

## Lab 1 : INTRODUCTION ARDUINO AND LED

### 1. Objectives: After this lab, the learner will be able to

- Using proteus to simulate an simple IoT project
- Using Arduino IDE to program Arduino board

### 2. Facilities

- Arduino Software: [Download from here](#)
- Proteus Simulator

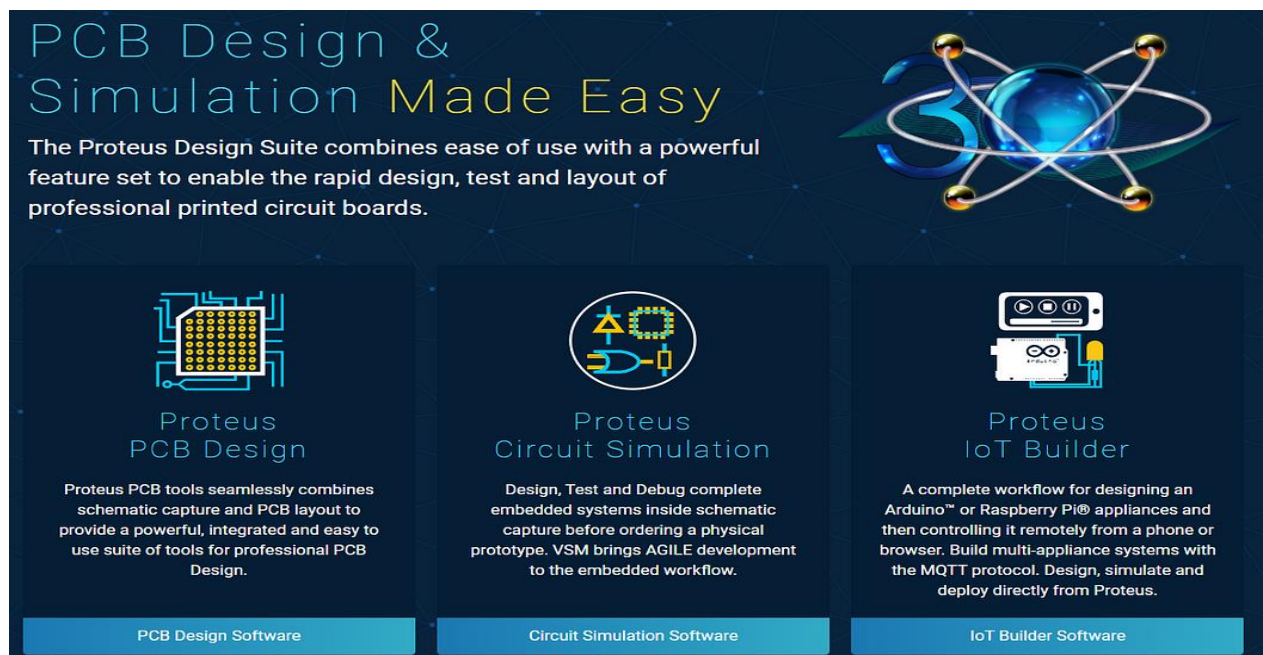
### 3. Prerequisite

- Basis electronic
- C programming language

### 4. Introduction to Proteus

#### 4.1. What is proteus

**Proteus Design Suite** is *one of the best circuit simulation programs* in its field. It also has Proteus Design Suite, the **PCB design**, and **IoT builder software**.



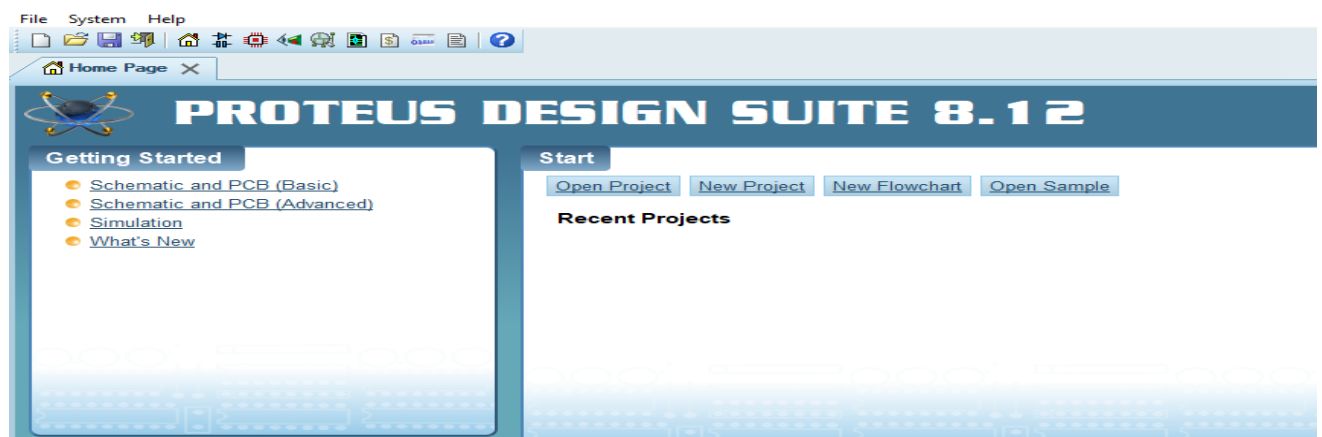
The banner features a dark blue background with a glowing atom-like graphic on the right. The main text reads 'PCB Design & Simulation Made Easy'. Below this, a paragraph states: 'The Proteus Design Suite combines ease of use with a powerful feature set to enable the rapid design, test and layout of professional printed circuit boards.' The banner is divided into three columns, each with an icon and a description of a Proteus tool: PCB Design, Circuit Simulation, and IoT Builder. Each column has a corresponding button at the bottom: 'PCB Design Software', 'Circuit Simulation Software', and 'IoT Builder Software'.

**PCB Design & Simulation Made Easy**

The Proteus Design Suite combines ease of use with a powerful feature set to enable the rapid design, test and layout of professional printed circuit boards.

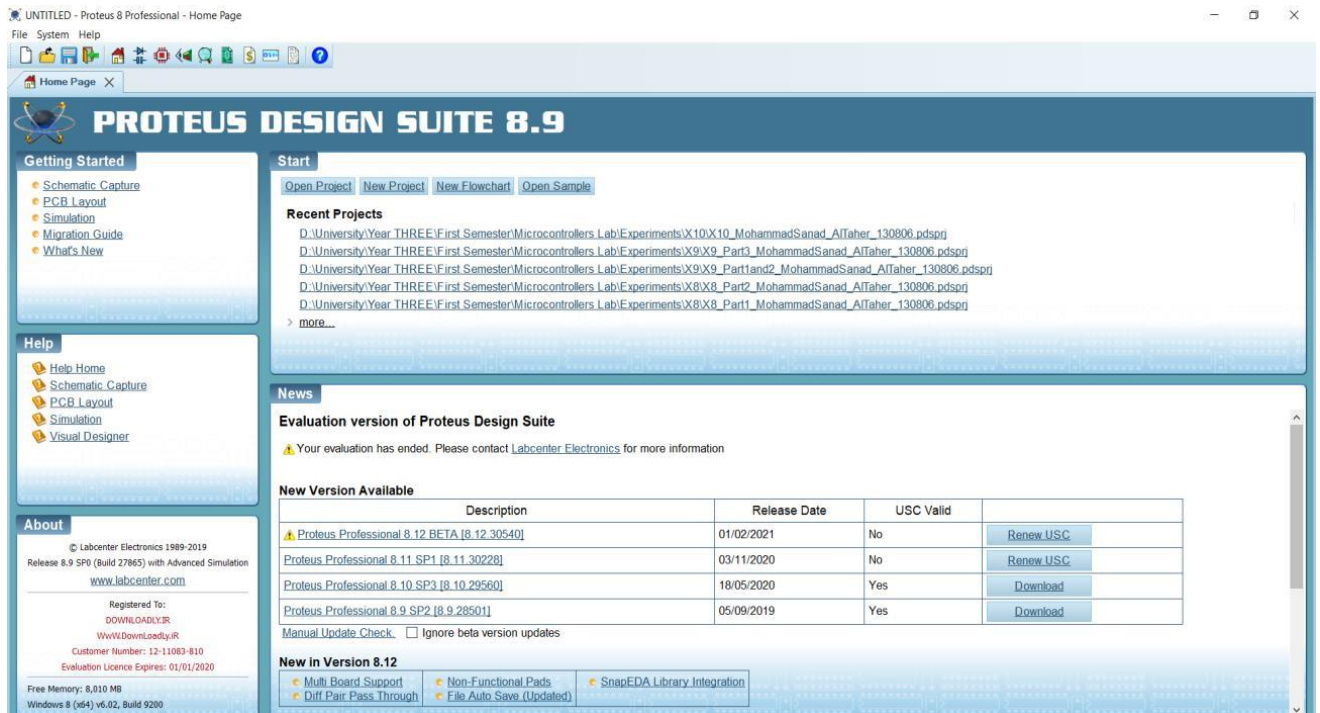
Proteus PCB Design	Proteus Circuit Simulation	Proteus IoT Builder
Proteus PCB tools seamlessly combines schematic capture and PCB layout to provide a powerful, integrated and easy to use suite of tools for professional PCB Design.	Design, Test and Debug complete embedded systems inside schematic capture before ordering a physical prototype. VSM brings AGILE development to the embedded workflow.	A complete workflow for designing an Arduino™ or Raspberry Pi® appliances and then controlling it remotely from a phone or browser. Build multi-appliance systems with the MQTT protocol. Design, simulate and deploy directly from Proteus.
PCB Design Software	Circuit Simulation Software	IoT Builder Software

#### 4.2. How can we use the program?



## 1. Creating a File:

After installing Proteus and activating your license, you will be met with a page similar to that shown below:



**“Getting Started” & “Help”:** Some useful guides can be found here, but they tend to be wordy and filled with jargon. It is advised to avoid them.

**“Start” \ “Recent Projects”:** Here you will find the projects that you opened last. This section will be empty if you just installed Proteus.

**“News”:** This section will contain news about your current license, recent versions of the software, and **links to basic video tutorials** that you might find helpful.

