

# OFDM-based Joint Radar and Communication

*By Dylan Boland*

## Project Motivation:

- With the advance of IoT devices, especially in the automotive industry, more and more services are being integrated into single devices. For example, many modern-day cars are equipped with Radar, GPS, and communication functionality.

## Principal Aim:

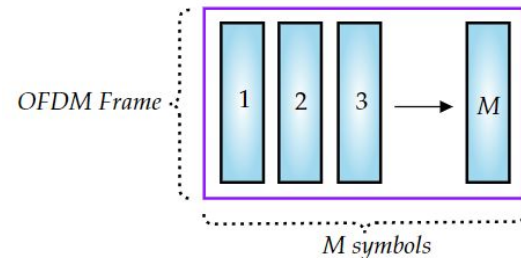
- The OFDM waveform has been adopted by 4G and 5G communication systems. With this in mind, it seems worthwhile to explore and analyse the possibility of adapting the waveform so that the communication system can *also* perform Radar functionality, thereby **combining** the two systems into one.

## The Benefits:

- Less Hardware
- Reduced Costs
- Possibility for less of the frequency spectrum needing to be used - especially beneficial given how valuable it is.

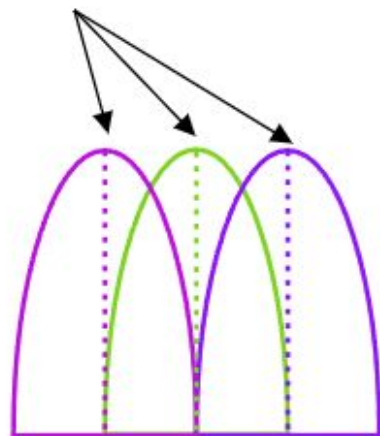
# OFDM (Orthogonal Frequency-Division Multiplexing):

- Data is transmitted in parallel over separate **subcarrier** channels.
- The subcarriers are **orthogonal** and partly overlapping: in this way, the frequency spectrum is used more efficiently, and a very high data rate can be achieved.
- The data output of all the subcarrier channels constitutes an OFDM **symbol**.
- Symbols are sent in bursts, and a burst of symbols is often referred to as a **Frame**.
- The **Cyclic Prefix** is used to combat **Intersymbol Interference (ISI)**



