# **Package**

June 22, 2019

Type Package

Title Stationary Linear Models
Version 1.0.0
Author Emmanuel Caron, Jérôme Dedecker, Bertrand Michel
Maintainer Emmanuel Caron <emmanuelcaron3@gmail.com></emmanuelcaron3@gmail.com>
<b>Description</b> The package provides statistical procedures for linear regression in the general context where the errors are assumed to be correlated. Different ways to estimate the asymptotic covariance matrix of the least squares estimators are available. Starting from this estimation of the covariance matrix, the confidence intervals and the usual tests on the parameters are modified. The functions of this package are very similar to those of lm: it contains methods such as summary, plot, confint and predict. The slm package is described in the paper by E. Caron, J. Dedecker and B. Michel (2019), Linear regression with stationary errors: the R package slm, arXiv preprint arXiv:1906.06583.
License GPL-3 + file LICENSE
Encoding UTF-8
LazyData true
RoxygenNote 6.1.1
<b>Depends</b> R (>= $2.10$ )
Collate 'slm-main.R'     'slm.R'     'generative.R'     'auxiliary-fun.R'     'slm-method.R'     'data.R'
Imports ltsa,
methods, stats, datasets, capushe
R topics documented:
slm-package

2 slm-package

	cov_kernel	(
	cov_matrix_estimator	1
	cov_method	1
	cov_select	8
	cov_spectralproj	9
	generative_model	10
	generative_process	
	plot.slm	
	predict.slm	
	Rboot	
	rectangle	
	shan	
	slm	
	slm-class	
	summary.slm	
	trapeze	
	triangle	
Index		2
		_
slm-	ackage slm: A package for stationary linear models	

#### **Description**

The slm package enables to fit linear models on datasets considering the dependence between the observations. Most of the functions are based on the functions and methods of lm, with the same arguments and the same format for the outputs.

# slm function, in "slm-main.R"

The slm function is the main function of this package. Its architecture is the same as the lm function but it takes into account the possible correlation between the observations. To estimate the asymptotic covariance matrix of the least squares estimator, several approaches are available: "fitAR" calls the cov\_AR function, "spectralproj" the cov\_spectralproj function, "kernel" the cov\_kernel function, "efromovich" the cov\_efromovich function and "select" the cov\_select function.

#### Methods for slm, in "slm-method.R"

The slm function has several associated methods, which are the same as for the lm function. The available methods are: summary, confint, predict and plot.

#### Others functions, in "auxiliary-fun.R"

The package has some auxiliary functions, in particular some predefined kernels for the kernel method of slm function: the trapeze kernel, the triangle kernel and the rectangular kernel. The user can also define his own kernel and put it in the argument kernel\_fonc in the slm function.

### Generative functions, in "generative.R"

The generative\_process function generates some stationary processes. The generative\_model function generates some designs.

confint.slm 3

#### Data

The package contains a dataset "shan". This dataset comes from a study about fine particle pollution in the city of Shanghai. The data are available on the following website https://archive.ics.uci.edu/ml/datasets/PM2.5+Data+of+Five+Chinese+Cities#.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv* preprint arXiv:1906.06583. https://arxiv.org/abs/1906.06583.

confint.slm

Confidence intervals for the Model Parameters

### Description

Computes confidence intervals for the model parameters.

### Usage

```
## S3 method for class 'slm'
confint(object, parm = NULL, level = 0.95, ...)
```

### **Arguments**

object a fitted model object of class slm.

parm a specification of which parameters are to be given confidence intervals, that is

a vector of numbers. If missing, all parameters are considered.

level the confidence level required.

... additional argument(s) for methods.

#### Value

This function returns the confidence intervals for the parameters of the model.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

#### See Also

```
confint.lm.
```

4 cov\_AR

#### **Examples**

```
data("shan")
reg1 = slm(shan$PM_Xuhui ~ . , data = shan, method_cov_st = "fitAR", model_selec = -1)
confint(reg1, level = 0.8)

data("co2")
y = as.vector(co2)
x = as.vector(time(co2)) - 1958
reg2 = slm(y ~ x + I(x^2) + I(x^3) + sin(2*pi*x) + cos(2*pi*x) + sin(4*pi*x) +
cos(4*pi*x) + sin(6*pi*x) + cos(6*pi*x) + sin(8*pi*x) + cos(8*pi*x),
method_cov_st = "fitAR", model_selec = -1, plot = TRUE)
confint(reg2, level = 0.9)
```

cov\_AR

Covariance estimation by AR fitting

### **Description**

Fit an autoregressive model to the process and compute the theoretical autocovariances of the fitted AR process. By default, the order is chosen by using the AIC criterion (model\_selec = -1).