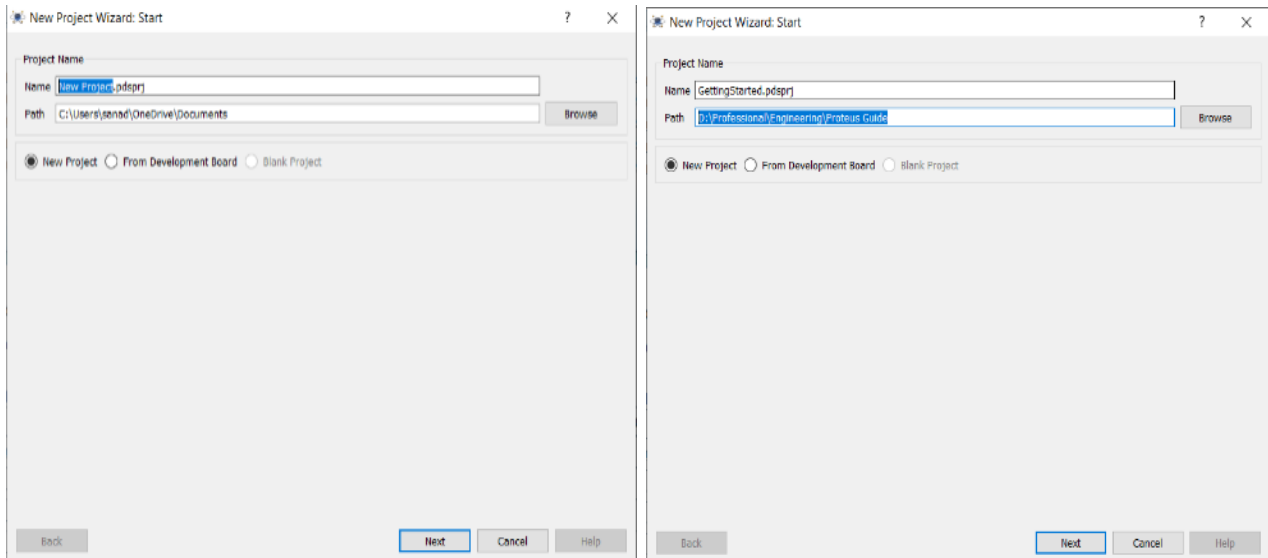
**To create a new project, follow the steps below:**

- Step 1: Click on “New Project” under the “Start” header in the home page:



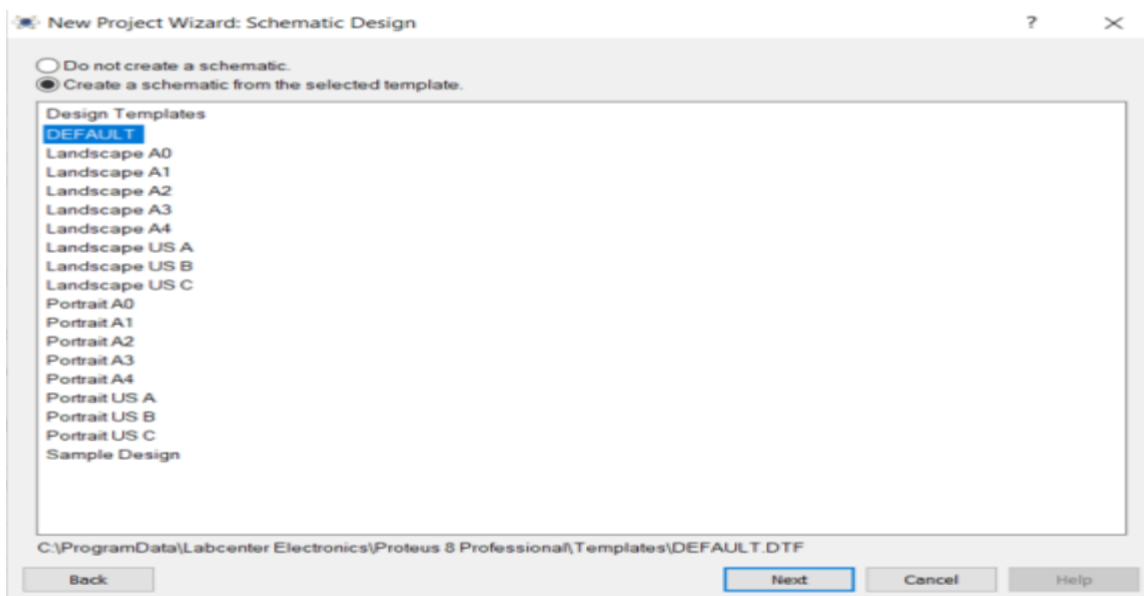
The “New Project Wizard” window will now open

- Step 2: Choose a name and file-path for your project:



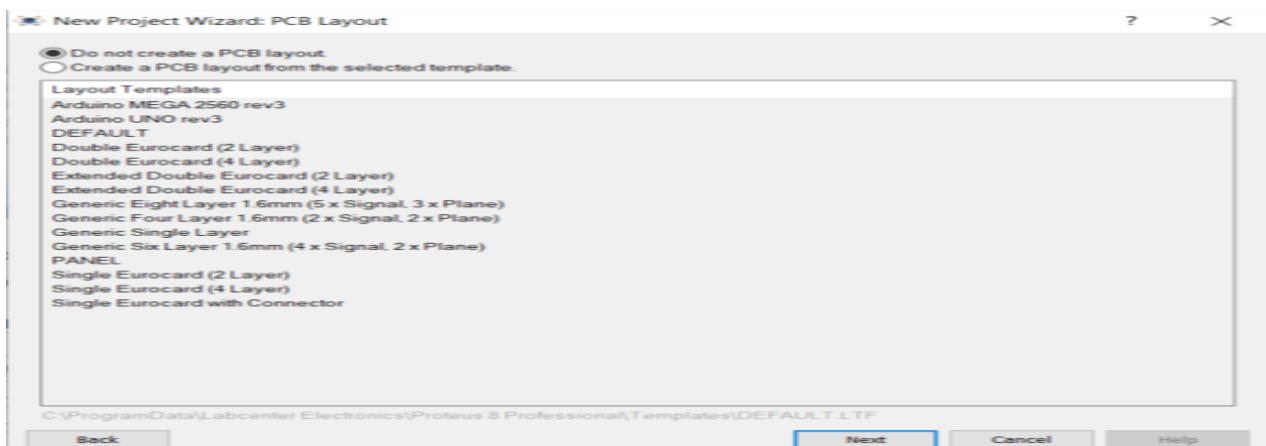
Then click “Next”.

- Step 3: Select the Schematic Design:



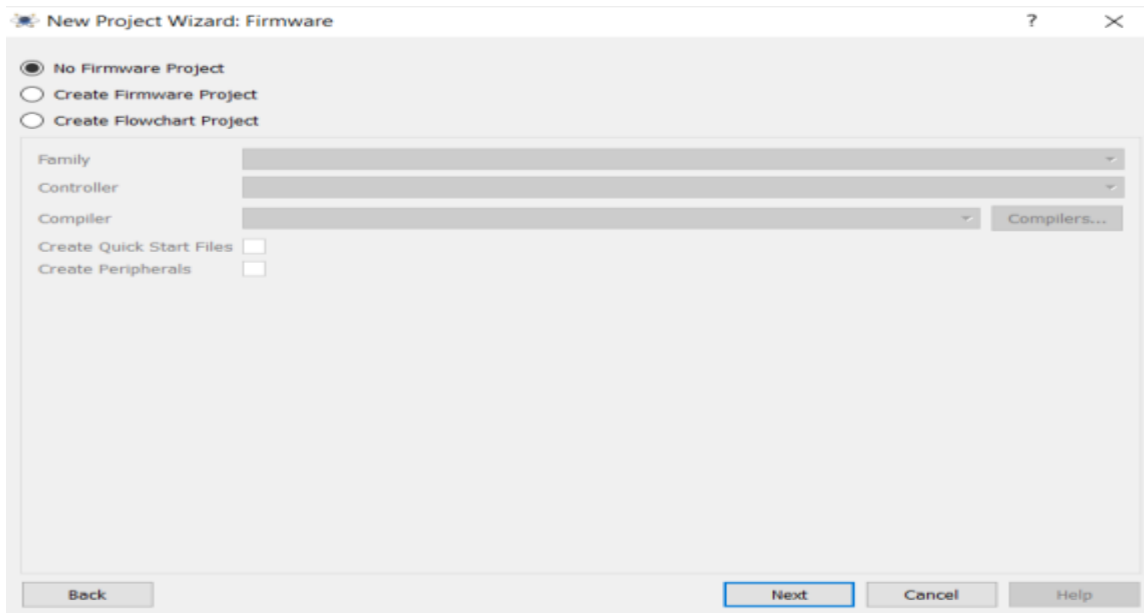
Unless certain dimensions are required (for printing or otherwise), “DEFAULT” will suffice. Click “Next”.

- Step 3: Select the PCB Layout:



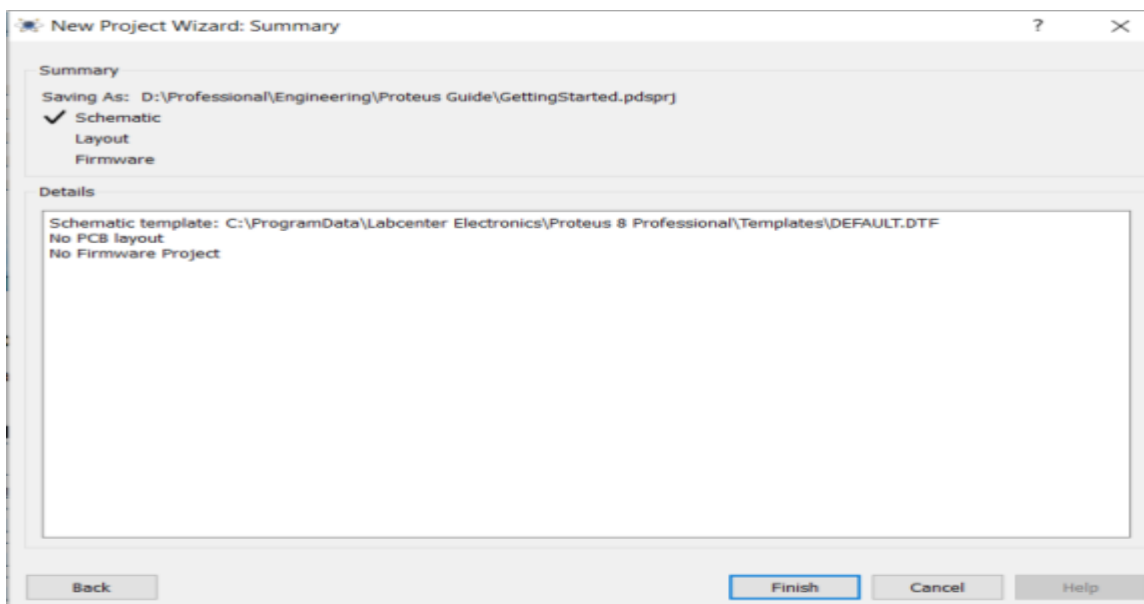
PCB design will not be included in this guide. Select “Do not create a PCB layout” and click “Next

- Step 4: Select Firmware:



Editing source code is beyond the scope of this guide, select “No Firmware Project” and click “Next”.

