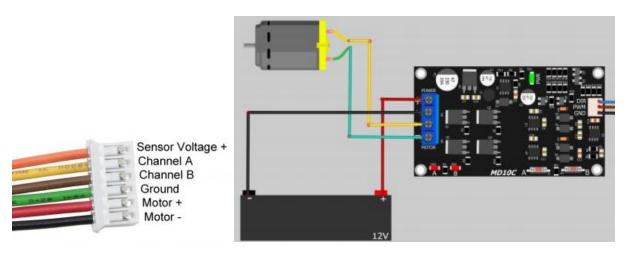


NOTE: THE COMMON GROUND IS ONLY FOR PROTOTYPING PURPOSES. THE SERVO'S POWER AND LOGIC CONNECTIONS WILL BE ISOLATED IN THE FINAL DESIGN

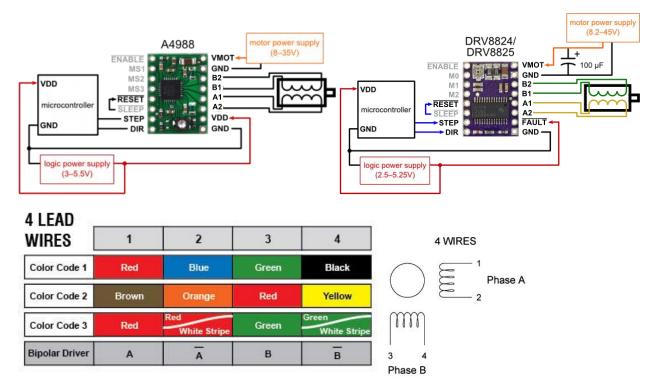


			GN						
			D		VIN				
DV ODDOID	DV4		•		AGN				
RX_ODROID	RX1		0		D				
TX_ODROID	TX1		1		3.3v				
		PW M	2		23	A9	PW M		M3_LIMIT_SW_EXTEN D
RESERVED FOR I2C	SCL 2	PW M	3		22	A8	PW M		M3_LIMIT_SW_FLEX
RESERVED FOR I2C	SDA 2	PW M	4		21	A7	PW M		M3_STEP
M1_DIR		PW M	5		20	A6	PW M	SDA 0	M3_DIR
M1_PWM		PW M	6			A5		SCL 0	M3_ENCODER_A
W1_1 VVW		PW	J		10	710			INO_ENCODEN_/
M1_ENCODER_A	RX3	М	7		18	A4			M3_ENCODER_B
M1 ENCODER B	TX3	PW M	8		17	A3	PW M		M3_ENABLE
		PW	Ü			, .0	PW		WO_ENVISEE
M1_LIMIT_SW_CW	RX2	М	9		16	A2	М		M4_ENABLE
M1_LIMIT_SW_CCW	TX2	PW M	10	TEENS Y 3.6	15	A1			M4_DIR
M4_ENCODER_A			11		14	A0	PW M		M4_STEP
M4_ENCODER_B			12		13				HEARTBEAT
			3.3v		GND				
M4_LIMIT_SW_EXTEN			24			DAC 1			
M4_LIMIT_SW_FLEX			25			DAC 0			
M2_ENCODER_A			26		30	A20			
WZ_LNOODLN_A			20		33	720	PW	SDA	
M2_ENCODER_B			27		38	A19	M	1	M6_ENCODER_B
M2_LIMIT_SW_FLEX			28		37	A18	PW M	SCL 1	M6_ENCODER_A
M2_LIMIT_SW_EXTEN D		PW M	29		36	A17	PW M		M6_PWM
M2_PWM		PW M	30		35	A16	PW M		M5_PWM
M2_DIR_PIN	RX4	A12	31		34	A15		RX5	M5_ENCODER_B
	TX4	A13	32		33	A14		TX5	M5 ENCODER A
NOTE: the encoders for M5 and M6 won't be implemented yet because it would require modifying the serves									

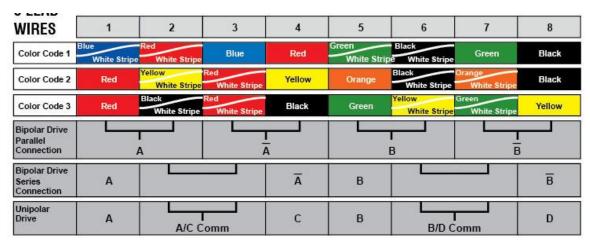
NOTE: the encoders for M5 and M6 won't be implemented yet because it would require modifying the servos which is risky.

	DC Motors		Steppers		Servos	
	M1		M3		M5	
Encoder A	7	Encoder A	19	Encoder A	33	
Encoder B	8	Encoder B	18	Encoder B	34	
Direction	5	Enable	17	PWM	35	
PWM	6	Step	21			
		Direction	20			
	M2		M4		M6	
Encoder A	26	Encoder A	11	Encoder A	38	
Encoder B	27	Encoder B	12	Encoder B	39	
Direction	31	Enable	16	PWM	36	
PWM	30	Step	14			
		Direction	15			

NOTE: Orange and red means the encoders are unused right now. Red because it's likely we won't have encoders in the servos and orange because we may use the encoders in the steppers in the future.



NOTE: Ignore this and just use colour code 1 from the 4 wire stepper diagram. Reasoning is that in our case, we're connecting 8 wires into 4 using the series connection (see 8-wire diagram above). I wired it up so both motors have the same colour code which makes things easier for prototyping.



8 WIRES

