

# README

## Seizure Simulation Framework

This project provides a simulation pipeline for generating synthetic seizure data using different bifurcation-based dynamotypes, aligned with mechanisms from dynamical systems theory. The simulations aim to replicate neural activity patterns and model the transitions into and out of seizures.

## Overview

This repository contains scripts to:

- Simulate seizures based on Hysteresis, Slow Wave, and Piecewise bifurcation dynamics
- Annotate onset and offset times
- Post-process signals with high-pass filtering and additive pink noise
- Output labeled seizure datasets

## Key Features

- Generates seizures across dynamotype classes
- Uses .fit models to estimate the noise level per bifurcation path point
- Outputs labeled cell arrays: {signal, onset\_time, offset\_time}
- Allows for parameter sweeping (though only onset/offset curves are currently varied)
- High-pass filtering and pink noise augmentation included in post-processing

## Simulation Workflow

### 1. Choose Generator

You may choose from:

- hysteresis
- Slow wave
- piecewise

Each generator will:

- Select random points on bifurcation onset/offset curves
- Construct a path (arc/circle/piecewise)
- Integrate using the Euler-Maruyama method with stochastic noise  
Save simulated signal with labeled onset/offset times

### 2. Post-Processing

Run `post_processing.m` to:

- Normalize signal
- Apply high-pass filtering to model electrode drift
- Add “signal acquisition” noise
- Output: {signal, onset, offset} array of `post_processed_seizures`

## Hyperparameters & Known Challenges

This simulation framework allows users to model seizures via bifurcation dynamics. The core simulation uses fixed hyperparameters ( $k$ ,  $k_{\text{fast}}$ ,  $\alpha$ ,  $d_{\text{star}}$ , and  $\sigma$ ) and sweeps only over onset and offset curve points by default. This section documents all hyperparameters and the implications of modifying or sweeping them.

### Hyperparameters Used

Parameter	Description
$k$	Controls the speed of the slow variable. Lower $k$ leads to longer seizures. Requires longer $t_{\text{max}}$ .
$k_{\text{fast}}$	Controls fast subsystem frequency.
$\alpha$	Scales the amplitude of the seizure in the fast subsystem
$d_{\text{star}}$	Excitability parameter modulating distance from the resting state
$\sigma$	Noise level injected into the system. Set via .fit files tied to onset/offset bifurcation path points.
$t_{\text{max}}$	Total simulation time. Must be increased for longer seizures (e.g., with small $k$ ).
$t_{\text{step}}$	Integration time step.
$N$	Hysteresis branch mode selector. Affects loop behavior (e.g., upper vs. lower branch dynamics).
$x_0$	Initial condition $[0; 0; 0]$ . Start state of the system.

## Noise Handling (sigma)

- Noise is dynamically set from .fit models per onset/offset curve point.
- You must modify the code if you want to:
  - Manually specify sigma
  - Use a custom noise distribution
- Key note: Noise is proportional to seizure length and path length. Excessive noise may:
  - Disrupt waveform clarity
  - Cause stuttering in both the main signal and x3
  - Hinder onset/offset detection (especially for hysteresis models in the bistable region)

## Sweeping Other Parameters: Known problems

Parameter	Known Challenges
k	Small values → longer seizures → may not finish within tmax. You must increase tmax when sweeping low k.
alpha, k_fast, dstar	Arbitrary values are not always valid. Poor combinations may:

- Fail to generate seizures
- Result in unstable or uninformative dynamics which requires manual tuning and verification

## Bistability & Detection Issues

- Hysteresis models involve bistability (rest + seizure attractors). This creates:
  - Path-dependent responses
  - Hysteresis loops
- Under high noise:
  - System may "stutter" near transition thresholds
  - Difficult to determine seizure boundaries
  - $x_3$  may oscillate near saddle-node bifurcations

## File Descriptions

### curves.mat

Contains select portions of bifurcation curves for **hysteresis bursts**.

- Each curve is stored as a MATLAB array.
- Example: *SHB* is a  $3 \times 62$  double where:
  - **1st dimension:**  $\mu_2$
  - **2nd dimension:**  $\mu_1$
  - **3rd dimension:**  $nu$
- Used in example **Class SN/SH**

### curves2.mat

Contains select portions of bifurcation curves for **slow wave bursts**.

- Each curve is stored as a MATLAB array.
- Example: *SNIC* is a  $3 \times 44$  double where:
  - **1st dimension:**  $\mu_2$
  - **2nd dimension:**  $\mu_1$
  - **3rd dimension:**  $nu$
- Used in example **Class SNIC/SH**

### curves2.mat

Contains **all bifurcation curves** (more comprehensive than ``curves.mat`` and ``curves2.mat``).

- Used for **piecewise** slow wave bursts

### **test\_mesh.mat**

- Contains a mesh (vertices and faces) for plotting:
  - Bistable regions
  - Seizure regions
  - Active rest regions

### **Sphere\_mesh.mat**

- Contains a mesh (vertices and faces) for plotting the **sphere**.

### **.fit Files (Hysteresis & Slow Wave Classes)**

The effect of **dynamical noise** depends on the path through parameter space because:

1. Integration methods scale differently for different paths.
2. Noise produces varying effects in different dynamical regimes.

To account for this, we empirically modeled noise amplitude for each dynamotype:

- Manually adjusted noise for a subset of paths to achieve **5-10% deviation in seizure length** (across 10 simulations).
- Fitted a surface (*linearinterp* in MATLAB) to tested points.
- These surfaces assign an appropriate noise amplitude to every simulated path.

This noise model serves to create a relationship between appropriate noise and paths for each class.