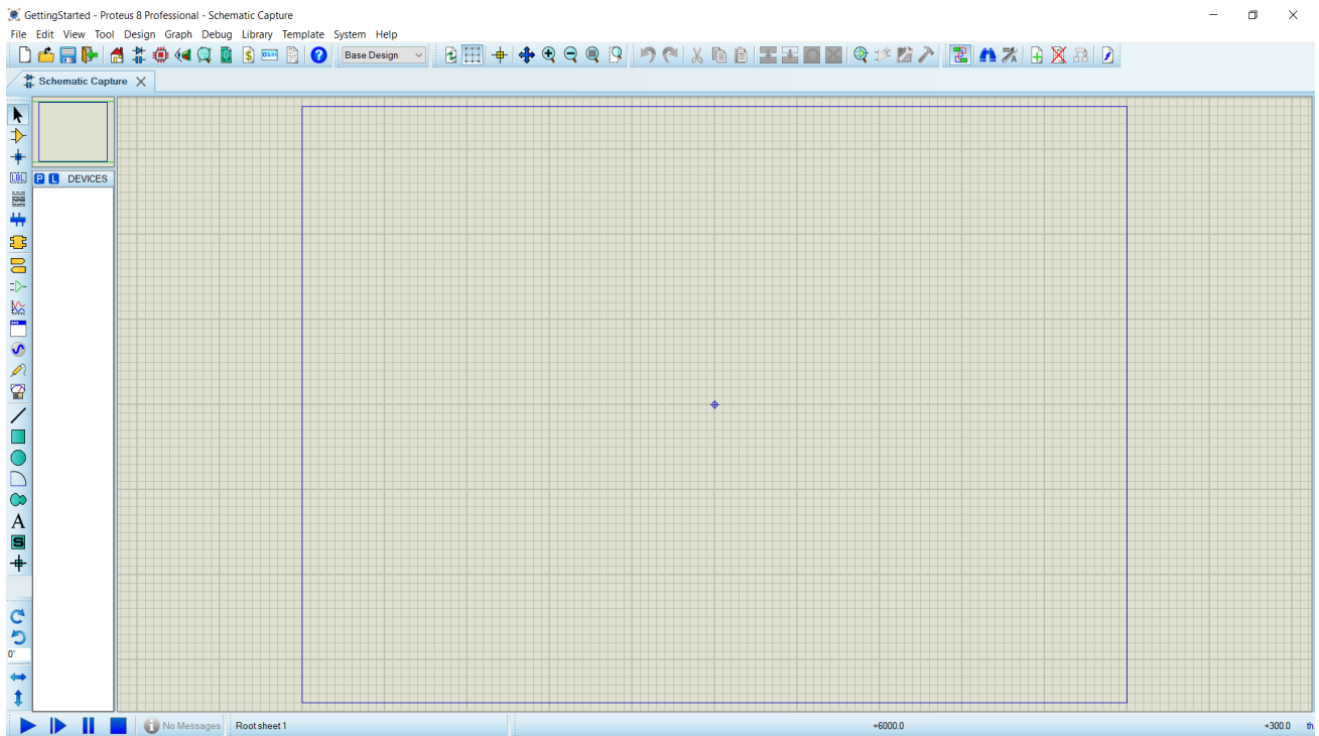
- Summary page:



You should now see a summary of all your previous selections. If any mistakes were made, you can click “Back” and correct them.

- Click “Finish” to open the Schematic Capture module and begin working on your project.

## 2. Interface:



The Schematic Capture interface is split into four main parts, the Menu and Module bars on top, the Sidebar on the left-hand side, the Root sheet in the center, and the Simulation Control bar at the bottom.

Our circuits will be shown on the Root sheet, whereas most of our work will be done using the Sidebar.

### Module Bar:

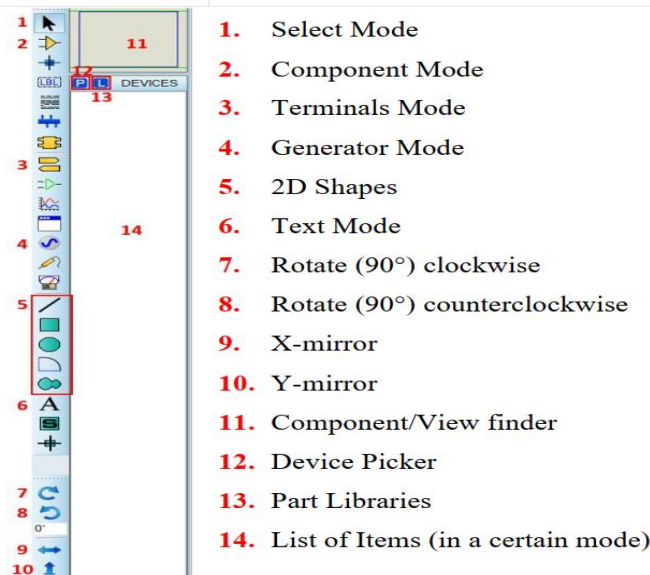


- |                     |                       |                |
|---------------------|-----------------------|----------------|
| 1. New Project      | 6. Zoom in            | 11. Cut        |
| 2. Open Project     | 7. Zoom out           | 12. Copy       |
| 3. Save Project     | 8. Zoom to View Sheet | 13. Paste      |
| 4. Close Project    | 9. Undo               | 14. Pick Parts |
| 5. Center at Cursor | 10. Redo              |                |

Note: letter “M” before a number will indicate a button on the Module bar. Thus, M12 refers to the “Copy” button on the Module bar.

### Sidebar:





Note: letter “S” before a number will indicate a button on the Sidebar. Thus, S12 refers to the “Device Picker” button on the Sidebar.

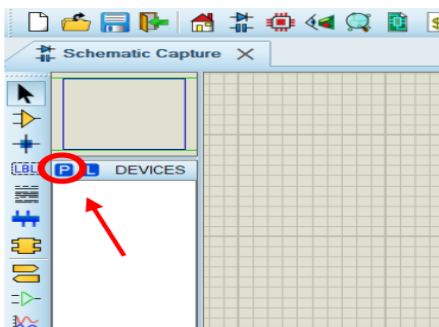
### 3. Collecting Parts:

In this part, we will prepare all the parts needed for our experiment. Experiment two will be used to demonstrate the steps

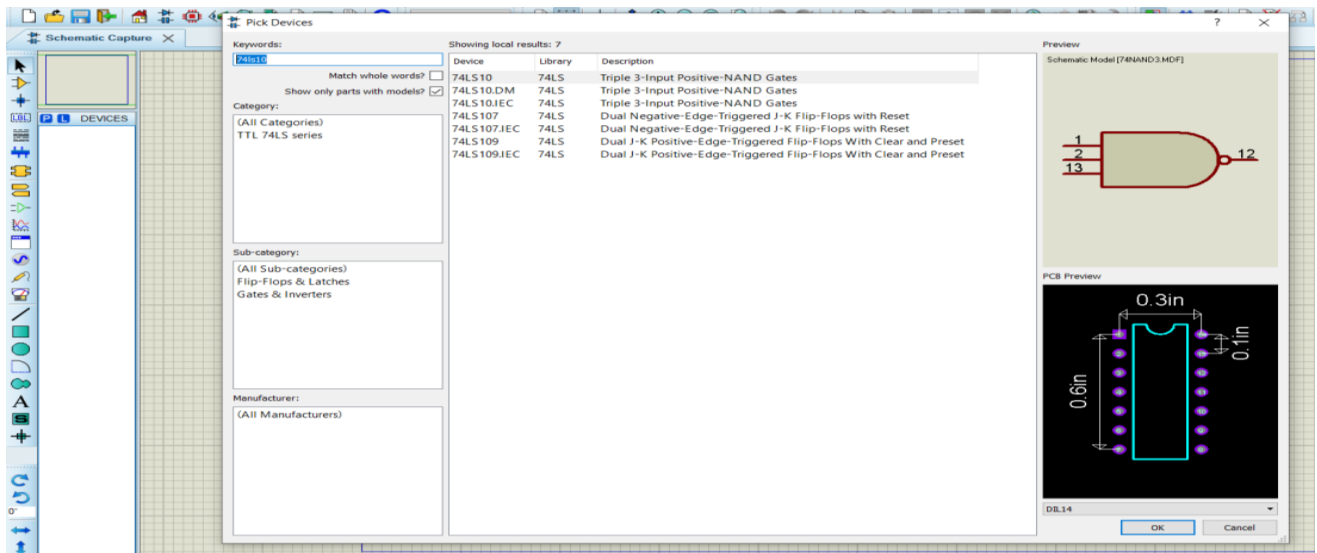
- 0 Identify the needed parts:
  - Usually, all needed chips for a certain experiment are listed in its document.
  - The chips needed for experiment two are in the excerpt below:

“  
 7410 TRIPLE 3-INPUT NAND GATE, QTY = 2 Chips  
 7427 TRIPLE 3-INPUT NOR GATE, QTY = 2 Chips  
 7404 HEX INVERTER, QTY = 1 needed in order to make the variables and their complements available.  
 7400 QUADRUPLE 2-INPUT NAND GATE, QTY = 1 Chip  
 7402 QUADRABLE 2-INPUT NOR GATE, QTY = 1 Chip  
 74283 4-BIT BIANRY ADDER  
 ”

- Step 1: Open the Part Picker (S12 or M14):



- Step 2: After the “Pick Devices” window has appeared, begin writing keywords for the part you are looking for:



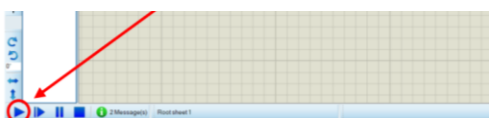
- Step 3: Click “OK” to add the part to your list of components.
- Repeat step 2 for all other components while making sure that all components have “Simulator Model(s)”. If “No Simulator Model” is **not** written, then it is assumed that there is a simulator model for the selected component.
- Step 4: Now we add other required components such as: Switches, LEDs, Clock, etc. Inputs: The two most common input components are “LOGICTOGGLE” and “SW-SPDT” (Single Pole Double Throw) and can be added from “Device Picker”. There are no practical differences between them.