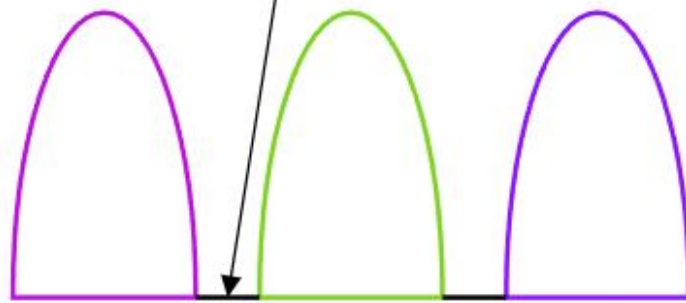
OFDM

*Overlapping subcarriers*



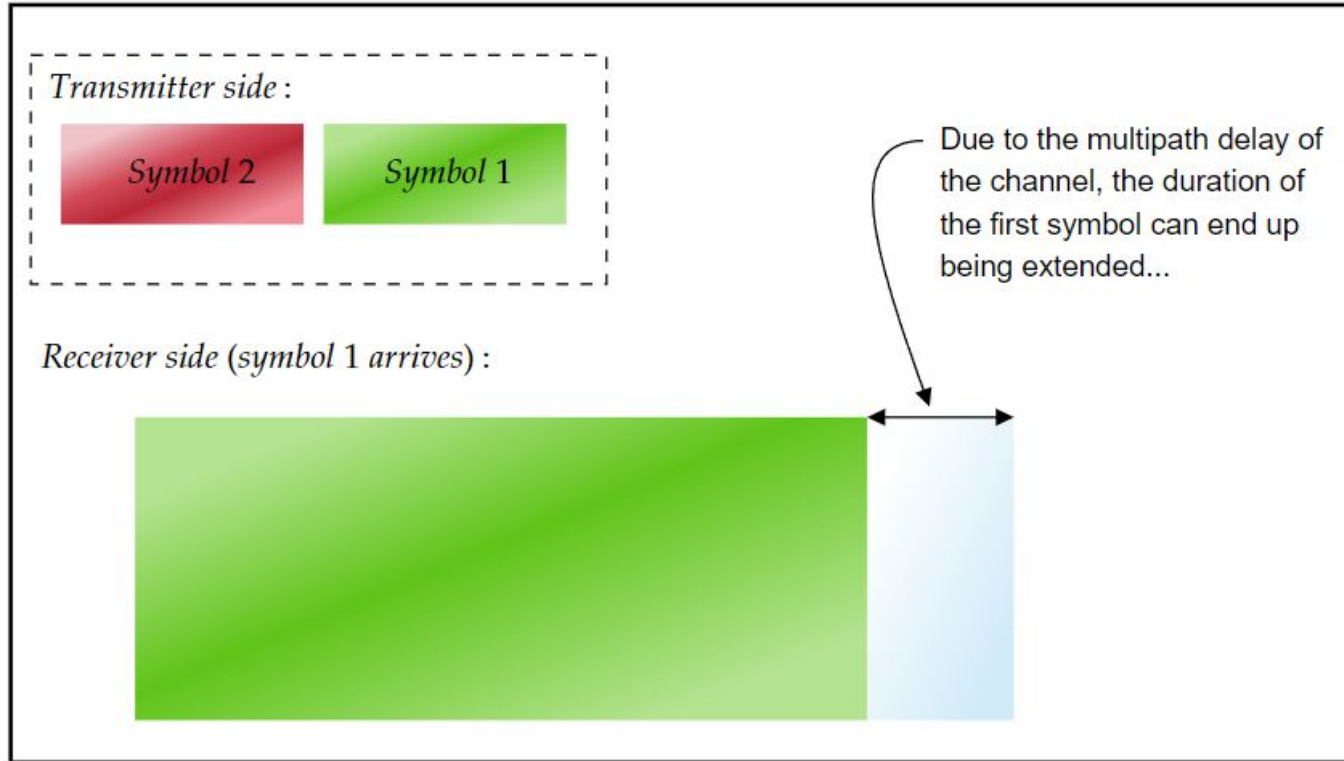
FDM

*Guard band needed*

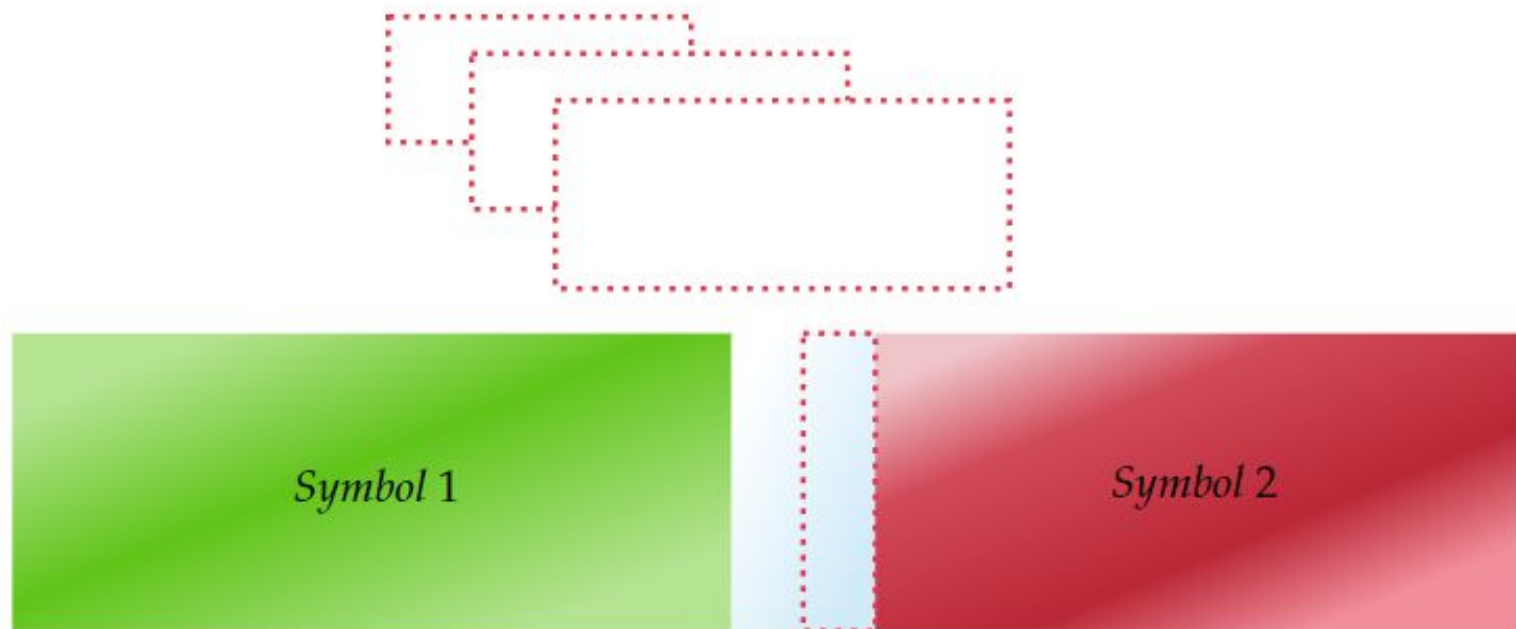


- Less of the frequency spectrum used – meaning a higher spectral efficiency...
- Higher data rates...
- The subcarriers are orthogonal: the peak of each subcarrier lines up with the side nulls of its two neighbours... and so no interference occurs