#### Usage

```
cov_AR(epsilon, model_selec = -1, plot = FALSE)
```

#### **Arguments**

epsilon an univariate process.

model\_selec the order of the method. If model\_selec = -1, it is chosen automatically by

using the AIC criterion.

plot logical. By default, plot = FALSE. If plot = TRUE, then the ACF and the PACF

of the vector epsilon is plotted.

#### Value

The function returns the vector of the theoretical autocovariances of the AR process fitted on the process epsilon.

model\_selec the order selected.

cov\_st the vector of theoretical autocovariances of the fitted AR process.

#### References

P.J. Brockwell and R.A. Davis (1991). Time Series: Theory and Methods. *Springer Science & Business Media*.

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv* preprint *arXiv*:1906.06583. https://arxiv.org/abs/1906.06583.

```
x = arima.sim(list(ar=c(0.4,0.2)),1000)

cov\_AR(x, model\_selec = 2, plot = TRUE)
```

cov\_efromovich 5

	_efromc	
COV	D T C C M C	พหาก
COV_		VATCII

Spectral density estimation: Efromovich method

### **Description**

This method estimates the spectral density and the autocovariances of the error process via a lagwindow estimator based on the rectangular kernel (see P.J. Brockwell and R.A. Davis (1991). Time Series: Theory and Methods. *Springer Science & Business Media*, page 330). The lag is computed according to Efromovich's algorithm.

### Usage

```
cov_efromovich(epsilon, plot = FALSE)
```

#### **Arguments**

epsilon an univariate process.

plot logical. By default, plot = FALSE. If plot = TRUE, the ACF of the process

epsilon is plotted.

#### Value

The function returns the estimated autocovariances of the process, that is the Fourier coefficients of the spectral density estimates, and the dimension chosen by the algorithm.

model\_selec the number of selected autocovariance terms.

cov\_st the estimated autocovariances.

#### References

- P.J. Brockwell and R.A. Davis (1991). Time Series: Theory and Methods. *Springer Science & Business Media*.
- E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.
- S. Efromovich (1998). Data-driven efficient estimation of the spectral density. *Journal of the American Statistical Association*, 93(442), 762-769.

```
x = arima.sim(list(ar=c(0.4,0.2)),1000)
cov_efromovich(x)
```

cov\_kernel

		1
COV	kerne:	
CUV	תכוווכ.	1

Kernel estimation: bootstrap method

### Description

This method estimates the spectral density and the autocovariances of the error process via a lagwindow (or kernel) estimator (see P.J. Brockwell and R.A. Davis (1991). Time Series: Theory and Methods. *Springer Science & Business Media*, page 330). The weights are computed according to a kernel K and a bandwidth h (or a lag), to be chosen by the user. The lag can be computed automatically by using a bootstrap technique (via the Rboot function).

#### Usage

```
cov_kernel(epsilon, model_selec = -1,
  model_max = min(50,length(epsilon)/2), kernel_fonc = triangle,
  block_size = length(epsilon)/2, block_n = 100, plot = FALSE)
```

#### **Arguments**

epsilon an univariate process.

model\_selec the order of the method. If model\_selec = -1, the method chooses the treshold

automatically. If model\_selec = k, then only k autocovariance terms are kept

and smoothed by the kernel.

model\_max the maximal order.

kernel\_fonc define the kernel to use in the method. The user can give his own kernel function.

block\_size size of the bootstrap blocks. block\_size must be greater than model\_max.

block\_n blocks number to use for the bootstrap.

plot logical. By default, plot = FALSE. If plot = TRUE, the risk curve is returned

and the ACF of the process.