## 5. Connecting a Circuit:

Once we have all the needed parts listed (in S14) in the Component Mode (S2), we are ready to begin constructing a circuit. In this part, a half-adder will be constructed using NOT gates and NOR gates (from experiment two)

## 6. Running the Simulator:

Perhaps the easiest part of this guide is running a simulation. Once all components are connected, simply click the “Play” button at the bottom-left corner of the page.



## 7. Introduction to arduino

### 7.1. What is Arduino

- Arduino is nothing but a simple microcontroller board which is normally used in engineering projects where there's a need to automate something.
- You can interface sensors with this board, can drive motors with this board, can plug switches in it etc.
- In old ages ( not old enough 😊 ), people used simple switches for turning ON a bulb so like you click the switch and the bulb is ON, it was quite a simple circuit, after that relays are invented and then engineers used 555 timer circuits in order to turn ON lights on some specific time. But the 555 timer circuits are quite big

in size, so finally engineers discovered Microcontrollers in which there are simple OUTPUT and INPUT pins, so now if you want to turn on light at some certain time then you just simply plug the bulb on output pin of microcontroller and then do some programming and add a timer to automatically turn on the bulb.

- So, the benefit of microcontroller is the circuit is quite simple and small in size. Moreover, it's flexible, suppose you want to change the time of turning ON bulb then what you need to do is simply change the coding and it will be changed, but in 555 timer circuits you need to change the components in order to do so.
- Now, we know the use of microcontroller and also their benefit but thing is what is Arduino ??? In microcontrollers like PIC or Atmel, there's a small drawback.
- Suppose you want to work on PIC then you have to first design its basic circuit also need to design a power circuit to supply power to it and after that in order to upload the code in it, you have to buy a programmer/ burner as well. So, first of all you need to write the code for PIC Microcontroller and after that you need to upload code in it using a programmer and then place PIC microcontroller back into the circuit and test, which is quite lengthy plus also got hectic when you are working on some project because you have to test code again and again.
- By the way, now advance programmers like PICkit2 and PICkit3 can be plugged on board but still you have to design the basic circuit so coming to bottom line, in order to do project with PIC or Atmel microcontroller you have to do soldering etc.
- But that's not the case with Arduino Board, Arduino has built in programmer and the basic circuit in it. So what you need to do is simply plug in Arduino with your computer via usb cable, get its software and start uploading code and also start testing.
- So, you don't need to plug unplug or do anything, simply upload the code and test. Moreover, it also has some very efficient tools using which you can test your output as well quite easily. Arduino board also has the pins on which you can simply plug your devices and can turn them ON or OFF. So, hats off to Arduino team for providing us a simple board which has everything on it.

## **7.2. Types of Arduino Boards**



- There's a long range of Arduino boards available online, the basic Arduino board is named as Arduino UNO which is most widely used in projects.
- Arduino UNO has total 13 digital pins and 6 analog pins which are used for connecting sensors with them.
- Suppose you have a project in which you want to interface 30 sensors, then what you need to do ?? Now you need to buy another Arduino board named as Arduino Mega 2560. This board has around 70 pins on it which can be used as output or input and hence you can plug your sensors quite easily.



### 7.3. The Arduino Microcontroller: Atmel ARV Atmega 328

Atmel AVR ATmega 328			
(PCINT14/RESET) Reset	1	PC6	PC5 28 (PCINT13/ADC5/SCL) Analog input A5
(PCINT16/RXD) Digital pin D0 (Rx)	2	PD0	PC4 27 (PCINT12/ADC4/SDA) Analog input A4
(PCINT17/TXD) Digital pin D1 (Tx)	3	PD1	PC3 26 (PCINT11/ADC3) Analog input A3
(PCINT18/INT0) Digital pin D2	4	PD2	PC2 25 (PCINT10/ADC2) Analog input A2
(PCINT19/OC2B/INT1) Digital pin D3*	5	PD4	PC1 24 (PCINT9/ADC1) Analog input A1
(PCINT20/XCK/T0) Digital pin D4	6	PD4	PC0 23 (PCINT8/ADC0) Analog input A0
5V	7	VCC	GND 22 Gnd
Gnd	8	GND	AREF 21 AREF
(PCINT6/XTAL1/TOSC1) (crystal)	9	PB6	AVCC 20 5V
(PCINT7/XTAL2/TOSC2) (crystal)	10	PB7	PB5 19 (PCINT5/SCK) Digital pin D13
(PCINT21/OC0B/T1) Digital pin D5*	11	PD5	PB4 18 (PCINT4/MISO) Digital pin D12
(PCINT22/OC0A/AIN0) Digital pin D6*	12	PD6	PB3 17 (PCINT3/MOSI/OC2A) Digital pin D11*
(PCINT23/AIN1) Digital pin D7	13	PD7	PB2 16 (PCINT2/SS/OC1B) Digital pin D10*
(PCINT10/CLKO/ICP1) Digital pin D8	14	PB0	PB1 15 (PCINT1/OC1A) Digital pin D9*

Arduino pin mapping in blue  
\* denotes capable of PWM output

## 7.4. What is the Arduino

The word “Arduino” can mean 3 things

A physical piece of hardware



A programming environment



A community & philosophy



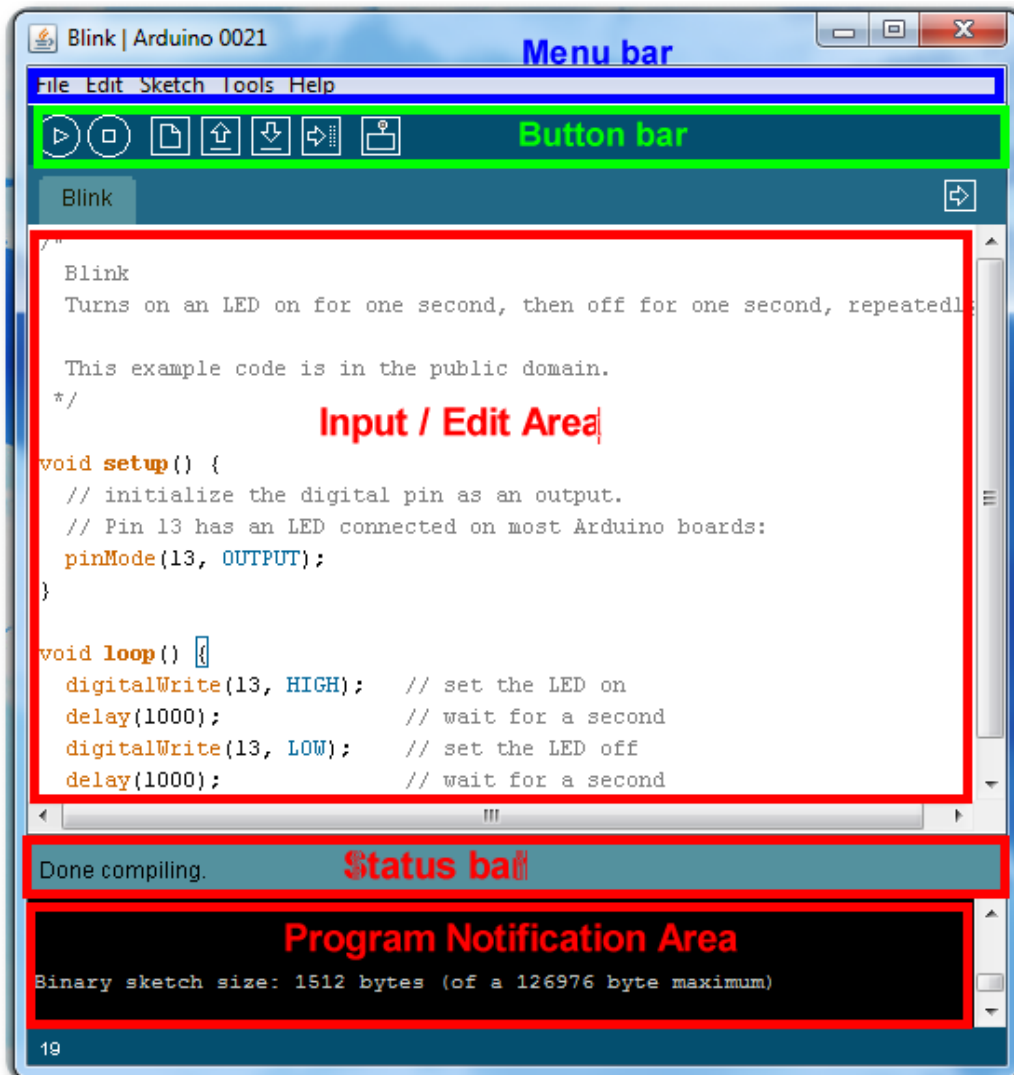
## 7.5. How to use Arduino

- Now I think you have got the basic idea of what is Arduino ? and why is it so popular ? So now lets have a look at how to use Arduino.
- When you order for your Arduino board, you will get a package similar to the image below:

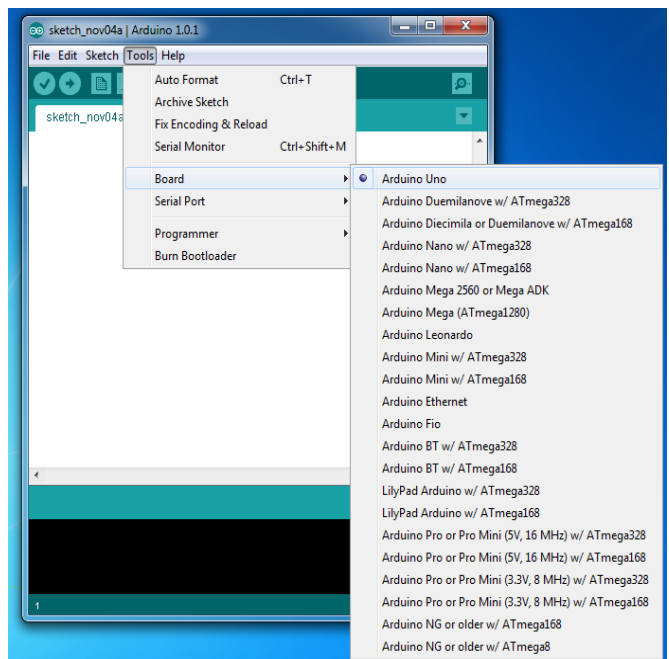
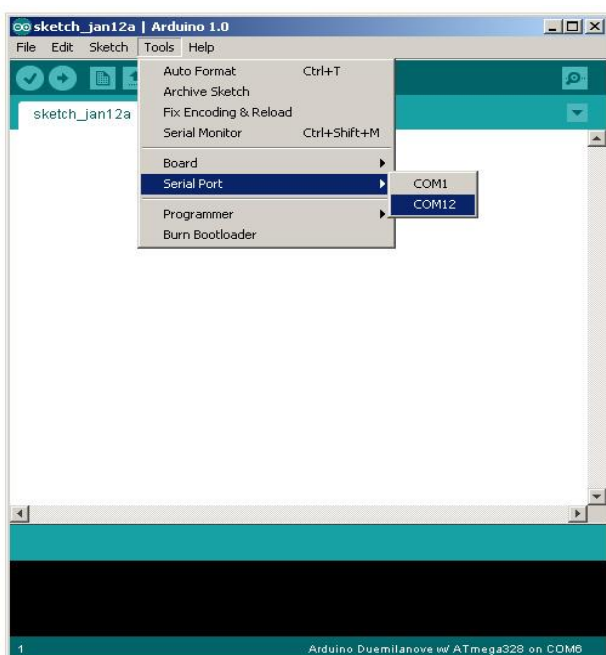


- 
- Along with this box, you will also have the USB cable, now take your Arduino board out of this box and plug the cable in it, connect the Arduino with your computer and you are ready to start working on it.
- In order to connect Arduino with your computer you have to install the Arduino drivers in Windows.
- That's all for today, hope I have conveyed some knowledge and you now know the basics of Arduino i.e. what is Arduino ? and why to use Arduino.

