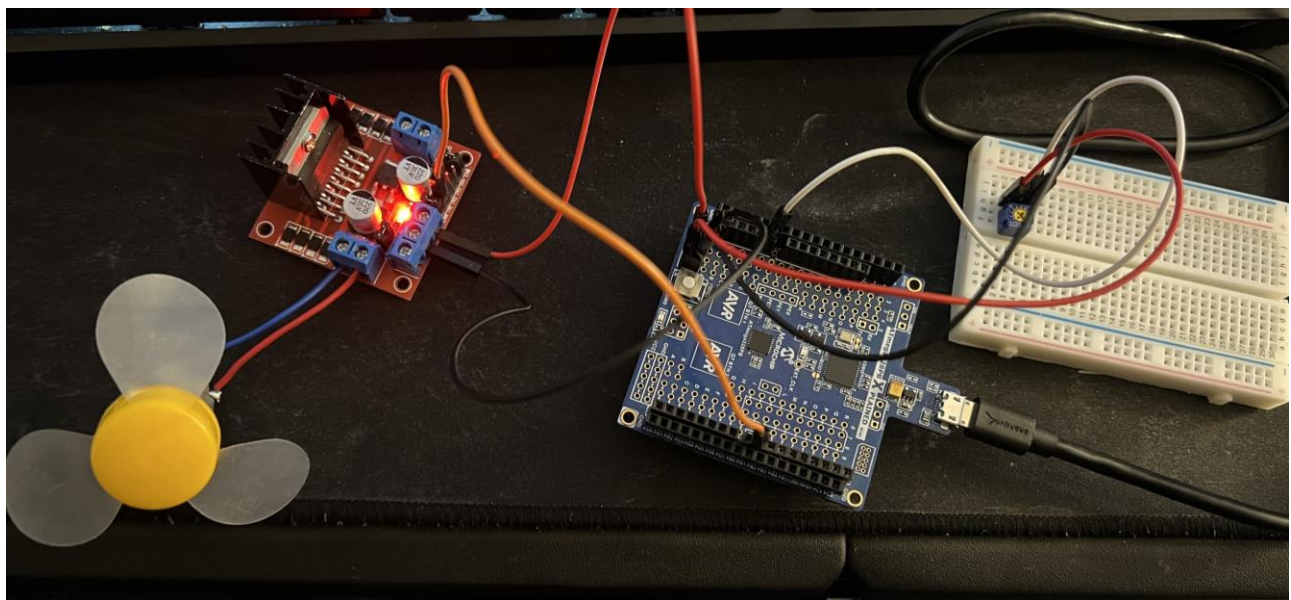
[illegible]

### Task 3

[illegible]

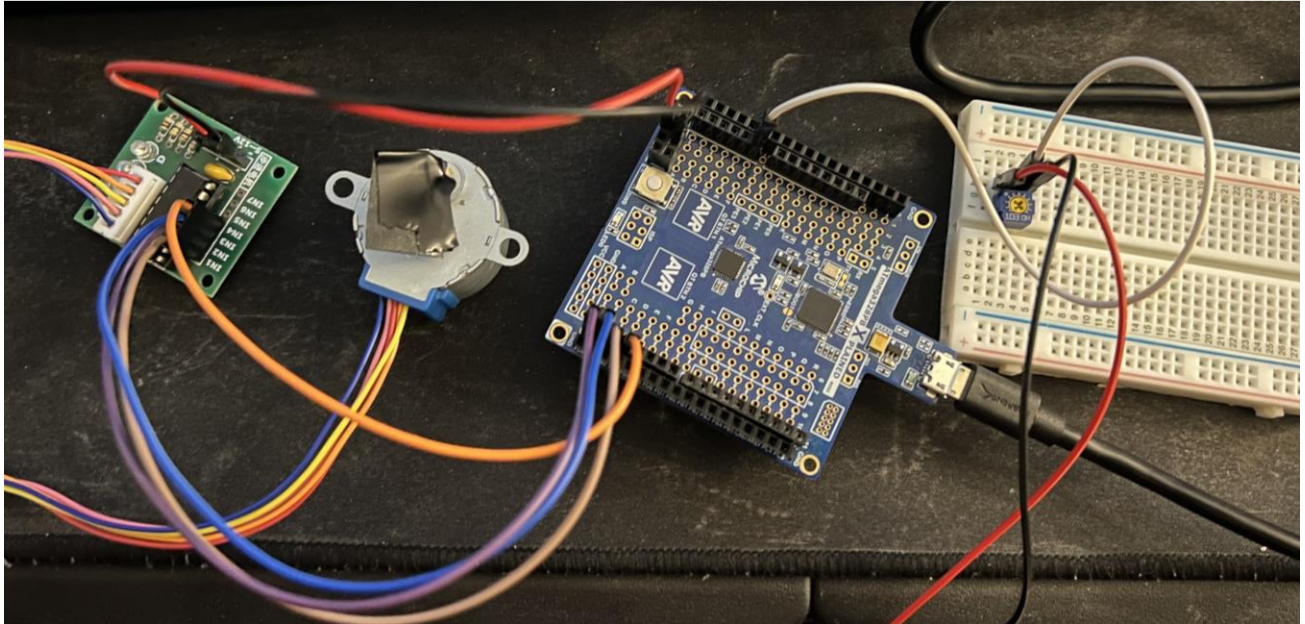
## 7. SCREENSHOT OF EACH DEMO (BOARD SETUP)