#### Value

The method returns the tapered autocovariance vector with model\_selec autocovariance terms.

model\_selec the number of selected autocovariance terms.

cov\_st the estimated autocovariances.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

W.B. Wu, M. Pourahmadi (2009). Banding sample autocovariance matrices of stationary processes. *Statistica Sinica*, pp. 1755–1768.

```
x = arima.sim(list(ar=c(0.7)),1000)

cov_kernel(x, model_selec = -1, block_n = 10, plot = TRUE)
```

cov\_matrix\_estimator 7

cov\_matrix\_estimator Covariance matrix estimator for slm object

#### **Description**

This function gives the estimation of the asymptotic covariance matrix of the least squares estimator in the case of the linear regression model with strictly stationary errors.

#### Usage

```
cov_matrix_estimator(object)
```

#### **Arguments**

object

an object of class slm.

#### **Details**

The function computes the covariance matrix estimator of the least squares estimator from the vector cov\_st of a slm object. If the user has given the argument Cov\_ST in the slm object, then it is used to compute the final covariance matrix. For the methods "efromovich", "kernel" and "select", the covariance matrix estimator may not be positive definite. Then we apply the "Positive definite projection" algorithm, which consists in replacing all eigenvalues lower or equal to zero with the smallest positive eigenvalue of the covariance matrix.

#### Value

This function returns the covariance matrix estimator.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv* preprint arXiv:1906.06583. https://arxiv.org/abs/1906.06583.

 ${\tt cov\_method}$ 

Methods to estimate the autocovariances of a process

#### **Description**

This function gives the estimation of the autocovariances of the error process, with the method chosen by the user. Five methods are available: "fitAR", "spectralproj", "efromovich", "kernel" and "select".

# Usage

```
cov_method(epsilon, method_cov_st = "fitAR", model_selec = -1,
  model_max = NULL, kernel_fonc = NULL, block_size = NULL,
  block_n = NULL, plot = FALSE)
```

8 cov\_select

#### **Arguments**

epsilon an univariate process. method\_cov\_st the method chosen by the user. model\_selec the order of the method. If  $model_selec = -1$ , the method works automatically. model\_max maximal dimension of the method. to use if method\_cov\_st = kernel. Define the kernel to use in the method. kernel\_fonc The user can give his own kernel function. size of the bootstrap blocks if method\_cov\_st = kernel. block\_size must be block\_size greater than model\_max. block\_n blocks number to use for the bootstrap if method\_cov\_st = kernel. logical. By default, plot = FALSE. plot

#### Value

The function returns the autocovariances computed with the chosen method.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

# **Examples**

```
x = arima.sim(list(ar=c(0.4,0.2)),1000)
cov_method(x, method_cov_st = "fitAR", model_selec = -1)
```

cov\_select Covariances Selection

#### **Description**

Allows the user to select the lags of the autocovariance terms of the process to be kept.

#### Usage

```
cov_select(epsilon, model_selec, plot = FALSE)
```

### **Arguments**

epsilon an univariate process.

model\_selec a vector with the positive lags of the selected autocovariance terms. The variance

(lag = 0) is automatically selected.

plot logical. By default, plot = FALSE. If plot = TRUE the ACF of the process is

plotted.

### **Details**

In the framework of slm, this is a manual method for estimating the covariance matrix of the error process by only selecting some autocovariance terms from the residual autocovariances.

cov\_spectralproj 9

#### Value

This function returns the estimated autocovariance terms.

model\_selec the vector with the positive lag of the selected autocovariance terms.

cov st the vector of the selected autocovariances.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv* preprint arXiv:1906.06583. https://arxiv.org/abs/1906.06583.

#### **Examples**

```
x = arima.sim(list(ar=c(0.2,0.1,0.25)),1000)

cov_select(x, c(1,3,5))
```

cov\_spectralproj

Data-driven spectral density estimation

#### **Description**

Computes a data-driven histogram estimator of the spectral density of a process and compute its Fourier coefficients, that is the associated autocovariances. For a dimension d, the estimator of the spectral density is an histogram on a regular basis of size d. Then we use a penalized criterion in order to choose the dimension which balance the bias and the variance. The penalty is of the form c\*d/n, where c is the constant and n the sample size. The dimension and the constant of the penalty are chosen with the slope heuristic method, with the dimension jump algorithm (from package "capushe").