## 7.6. Arduino IDE



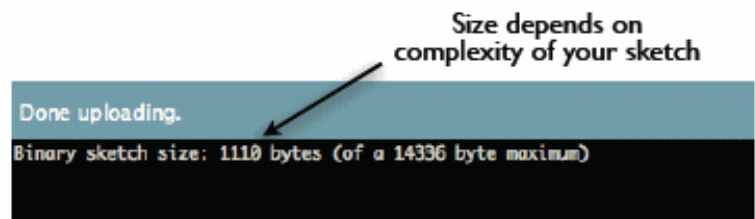
- Select Serial Port and Board



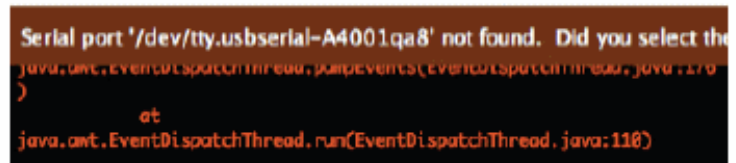


- Status Messages

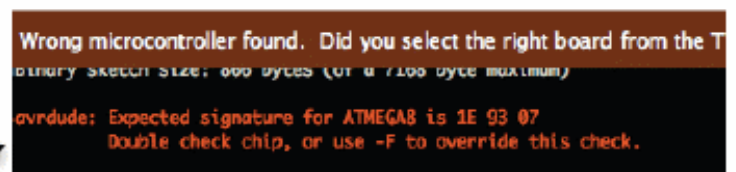
## Uploading worked



## Wrong serial port selected



## Wrong board selected



nerdy cryptic error messages

- In the above figure, I have used the simple blink example and I am gonna generate its hex file.
- Now when you click on the Preferences, a new window will pop up.
- In this new window, tick the **compilation** option as shown in below figure:

# Using Arduino

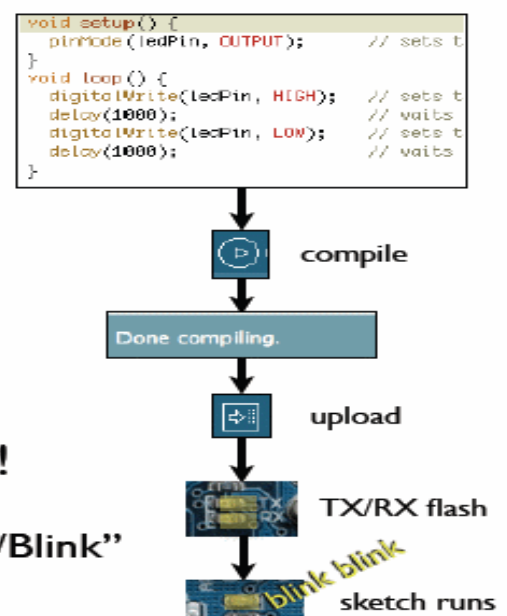
- Write your sketch
- Press Compile button (to check for errors)
- Press Upload button to program Arduino board with your sketch

Try it out with the “Blink” sketch!

Load “File/Sketchbook/Examples/Digital/Blink”

## 7.7. A Little Bit About Programming

- Code is case sensitive
- Statements are commands and must end with a semi-colon



- Comments follow a `//` or begin with `/*` and end with `*/`



## 7.8. Terminology

“*sketch*” – a program you write to run on an Arduino board

“*pin*” – an input or output connected to something.  
e.g. output to an LED, input from a knob.

“*digital*” – value is either HIGH or LOW.  
(aka on/off, one/zero) e.g. switch state

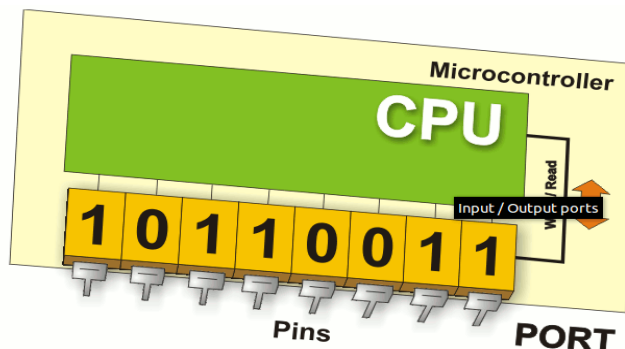
“*analog*” – value ranges, usually from 0-255.  
e.g. LED brightness, motor speed, etc.

## 7.9. Variables

- **boolean** (8 bit) – Chứa logic đơn giản là true/false
- **byte** (8 bit) – Chứa các số không dấu (chỉ chứa số dương không chứa số âm) từ 0-255
- **char** (8 bit) – Số có dấu từ -128 đến 127. IDE sẽ mặc định dùng biến này để chỉ ký tự tương ứng trong bảng mã ASCII khi dùng các lệnh, hàm liên quan đến ký tự.
- **unsigned char** (8 bit) – Tương tự như Byte. Thông thường bạn nên sử dụng Byte để tránh nhầm lẫn
- **word** (16 bit) – Số không dấu từ 0-65535

- **unsigned int** (16 bit)- Tương tự như Word. Bạn nên sử dụng Word để tránh nhầm lẫn. Tuy nhiên, một số bạn vẫn tiện tay dùng.
- **int** (16 bit) – Số có dấu từ -32768 đến 32767. Đây là biến thông dụng
- **unsigned long** (32 bit) – Số không dấu từ 0-4,294,967,295. thường sử dụng để lưu giá trị trong hàm millis(), đây là hàm trả về giá trị milli giây kể từ khi Arduino bắt đầu hoạt động.
- **long** (32 bit) – Số có dấu từ -2,147,483,648 to 2,147,483,647
- **float** (32 bit) – Số có dấu từ -3.4028235E38 to 3.4028235E38. Dấu chấm động thường ít được sử dụng trong Arduino vì trình biên dịch rất khó khăn để chuyển đổi thực thi các lệnh liên quan. Nếu thật sự không quá cần thiết, bạn không nên sử dụng đến nó.
- **String** – Biến chứa một chuỗi các ký tự (char).
- **Void** – Chỉ sử dụng để khai báo hàm khi không cần phải trả về bất cứ giá trị nào.

### 7.10. Digital I/O



- `pinMode(pin, mode)`: Sets pin to either INPUT or OUTPUT
- `digitalRead(pin)`: Reads HIGH or LOW from a pin
- `digitalWrite(pin, value)`: Writes HIGH or LOW to a pin
- Electronic stuff : Output pins can provide 40 mA of current, Writing HIGH to an input pin installs a 20KΩ pullup

### 7.11. Arduino Timing

- `delay(ms)`: Pauses for a few milliseconds
- `delayMicroseconds(us)`: Pauses for a few microseconds

### 7.12. Digital? Analog?

- Digital has two values: **on** and **off**
- Analog has many (infinite) values
- Computers don't really do analog, they **quantize**
- Remember the 6 analog input pins---here's how they work

### 7.13. Important functions

- `Serial.println(value)`;
  - o Prints the value to the Serial Monitor on your computer
- `pinMode(pin, mode)`;
  - o Configures a digital pin to read (input) or write (output) a digital value
- `digitalRead(pin)`;
  - o Reads a digital value (HIGH or LOW) on a pin set for input
- `digitalWrite(pin, value)`;
  - o Writes the digital value (HIGH or LOW) to a pin set for output



## 8. Simple Steps to of Arduino code simulator using Proteus

### 8.1. Write Arduino Codes in Arduino Software IDE

### 8.2. Configure Arduino Proteus Library Files

We are turning the Proteus as a Simulator for Arduino with the help of Arduino Preoteus library files. [Download Arduino Protius library from here](#), then copy and paste the 2 library files (ARDUINO.IDX, ARDUINO.LIB) in to LIBRARY folder of Proteus.

LIBRARY location of Proteus may be different according to your Proteus version.