# Cyclic Prefix (Why is it useful?):



*Receiver side (symbol 2 arrives) :*



*symbol 2 is affected by the **tail** of symbol 1...*

# Adding the Cyclic Prefix

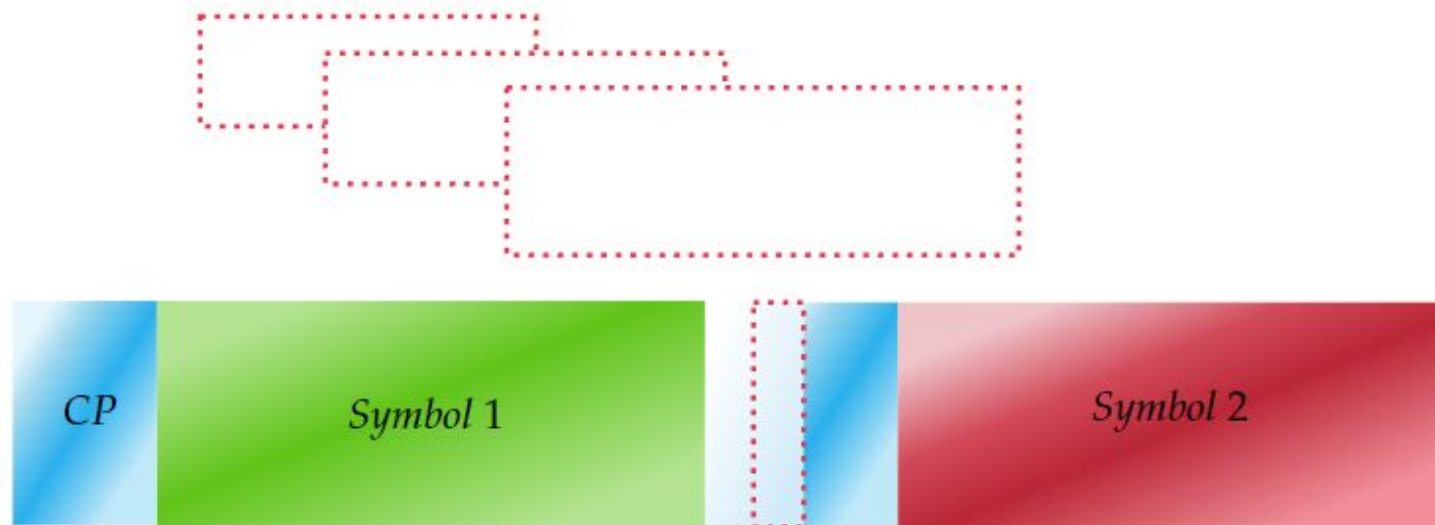


*The end of symbol 1 is prefixed to its front. The symbol now appears cyclical to the receiver...*

*\*The Cyclic Prefix acts as a guard interval, and helps protect against ISI...*



*Now when symbol 2 arrives at the receiver :*



*The **tail** of symbol 1 now  
only interferes with the CP  
of symbol 2!*

## Channel Estimation with Pilot Tones:

- Not *all* of the subcarriers are used for transferring data: some are used for estimating the channel, as well as to help the receiving side to synchronize itself with the incoming symbols.
- **Pilot tones** (symbols) are uniformly inserted onto subcarrier channels. At the receiver side, an estimation of the channel's effect on the pilot tones can be made - in this way the channel can be estimated, and interpolation can be used to estimate the channel's effect on the **other subcarrier** channels.