### Usage

```
cov_spectralproj(epsilon, model_selec = -1,
  model_max = min(100,length(epsilon)/2), plot = FALSE)
```

### Arguments

epsilon an univariate process.

model\_selec the dimension of the method. If model\_selec = -1, the method works auto-

matically and take a dimension between 1 and model\_max.

model\_max the maximal dimension. By default, it is equal to the minimum between 100 and

the length of the process divided by 2.

plot logical. By default, plot = FALSE. If plot = TRUE, plot the spectral density

estimator of the process.

#### Value

The function returns the estimated autocovariances of the process, that is the Fourier coefficients of the spectral density estimates, and the dimension chosen by the algorithm.

model\_selec the dimension selected.
cov\_st the estimated autocovariances.

10 generative\_model

#### References

J.P. Baudry, C. Maugis B. and Michel (2012). Slope heuristics: overview and implementation. *Statistics and Computing*, 22(2), 455–470.

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

F. Comte (2001). Adaptive estimation of the spectrum of a stationary Gaussian sequence. *Bernoulli*, 7(2), 267-298.

#### See Also

The R package capushe.

Slope heuristic algorithm DDSE.

Dimension jump algorithm Djump.

### **Examples**

```
x = arima.sim(list(ar=c(0.2), ma=c(0.3,0.05)), n=1000)

cov\_spectralproj(x, model\_selec = -1)
```

generative\_model

Some linear model

#### **Description**

This function returns a design for the regression linear model, without the intercept. The user can choose one of the two models: "mod1" or "mod2". The first model "mod1" contains just one column, equal to  $i^2 + X_i$ , i = 1, ..., n, where X is an AR(1) process with phi\_1 = 0.5.

The second model "mod2" contains two columns, the first equal to  $log(i) + sin(i) + X_i$  and the second equal to i, for i = 1, ..., n. The process X is again an AR(1) process with phi\_1 = 0.5. More information about "mod2" is available in the paper of E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm.  $arXiv\ preprint\ arXiv:1906.06583$ . https://arxiv.org/abs/1906.06583.

#### Usage

```
generative_model(n, model = "mod1")
```

#### **Arguments**

n samples size.

model a list of character to choose the model.

### Value

This function returns a data-frame which contains a simulated random design.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

generative\_process 11

#### **Examples**

```
generative_model(500,"mod1")
```

generative\_process

Some stationary processes

### **Description**

This is a generative function. The user chooses one of the process: "AR1", "AR12", "MA12", "Nonmixing", "sysdyn", and it generates the chosen process. These processes are fully described in the paper of E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv* preprint *arXiv*:1906.06583. https://arxiv.org/abs/1906.06583.

#### Usage

```
generative_process(n, process = "AR1", phi = "numeric",
    theta = "numeric")
```

# Arguments

n sample size.

process a list of character to choose the process.

phi a numeric vector with AR parameters if the process is "AR1" or "AR12".

theta a numeric vector with MA parameters if the process is "MA12".

#### Value

This function returns a vector of observations drawn according to the selected process.

### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv* preprint arXiv:1906.06583. https://arxiv.org/abs/1906.06583.

```
generative_process(200,"Nonmixing")
```

12 predict.slm

plot.slm Plot.slm

### **Description**

Same function as the plot.lm function.

# Usage

```
## S3 method for class 'slm' plot(x, ...)
```

# **Arguments**

x slm object.

... other parameters to be passed through to plotting functions.

### Value

This function returns the graphics of plot.lm(x).

### **Examples**

```
data("shan")
reg = slm(shan$PM_Xuhui ~ . , data = shan, method_cov_st = "fitAR", model_selec = -1)
plot(reg)
```

predict.slm

Predict for slm object

#### **Description**

Predicted values based on slm object.

#### Usage

```
## S3 method for class 'slm'
predict(object, newdata = NULL, interval = "confidence",
  level = 0.95, ...)
```

# Arguments

object an object of class slm.

newdata an optional data frame in which to look for variables with which to predict.

newdata must contain only variables and not the intercept. If omitted, the fitted

values are used.

interval type of interval calculation. It can be only interval = "confidence", the

default value. It computes the confidence intervals for x'beta, where x' is a new

observation of the design.

level tolerance/confidence level.

... further arguments passed to or from other methods.