#### Proteus 8 Users

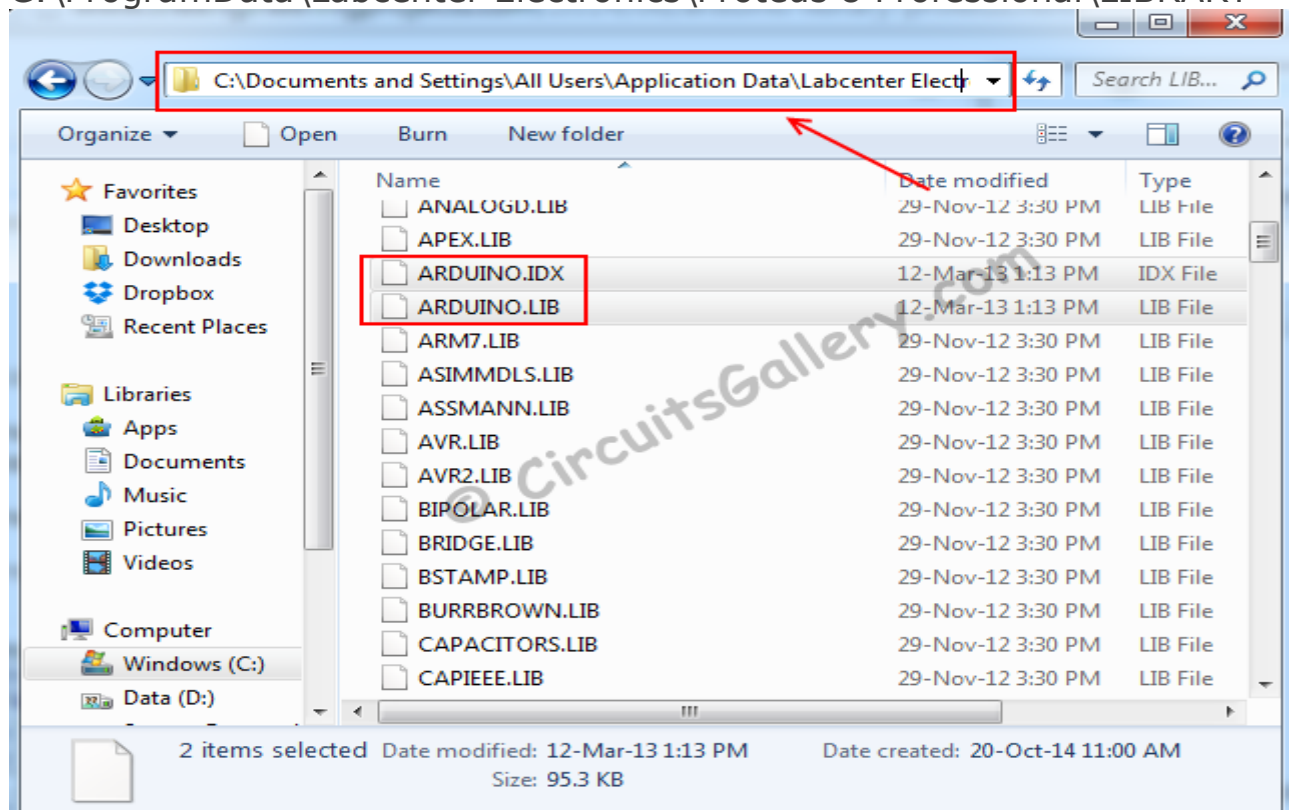
C:\Documents and Settings\All Users\Application Data\Labcenter Electronics\Proteus 8 Professional\LIBRARY

#### Proteus 7 Users

C:\Labcenter Electronics\Proteus 7 Professional\LIBRARY

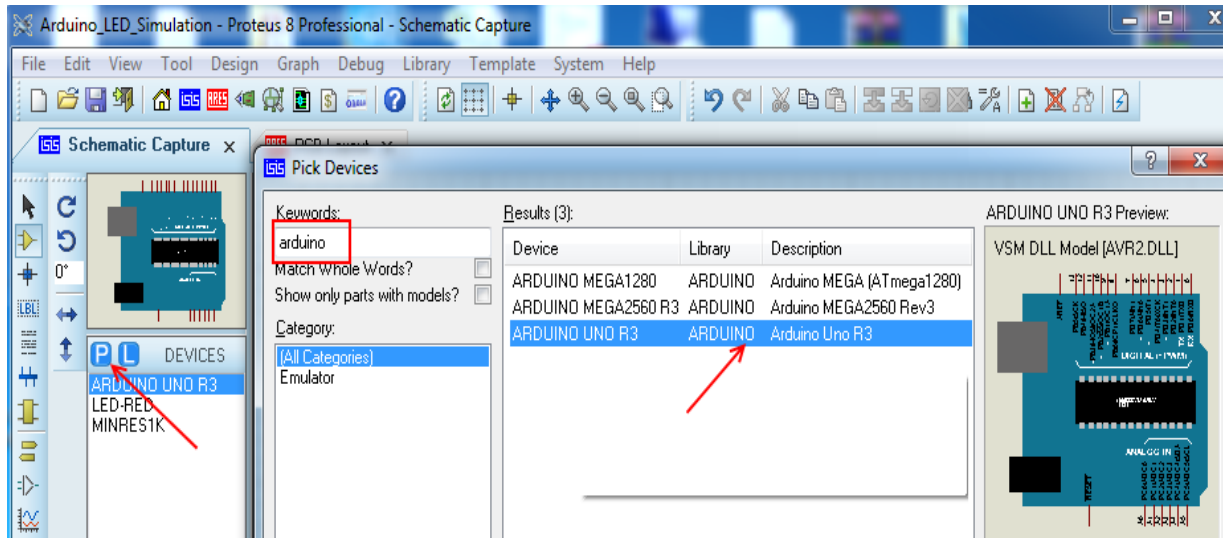
**Notes:** if you use windows-10, path of following is used:

C:\ProgramData\Labcenter Electronics\Proteus 8 Professional\LIBRARY

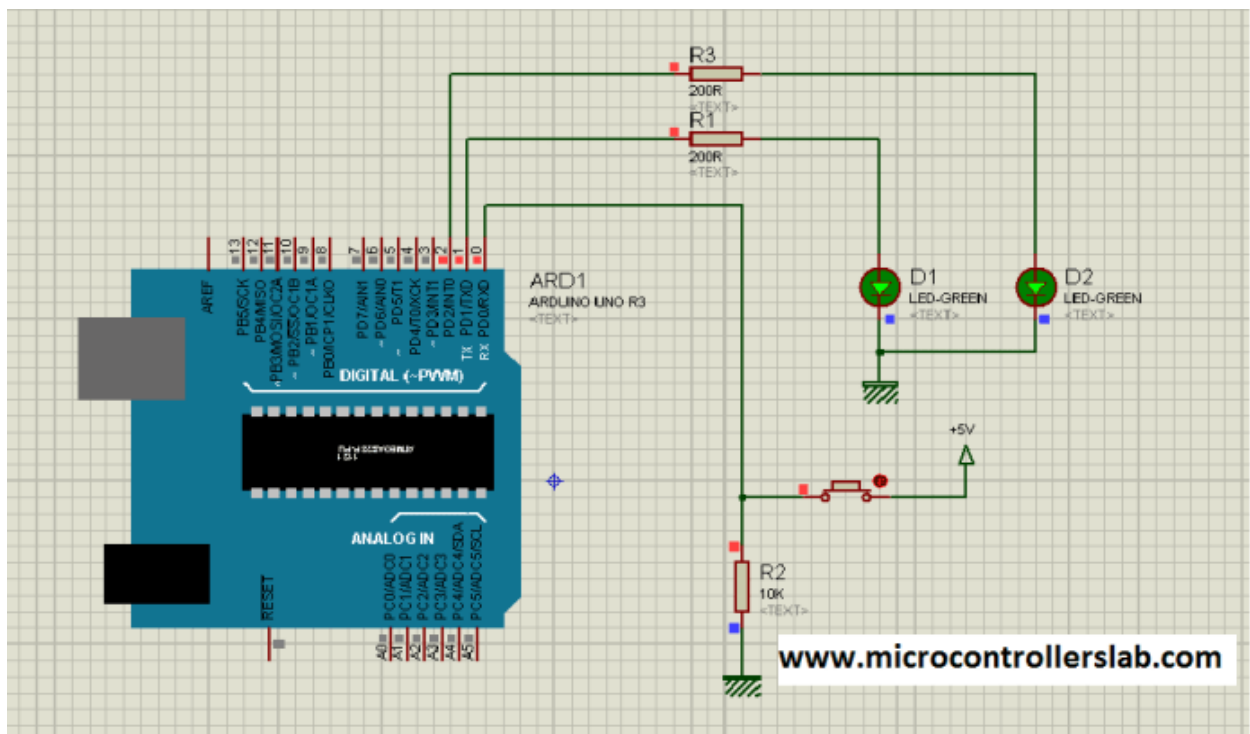


### 8.3. Draw schematics in Proteus

Draw the required schematic diagram of Proteus that you would like to Simulate, you can choose the **Arduino board** from the menu.



In our example I'm using LED blinking program and my schematics is shown below.



#### 8.4. Programming For Push Button With Arduino

To understand the programming of push button use with Arduino, First, you need to know the input function and its use. Explanation of the input function is given below :

**pinMode(pin number, INPUT):** I have already discussed pinMode function use in [LED blinking with Arduino UNO R3](#). The same function is used to declare pin as an input pin. Where **INPUT** argument is used to declare the specified pin number as an input pin. For example pinMode(0, INPUT) function declare pin 0 as a input pin.

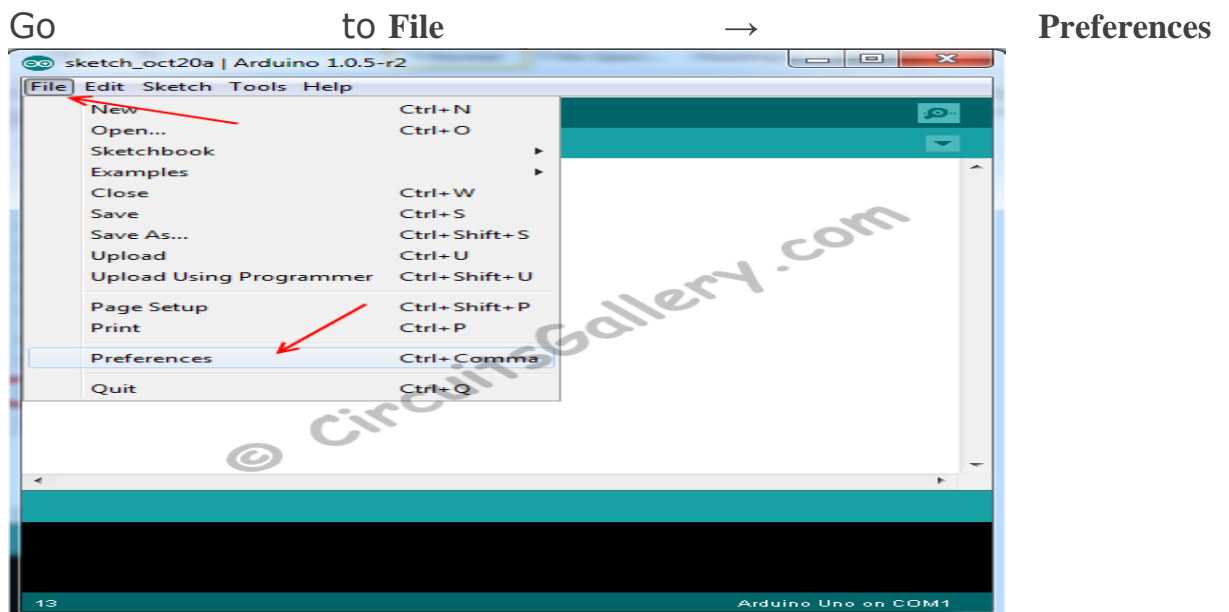
**digitalRead(pin number):** digitalRead function is used to read status of input pin either pin is at logic level high or logic level low. The output of this function is stored in another variable which can be used to perform other functions according to your application.