*Pilot symbols*

$X_{p_1}$

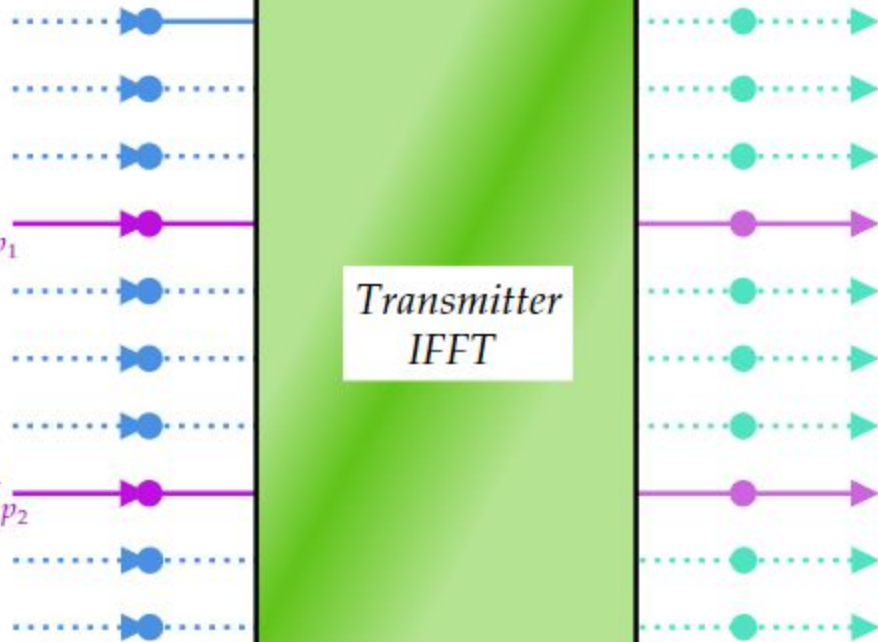
$X_{p_2}$

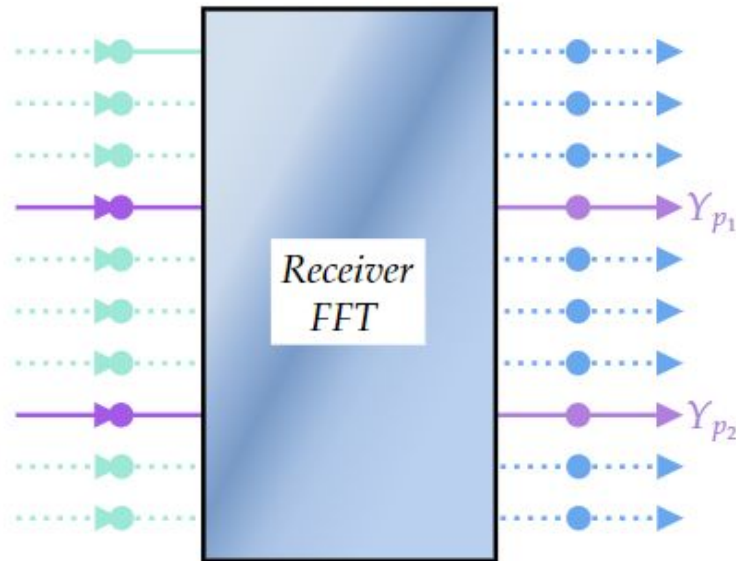
*Transmitter  
IFFT*

*Used for :*

→ *Channel estimation*

→ *Symbol synchronisation*





...Information  
about the channel  
can be obtained  
based on how it  
**affects** the pilot tones  
that were transmitted

Pilot tone transmitted :  $\rightarrow X_{p_1}$

Pilot tone received :  $\rightarrow Y_{p_1}$

$$Y_{p_1} = X_{p_1} \hat{H}_{p_1} + Z_{p_1} \quad \therefore \hat{H}_{p_1} = \frac{Y_{p_1}}{X_{p_1}} - \frac{Z_{p_1}}{X_{p_1}}$$

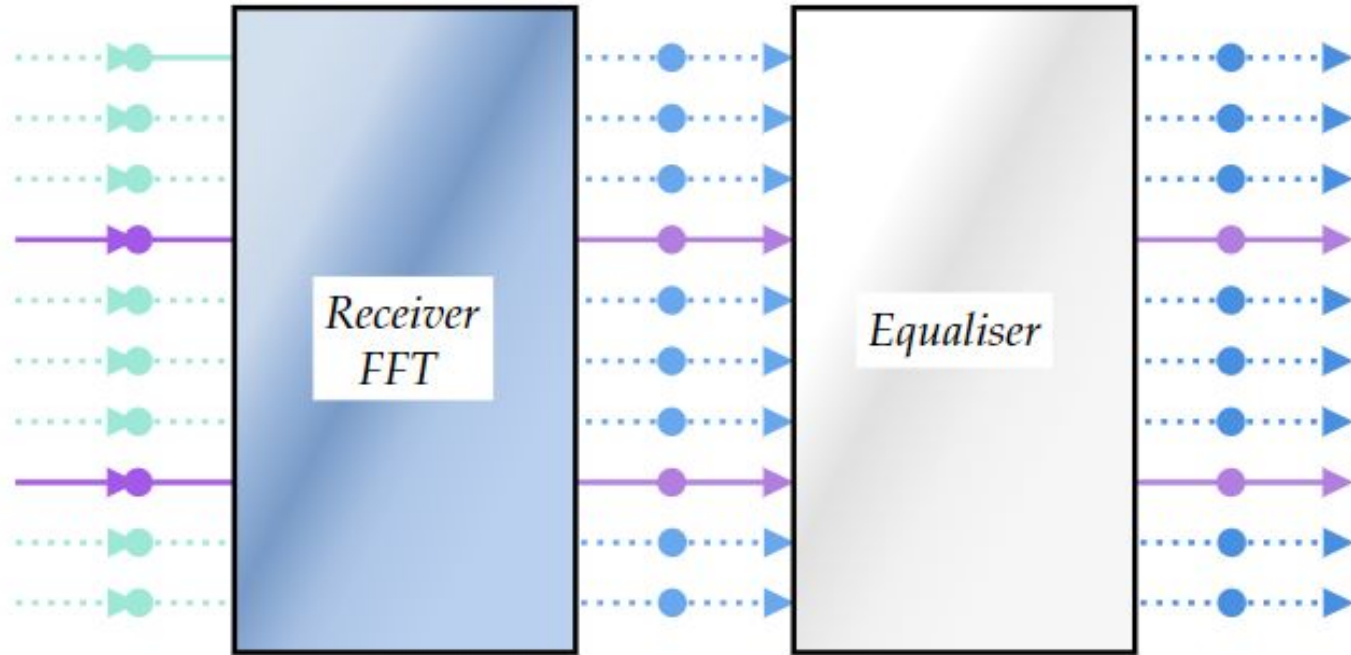
$$Y_{p_2} = X_{p_2} \hat{H}_{p_2} + Z_{p_2} \quad \therefore \hat{H}_{p_2} = \frac{Y_{p_2}}{X_{p_2}} - \frac{Z_{p_2}}{X_{p_2}}$$