Rboot 13

#### **Details**

This function produces predicted values, obtained by evaluating the regression function in the frame newdata (which defaults to model.frame(object)). If newdata is omitted the predictions are based on the data used for the fit.

#### Value

This function produces a vector of predictions or a matrix of predictions and bounds with column names fit, lwr, and upr if interval is set.

#### See Also

```
predict.lm.
```

#### **Examples**

```
data("shan")
reg1 = slm(shan$PM_Xuhui ~ . , data = shan, method_cov_st = "fitAR", model_selec = -1)
predict(reg1)

data("co2")
y = as.vector(co2)
x = as.vector(time(co2)) - 1958
reg2 = slm(y ~ x + I(x^2) + I(x^3) + sin(2*pi*x) + cos(2*pi*x) + sin(4*pi*x) +
cos(4*pi*x) + sin(6*pi*x) + cos(6*pi*x) + sin(8*pi*x) + cos(8*pi*x),
method_cov_st = "fitAR", model_selec = -1)
predict(reg2)
```

Rboot

Risk estimation for a tapered covariance matrix estimator via bootstrap method

### **Description**

This function computes an estimation of the risk for the tapered covariance matrix estimator of a process via a bootstrap method, for a specified treshold and a specified kernel.

#### Usage

```
Rboot(epsilon, treshold, block_size, block_n, model_max, kernel_fonc)
```

### **Arguments**

epsilon	an univariate process.
treshold	number of estimated autocovariance terms that we consider for the estimation of the covariance matrix.
block_size	the size of the bootstrap blocks. $block\_size$ must be greater than $model\_max$ .
block_n	blocks number used for the bootstrap.
model_max	the maximal dimension, that is the maximal number of terms available to estimate the covariance matrix.
kernel_fonc	the kernel to use. The user can define his own kernel and put it in the argument.

14 rectangle

### Value

This function returns a list with:

risk for one treshold, the value of the estimated risk.

SE the standard-error due to the bootstrap.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

W.B. Wu, M. Pourahmadi (2009). Banding sample autocovariance matrices of stationary processes. *Statistica Sinica*, pp. 1755–1768.

rectangle

Rectangular kernel

# **Description**

Rectangular kernel

### Usage

```
rectangle(x)
```

# Arguments

Х

a vector of real numbers.

# Value

This function computes the values of the rectangular kernel at points x.

```
x = seq(-2,2,length=1000)
y = rectangle(x)
plot(x,y)
```

shan 15

shan

PM2.5 Data of Shanghai

### **Description**

This dataset comes from a study about fine particle pollution in five Chinese cities. The data are available on the following website <a href="https://archive.ics.uci.edu/ml/datasets/PM2.5+Data+of+Five+Chinese+Cities#">https://archive.ics.uci.edu/ml/datasets/PM2.5+Data+of+Five+Chinese+Cities#</a>. The present dataset concerns the city of Shanghai. From the initial dataset, we have removed the lines that contain NA observations and we then extract the first 5000 observations. Then we consider only pollution variables and weather variables.

#### Usage

```
data("shan")
```

### **Format**

A data frame with 5000 rows and 10 variables:

**PM\_Xuhui** PM2.5 concentration in the Xuhui district (ug/m3).

**PM\_Jingan** PM2.5 concentration in the Jing'an district (ug/m3).

**PM\_US.Post** PM2.5 concentration in the U.S diplomatic post (ug/m3).

**DEWP** Dew Point (CelsiusDegree).

**TEMP** Temperature (CelsiusDegree).

**HUMI** Humidity (%).

**PRES** Pressure (hPa).

**Iws** Cumulated wind speed (m/s).

**precipitation** hourly precipitation (mm).

**Iprec** Cumulated precipitation (mm).

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

X. Liang, S. Li, S. Zhang, H. Huang, S.X. Chen (2016). PM2.5 data reliability, consistency, and air quality assessment in five Chinese cities. *Journal of Geophysical Research: Atmospheres*, 121(17), 10–220.

16 slm

|--|

# Description

slm is used to fit linear models when the error process is assumed to be strictly stationary.