**digitalWrite(pin number, HIGH/LOW):** digitalWrite function is used to write or output at specified pin number either output is logic high or logic low.

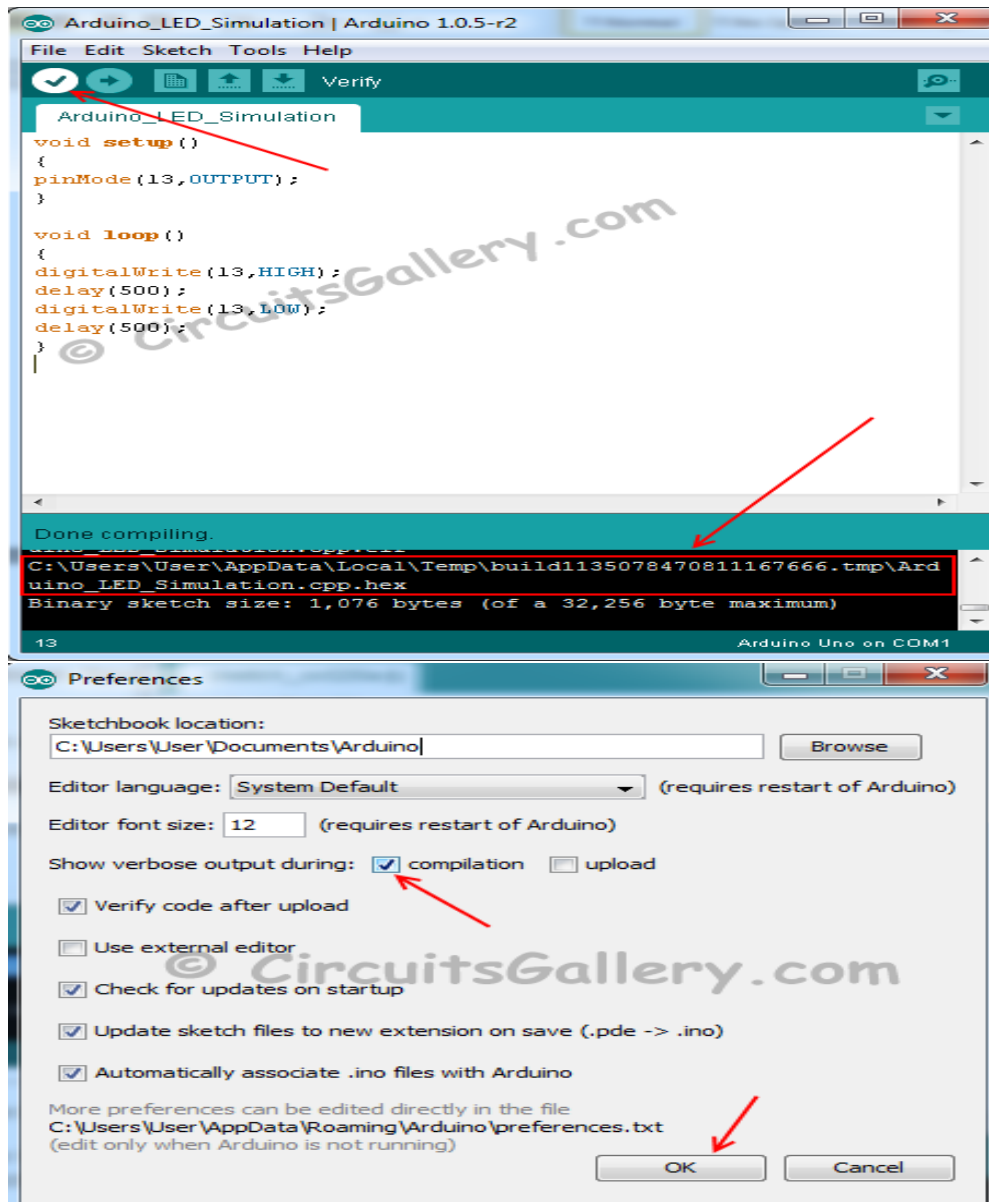
The code of the above circuit is given below. Copy this code to Arduino software.

```
int buttonStatus; // Variable declare to store status of digitalWrite
void setup() {
    pinMode(1, OUTPUT);
    pinMode(2, OUTPUT);
    pinMode(0, INPUT);
}
void loop()
{
    buttonStatus = digitalRead(0);
    if (buttonStatus == HIGH)
    {
        digitalWrite(1, HIGH);
        digitalWrite(2, HIGH);
    }
    else
    {
        digitalWrite(1, LOW);
        digitalWrite(2, LOW);
    }
}
```

#### 8.5. Build .hex file from Arduino Software

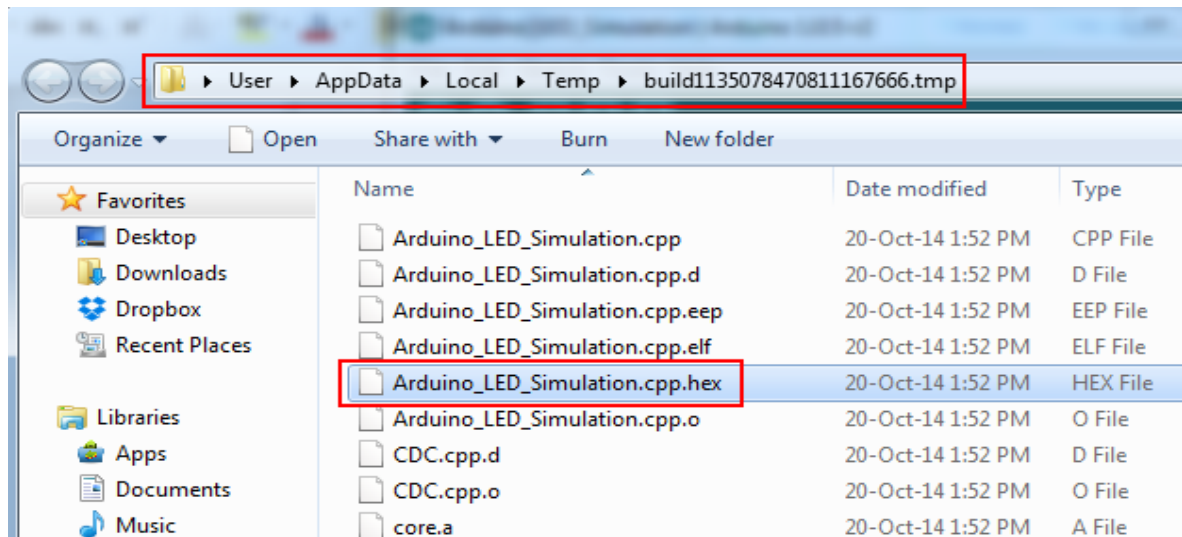


There will be one 2 check box near to 'Show verbose output during', please check the first one.



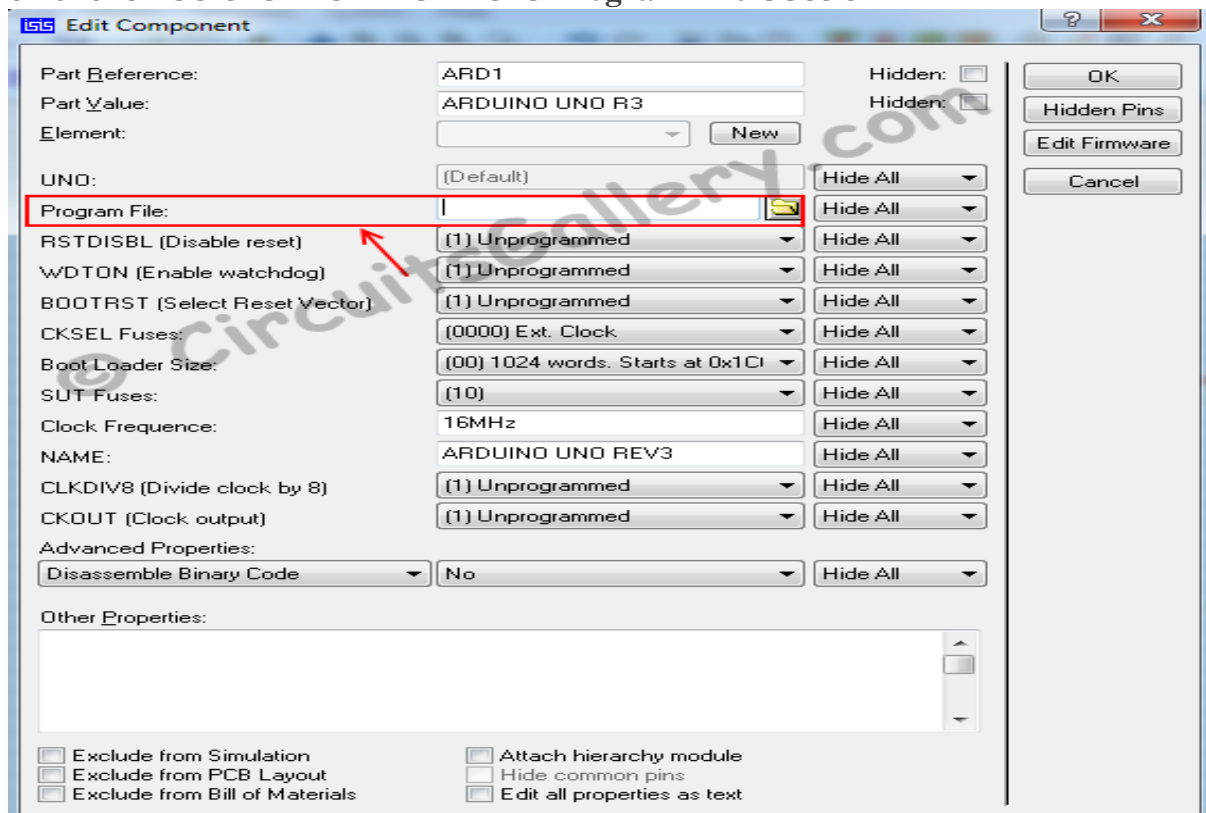
Now click **Compile** button.

Compilation yields .hex file, go to the directory location marked above (may be different location in your case), this is the **location of your .hex file**. Copy the file and keep it in a safe location.