Noise

\*The receiver knows which  
subcarriers correspond to  
the pilot tones...

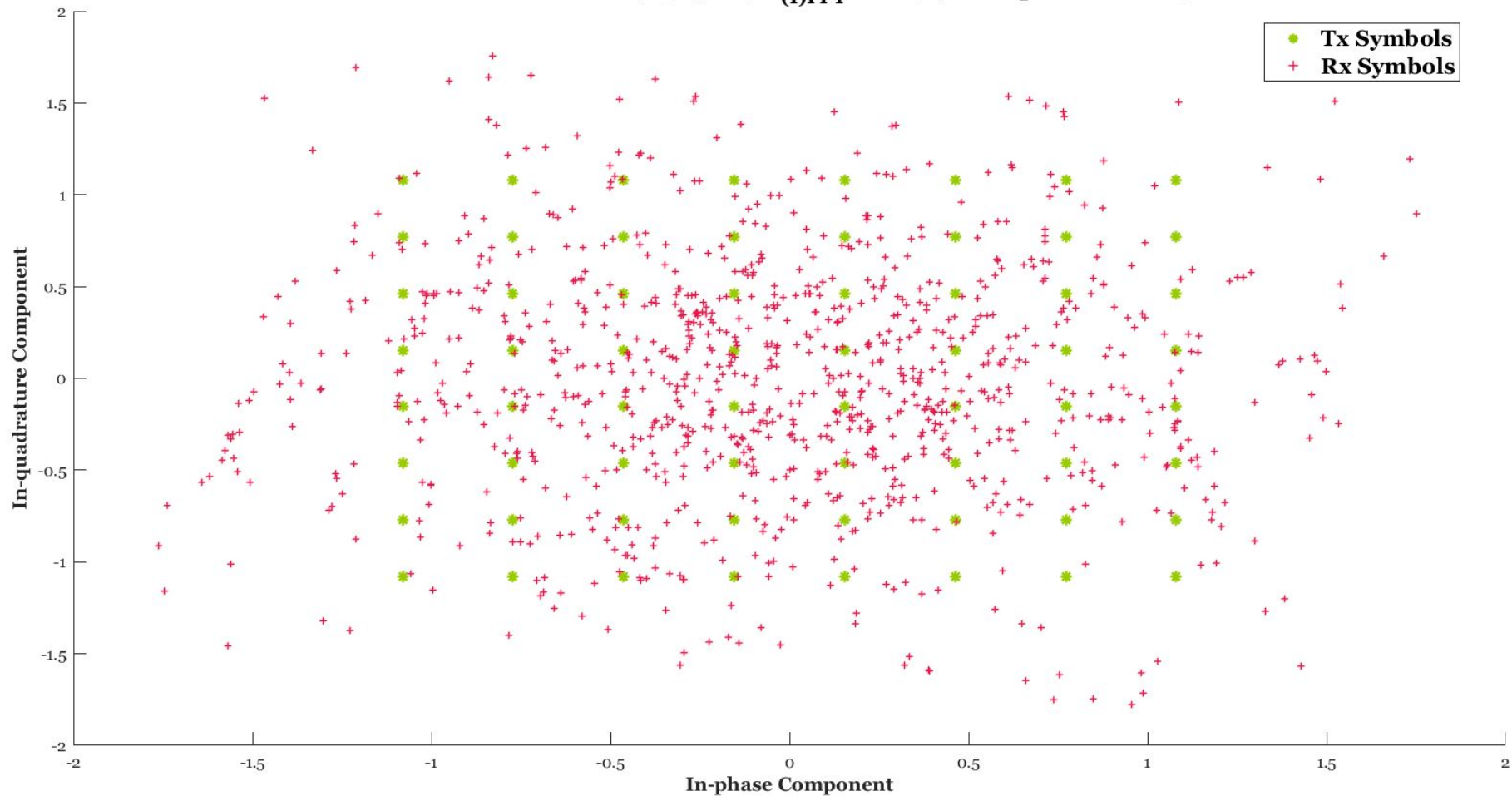
## Equaliser Block:

*Equaliser block : combats channel's effect on the transmitted signal and aids in the recovery of the data symbols*



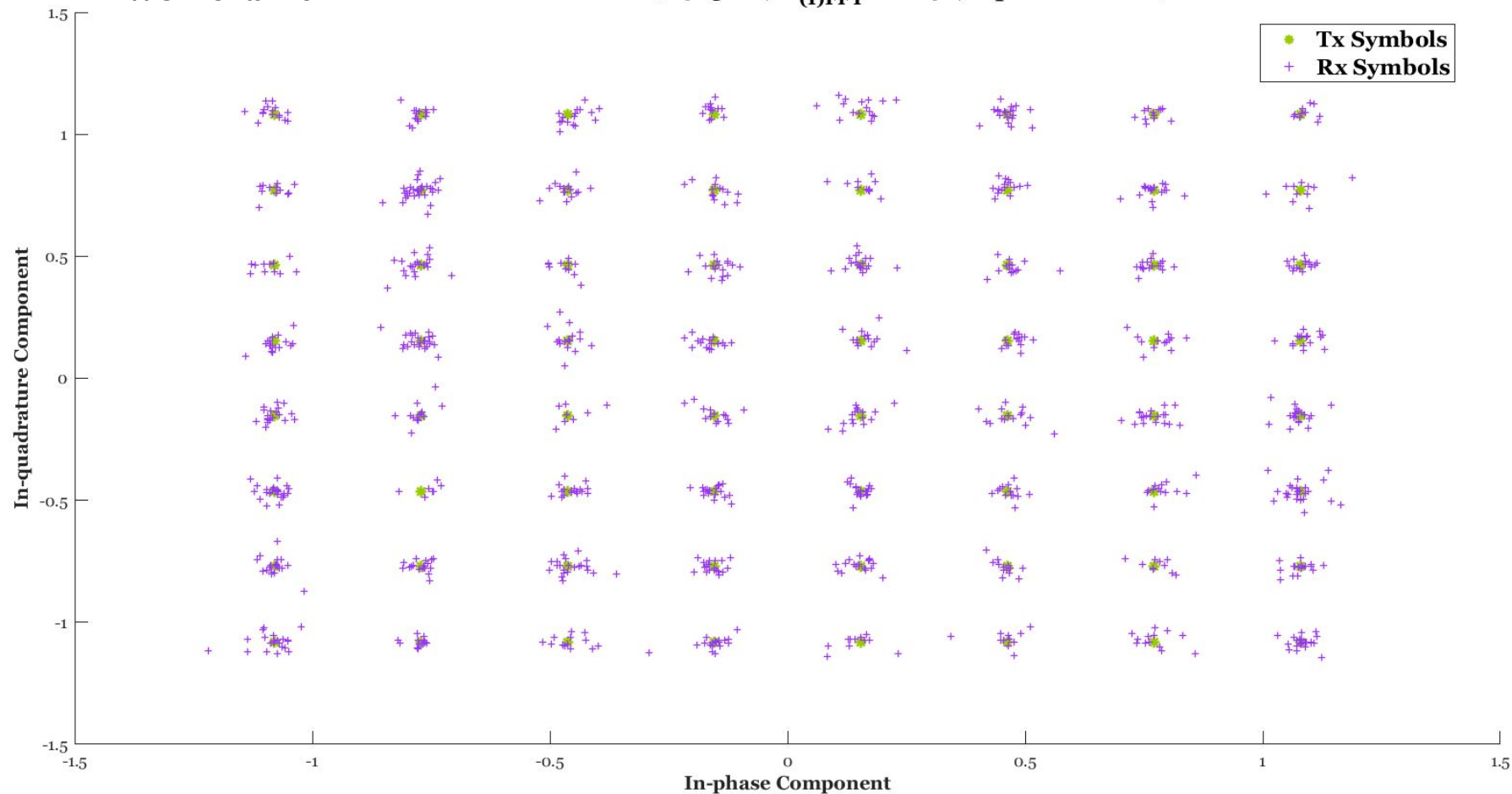
**AWGN Channel**

**Constellation Chart (64-QAM,  $N_{\text{IFFT}} = 