### Usage

```
slm(myformula, data = NULL, model = TRUE, x = FALSE, y = FALSE,
    qr = TRUE, method_cov_st = "fitAR", cov_st = NULL, Cov_ST = NULL,
    model_selec = -1, model_max = 50, kernel_fonc = NULL,
    block_size = NULL, block_n = NULL, plot = FALSE)
```

# **Arguments**

myformula	an object of class "formula" (or one that can be coerced to that class): a symbolic description of the model to be fitted.
data	an optional data frame, list or environment (or object coercible by as.data.frame to a data frame) containing the variables in the model. If not found in data, the variables are taken from environment(formula), typically the environment from which slm is called.
model, x, y, q	r
	logicals. If TRUE the corresponding components of the fit (the model frame, the model matrix, the response, the QR decomposition) are returned.
method_cov_st	the method chosen by the user to estimate the autocovariances of the error process. The user has the choice between the methods "fitAR", "spectralproj", "efromovich", "kernel", or "select". By default, the "fitAR" method is used.
cov_st	the estimated autocovariances of the error process. The user can give his own vector.
Cov_ST	an argument given by the user if he wants to use his own covariance matrix estimator.
model_selec	the order of the method. If $model_selec = -1$ , the method works automatically.
model_max	maximal order of the method.
kernel_fonc	to use if method_cov_st = kernel. Define the kernel to use in the method. The user can give his own kernel function.
block_size	<pre>size of the bootstrap blocks if method_cov_st = kernel. block_size must be greater than model_max.</pre>
block_n	blocks number to use for the bootstrap if method_cov_st = kernel.
plot	logical. By default, plot = FALSE.

### **Details**

The slm function is based on the architecture of the lm function. Models for slm are specified symbolically. A typical model has the form response  $\sim$  terms where response is the (numeric) response vector and terms is a series of terms which specifies a linear predictor for response. See the documentation of lm for more details.

slm 17

#### Value

slm returns an object of class "slm". The function summary is used to obtain and print a summary of the results. The generic accessor functions coefficients, effects, fitted.values and residuals extract various useful features of the value returned by slm. An object of class "slm" is a list containing at least the following components:

method\_cov\_st print the method chosen.

cov\_st the estimated autocovariances of the error process.

Cov\_ST if given by the user, the estimated covariance matrix of the error process.

model selec the order of the method.

norm\_matrix the normalization matrix of the design.

design\_qr the matrix  $(X^tX)^{-1}$ .

coefficients a named vector of coefficients.

residuals the residuals, that is response minus fitted values.

fitted.values the fitted mean values.

rank the numeric rank of the fitted linear model.

df.residual the number of observations minus the number of variables.

call the matched call.
terms the terms object used.

xlevels (only where relevant) a record of the levels of the factors used in fitting.

y if requested, the response used.
x if requested, the model matrix used.

model if requested (the default), the model frame used.

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

### See Also

summary for summaries.

The generic functions coef, effects, residuals, fitted, vcov.

predict for prediction, including confidence intervals for x'beta, where x' is a new observation of the design.

confint for confidence intervals of parameters.

```
data("shan") slm(shan\$PM\_Xuhui ~ .~, data = shan, method\_cov\_st = "fitAR", model\_selec = -1) data("co2") \\ y = as.vector(co2) \\ x = as.vector(time(co2)) - 1958 \\ reg1 = slm(y ~ x + I(x^2) + I(x^3) + sin(2*pi*x) + cos(2*pi*x) + sin(4*pi*x) + cos(4*pi*x) + sin(6*pi*x) + cos(6*pi*x) + sin(8*pi*x) + cos(8*pi*x), \\ method\_cov\_st = "fitAR", model\_selec = -1, plot = TRUE)
```

18 summary.slm

```
reg2 = slm(y \sim x + I(x^2) + I(x^3) + sin(2*pi*x) + cos(2*pi*x) + sin(4*pi*x) + cos(4*pi*x) + sin(6*pi*x) + cos(6*pi*x) + sin(8*pi*x) + cos(8*pi*x), method_cov_st = "kernel", model_selec = -1, model_max = 50, kernel_fonc = triangle, block_size = 100, block_n = 100)
```

slm-class

slm class

#### **Description**

An S4 class to create an s1m object.

#### **Slots**

method\_cov\_st the method used to compute the autocovariance vector of the error process.

cov\_st a numeric vector with the estimated autocovariances of the error process, computed from the method\_cov\_st method.