## 8.6. Load the .hex file to Proteus

To load .hex file to the Arduino board, just double click on the board and browse the .hex file in the **Program File** section.

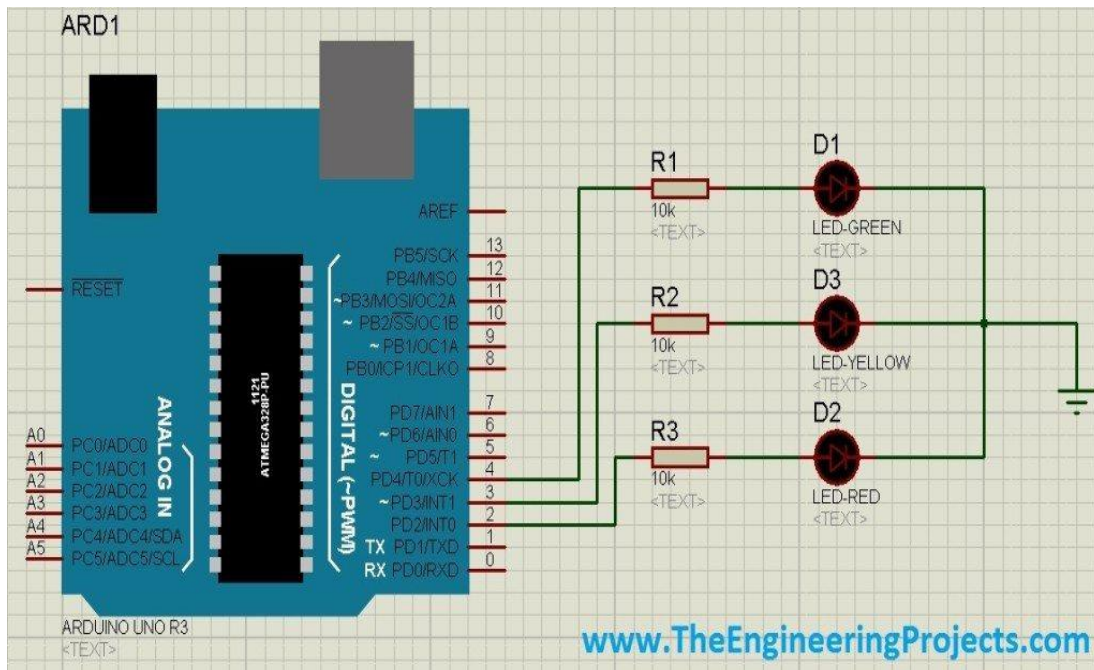


Everything is ready to go! **Run the Simulation** now. You can see the simulated output of the Arduino Program, watch the video for my simulation output.

## 9. Traffic signal control

### 9.1.circuit in Proteus





## 10. Lưu file Hex vào vị trí mong muốn

- Bước 1: Mở tập tin **C:\Program Files\Arduino\lib\preferences.txt** bằng Notepad hoặc Notepad++
- Bước 2: Thêm dòng lệnh sau vào cuối file preferences.txt: **build.path = <path>** (<path> là đường dẫn đến thư mục mà bạn muốn chứa file hex sau khi Arduino hoàn tất quá trình biên dịch)
- Ví dụ: Để lưu vào thư mục **Built\_Arduino** (mình vừa tạo) trên desktop của mình, mình viết như sau:

```
#launcher.linux = xdg-open

# FULL SCREEN (PRESENT MODE)
run.present.bgcolor = #666666
run.present.stop.color = #cccccc
# starting in release 0159, don't use full screen exclusive anymore
run.present.exclusive = false
# use this by default to hide the menu bar and dock on OSX
run.present.exclusive.macosx = true

# ARDUINO PREFERENCES
target_package = arduino
target_platform = avr
board = uno
software=ARDUINO
# Warn when data segment uses greater than this percentage
build.warn_data_percentage = 75

programmer = arduino:avrispmkii


upload.using = bootloader
upload.verify = true

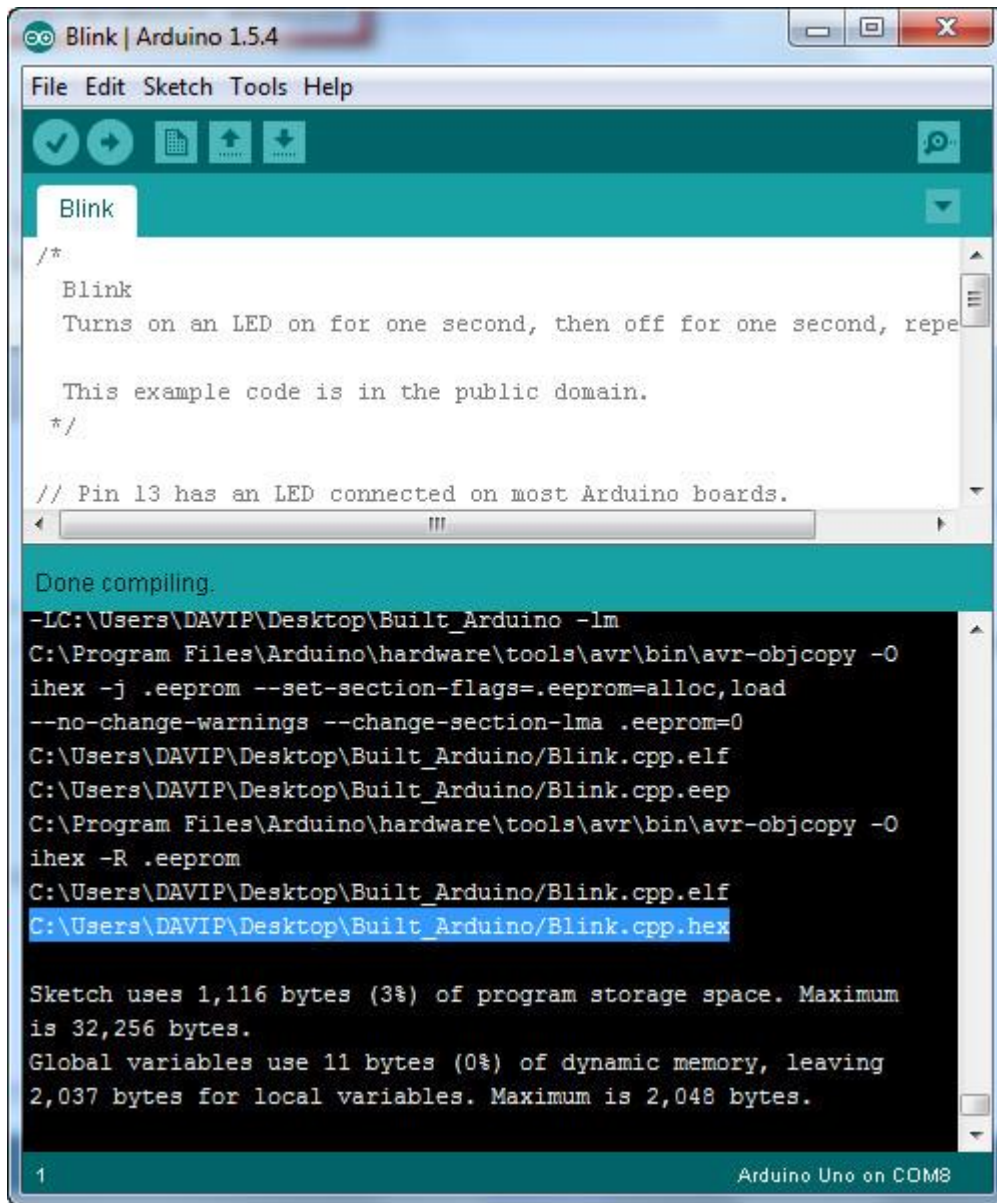
serial.port=COM1
serial.databits=8
serial.stopbits=1
serial.parity=N
serial.debug_rate=9600

# I18 Preferences

# default chosen language (none for none)
editor.languages.current =
build.path = C:\Users\DAVIP\Desktop\Built_Arduino
```



- Sau đó bạn nhớ ấn **Ctrl + S** để **Save** lại nhé :D
- Tiếp theo bạn **tắt IDE đi và mở lại** (nhất thiết phải vậy nhé), mở **CODE** 
- Blink** led nhấp nháy như trên mình trình bày và **Verify**
- Bạn sẽ thấy file .hex đã không còn ở thư mục temp khó tìm nữa mà vào đúng thư mục mình mong muốn.



The screenshot shows the Arduino IDE 1.5.4 interface. The top menu bar includes File, Edit, Sketch, Tools, and Help. Below the menu is a toolbar with icons for opening, saving, and uploading. The main editor window displays the 'Blink' sketch, which includes a comment block describing the sketch's function and a line of code: `// Pin 13 has an LED connected on most Arduino boards.`. Below the editor is a status bar showing '1' and 'Arduino Uno on COM8'. The bottom panel is the output window, which displays the compilation results. It starts with 'Done compiling.' followed by a series of command-line commands and their outputs, including the path to the generated hex file: `C:\Users\DAVIP\Desktop\Built_Arduino/Blink.cpp.hex`. The output also shows the program size: 'Sketch uses 1,116 bytes (3%) of program storage space. Maximum is 32,256 bytes.' and 'Global variables use 11 bytes (0%) of dynamic memory, leaving 2,037 bytes for local variables. Maximum is 2,048 bytes.'

```
/*
  Blink
  Turns on an LED on for one second, then off for one second, repeatedly.

  This example code is in the public domain.
  */

// Pin 13 has an LED connected on most Arduino boards.

Done compiling.
-LC:\Users\DAVIP\Desktop\Built_Arduino -lm
C:\Program Files\Arduino\hardware\tools\avr\bin\avr-objcopy -O ihex -j .eeprom --set-section-flags=.eeprom=alloc,load --no-change-warnings --change-section-lma .eeprom=0 C:\Users\DAVIP\Desktop\Built_Arduino/Blink.cpp.elf C:\Users\DAVIP\Desktop\Built_Arduino/Blink.cpp.eep
C:\Program Files\Arduino\hardware\tools\avr\bin\avr-objcopy -O ihex -R .eeprom C:\Users\DAVIP\Desktop\Built_Arduino/Blink.cpp.elf C:\Users\DAVIP\Desktop\Built_Arduino/Blink.cpp.hex

Sketch uses 1,116 bytes (3%) of program storage space. Maximum is 32,256 bytes.
Global variables use 11 bytes (0%) of dynamic memory, leaving 2,037 bytes for local variables. Maximum is 2,048 bytes.
```

11.