2048$ , No Equaliser at Rx)**

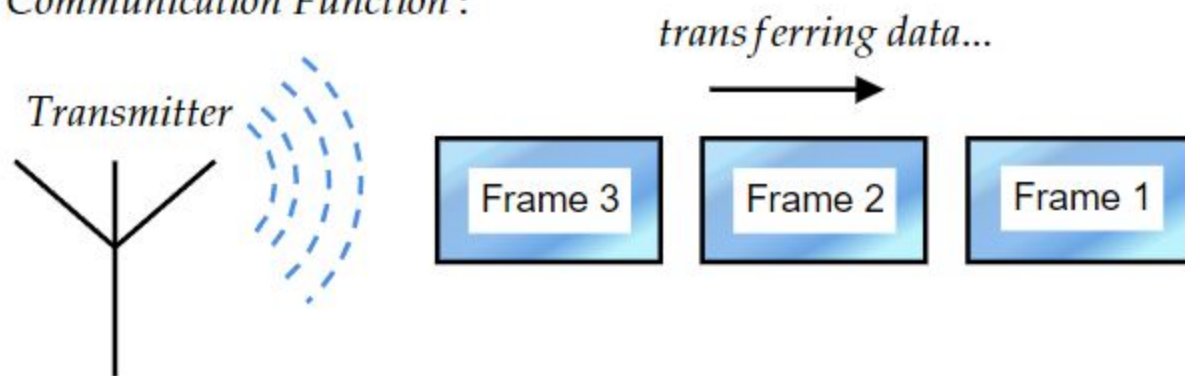


**AWGN Channel**

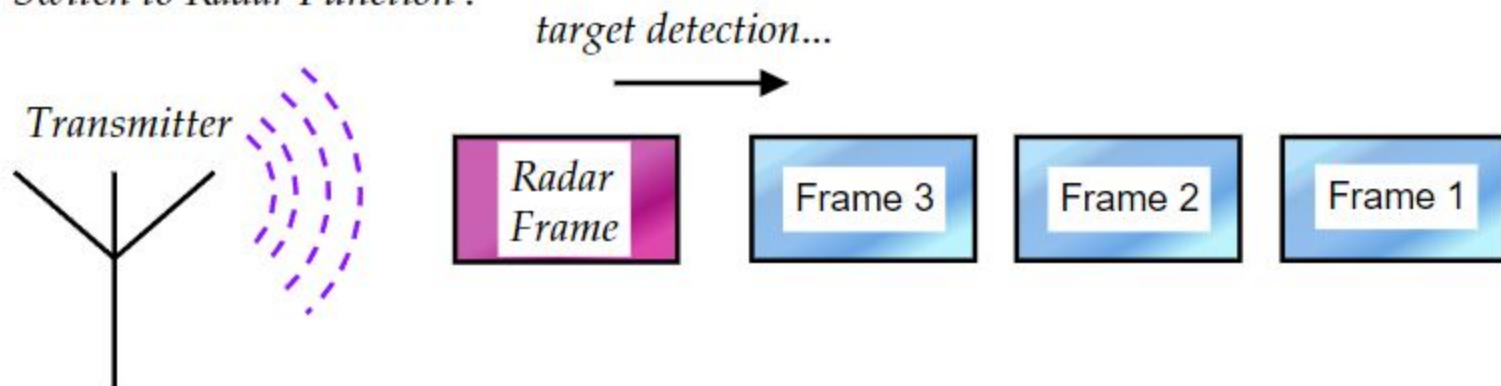
**Constellation Chart (64-QAM,  $N_{\text{IFFT}} = 2048$ , Equaliser at Rx)**



