view_frames Result Recorded at time: 3387.309 world Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (3387.309 sec old) Most recent transform: 0.000 (3387.309 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec base_link kinect2_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 49.458 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (3387.309 sec old) Most recent transform: 0.000 (3387.309 sec old) Most recent transform: 3387.297 (0.012 sec old) Buffer length: 2.952 sec Buffer length: 0.000 sec Buffer length: 0.000 sec kinect2_rgb_link shoulder_link base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 49.458 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (3387.309 sec old) Most recent transform: 0.000 (3387.309 sec old) Most recent transform: 3387.297 (0.012 sec old) Buffer length: 2.952 sec Buffer length: 0.000 sec Buffer length: 0.000 sec upper_arm_link kinect2_ir_link kinect2_rgb_optical_frame Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 49.458 Hz Average rate: 10000.000 Hz Most recent transform: 3387.297 (0.012 sec old) Most recent transform: 0.000 (3387.309 sec old) Buffer length: 2.952 sec Buffer length: 0.000 sec forearm_link kinect2_ir_optical_frame Broadcaster: /robot_state_publisher Average rate: 49.458 Hz Most recent transform: 3387.297 (0.012 sec old) Buffer length: 2.952 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 49.458 Hz Most recent transform: 3387.297 (0.012 sec old) Buffer length: 2.952 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 49.458 Hz Most recent transform: 3387.297 (0.012 sec old) Buffer length: 2.952 sec wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (3387.309 sec old) Most recent transform: 0.000 (3387.309 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec ee_link tool0 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (3387.309 sec old) Buffer length: 0.000 sec robotiq_coupler Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (3387.309 sec old) Buffer length: 0.000 sec robotiq_85_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 49.458 Hz Average rate: 49.458 Hz Average rate: 49.458 Hz Average rate: 49.458 Hz Most recent transform: 3387.297 (0.012 sec old) Buffer length: 2.952 sec Buffer length: 2.952 sec Buffer length: 2.952 sec Buffer length: 2.952 sec robotiq_85_left_knuckle_link robotiq_85_right_knuckle_link robotiq_85_left_inner_knuckle_link robotiq_85_right_inner_knuckle_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 49.458 Hz Average rate: 49.458 Hz Most recent transform: 0.000 (3387.309 sec old) Most recent transform: 3387.297 (0.012 sec old) Most recent transform: 3387.297 (0.012 sec old) Most recent transform: 0.000 (3387.309 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 2.952 sec Buffer length: 2.952 sec robotiq_85_left_finger_link robotiq_85_left_finger_tip_link robotiq_85_right_finger_link robotiq_85_right_finger_tip_link