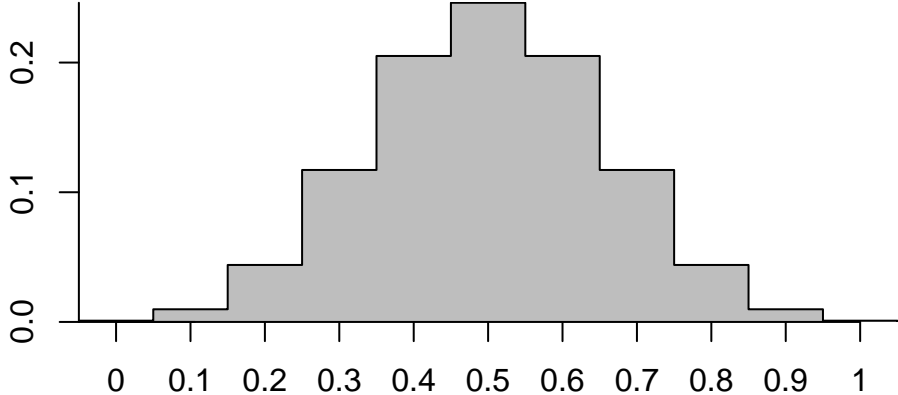


Probability



Observed Proportion