*Communication Function :*



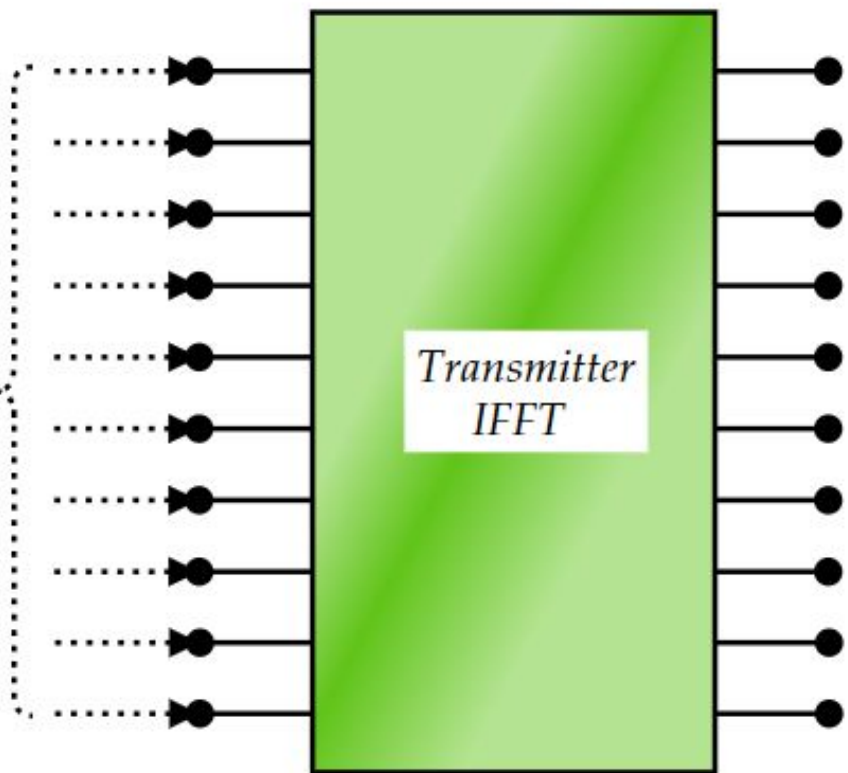
*Switch to Radar Function :*



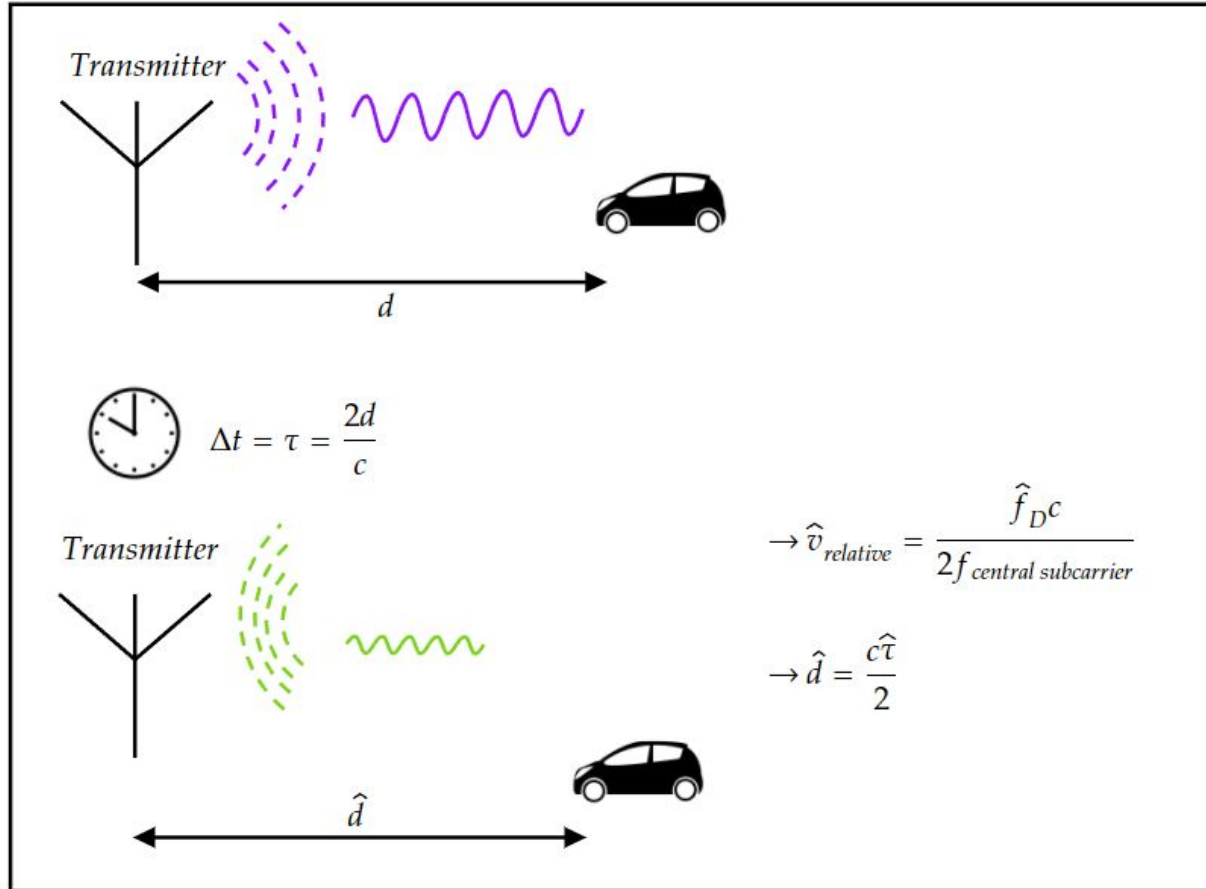


*Radar Function :*

*How should we load the subcarriers in order to best perform the radar function?*



# Estimation of the Time Delay and the Doppler Shift:



Some of the key performance measures of Radar systems are its:

- Its maximum range
- Its accuracy
- Its resolution
- Its ability to detect the desired echo