## Task 1

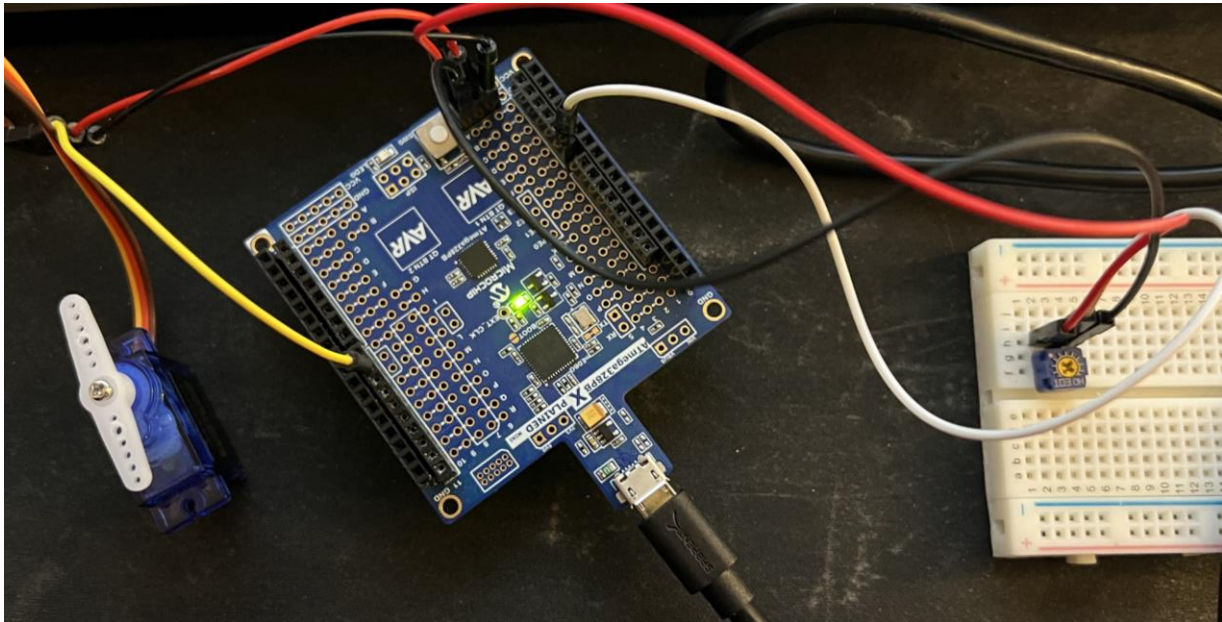




## Task 2



## Task 3



## 8. VIDEO LINKS OF EACH DEMO

[TASK 1](#)

[TASK 2](#)

[TASK 3](#)

## 9. GITHUB LINK OF THIS DA

[https://github.com/DylanCaz/Submission\\_DA/tree/main/Design\\_Assignments\\_sub/DA\\_5\\_sub](https://github.com/DylanCaz/Submission_DA/tree/main/Design_Assignments_sub/DA_5_sub)

**Student Academic Misconduct Policy**

<http://studentconduct.unlv.edu/misconduct/policy.html>

*"This assignment submission is my own, original work".*