Cov\_ST the estimated covariance matrix of the error process, computed from the method\_cov\_st method

model\_selec the order of the chosen method. If model\_selec = -1, the method works automatically.

 $\label{lem:norm_matrix} \mbox{ norm_matrix of the design } X.$ 

design\_qr the matrix  $(X^tX)^{-1}$ .

#### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv preprint arXiv:1906.06583*. https://arxiv.org/abs/1906.06583.

summary.slm

Summarizing Stationary Linear Model Fits

#### **Description**

Summary method for class "slm".

### Usage

```
## S3 method for class 'slm'
summary(object, correlation = FALSE,
    symbolic.cor = FALSE, ...)
```

# Arguments

object an object of class "slm", usually, a result of a call to slm.

correlation logical; if TRUE, the correlation matrix of the estimated parameters is returned

and printed.

symbolic.cor logical. If TRUE, print the correlations in a symbolic form (see symnum) rather

than as numbers.

... further arguments passed to or from other methods.

summary.slm 19

#### Value

The function summary.slm computes and returns a list of summary statistics of the fitted linear model given in object, using the components (list elements) "call" and "terms" from its argument, plus:

residuals	the residuals, that is response minus fitted values.
coefficients	a $p*4$ matrix with columns for the estimated coefficient, its standard error, z-statistic and corresponding (two-sided) p-value. Aliased coefficients are omitted.
aliased	named logical vector showing if the original coefficients are aliased.
sigma	the square root of the estimated variance of the error process.
df	degrees of freedom, a 3-vector $(p, n-p, p*)$ , the first being the number of non-aliased coefficients, the last being the total number of coefficients.
chi2statistic	a 2-vector with the value of the chi2-statistic with its degree of freedom.
r.squared	$R^2$ , the 'fraction of variance explained by the model'.
cov.unscaled	a $p*p$ matrix of (unscaled) covariances of the $coef[j], j=1,\ldots,p$ .
correlation	the correlation matrix corresponding to the above ${\tt cov.unscaled},$ if ${\tt correlation}$ = TRUE is specified.
symbolic.cor	(only if correlation is true.) The value of the argument symbolic.cor.

### References

E. Caron, J. Dedecker and B. Michel (2019). Linear regression with stationary errors: the R package slm. *arXiv* preprint arXiv:1906.06583. https://arxiv.org/abs/1906.06583.

#### See Also

The model fitting function slm, summary.

The function coef extracts the matrix of coefficients with standard errors, z-statistics and p-values.

20 triangle

trapeze

Trapeze kernel

# Description

Trapeze kernel

# Usage

```
trapeze(x, width = 0.8)
```

### **Arguments**

x a vector of real numbers. width a number between 0 and 1.

### Value

This function computes the values of the trapeze kernel at points x.

# **Examples**

```
x = seq(-2,2,length=1000)
y = trapeze(x, width=0.5)
plot(x,y)
```

triangle

Kernel triangle

# Description

Kernel triangle

# Usage

```
triangle(x)
```

# Arguments

Χ

a vector of real numbers.

### Value

This function computes the values of the triangle kernel at points x.

```
x = seq(-2,2,length=1000)
y = triangle(x)
plot(x,y)
```

# **Index**

```
*Topic datasets
    shan, 15
as.data.frame, 16
capushe, 9, 10
class, 17
coef, 17, 19
confint, 17
confint.lm, 3
confint.slm, 3
cov_AR, 4
\verb"cov_efromovich", 5"
cov_kernel, 6
cov_matrix_estimator, 7
cov_method, 7
cov_select, 8
cov_spectralproj, 9
DDSE, 10
Djump, 10
effects, 17
fitted, 17
formula, 16
{\tt generative\_model}, \\ 10
generative_process, 11
lm, 16
plot.lm, 12
plot.slm, 12
predict, 17
predict.lm, 13
predict.slm, 12
Rboot, 6, 13
rectangle, 14
residuals, 17
shan, 15
slm, 16, 19
slm-class, 18
```

```
slm-package, 2
slm.class(slm-class), 18
summary, 17, 19
summary.slm, 18
symnum, 18
terms, 17
trapeze, 20
triangle, 20
vcov, 17
```